CNN Lab 2023

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1 CNN Image Classification Laboration

Images used in this laboration are from CIFAR 10 (https://en.wikipedia.org/wiki/CIFAR-10). The CIFAR-10 dataset contains 60,000 32x32 color images in 10 different classes. The 10 different classes represent airplanes, cars, birds, cats, deer, dogs, frogs, horses, ships, and trucks. There are 6,000 images of each class. Your task is to make a classifier, using a convolutional neural network, that can correctly classify each image into the correct class.

You need to answer all questions in this notebook.

1.1 Part 1: What is a convolution

To understand a bit more about convolutions, we will first test the convolution function in scipy using a number of classical filters.

Convolve the image with Gaussian filter, a Sobel X filter, and a Sobel Y filter, using the function 'convolve2d' in 'signal' from scipy.

https://docs.scipy.org/doc/scipy/reference/generated/scipy.signal.convolve2d.html

In a CNN, many filters are applied in each layer, and the filter coefficients are learned through back propagation (which is in contrast to traditional image processing, where the filters are designed by an expert).

```
[]: # This cell is finished

from scipy import signal
import numpy as np

# Get a test image
from scipy import misc
image = misc.ascent()

# Define a help function for creating a Gaussian filter
def matlab_style_gauss2D(shape=(3,3),sigma=0.5):
    """

2D gaussian mask - should give the same result as MATLAB's
```

```
fspecial('qaussian',[shape],[siqma])
    m,n = [(ss-1.)/2. \text{ for ss in shape}]
    y,x = np.ogrid[-m:m+1,-n:n+1]
    h = np.exp(-(x*x + y*y) / (2.*sigma*sigma))
    h[ h < np.finfo(h.dtype).eps*h.max() ] = 0</pre>
    sumh = h.sum()
    if sumh != 0:
        h /= sumh
    return h
# Create Gaussian filter with certain size and standard deviation
gaussFilter = matlab_style_gauss2D((15,15),4)
# Define filter kernels for SobelX and Sobely
sobelX = np.array([[1, 0, -1],
                    [2, 0, -2],
                     [1, 0, -1]])
sobelY = np.array([[ 1, 2, 1],
                     [0, 0, 0],
                     [-1, -2, -1]
```

<ipython-input-1-f842718450cf>:8: DeprecationWarning: scipy.misc.ascent has been
deprecated in SciPy v1.10.0; and will be completely removed in SciPy v1.12.0.
Dataset methods have moved into the scipy.datasets module. Use
scipy.datasets.ascent instead.

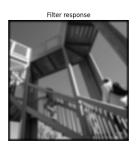
```
image = misc.ascent()
```

```
[]: # Perform convolution using the function 'convolve2d' for the different filters filterResponseGauss = signal.convolve2d(image,gaussFilter) filterResponseSobelX = signal.convolve2d(image,sobelX) filterResponseSobelY = signal.convolve2d(image,sobelY)
```

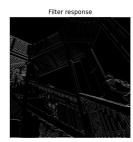
```
# Show filter responses
fig, (ax_orig, ax_filt1, ax_filt2, ax_filt3) = plt.subplots(1, 4, figsize=(20, 6))
ax_orig.imshow(image, cmap='gray')
ax_orig.set_title('Original')
ax_orig.set_axis_off()
ax_filt1.imshow(np.absolute(filterResponseGauss), cmap='gray')
ax_filt1.set_title('Filter response')
ax_filt1.set_axis_off()
ax_filt2.imshow(np.absolute(filterResponseSobelX), cmap='gray')
ax_filt2.set_title('Filter response')
```

```
ax_filt2.set_axis_off()
ax_filt3.imshow(np.absolute(filterResponseSobelY), cmap='gray')
ax_filt3.set_title('Filter response')
ax_filt3.set_axis_off()
```









1.2 Part 2: Understanding convolutions

Question 1: What do the 3 different filters (Gaussian, SobelX, SobelY) do to the original image?

Question 2: What is the size of the original image? How many channels does it have? How many channels does a color image normally have?

Question 3: What is the size of the different filters?

Question 4: What is the size of the filter response if mode 'same' is used for the convolution?

Question 5: What is the size of the filter response if mode 'valid' is used for the convolution? How does the size of the valid filter response depend on the size of the filter?

Question 6: Why are 'valid' convolutions a problem for CNNs with many layers?

Question 1: The Gaussian filter is used to reduce the noise in the image and also blurs the image. The SobelX filter helps detect edges in the horizontal direction and the SobelY filter helps detect edges in the vertical direction.

Question 2: Size of the original image is 512×512 . It has only one channel since its grayscale. For color, there is 3 channel (RGB)

Question 3: Gaussian $-> 15 \times 15$, sobelX $-> 3 \times 3$, sobeY $-> 3 \times 3$

Question 4: When mode = "same", the size for all 3 is 512×512

Question 5: When mode = "valid", the size of Gaussian -> 498×498 , the size of sobelX -> 510×510 , the size of sobelY -> 510×510 . The size of the valid filter becomes (Image size) - (size of the filter - 1)

Question 6: Because there is information loss in each layer due to the filtering that happens in each layer. The size of the filter response reduces in each layer due to the valid mode, so there is information loss.

[]: # Your code for checking sizes of image and filter responses

```
print(image.shape)
print(gaussFilter.shape)

print(sobelX.shape)

print(sobelY.shape)

filterResponseGauss_1 = signal.convolve2d(image,gaussFilter, mode = "valid")
print(filterResponseGauss_1.shape)

filterResponseSobelX = signal.convolve2d(image,sobelX, mode = "valid")
print(filterResponseSobelX.shape)
filterResponseSobelY = signal.convolve2d(image,sobelY, mode = "valid")
print(filterResponseSobelY.shape)
```

(512, 512) (15, 15) (3, 3) (3, 3) (498, 498) (510, 510) (510, 510)

1.3 Part 3: Get a graphics card

Skip this part if you run on a CPU (recommended)

Let's make sure that our script can see the graphics card that will be used. The graphics cards will perform all the time consuming convolutions in every training iteration.

```
tf.config.experimental.set_memory_growth(physical_devices[0], True)
```

1.4 Part 4: How fast is the graphics card?

Question 7: Why are the filters used for a color image of size 7 x 7 x 3, and not 7 x 7?

Question 8: What operation is performed by the 'Conv2D' layer? Is it a standard 2D convolution, as performed by the function signal.convolve2d we just tested?

Question 9: Do you think that a graphics card, compared to the CPU, is equally faster for convolving a batch of 1,000 images, compared to convolving a batch of 3 images? Motivate your answer.

Question 7: This is beacuse color images have 3 channels (RGB) so we need one fillter for each of the channels.

Question 8: It produces a different result compared to signal.convolve2d . In "signal.convolve2d", the filter (Kernel) is inverted before applying to the image while in "Conv2D" it is not.

Question 9: For a batch of 3 images, using a graphic card compared to the CPU might not yield drastic change in computational efficiency but for 1,000 images we should notice computational efficiency with using graphic card as comapred to the CPU. Graphic cards are designed to do multiple task in parallel making it perform overall tasks faster than the CPU.

1.5 Part 5: Load data

Time to make a 2D CNN. Load the images and labels from keras.datasets, this cell is already finished.

```
[]: from keras.datasets import cifar10
     import numpy as np
     classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', L
      ⇔'ship', 'truck']
     # Download CIFAR train and test data
     (Xtrain, Ytrain), (Xtest, Ytest) = cifar10.load data()
     print("Training images have size {} and labels have size {} ".format(Xtrain.
      ⇔shape, Ytrain.shape))
     print("Test images have size {} and labels have size {} \n ".format(Xtest.
      ⇒shape, Ytest.shape))
     # Reduce the number of images for training and testing to 10000 and 2000_{\square}
      ⇔respectively,
     # to reduce processing time for this laboration
     Xtrain = Xtrain[0:10000]
     Ytrain = Ytrain[0:10000]
     Xtest = Xtest[0:2000]
     Ytest = Ytest[0:2000]
```

```
Ytestint = Ytest
print("Reduced training images have size %s and labels have size %s " % (Xtrain.
  ⇒shape, Ytrain.shape))
print("Reduced test images have size %s and labels have size %s \n" % (Xtest.
 ⇒shape, Ytest.shape))
# Check that we have some training examples from each class
for i in range(10):
    print("Number of training examples for class {} is {}" .format(i,np.
  ⇔sum(Ytrain == i)))
Downloading data from https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz
170498071/170498071 [============ ] - 13s Ous/step
Training images have size (50000, 32, 32, 3) and labels have size (50000, 1)
Test images have size (10000, 32, 32, 3) and labels have size (10000, 1)
Reduced training images have size (10000, 32, 32, 3) and labels have size
(10000, 1)
Reduced test images have size (2000, 32, 32, 3) and labels have size (2000, 1)
Number of training examples for class 0 is 1005
Number of training examples for class 1 is 974
Number of training examples for class 2 is 1032
Number of training examples for class 3 is 1016
Number of training examples for class 4 is 999
Number of training examples for class 5 is 937
```

