

SAI SIDDARTH NICHENAMETLA

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EDUCATION

Master of Science, August 2022 – December 2023

- **Engineering Science (Robotics)**, University at Buffalo, The State University of New York, GPA: 3.519/4

Bachelor of Technology, August 2017 - July 2021

- **Mechanical Engineering**, Jawaharlal Nehru Technological University-Hyderabad, India, GPA: 7.66/10

WORK EXPERIENCE

Manufacturing Automation Engineer, Xylem, Buffalo, NY: September 2023 – December 2023

- Spearheaded the design and implementation of an automated production line for manufacturing of compact coolers utilizing Fanuc Robots and Fanuc m710ic/45 robot for simulation purposes using python.
- This integration of welding, testing, painting, and curing processes significantly enhanced productivity, assembling, and operating machinery, reducing manufacturing time to 45 minutes, and reduced manual labor requirements by 85%.
- Engineered a sophisticated motion planning algorithm with an automatic tool switching feature, significantly improving operational safety, and reducing machinery collision risks which led to safer, and more efficient production workflows.
- Directed the integration of conveyor belt systems and hardware with PLC programming, achieving seamless automation and synchronized operations across the production line that significantly optimized efficiency and minimized downtime.

Assistant Systems Engineer, Tata Consultancy Services, Hyderabad, Telangana, India: October 2021 – May 2022

- Served as an SAP Fiori Security Consultant, overseeing management and optimization of EAS tasks (enterprise application system) within SAP Fiori application, with a particular emphasis on assignment of roles and access controls.
- This role involved the meticulous allocation of system privileges and the safeguarding of application data integrity.
- Crafted and implemented comprehensive protocols for creation of security roles and testing of applications. This process included defining access permissions, establishing security guidelines.
- This responsibility entailed the precise configuration of access rights, the maintenance of user permissions, and the preparation of applications for further processing, thereby enhancing overall system security and functionality.

Engineer- Intern, Uniscent Engineering Private Limited, Hyderabad, Telangana, India: May 2019 – July 2019

- Specialized in designing a range of heat exchangers tailored to specific customer requirements using Catia V5 and SolidWorks, ensuring precise and functional product development from initial concept to final design.
- Conducted comprehensive Computational Fluid Dynamics (CFD) simulations and thermal analyses using Ansys, incorporating Finite Element Analysis (FEA) to evaluate and optimize heat exchanger performance under various operational conditions.
- Finalized and prepared detailed product drafts and documentation in AutoCAD, ensuring accuracy and adherence to engineering standards, facilitating a smooth transition from design to manufacturing.

ENGINEERING PROJECTS

Intelligent Radar based Autonomous Navigation for Turtlebot, 2024: Python, ROS, Linux

- Designed and deployed a neural network-based control system for a Turtlebot equipped with a trio of radars, achieving autonomous navigation within circuit environments with a remarkable accuracy rate of 98.9%.
- Utilized radars for precise obstacle detection and distance measurement, enabling the robot to dynamically adjust its path in real-time, ensuring efficient and uninterrupted circuit navigation.
- Implemented strategic logic within the control system to optimize the robot's movements based on environmental feedback, significantly reducing collision risk, and enhancing pathfinding efficiency across multiple circuits.

Collision Avoidance, 2023: MATLAB, CoppeliaSim (V-rep)

- Adapted autonomous vehicle collision avoidance concepts to engineer a path and motion planning algorithm for a Powerball robot manipulator, navigating around both static and dynamic obstacles through Probabilistic Road Maps (PRM), and Temporal Probabilistic Road Maps (T-PRM) with A* search.
- Upgrading obstacle prediction accuracy by incorporating a vision system and Kalman filter into the system, reaching a 70% success rate in dynamic obstacle avoidance scenarios.

Path Planning, 2023: Python, OpenCV

- Developed 3 path planning algorithms-RRT, A* search, and Dijkstra's for static obstacle avoidance, leveraging libraries of Python for map processing and visualization, and highlighting applications in self-driving vehicles and collaborative robotics.

Emotion, Age and Gender Recognition, 2023: MATLAB

- Crafted a linear classifier for precise identification of characteristics including gender, age, and emotion, utilizing inherent feature-extraction functions.
- Discovered a positive correlation between enlarged training dataset size and recognition accuracy, achieving 97% accuracy in gender detection, 90% in age, and 51% in emotion recognition.

