Yoga Pose Classification Model

Overview

This project implements a machine learning pipeline to classify yoga poses from images. It uses the MoveNet pose estimation model to extract human body keypoints from images, preprocesses these keypoints, and then trains a neural network to classify the pose. The project is structured for extensibility and clarity, with modular code for data handling, preprocessing, pose estimation, and model training.

Directory and File Structure

```
classification model/
— data.py
- training.py
- proprocessing.py
- movenet.py
movenet_thunder.tflite
- weights.best.hdf5
- train_data.csv
- test_data.csv
- model/
- model.json
  └── group1-shard1of1.bin
- csv_per_pose/
- chair.csv
  - cobra.csv
  - dog.csv
  - no_pose.csv
  - shoudler_stand.csv
 - traingle.csv
  - tree.csv
  L- warrior.csv
└─ yoga_poses/
   - train/
   - chair/
     - cobra/
     --- dog/
     - no_pose/
   - shoudler_stand/
     - traingle/
     -- tree/
     L- warrior/
   L_ test/
      - chair/
      - cobra/
      - dog/
      - no_pose/
      - shoudler_stand/
      - traingle/
```

Detailed Explanation of Each File

1. data.py

• Purpose:

Provides data structures and utility functions for pose estimation, adapted from the TensorFlow example repository.

• Key Components:

- BodyPart (Enum): Enumerates the 17 keypoints detected by pose estimation models (e.g., NOSE, LEFT_EYE, RIGHT_SHOULDER, etc.).
- Point, Rectangle, KeyPoint, Person (NamedTuple): Data structures to represent 2D points, bounding boxes, keypoints, and detected persons.
- person_from_keypoints_with_scores: Converts raw keypoint output from MoveNet into a Person object, computes bounding boxes, and averages keypoint scores.
- Category (NamedTuple): Represents a classification result (label and score).

2. training.py

Purpose:

Loads preprocessed data, defines the neural network architecture, trains the model, evaluates it, and exports it for deployment.

Key Components:

- load_csv: Loads a CSV file, drops the filename, extracts class labels, and prepares features and one-hot encoded targets.
- get_center_point, get_pose_size, normalize_pose_landmarks: Functions for normalizing pose keypoints, centering, and scaling them for model input.
- o landmarks_to_embedding: Converts 17 keypoints (x, y, score) into a flattened embedding vector.
- o preprocess_data: Applies embedding transformation to all samples.
- Model Definition:
 - Input: 34-dimensional vector (flattened, normalized keypoints).
 - Hidden Layers: Dense (128, relu6) \rightarrow Dropout (0.5) \rightarrow Dense (64, relu6) \rightarrow Dropout (0.5).
 - Output: Dense (number of classes, softmax).

o Training Loop:

- Uses early stopping and model checkpointing.
- Trains for up to 200 epochs, batch size 16.
- Evaluates on test data and prints loss/accuracy.
- Exports the model to TensorFlow.js format (model/directory).

3. proprocessing.py

• Purpose:

Preprocesses images to extract pose keypoints using MoveNet, saves per-pose CSVs, and combines them into training/testing datasets.

. Key Components:

- Movenet Model Download: Downloads the MoveNet Thunder TFLite model if not present.
- o detect: Runs pose detection on an image tensor, with multiple inference passes for stability.

o Preprocessor Class:

- init: Sets up input/output paths, creates output directories, and lists pose classes.
- process: For each pose class, iterates over images, runs pose detection, filters by keypoint confidence, and writes keypoints to CSV. Skips invalid or low-confidence images.
- all_landmarks_as_dataframe: Merges all per-class CSVs into a single DataFrame, adds class labels, and writes to a combined CSV.

Script Execution:

Runs preprocessing for both training and testing images, generating train_data.csv and test data.csv.

4. movenet.py

• Purpose:

Implements the MoveNet pose estimation model wrapper, handling model loading, inference, and smart cropping.

· Key Components:

Movenet Class:

- init: Loads the TFLite model, sets up input/output details.
- init_crop_region: Computes a default crop region to ensure the person is centered and scaled.
- _torso_visible, _determine_torso_and_body_range, _determine_crop_region: Helper methods for smart cropping based on detected keypoints.
- _crop_and_resize, _run_detector: Internal methods for image preprocessing and running inference.
- detect: Main method to run pose estimation on an input image, returning a Person object with keypoints and scores.

• Purpose:

The pre-trained MoveNet Thunder model in TensorFlow Lite format, used for fast and accurate pose estimation.

• Purpose:

Stores the best weights of the trained classification model, used for inference or further training.

7. train data.csv/test data.csv

• Purpose:

Combined CSVs containing all keypoints and labels for training and testing, generated by the preprocessing pipeline.

Purpose:

Contains per-pose CSV files, each storing keypoints for all images of a specific pose class (e.g., chair.csv, cobra.csv, etc.).

• Purpose:

Stores the exported trained model in TensorFlow.js format for deployment in web applications.

- model.json: Model architecture and metadata.
- o group1-shard1of1.bin: Model weights.

• Purpose:

Contains all raw images, organized by pose and split into train/ and test/ sets. Each subfolder corresponds to a yoga pose class.

Data Flow and Pipeline

1. Image Collection:

• Images are stored in yoga_poses/train/ and yoga_poses/test/, organized by pose class.

2. Pose Estimation (Preprocessing):

- proprocessing.py uses movenet.py and movenet_thunder.tflite to extract 17 keypoints (x, y, score) from each image.
- Keypoints are saved in per-pose CSVs (csv_per_pose/) and then merged into train_data.csv and test data.csv.

3. Data Normalization and Embedding:

 training.py normalizes keypoints (centering, scaling) and flattens them into 34-dimensional vectors for model input.

4. Model Training:

- A neural network is trained on the processed data, with early stopping and checkpointing.
- The best model is saved as weights.best.hdf5 and exported to TensorFlow.js format.

5. Evaluation and Deployment:

- The model is evaluated on test data.
- o The exported model can be used in web applications for real-time yoga pose classification.

How to Use

1. Prepare Data

Place your images in the appropriate folders under yoga_poses/train/ and yoga_poses/test/, organized by pose class.

2. Preprocess Data

• Run proprocessing.py to extract keypoints and generate train_data.csv and test_data.csv.

3. Train the Model

Run training.py to train the classifier. The best weights will be saved, and the model will be exported for web
use.

4. Inference

• Use the trained model (weights.best.hdf5 or the TensorFlow.js model) to classify new images.

Major Code Blocks and Their Roles

- Keypoint Extraction:
 - o movenet.py and proprocessing.py work together to extract and store pose keypoints from images.
- Data Normalization:
 - training.py normalizes and embeds keypoints for robust model training.
- Model Architecture:
 - Defined in training.py as a simple feedforward neural network with dropout for regularization.
- Training and Evaluation:

• training.py handles the full training loop, validation, checkpointing, and evaluation.

• Export and Deployment:

• Model is exported to TensorFlow.js format for use in web applications.

Notes

- The code is modular and can be extended to support more poses or different model architectures.
- The MoveNet model is efficient and suitable for real-time applications.
- The preprocessing pipeline ensures only high-confidence keypoints are used for training, improving model accuracy.

Credits

• Some modules (notably data.py and movenet.py) are adapted from the official TensorFlow examples.

If you need further breakdowns (e.g., function-by-function documentation or code comments), let me know!