1.6 Part 6: Plotting

Number of training examples for class 6 is 1030 Number of training examples for class 7 is 1001 Number of training examples for class 8 is 1025 Number of training examples for class 9 is 981

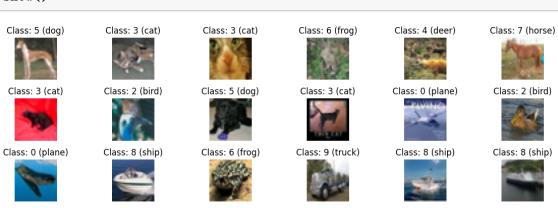
Lets look at some of the training examples, this cell is already finished. You will see different examples every time you run the cell.

```
[]: import matplotlib.pyplot as plt

plt.figure(figsize=(12,4))
for i in range(18):
    idx = np.random.randint(7500)
    label = Ytrain[idx,0]

plt.subplot(3,6,i+1)
    plt.tight_layout()
```

```
plt.imshow(Xtrain[idx])
  plt.title("Class: {} ({})".format(label, classes[label]))
  plt.axis('off')
plt.show()
```



1.7 Part 7: Split data into training, validation and testing

Split your training data into training (Xtrain, Ytrain) and validation (Xval, Yval), so that we have training, validation and test datasets (as in the previous laboration). We use a function in scikit learn. Use 25% of the data for validation.

https://scikit-learn.org/stable/modules/generated/sklearn.model_selection.train_test_split.html

```
Xtest has size (2000, 32, 32, 3).
Ytest has size (2000, 1).
```

1.8 Part 8: Preprocessing of images

Lets perform some preprocessing. The images are stored as uint8, i.e. 8 bit unsigned integers, but need to be converted to 32 bit floats. We also make sure that the range is -1 to 1, instead of 0 - 255. This cell is already finished.

```
[]: # Convert datatype for Xtrain, Xval, Xtest, to float32
Xtrain = Xtrain.astype('float32')
Xval = Xval.astype('float32')

Xtest = Xtest.astype('float32')

# Change range of pixel values to [-1,1]
Xtrain = Xtrain / 127.5 - 1
Xval = Xval / 127.5 - 1
Xtest = Xtest / 127.5 - 1
```

1.9 Part 9: Preprocessing of labels

The labels (Y) need to be converted from e.g. '4' to "hot encoded", i.e. to a vector of type [0, 0, 0, 1, 0, 0, 0, 0, 0]. We use a function in Keras, see https://keras.io/api/utils/python_utils/#to_categorical-function

```
[]: from tensorflow.keras.utils import to_categorical

# Print shapes before converting the labels
print(Ytrain.shape)
print(Yval.shape)
print(Ytest.shape)

# Your code for converting Ytrain, Yval, Ytest to categorical
Ytrain_enc=to_categorical((Ytrain),10)
Yval_enc=to_categorical((Yval),10)
Ytest_enc=to_categorical((Ytest),10)

# Print shapes after converting the labels
print(Ytrain_enc.shape)
print(Yval_enc.shape)
print(Ytest_enc.shape)
```

```
(7500, 1)
(2500, 1)
(2000, 1)
(7500, 10)
```

```
(2500, 10)
(2000, 10)
```

1.10 Part 10: 2D CNN

Finish this code to create the image classifier, using a 2D CNN. Each convolutional layer will contain 2D convolution, batch normalization and max pooling. After the convolutional layers comes a flatten layer and a number of intermediate dense layers. The convolutional layers should take the number of filters as an argument, use a kernel size of 3×3 , 'same' padding, and relu activation functions. The number of filters will double with each convolutional layer. The max pooling layers should have a pool size of 2×2 . The intermediate dense layers before the final dense layer should take the number of nodes as an argument, use relu activation functions, and be followed by batch normalization. The final dense layer should have 10 nodes (= the number of classes in this laboration) and 'softmax' activation. Here we start with the Adam optimizer.

Relevant functions are

model.add(), adds a layer to the network

Dense(), a dense network layer

Conv2D(), performs 2D convolutions with a number of filters with a certain size (e.g. 3 x 3).

BatchNormalization(), perform batch normalization

MaxPooling2D(), saves the max for a given pool size, results in down sampling

Flatten(), flatten a multi-channel tensor into a long vector

model.compile(), compile the model, add "metrics=['accuracy']" to print the classification accuracy during the training

See https://keras.io/api/layers/core_layers/dense/ and https://keras.io/api/layers/reshaping_layers/flatten/ for information on how the Dense() and Flatten() functions work

See https://keras.io/layers/convolutional/ for information on how Conv2D() works

See https://keras.io/layers/pooling/ for information on how MaxPooling2D() works

Import a relevant cost function for multi-class classification from keras.losses (https://keras.io/losses/), it relates to how many classes you have.

See the following links for how to compile, train and evaluate the model

https://keras.io/api/models/model_training_apis/#compile-method

https://keras.io/api/models/model training apis/#fit-method

https://keras.io/api/models/model training apis/#evaluate-method

```
[]: from keras.models import Sequential, Model
from keras.layers import Input, Conv2D, BatchNormalization, MaxPooling2D,

→Flatten, Dense, Dropout
from tensorflow.keras.optimizers import Adam
from keras.losses import CategoricalCrossentropy
```

```
# Set seed from random number generator, for better comparisons
from numpy.random import seed
seed(123)
def build_CNN(input_shape, n_conv_layers=2, n_filters=16, n_dense_layers=0,_u
 on_nodes=50, use_dropout=False, learning_rate=0.01):
    # Setup a sequential model
    model = Sequential()
    # Add first convolutional layer to the model, requires input shape
    model.add(Conv2D(filters=n_filters,kernel_size=(3,3), padding = "same",
        activation= "ReLU" , input_shape=input_shape ))
    model.add(MaxPooling2D(pool_size=(2, 2)))
    # Add remaining convolutional layers to the model, the number of filters \Box
 ⇒should increase a factor 2 for each layer
    for i in range(n_conv_layers-1):
      n_filters = n_filters*2
      model.add(Conv2D(filters=n_filters,kernel_size=(3,3), padding = "same",
        activation= "ReLU"))
      model.add(MaxPooling2D(pool_size=(2, 2)))
    # Add flatten layer
    model.add(Flatten())
    # Add intermediate dense layers
    for i in range(n_dense_layers):
      model.add(Dense(n_nodes, activation = "ReLU"))
      model.add(BatchNormalization())
      if use_dropout:
        model.add(Dropout(rate=0.5))
    # Add final dense layer
    model.add(Dense(10 , activation="softmax"))
    # Compile model
    model.compile(loss = CategoricalCrossentropy(), metrics=["accuracy"],__
 ⇔optimizer = Adam(learning_rate=learning_rate))
    #model.summary()
    return model
```

```
[]: # Lets define a help function for plotting the training results
     import matplotlib.pyplot as plt
     def plot_results(history):
         loss = history.history['loss']
         acc = history.history['accuracy']
         val loss = history.history['val loss']
         val_acc = history.history['val_accuracy']
         plt.figure(figsize=(10,4))
         plt.xlabel('Epochs')
         plt.ylabel('Loss')
         plt.plot(loss)
         plt.plot(val_loss)
         plt.legend(['Training','Validation'])
         plt.figure(figsize=(10,4))
         plt.xlabel('Epochs')
         plt.ylabel('Accuracy')
         plt.plot(acc)
         plt.plot(val_acc)
         plt.legend(['Training','Validation'])
         plt.show()
```

1.11 Part 11: Train 2D CNN

Time to train the 2D CNN, start with 2 convolutional layers, no intermediate dense layers, learning rate = 0.01. The first convolutional layer should have 16 filters (which means that the second convolutional layer will have 32 filters).

Relevant functions

```
build_CNN, the function we defined in Part 10, call it with the parameters you want to use
```

model.fit(), train the model with some training data

model.evaluate(), apply the trained model to some test data

See the following links for how to train and evaluate the model

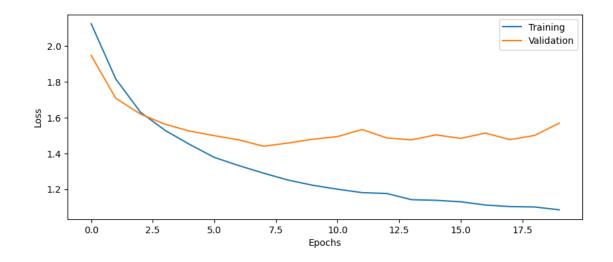
https://keras.io/api/models/model_training_apis/#fit-method

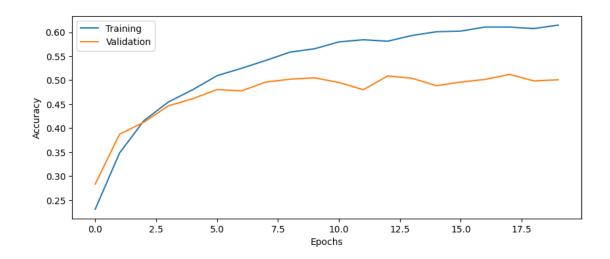
https://keras.io/api/models/model_training_apis/#evaluate-method