Gesture Recognition, 2023: MATLAB

- Designed a sophisticated gesture recognition system by extracting Rubine features, with weight derivation from collected training data via MATLAB GUI enhancing linear classification and accurately differentiates gestures.
- Boasted a 98.9% accuracy rate in comparing the test data against the training data, showcasing the systems for applications such as gesture-based control systems.

Stereo Visual Odometry, 2023: Python, Robotic Operating Systems (ROS), Linux, OpenCV, Structure from Motion

- Engineered a Stereo Camera framework to achieve advanced visual odometry for precise 3D pose retrieval, focusing exclusively on the odometry dataset. This project was developed from scratch using computer vision techniques, OpenCV, and NumPy.
- Performed visual odometry entirely using computer vision techniques to accurately estimate the trajectory of the stereo camera setup. This approach enabled the precise tracking of vehicle movement through complex environments without relying on sensor fusion methods.
- Utilized advanced camera calibration and feature extraction methods to enhance the accuracy and reliability of odometry calculations utilizing RANSAC, achieving a significant improvement in performance and providing a robust foundation for autonomous vehicle navigation systems.

Markov Localization, 2023: MATLAB

- Devised a Markov localization algorithm for Simultaneous Localization and Mapping (SLAM) suite, enhancing robot's state estimation for location scanning by combining sensor data with motion models, continued by simulations to validate effectiveness, confirming its robustness and dependability through extensive testing.

Path Following Mobile Robot Using PID and Pure Pursuit Controller, 2023: Python, Linux, Robot Operating Systems (ROS)

- Incorporated PID and Pure Pursuit control techniques into Linux-based ROS frameworks to strengthen robot's path tracing and motion planning functions, exploiting ROS utilities for seamless meshing.
- Customized application for F1tenth autonomous race car, showcasing adaptability to robotic models and acquire a precise error margin of 0.2 meters.

Face Recognition, 2022: Python, OpenCV

- Leveraged OpenCV capabilities to detect faces and extract encodings, then clustered with K-means to categorize similar faces, resulting in 5 distinct clusters corresponding to five celebrity visages with flawless 100% precision, attributed to comprehensive utilization of unique features processed by OpenCV library.

Industrial Grease Interceptor, 2021: SolidWorks, Catia V5, Ansys, AutoCAD

- A device is engineered to segregate solid from liquid waste before it enters sewage, employed SolidWorks and Catia V5 for 3D modeling, Ansys for analytical assessment, and AutoCAD for precision drafting followed by production involving sheet metal bending, welding, and plumbing.

All-Terrain Vehicle, 2020: SolidWorks, Catia V5, Ansys, NX CAD, AutoCAD, Lotus, MSC ADAMS

- Modelled an all-terrain vehicle 3D modeling software, conducted FEA analysis in Ansys, and static and dynamic analysis via ADAMS.
- My manufacturing support, particularly in vibration mitigation, CNC machining, welding, and fabrication boosted my project management expertise.
- Created a detailed bill of materials, a technical presentation, and carried out cost and sales analysis, and vehicle was displayed at SAE BAJA 2020, showcasing my leadership in the college's SAE club as an executive council member.

Plastic Shredder Machine, 2019: Catia V5, NX CAD, AutoCAD

- Launched a primary plastic recycling device, designing blade profiles and components are machined by laser and plasma cutting.
- My prior accomplishments, clinching 1st place in Welding, Tier 1 event at SAE 2018, assisted our team's commitment to quality manufacturing and the system is driven by a 1.5HP motor coupled directly to mechanism.

CASE STUDY & RESEARCH

Design of Suspension System and its effects on different Sub-systems of an All-Terrain Vehicle, IJAIE, 2020

- Designed and analyzed an all-terrain vehicle suspension system and its interconnected sub-systems with SolidWorks and Catia V5. Conducted structural analysis with Ansys and extracted suspension characteristics through Lotus, ensuring comprehensive assessment and optimization of suspension performance.

SKILLS & TOOLS

Languages: Python, C++, PLC, Linux, Pneumatics, AWS, SQL, MATLAB – Workspace, Simulink

Computer Skills: Microsoft Office

3D Modelling and Drafting Programs: AutoCAD, Catia V5, SolidWorks-CSWP, Ansys, Autodesk Sketchbook, NX CAD, Autodesk Fusion, 3D Printing and Scanning