1.12 2 convolutional layers, no intermediate dense layers

```
[]: # Setup some training parameters
batch_size = 100
epochs = 20
input_shape = (32,32,3)
```

```
0.5812 - val_loss: 1.4862 - val_accuracy: 0.5088
  Epoch 14/20
  0.5932 - val_loss: 1.4753 - val_accuracy: 0.5040
  Epoch 15/20
  0.6009 - val_loss: 1.5033 - val_accuracy: 0.4884
  Epoch 16/20
  0.6023 - val_loss: 1.4838 - val_accuracy: 0.4960
  Epoch 17/20
  0.6108 - val_loss: 1.5134 - val_accuracy: 0.5016
  Epoch 18/20
  0.6107 - val_loss: 1.4768 - val_accuracy: 0.5120
  Epoch 19/20
  0.6076 - val_loss: 1.5002 - val_accuracy: 0.4984
  Epoch 20/20
  0.6148 - val_loss: 1.5689 - val_accuracy: 0.5008
[]: # Evaluate the trained model on test set, not used in training or validation
  score = model1.evaluate(Xtest, Ytest_enc, batch_size=batch_size)
  print('Test loss: %.4f' % score[0])
  print('Test accuracy: %.4f' % score[1])
  0.4960
  Test loss: 1.5552
  Test accuracy: 0.4960
[]: # Plot the history from the training run
  plot_results(history1)
```





1.13 Part 12: Improving performance

Write down the test accuracy, are you satisfied with the classifier performance (random chance is 10%)?

Question 10: How big is the difference between training and test accuracy?

Question 11: For the DNN laboration we used a batch size of 10,000, why do we need to use a smaller batch size in this laboration?

Consistering that we created a simple CNN for 10 classes, we get 50% accuracy which is better than a random chance which is 10%

Question 10: Test accuracy: 0.5025 and training accuracy: 0.6807

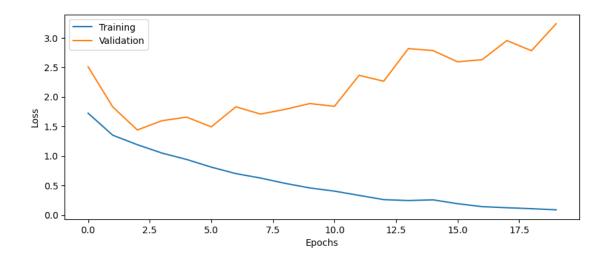
Question 11: Having a very high batch size will more computational intensive for a CNN model. Additionally, the dataset was more for the DNN lab compared to this lab.

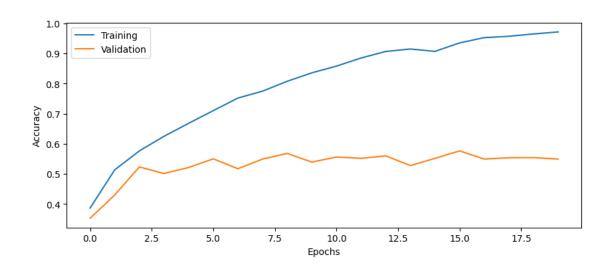
1.14 2 convolutional layers, 1 intermediate dense layer (50 nodes)

```
[]: # Setup some training parameters
  batch size = 100
  epochs = 20
  input_shape = (32, 32, 3)
  # Build model
  model2 = build_CNN(input_shape, n_conv_layers=2, n_filters=16,__
   →n_dense_layers=1, n_nodes=50, learning_rate=0.01)
  # Train the model using training data and validation data
  history2 = model2.fit(Xtrain, Ytrain_enc, validation_data=(Xval, Yval_enc),_
   ⇔epochs=epochs, batch_size=batch_size)
  Epoch 1/20
  0.3867 - val_loss: 2.5080 - val_accuracy: 0.3528
  Epoch 2/20
  0.5135 - val_loss: 1.8296 - val_accuracy: 0.4300
  Epoch 3/20
  0.5764 - val_loss: 1.4389 - val_accuracy: 0.5232
  Epoch 4/20
  0.6247 - val_loss: 1.5968 - val_accuracy: 0.5012
  Epoch 5/20
  0.6680 - val_loss: 1.6565 - val_accuracy: 0.5212
  Epoch 6/20
  0.7100 - val_loss: 1.4924 - val_accuracy: 0.5500
  Epoch 7/20
  0.7517 - val_loss: 1.8315 - val_accuracy: 0.5172
  Epoch 8/20
  0.7747 - val_loss: 1.7077 - val_accuracy: 0.5492
  0.8073 - val_loss: 1.7888 - val_accuracy: 0.5680
  Epoch 10/20
  0.8355 - val_loss: 1.8865 - val_accuracy: 0.5392
  Epoch 11/20
  0.8577 - val_loss: 1.8394 - val_accuracy: 0.5560
```

```
75/75 [============= ] - 1s 10ms/step - loss: 0.3321 - accuracy:
  0.8847 - val_loss: 2.3646 - val_accuracy: 0.5516
  Epoch 13/20
  0.9064 - val_loss: 2.2644 - val_accuracy: 0.5600
  Epoch 14/20
  0.9145 - val_loss: 2.8163 - val_accuracy: 0.5276
  Epoch 15/20
  0.9067 - val_loss: 2.7839 - val_accuracy: 0.5516
  Epoch 16/20
  0.9348 - val_loss: 2.5925 - val_accuracy: 0.5764
  Epoch 17/20
  0.9523 - val_loss: 2.6296 - val_accuracy: 0.5492
  Epoch 18/20
  0.9568 - val_loss: 2.9528 - val_accuracy: 0.5536
  Epoch 19/20
  0.9645 - val_loss: 2.7806 - val_accuracy: 0.5540
  Epoch 20/20
  0.9712 - val_loss: 3.2369 - val_accuracy: 0.5492
[]: # Evaluate the trained model on test set, not used in training or validation
  score = model2.evaluate(Xtest, Ytest_enc, batch_size=batch_size)
  print('Test loss: %.4f' % score[0])
  print('Test accuracy: %.4f' % score[1])
  0.5480
  Test loss: 2.9601
  Test accuracy: 0.5480
[]: # Plot the history from the training run
  plot results(history2)
```

Epoch 12/20





1.15 4 convolutional layers, 1 intermediate dense layer (50 nodes)

```
[]: # Setup some training parameters
batch_size = 100
epochs = 20
input_shape = (32,32,3)

# Build model
model3 = build_CNN(input_shape, n_conv_layers=4, n_filters=16,u
n_dense_layers=1, n_nodes=50, learning_rate=0.01)

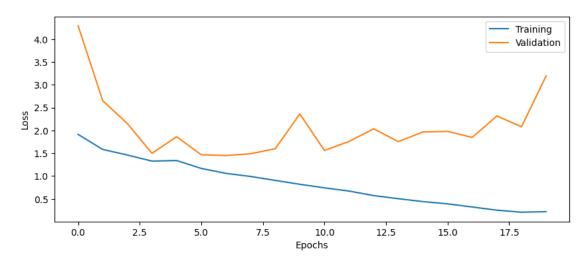
# Train the model using training data and validation data
```

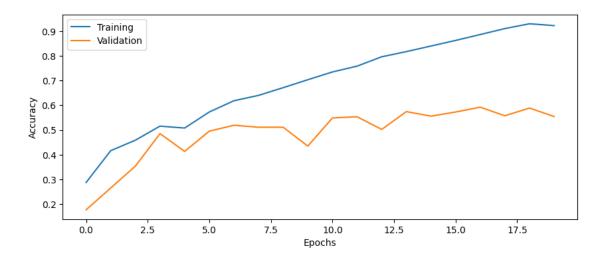
```
Epoch 1/20
0.2875 - val_loss: 4.2951 - val_accuracy: 0.1768
Epoch 2/20
0.4163 - val_loss: 2.6513 - val_accuracy: 0.2652
Epoch 3/20
0.4587 - val_loss: 2.1522 - val_accuracy: 0.3536
Epoch 4/20
0.5156 - val_loss: 1.4999 - val_accuracy: 0.4852
Epoch 5/20
0.5079 - val_loss: 1.8630 - val_accuracy: 0.4132
Epoch 6/20
0.5728 - val_loss: 1.4670 - val_accuracy: 0.4952
Epoch 7/20
0.6184 - val_loss: 1.4506 - val_accuracy: 0.5192
Epoch 8/20
0.6401 - val_loss: 1.4897 - val_accuracy: 0.5112
Epoch 9/20
0.6713 - val_loss: 1.5992 - val_accuracy: 0.5112
Epoch 10/20
0.7035 - val_loss: 2.3633 - val_accuracy: 0.4348
Epoch 11/20
0.7349 - val_loss: 1.5621 - val_accuracy: 0.5488
Epoch 12/20
0.7585 - val_loss: 1.7596 - val_accuracy: 0.5536
Epoch 13/20
0.7964 - val_loss: 2.0371 - val_accuracy: 0.5024
Epoch 14/20
0.8173 - val_loss: 1.7549 - val_accuracy: 0.5744
Epoch 15/20
```

```
0.8400 - val_loss: 1.9686 - val_accuracy: 0.5560
  Epoch 16/20
  0.8627 - val_loss: 1.9794 - val_accuracy: 0.5728
  Epoch 17/20
  0.8865 - val_loss: 1.8477 - val_accuracy: 0.5924
  Epoch 18/20
  0.9107 - val_loss: 2.3182 - val_accuracy: 0.5576
  Epoch 19/20
  0.9301 - val_loss: 2.0814 - val_accuracy: 0.5888
  Epoch 20/20
  0.9227 - val_loss: 3.1974 - val_accuracy: 0.5544
[]: # Evaluate the trained model on test set, not used in training or validation
  score = model3.evaluate(Xtest, Ytest_enc, batch_size=batch_size)
  print('Test loss: %.4f' % score[0])
  print('Test accuracy: %.4f' % score[1])
```

Test loss: 3.1183 Test accuracy: 0.5350

[]: # Plot the history from the training run plot_results(history3)





1.16 Part 13: Plot the CNN architecture

To understand your network better, print the architecture using model.summary()

Question 12: How many trainable parameters does your network have? Which part of the network contains most of the parameters?

Question 13: What is the input to and output of a Conv2D layer? What are the dimensions of the input and output?

Question 14: Is the batch size always the first dimension of each 4D tensor? Check the documentation for Conv2D, https://keras.io/layers/convolutional/

Question 15: If a convolutional layer that contains 128 filters is applied to an input with 32 channels, what is the number of channels in the output?

Question 16: Why is the number of parameters in each Conv2D layer *not* equal to the number of filters times the number of filter coefficients per filter (plus biases)?

Question 17: How does MaxPooling help in reducing the number of parameters to train?

Question 12: Total params: 123800 . The 4th Convolutional Layer has the most number of parameters (73856)

Question 13: For the first layer, the output is (batch_size, 32,32,3) and once it passes through the first convolutional layer, it becomes (batch_size,32,32,16), it changes to 16 due to the 16 filters that is applied to the image.

Input dim: (batch size,32,32,3) Ouptput dim: (batch size,10)

Question 14: Yes, it is always the first dimension.

Question 15: 128 channels

Question 16: Cause we also need to add the different channels as well which in this case is 3 (RGB) since each of the filter is applied to those 3 channels as well thus creating additional parameters.

Question 17: Max pooling takes the maximum value within a local neighborhood of pixels. There by capturing dominant features in the input while also reducing the shape it outputs due to this.

[]: # Print network architecture

model3.summary()

Model: "sequential_2"

| Layer (type) | out for search | Param # ======= |
|--|--------------------|--------------------|
| conv2d_4 (Conv2D) | (None, 32, 32, 16) | 448 |
| <pre>max_pooling2d_4 (MaxPoolin g2D)</pre> | (None, 16, 16, 16) | 0 |
| conv2d_5 (Conv2D) | (None, 16, 16, 32) | 4640 |
| <pre>max_pooling2d_5 (MaxPoolin g2D)</pre> | (None, 8, 8, 32) | 0 |
| conv2d_6 (Conv2D) | (None, 8, 8, 64) | 18496 |
| <pre>max_pooling2d_6 (MaxPoolin g2D)</pre> | (None, 4, 4, 64) | 0 |
| conv2d_7 (Conv2D) | (None, 4, 4, 128) | 73856 |
| <pre>max_pooling2d_7 (MaxPoolin g2D)</pre> | (None, 2, 2, 128) | 0 |
| flatten_2 (Flatten) | (None, 512) | 0 |
| dense_3 (Dense) | (None, 50) | 25650 |
| <pre>batch_normalization_1 (Bat chNormalization)</pre> | (None, 50) | 200 |
| dense_4 (Dense) | (None, 10) | 510 |

Total params: 123800 (483.59 KB)
Trainable params: 123700 (483.20 KB)
Non-trainable params: 100 (400.00 Byte)

1.17 Part 14: Dropout regularization

Add dropout regularization between each intermediate dense layer, dropout probability 50%.

Question 18: How much did the test accuracy improve with dropout, compared to without dropout?

Question 19: What other types of regularization can be applied? How can you add L2 regularization for the convolutional layers?

Question 18: The test accuracy actually reduced from 0.5625 to 0.5225 when the dropout was used. This could be that the droput rate is too high and its removing a lot of important aspects from the model.

Question 19: Other types of regularization are: L1, L2 regularization, data augmentation, early stopping, bagging method.

We can do L2 regularization by adding this to each of the layers: kernel_regularizer=keras.regularizers.L2(lambda), keras.activity_regularizer=regularizers.L2(lambda))

1.18 4 convolutional layers, 1 intermediate dense layer (50 nodes), dropout

```
0.4627 - val_loss: 1.7151 - val_accuracy: 0.4144
  Epoch 7/20
  0.4829 - val_loss: 2.0145 - val_accuracy: 0.4128
  Epoch 8/20
  0.5152 - val_loss: 1.4610 - val_accuracy: 0.4544
  Epoch 9/20
  0.5329 - val_loss: 1.5356 - val_accuracy: 0.4632
  Epoch 10/20
  0.5459 - val_loss: 1.1965 - val_accuracy: 0.5796
  Epoch 11/20
  0.5743 - val_loss: 1.3414 - val_accuracy: 0.5312
  Epoch 12/20
  0.5879 - val_loss: 2.7028 - val_accuracy: 0.4080
  Epoch 13/20
  0.6155 - val_loss: 1.4631 - val_accuracy: 0.5412
  Epoch 14/20
  75/75 [=============== ] - Os 7ms/step - loss: 1.0129 - accuracy:
  0.6287 - val_loss: 1.5840 - val_accuracy: 0.5188
  Epoch 15/20
  0.6439 - val_loss: 1.9498 - val_accuracy: 0.4852
  Epoch 16/20
  0.6605 - val_loss: 1.3473 - val_accuracy: 0.5656
  Epoch 17/20
  0.6728 - val_loss: 1.4314 - val_accuracy: 0.5580
  Epoch 18/20
  0.6937 - val_loss: 1.6338 - val_accuracy: 0.5316
  Epoch 19/20
  75/75 [=============== ] - Os 6ms/step - loss: 0.7924 - accuracy:
  0.7047 - val_loss: 1.9150 - val_accuracy: 0.5144
  Epoch 20/20
  0.7316 - val_loss: 1.5956 - val_accuracy: 0.5508
[]: # Evaluate the trained model on test set, not used in training or validation
```

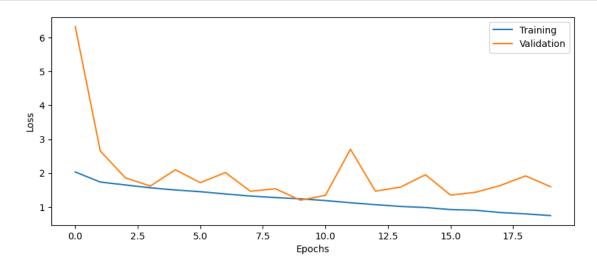
score = model4.evaluate(Xtest, Ytest_enc, batch_size=batch_size)

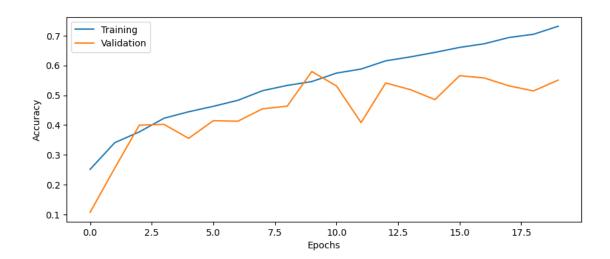
```
print('Test loss: %.4f' % score[0])
print('Test accuracy: %.4f' % score[1])
```

0.5620

Test loss: 1.6627 Test accuracy: 0.5620

[]: # Plot the history from the training run plot_results(history4)





1.19 Part 15: Tweaking performance

You have now seen the basic building blocks of a 2D CNN. To further improve performance involves changing the number of convolutional layers, the number of filters per layer, the number of intermediate dense layers, the number of nodes in the intermediate dense layers, batch size, learning rate, number of epochs, etc. Spend some time (30 - 90 minutes) testing different settings.

```
Question 20: How high test accuracy can you obtain? What is your best configuration?
```

```
Question 20: The highest test accuray: 0.5990 Configuration: Batch_size: 100 epoch = 20 Conv_layers = 4 Kernel_filter = 32 dense layers + nodes = 1, 50 nodes learning rate = 0.01 dropout = False
```

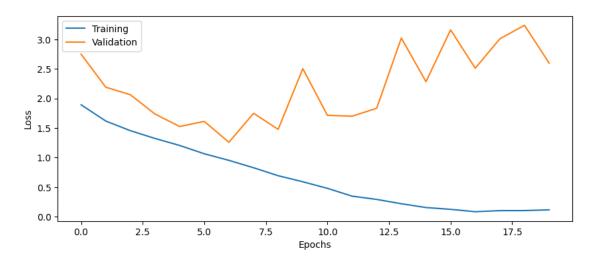
1.20 Your best config

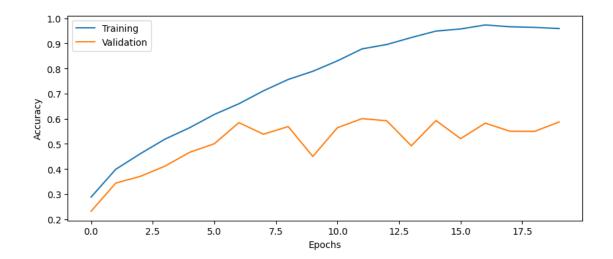
```
Epoch 5/20
0.5643 - val_loss: 1.5253 - val_accuracy: 0.4664
Epoch 6/20
0.6169 - val_loss: 1.6115 - val_accuracy: 0.5004
Epoch 7/20
0.6596 - val_loss: 1.2583 - val_accuracy: 0.5844
Epoch 8/20
0.7112 - val_loss: 1.7482 - val_accuracy: 0.5384
Epoch 9/20
0.7561 - val_loss: 1.4774 - val_accuracy: 0.5688
Epoch 10/20
0.7887 - val_loss: 2.5039 - val_accuracy: 0.4500
Epoch 11/20
0.8303 - val_loss: 1.7140 - val_accuracy: 0.5644
Epoch 12/20
0.8779 - val_loss: 1.6995 - val_accuracy: 0.6004
Epoch 13/20
0.8952 - val_loss: 1.8337 - val_accuracy: 0.5920
Epoch 14/20
0.9229 - val_loss: 3.0220 - val_accuracy: 0.4924
Epoch 15/20
0.9487 - val_loss: 2.2830 - val_accuracy: 0.5928
Epoch 16/20
0.9571 - val_loss: 3.1595 - val_accuracy: 0.5208
Epoch 17/20
0.9731 - val_loss: 2.5117 - val_accuracy: 0.5824
Epoch 18/20
0.9659 - val_loss: 3.0090 - val_accuracy: 0.5504
0.9633 - val_loss: 3.2371 - val_accuracy: 0.5496
Epoch 20/20
0.9588 - val_loss: 2.5970 - val_accuracy: 0.5872
```

[]: # Evaluate the trained model on test set, not used in training or validation
score = model5.evaluate(Xtest, Ytest_enc, batch_size=batch_size)
print('Test loss: %.4f' % score[0])
print('Test accuracy: %.4f' % score[1])

Test loss: 2.6117
Test accuracy: 0.5775

[]: # Plot the history from the training run plot_results(history5)





1.21 Part 16: Rotate the test images

How high is the test accuracy if we rotate the test images? In other words, how good is the CNN at generalizing to rotated images?

Rotate each test image 90 degrees, the cells are already finished.

Question 21: What is the test accuracy for rotated test images, compared to test images without rotation? Explain the difference in accuracy.

Question 21: The test accuracy has drasticly reduced to 0.2370. The CNN learns based on the specific orientation of the image so if we want the model to perform well for rotated images then we would need to train the model on different orientations of the image.

```
[]: def myrotate(images):
    images_rot = np.rot90(images, axes=(1,2))
    return images_rot
```

```
[]: # Rotate the test images 90 degrees
Xtest_rotated = myrotate(Xtest)

# Look at some rotated images
plt.figure(figsize=(16,4))
for i in range(10):
    idx = np.random.randint(500)

plt.subplot(2,10,i+1)
    plt.imshow(Xtest[idx]/2+0.5)
    plt.title("Original")
    plt.axis('off')

plt.subplot(2,10,i+11)
    plt.imshow(Xtest_rotated[idx]/2+0.5)
    plt.title("Rotated")
    plt.axis('off')

plt.show()
```



```
[]: # Evaluate the trained model on rotated test set
score = model5.evaluate(Xtest_rotated, Ytest_enc, batch_size=batch_size)
print('Test loss: %.4f' % score[0])
print('Test accuracy: %.4f' % score[1])
```

Test loss: 7.5174
Test accuracy: 0.2260

1.22 Part 17: Augmentation using Keras ImageDataGenerator

We can increase the number of training images through data augmentation (we now ignore that CIFAR10 actually has 60 000 training images). Image augmentation is about creating similar images, by performing operations such as rotation, scaling, elastic deformations and flipping of existing images. This will prevent overfitting, especially if all the training images are in a certain orientation.

We will perform the augmentation on the fly, using a built-in function in Keras, called ImageDataGenerator

See https://www.tensorflow.org/api_docs/python/tf/keras/preprocessing/image/ImageDataGenerator , the .flow(x,y) functionality

Make sure to use different subsets for training and validation when you setup the flows, otherwise you will validate on the same data...

```
[]: # Set up a data generator with on-the-fly data augmentation, 20% validation

split

# Use a rotation range of 30 degrees, horizontal and vertical flipping

from keras.preprocessing.image import ImageDataGenerator

#Xtrain, Xval, Ytrain, Yval = train_test_split(Xtrain, Ytrain, test_size=0.20, userandom_state=123)
```

1.23 Part 18: What about big data?

Question 22: How would you change the code for the image generator if you cannot fit all training images in CPU memory? What is the disadvantage of doing that change?

Question 22: We could load the data in batches rather than loading the entire data at once. This could lead to longer training time.

```
[]: # Plot some augmented images
plot_datagen = datagen.flow(Xtrain, Ytrain, batch_size=1)

plt.figure(figsize=(12,4))
for i in range(18):
    (im, label) = plot_datagen.next()
    im = (im[0] + 1) * 127.5
    im = im.astype('int')
    label = np.flatnonzero(label)[0]

plt.subplot(3,6,i+1)
plt.tight_layout()
plt.imshow(im)
plt.title("Class: {} ({})".format(label, classes[label]))
plt.axis('off')
plt.show()
```



1.24 Part 19: Train the CNN with images from the generator

See https://keras.io/api/models/model_training_apis/#fit-method for how to use model.fit with a generator instead of a fix dataset (numpy arrays)

To make the comparison fair to training without augmentation

```
steps_per_epoch should be set to: len(Xtrain)*(1 - validation_split)/batch_size
```

validation steps should be set to: len(Xtrain)*validation split/batch size

This is required since with a generator, the fit function will not know how many examples your original dataset has.

Question 23: How quickly is the training accuracy increasing compared to without augmentation? Explain why there is a difference compared to without augmentation. We are here talking about the number of training epochs required to reach a certain accuracy, and not the training time in seconds. What parameter is necessary to change to perform more training?

Question 24: What other types of image augmentation can be applied, compared to what we use here?

Question 23: The training accuracy increases slower than compared to without augmentation. It takes more epoch to reach around the same level of accuracy that we see in the "without augementation" model. This could be beacuse the augmentated model has images of different configuration and changes to the image i.e rotation, horizontal and vertical flip. But this makes the model more generalized and robust due to the various changes applied to the images making the model more dynamic to images.

Increase the "epoch" would be needed to perform more training.

Question 24: Some other augmentation that can be done: zooming into the image, changing the brightness, changing the color, adding a shear etc.

```
[]: # Setup some training parameters
batch_size = 100
epochs = 200
input_shape = (32,32,3)
```

```
# Build model (your best confiq)
model6 = build_CNN(input_shape, n_conv_layers = 4, n_filters=32,__
 on_dense_layers=1, n_nodes=50, learning_rate=0.01)
validation split=0.2
steps_per_epoch = len(Xtrain)*(1 - validation_split)/batch_size
validation_steps = len(Xtrain)*validation_split/batch_size
# Train the model using on the fly augmentation
history6 = model6.fit(Xtrain_aug, validation_data= Xval_aug, epochs=epochs,__
 ⇒batch_size=batch_size, validation_split=validation_split,
                steps_per_epoch = steps_per_epoch , validation_steps =_
 →validation_steps)
Epoch 1/200
80/80 [============= ] - 8s 76ms/step - loss: 2.1090 - accuracy:
0.2170 - val_loss: 2.2775 - val_accuracy: 0.2600
Epoch 2/200
80/80 [============= ] - 6s 73ms/step - loss: 1.8154 - accuracy:
0.3158 - val loss: 2.6150 - val accuracy: 0.2095
0.3591 - val_loss: 1.9256 - val_accuracy: 0.3055
Epoch 4/200
0.3873 - val_loss: 2.4487 - val_accuracy: 0.2985
Epoch 5/200
0.4162 - val_loss: 1.9281 - val_accuracy: 0.3440
Epoch 6/200
0.4375 - val_loss: 2.8167 - val_accuracy: 0.2730
Epoch 7/200
80/80 [============= ] - 5s 60ms/step - loss: 1.4779 - accuracy:
0.4638 - val_loss: 1.7788 - val_accuracy: 0.3730
Epoch 8/200
0.4821 - val_loss: 1.7623 - val_accuracy: 0.4015
Epoch 9/200
0.4818 - val_loss: 1.4176 - val_accuracy: 0.4930
Epoch 10/200
80/80 [============ ] - 5s 61ms/step - loss: 1.3546 - accuracy:
0.5073 - val_loss: 1.5479 - val_accuracy: 0.4465
```

```
Epoch 11/200
80/80 [============= ] - 6s 71ms/step - loss: 1.3386 - accuracy:
0.5148 - val_loss: 1.7486 - val_accuracy: 0.4390
Epoch 12/200
0.5235 - val_loss: 1.5237 - val_accuracy: 0.4810
Epoch 13/200
0.5340 - val_loss: 1.7566 - val_accuracy: 0.4200
Epoch 14/200
0.5495 - val_loss: 1.3693 - val_accuracy: 0.4975
Epoch 15/200
80/80 [============ ] - 6s 73ms/step - loss: 1.2219 - accuracy:
0.5562 - val_loss: 1.3468 - val_accuracy: 0.5160
Epoch 16/200
80/80 [============ ] - 5s 62ms/step - loss: 1.1904 - accuracy:
0.5677 - val_loss: 1.3512 - val_accuracy: 0.5275
Epoch 17/200
0.5815 - val_loss: 1.3706 - val_accuracy: 0.5085
Epoch 18/200
0.5822 - val_loss: 1.3643 - val_accuracy: 0.5160
Epoch 19/200
80/80 [============ ] - 6s 74ms/step - loss: 1.1212 - accuracy:
0.5911 - val_loss: 1.6768 - val_accuracy: 0.4770
Epoch 20/200
80/80 [============ ] - 7s 82ms/step - loss: 1.1128 - accuracy:
0.6039 - val_loss: 1.4508 - val_accuracy: 0.5130
Epoch 21/200
80/80 [============ ] - 5s 60ms/step - loss: 1.1187 - accuracy:
0.5964 - val_loss: 1.3068 - val_accuracy: 0.5330
Epoch 22/200
80/80 [============= ] - 5s 64ms/step - loss: 1.0770 - accuracy:
0.6089 - val_loss: 1.2478 - val_accuracy: 0.5785
Epoch 23/200
0.6217 - val_loss: 1.2425 - val_accuracy: 0.5585
Epoch 24/200
0.6298 - val_loss: 1.3385 - val_accuracy: 0.5450
0.6376 - val_loss: 1.3779 - val_accuracy: 0.5380
Epoch 26/200
0.6310 - val_loss: 1.3308 - val_accuracy: 0.5695
```

```
Epoch 27/200
80/80 [============= ] - 5s 61ms/step - loss: 0.9913 - accuracy:
0.6482 - val_loss: 1.6615 - val_accuracy: 0.5680
Epoch 28/200
0.6534 - val_loss: 1.4583 - val_accuracy: 0.5200
Epoch 29/200
0.6631 - val_loss: 1.5173 - val_accuracy: 0.5155
Epoch 30/200
0.6549 - val_loss: 1.2278 - val_accuracy: 0.5850
Epoch 31/200
accuracy: 0.6704 - val_loss: 1.2179 - val_accuracy: 0.5795
Epoch 32/200
80/80 [============ ] - 5s 62ms/step - loss: 0.9256 - accuracy:
0.6705 - val_loss: 1.1845 - val_accuracy: 0.6230
Epoch 33/200
0.6794 - val_loss: 1.1553 - val_accuracy: 0.6100
Epoch 34/200
0.6773 - val_loss: 1.2193 - val_accuracy: 0.5870
Epoch 35/200
80/80 [============ ] - 8s 93ms/step - loss: 0.8975 - accuracy:
0.6815 - val_loss: 1.1630 - val_accuracy: 0.6125
Epoch 36/200
80/80 [============ ] - 7s 89ms/step - loss: 0.8817 - accuracy:
0.6836 - val_loss: 1.3220 - val_accuracy: 0.5565
Epoch 37/200
80/80 [============ ] - 5s 65ms/step - loss: 0.9022 - accuracy:
0.6796 - val_loss: 1.2216 - val_accuracy: 0.6045
Epoch 38/200
80/80 [============= ] - 5s 61ms/step - loss: 0.8718 - accuracy:
0.6917 - val_loss: 1.0685 - val_accuracy: 0.6240
Epoch 39/200
0.6980 - val_loss: 1.1094 - val_accuracy: 0.6135
Epoch 40/200
0.7017 - val_loss: 1.1266 - val_accuracy: 0.6235
0.6991 - val_loss: 1.2480 - val_accuracy: 0.6030
Epoch 42/200
80/80 [============ ] - 5s 59ms/step - loss: 0.8338 - accuracy:
0.7057 - val_loss: 1.1882 - val_accuracy: 0.6030
```

```
Epoch 43/200
80/80 [============= ] - 6s 74ms/step - loss: 0.8114 - accuracy:
0.7082 - val_loss: 1.2011 - val_accuracy: 0.6095
Epoch 44/200
0.7151 - val_loss: 1.0780 - val_accuracy: 0.6440
Epoch 45/200
0.7125 - val_loss: 1.1179 - val_accuracy: 0.6225
Epoch 46/200
80/80 [============= ] - 6s 70ms/step - loss: 0.7820 - accuracy:
0.7264 - val_loss: 1.0638 - val_accuracy: 0.6495
Epoch 47/200
0.7270 - val_loss: 1.0809 - val_accuracy: 0.6390
Epoch 48/200
80/80 [============= ] - 6s 73ms/step - loss: 0.7771 - accuracy:
0.7278 - val_loss: 1.0900 - val_accuracy: 0.6410
Epoch 49/200
0.7324 - val_loss: 1.2336 - val_accuracy: 0.6110
Epoch 50/200
0.7340 - val_loss: 1.4945 - val_accuracy: 0.5700
Epoch 51/200
80/80 [============ ] - 5s 60ms/step - loss: 0.7617 - accuracy:
0.7284 - val_loss: 1.2042 - val_accuracy: 0.6190
Epoch 52/200
80/80 [============ ] - 6s 76ms/step - loss: 0.7580 - accuracy:
0.7254 - val_loss: 1.0852 - val_accuracy: 0.6325
Epoch 53/200
80/80 [============ ] - 8s 97ms/step - loss: 0.7399 - accuracy:
0.7339 - val_loss: 1.1216 - val_accuracy: 0.6350
Epoch 54/200
accuracy: 0.7414 - val_loss: 1.1032 - val_accuracy: 0.6405
Epoch 55/200
accuracy: 0.7501 - val_loss: 1.1889 - val_accuracy: 0.6145
Epoch 56/200
accuracy: 0.7442 - val_loss: 1.2697 - val_accuracy: 0.6160
80/80 [============ - - 10s 119ms/step - loss: 0.7151 -
accuracy: 0.7445 - val_loss: 1.0706 - val_accuracy: 0.6435
Epoch 58/200
80/80 [============ ] - 8s 96ms/step - loss: 0.7137 - accuracy:
0.7516 - val_loss: 1.1748 - val_accuracy: 0.6115
```

```
Epoch 59/200
80/80 [============= ] - 5s 60ms/step - loss: 0.6834 - accuracy:
0.7515 - val_loss: 1.1261 - val_accuracy: 0.6405
Epoch 60/200
0.7467 - val_loss: 1.1666 - val_accuracy: 0.6205
Epoch 61/200
0.7561 - val_loss: 1.0904 - val_accuracy: 0.6515
Epoch 62/200
accuracy: 0.7560 - val_loss: 1.2080 - val_accuracy: 0.6180
Epoch 63/200
accuracy: 0.7596 - val_loss: 1.2024 - val_accuracy: 0.6210
Epoch 64/200
80/80 [============ ] - 8s 104ms/step - loss: 0.6550 -
accuracy: 0.7675 - val_loss: 1.2511 - val_accuracy: 0.6140
Epoch 65/200
0.7640 - val_loss: 1.2009 - val_accuracy: 0.6390
Epoch 66/200
0.7744 - val_loss: 1.1158 - val_accuracy: 0.6330
Epoch 67/200
80/80 [============ ] - 5s 65ms/step - loss: 0.6515 - accuracy:
0.7688 - val_loss: 1.2548 - val_accuracy: 0.6140
Epoch 68/200
80/80 [============ ] - 5s 68ms/step - loss: 0.6336 - accuracy:
0.7790 - val_loss: 1.1540 - val_accuracy: 0.6300
Epoch 69/200
80/80 [============ ] - 6s 74ms/step - loss: 0.6483 - accuracy:
0.7742 - val_loss: 1.1424 - val_accuracy: 0.6395
Epoch 70/200
0.7735 - val_loss: 1.1621 - val_accuracy: 0.6485
Epoch 71/200
accuracy: 0.7724 - val_loss: 1.1935 - val_accuracy: 0.6330
Epoch 72/200
0.7825 - val_loss: 1.1455 - val_accuracy: 0.6425
Epoch 73/200
accuracy: 0.7804 - val_loss: 1.2026 - val_accuracy: 0.6255
Epoch 74/200
80/80 [============ ] - 7s 91ms/step - loss: 0.6102 - accuracy:
0.7820 - val_loss: 1.1384 - val_accuracy: 0.6520
```

```
Epoch 75/200
80/80 [============= ] - 8s 95ms/step - loss: 0.5934 - accuracy:
0.7861 - val_loss: 1.2897 - val_accuracy: 0.6225
Epoch 76/200
0.7840 - val_loss: 1.1908 - val_accuracy: 0.6425
Epoch 77/200
0.7853 - val_loss: 1.1855 - val_accuracy: 0.6350
Epoch 78/200
80/80 [============= ] - 5s 60ms/step - loss: 0.5920 - accuracy:
0.7910 - val_loss: 1.2510 - val_accuracy: 0.6260
Epoch 79/200
80/80 [============ ] - 6s 73ms/step - loss: 0.5766 - accuracy:
0.7931 - val_loss: 1.1505 - val_accuracy: 0.6460
Epoch 80/200
80/80 [============ ] - 5s 63ms/step - loss: 0.5982 - accuracy:
0.7881 - val_loss: 1.1412 - val_accuracy: 0.6615
Epoch 81/200
0.7878 - val_loss: 1.3494 - val_accuracy: 0.5975
Epoch 82/200
0.8054 - val_loss: 1.3474 - val_accuracy: 0.6180
Epoch 83/200
accuracy: 0.8070 - val_loss: 1.1548 - val_accuracy: 0.6515
Epoch 84/200
80/80 [=========== ] - 7s 87ms/step - loss: 0.5560 - accuracy:
0.8035 - val_loss: 1.2529 - val_accuracy: 0.6355
Epoch 85/200
80/80 [============ ] - 8s 99ms/step - loss: 0.5425 - accuracy:
0.8109 - val_loss: 1.2703 - val_accuracy: 0.6270
Epoch 86/200
accuracy: 0.8074 - val_loss: 1.3261 - val_accuracy: 0.6300
Epoch 87/200
accuracy: 0.8080 - val_loss: 1.1101 - val_accuracy: 0.6695
Epoch 88/200
0.8101 - val_loss: 1.2124 - val_accuracy: 0.6405
80/80 [============ ] - 7s 87ms/step - loss: 0.5546 - accuracy:
0.8043 - val_loss: 1.1692 - val_accuracy: 0.6490
Epoch 90/200
80/80 [============= ] - 5s 63ms/step - loss: 0.5330 - accuracy:
0.8073 - val_loss: 1.3004 - val_accuracy: 0.6315
```

```
Epoch 91/200
80/80 [============= ] - 8s 97ms/step - loss: 0.5491 - accuracy:
0.8012 - val_loss: 1.1525 - val_accuracy: 0.6565
Epoch 92/200
0.8152 - val_loss: 1.1386 - val_accuracy: 0.6690
Epoch 93/200
0.8100 - val_loss: 1.2107 - val_accuracy: 0.6620
Epoch 94/200
80/80 [============= ] - 5s 61ms/step - loss: 0.5262 - accuracy:
0.8165 - val_loss: 1.1562 - val_accuracy: 0.6440
Epoch 95/200
accuracy: 0.8195 - val_loss: 1.2967 - val_accuracy: 0.6250
Epoch 96/200
80/80 [============ ] - 5s 63ms/step - loss: 0.5234 - accuracy:
0.8158 - val_loss: 1.1493 - val_accuracy: 0.6560
Epoch 97/200
0.8244 - val_loss: 1.2194 - val_accuracy: 0.6460
Epoch 98/200
0.8210 - val_loss: 1.3283 - val_accuracy: 0.6290
Epoch 99/200
accuracy: 0.8163 - val_loss: 1.1617 - val_accuracy: 0.6460
Epoch 100/200
80/80 [============ ] - 5s 61ms/step - loss: 0.4861 - accuracy:
0.8276 - val_loss: 1.2227 - val_accuracy: 0.6385
Epoch 101/200
80/80 [============ ] - 6s 74ms/step - loss: 0.4945 - accuracy:
0.8240 - val_loss: 1.3707 - val_accuracy: 0.6220
Epoch 102/200
0.8185 - val_loss: 1.2233 - val_accuracy: 0.6530
Epoch 103/200
0.8239 - val_loss: 1.2325 - val_accuracy: 0.6565
Epoch 104/200
0.8261 - val_loss: 1.1974 - val_accuracy: 0.6530
Epoch 105/200
0.8229 - val_loss: 1.1727 - val_accuracy: 0.6755
Epoch 106/200
80/80 [============ ] - 6s 73ms/step - loss: 0.4783 - accuracy:
0.8273 - val_loss: 1.2896 - val_accuracy: 0.6270
```

```
Epoch 107/200
80/80 [============= ] - 5s 61ms/step - loss: 0.4792 - accuracy:
0.8316 - val_loss: 1.2733 - val_accuracy: 0.6490
Epoch 108/200
0.8298 - val_loss: 1.2157 - val_accuracy: 0.6555
Epoch 109/200
0.8386 - val_loss: 1.2476 - val_accuracy: 0.6505
Epoch 110/200
80/80 [============== ] - 5s 60ms/step - loss: 0.4752 - accuracy:
0.8313 - val_loss: 1.2432 - val_accuracy: 0.6445
Epoch 111/200
80/80 [============ ] - 6s 75ms/step - loss: 0.4541 - accuracy:
0.8399 - val_loss: 1.1725 - val_accuracy: 0.6630
Epoch 112/200
80/80 [============= ] - 5s 59ms/step - loss: 0.4627 - accuracy:
0.8353 - val_loss: 1.3356 - val_accuracy: 0.6275
Epoch 113/200
0.8464 - val_loss: 1.3550 - val_accuracy: 0.6425
Epoch 114/200
0.8339 - val_loss: 1.2764 - val_accuracy: 0.6430
Epoch 115/200
80/80 [============ ] - 5s 66ms/step - loss: 0.4476 - accuracy:
0.8430 - val_loss: 1.4014 - val_accuracy: 0.6040
Epoch 116/200
80/80 [============ ] - 5s 60ms/step - loss: 0.4387 - accuracy:
0.8413 - val_loss: 1.2891 - val_accuracy: 0.6585
Epoch 117/200
80/80 [============ ] - 6s 75ms/step - loss: 0.4499 - accuracy:
0.8432 - val_loss: 1.2957 - val_accuracy: 0.6450
Epoch 118/200
80/80 [============ ] - 5s 60ms/step - loss: 0.4460 - accuracy:
0.8413 - val_loss: 1.3584 - val_accuracy: 0.6365
Epoch 119/200
0.8446 - val_loss: 1.2295 - val_accuracy: 0.6555
Epoch 120/200
0.8429 - val_loss: 1.2514 - val_accuracy: 0.6600
Epoch 121/200
0.8550 - val_loss: 1.3618 - val_accuracy: 0.6395
Epoch 122/200
80/80 [============ ] - 5s 63ms/step - loss: 0.4278 - accuracy:
0.8511 - val_loss: 1.2583 - val_accuracy: 0.6465
```

```
Epoch 123/200
0.8462 - val_loss: 1.3482 - val_accuracy: 0.6495
Epoch 124/200
0.8489 - val_loss: 1.1962 - val_accuracy: 0.6680
Epoch 125/200
0.8581 - val_loss: 1.2539 - val_accuracy: 0.6655
Epoch 126/200
80/80 [============== ] - 5s 60ms/step - loss: 0.4227 - accuracy:
0.8519 - val_loss: 1.3497 - val_accuracy: 0.6425
Epoch 127/200
80/80 [============ ] - 6s 72ms/step - loss: 0.4130 - accuracy:
0.8526 - val_loss: 1.2820 - val_accuracy: 0.6470
Epoch 128/200
80/80 [============ ] - 5s 62ms/step - loss: 0.4100 - accuracy:
0.8564 - val_loss: 1.2911 - val_accuracy: 0.6645
Epoch 129/200
0.8616 - val_loss: 1.2827 - val_accuracy: 0.6580
Epoch 130/200
0.8536 - val_loss: 1.5713 - val_accuracy: 0.6125
Epoch 131/200
80/80 [============ ] - 5s 60ms/step - loss: 0.4037 - accuracy:
0.8553 - val_loss: 1.2534 - val_accuracy: 0.6495
Epoch 132/200
80/80 [============ ] - 6s 74ms/step - loss: 0.4034 - accuracy:
0.8590 - val_loss: 1.5546 - val_accuracy: 0.6260
Epoch 133/200
80/80 [============ ] - 5s 61ms/step - loss: 0.4048 - accuracy:
0.8562 - val_loss: 1.3575 - val_accuracy: 0.6405
Epoch 134/200
80/80 [============= ] - 6s 75ms/step - loss: 0.3781 - accuracy:
0.8666 - val_loss: 1.3252 - val_accuracy: 0.6360
Epoch 135/200
0.8576 - val_loss: 1.2603 - val_accuracy: 0.6570
Epoch 136/200
0.8586 - val_loss: 1.2699 - val_accuracy: 0.6595
Epoch 137/200
80/80 [============ ] - 7s 87ms/step - loss: 0.4014 - accuracy:
0.8575 - val_loss: 1.3615 - val_accuracy: 0.6420
Epoch 138/200
80/80 [============ ] - 7s 85ms/step - loss: 0.3758 - accuracy:
0.8708 - val_loss: 1.3087 - val_accuracy: 0.6500
```

```
Epoch 139/200
80/80 [============= ] - 6s 80ms/step - loss: 0.3684 - accuracy:
0.8724 - val_loss: 1.4060 - val_accuracy: 0.6410
Epoch 140/200
0.8675 - val_loss: 1.3656 - val_accuracy: 0.6470
Epoch 141/200
80/80 [============ ] - 10s 123ms/step - loss: 0.3671 -
accuracy: 0.8719 - val_loss: 1.2605 - val_accuracy: 0.6600
Epoch 142/200
0.8670 - val_loss: 1.3535 - val_accuracy: 0.6420
Epoch 143/200
0.8640 - val_loss: 1.3989 - val_accuracy: 0.6430
Epoch 144/200
80/80 [============ ] - 10s 119ms/step - loss: 0.3818 -
accuracy: 0.8646 - val_loss: 1.3071 - val_accuracy: 0.6510
Epoch 145/200
0.8609 - val_loss: 1.2956 - val_accuracy: 0.6610
Epoch 146/200
0.8710 - val_loss: 1.3497 - val_accuracy: 0.6520
Epoch 147/200
80/80 [============= ] - 7s 93ms/step - loss: 0.3747 - accuracy:
0.8715 - val_loss: 1.2621 - val_accuracy: 0.6765
Epoch 148/200
0.8684 - val_loss: 1.4103 - val_accuracy: 0.6465
Epoch 149/200
80/80 [============ ] - 7s 82ms/step - loss: 0.3480 - accuracy:
0.8761 - val_loss: 1.4506 - val_accuracy: 0.6470
Epoch 150/200
0.8786 - val_loss: 1.2849 - val_accuracy: 0.6665
Epoch 151/200
0.8750 - val_loss: 1.4674 - val_accuracy: 0.6450
Epoch 152/200
0.8755 - val_loss: 1.4017 - val_accuracy: 0.6520
Epoch 153/200
0.8684 - val_loss: 1.3985 - val_accuracy: 0.6415
Epoch 154/200
80/80 [============= ] - 6s 74ms/step - loss: 0.3594 - accuracy:
0.8711 - val_loss: 1.2852 - val_accuracy: 0.6535
```

```
Epoch 155/200
0.8765 - val_loss: 1.3791 - val_accuracy: 0.6530
Epoch 156/200
0.8775 - val_loss: 1.2681 - val_accuracy: 0.6745
Epoch 157/200
0.8840 - val_loss: 1.4600 - val_accuracy: 0.6365
Epoch 158/200
80/80 [============= ] - 5s 61ms/step - loss: 0.3523 - accuracy:
0.8740 - val_loss: 1.3980 - val_accuracy: 0.6580
Epoch 159/200
80/80 [============ ] - 6s 74ms/step - loss: 0.3467 - accuracy:
0.8776 - val_loss: 1.4427 - val_accuracy: 0.6480
Epoch 160/200
80/80 [============= ] - 5s 66ms/step - loss: 0.3398 - accuracy:
0.8816 - val_loss: 1.3207 - val_accuracy: 0.6720
Epoch 161/200
0.8851 - val_loss: 1.4890 - val_accuracy: 0.6385
Epoch 162/200
0.8851 - val_loss: 1.4538 - val_accuracy: 0.6525
Epoch 163/200
80/80 [============ ] - 6s 74ms/step - loss: 0.3203 - accuracy:
0.8898 - val_loss: 1.3201 - val_accuracy: 0.6780
Epoch 164/200
80/80 [============ ] - 5s 62ms/step - loss: 0.3320 - accuracy:
0.8834 - val_loss: 1.3457 - val_accuracy: 0.6635
Epoch 165/200
80/80 [============ ] - 6s 75ms/step - loss: 0.3430 - accuracy:
0.8799 - val_loss: 1.3907 - val_accuracy: 0.6485
Epoch 166/200
80/80 [============= ] - 5s 61ms/step - loss: 0.3404 - accuracy:
0.8785 - val_loss: 1.3546 - val_accuracy: 0.6625
Epoch 167/200
0.8838 - val_loss: 1.4613 - val_accuracy: 0.6550
Epoch 168/200
0.8864 - val_loss: 1.4235 - val_accuracy: 0.6610
Epoch 169/200
0.8866 - val_loss: 1.4215 - val_accuracy: 0.6505
Epoch 170/200
80/80 [============ ] - 7s 83ms/step - loss: 0.3115 - accuracy:
0.8894 - val_loss: 1.3847 - val_accuracy: 0.6650
```

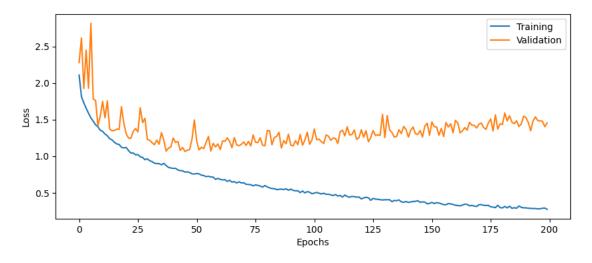
```
Epoch 171/200
80/80 [============ ] - 5s 62ms/step - loss: 0.3360 - accuracy:
0.8825 - val_loss: 1.4369 - val_accuracy: 0.6350
Epoch 172/200
0.8815 - val_loss: 1.4521 - val_accuracy: 0.6435
Epoch 173/200
0.8831 - val_loss: 1.3906 - val_accuracy: 0.6570
Epoch 174/200
0.8874 - val_loss: 1.3671 - val_accuracy: 0.6745
Epoch 175/200
80/80 [============ ] - 6s 74ms/step - loss: 0.3277 - accuracy:
0.8867 - val_loss: 1.4539 - val_accuracy: 0.6450
Epoch 176/200
0.8895 - val_loss: 1.5081 - val_accuracy: 0.6380
Epoch 177/200
0.8914 - val_loss: 1.3445 - val_accuracy: 0.6605
Epoch 178/200
0.8971 - val_loss: 1.5642 - val_accuracy: 0.6515
Epoch 179/200
accuracy: 0.8832 - val_loss: 1.3703 - val_accuracy: 0.6570
Epoch 180/200
80/80 [============ ] - 7s 90ms/step - loss: 0.2961 - accuracy:
0.8955 - val_loss: 1.4424 - val_accuracy: 0.6565
Epoch 181/200
80/80 [============ ] - 5s 69ms/step - loss: 0.2918 - accuracy:
0.8969 - val_loss: 1.4329 - val_accuracy: 0.6545
Epoch 182/200
80/80 [============= ] - 5s 60ms/step - loss: 0.3135 - accuracy:
0.8876 - val_loss: 1.5895 - val_accuracy: 0.6395
Epoch 183/200
0.8981 - val_loss: 1.4807 - val_accuracy: 0.6625
Epoch 184/200
0.8911 - val_loss: 1.5512 - val_accuracy: 0.6355
Epoch 185/200
0.9036 - val_loss: 1.4667 - val_accuracy: 0.6445
Epoch 186/200
80/80 [============ ] - 5s 63ms/step - loss: 0.2952 - accuracy:
0.8939 - val_loss: 1.4428 - val_accuracy: 0.6675
```

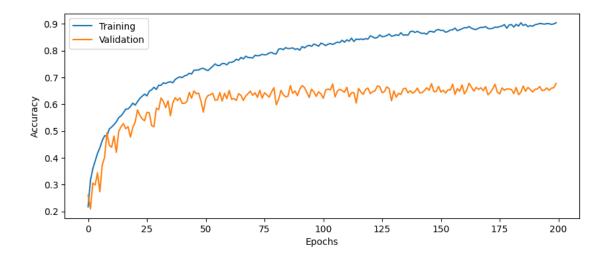
```
80/80 [============= ] - 7s 85ms/step - loss: 0.2874 - accuracy:
  0.8978 - val_loss: 1.4835 - val_accuracy: 0.6480
  Epoch 188/200
  0.8892 - val_loss: 1.4058 - val_accuracy: 0.6625
  Epoch 189/200
  0.8931 - val_loss: 1.4398 - val_accuracy: 0.6545
  Epoch 190/200
  80/80 [============= ] - 6s 75ms/step - loss: 0.2932 - accuracy:
  0.8906 - val_loss: 1.5475 - val_accuracy: 0.6455
  Epoch 191/200
  0.8966 - val_loss: 1.5266 - val_accuracy: 0.6555
  Epoch 192/200
  80/80 [============ ] - 6s 70ms/step - loss: 0.2878 - accuracy:
  0.8981 - val_loss: 1.4595 - val_accuracy: 0.6565
  Epoch 193/200
  0.9013 - val_loss: 1.3470 - val_accuracy: 0.6660
  Epoch 194/200
  0.9001 - val_loss: 1.4817 - val_accuracy: 0.6510
  Epoch 195/200
  80/80 [============= ] - 7s 87ms/step - loss: 0.2840 - accuracy:
  0.8984 - val_loss: 1.5376 - val_accuracy: 0.6520
  Epoch 196/200
  0.9007 - val_loss: 1.4867 - val_accuracy: 0.6605
  Epoch 197/200
  80/80 [============ ] - 7s 88ms/step - loss: 0.2803 - accuracy:
  0.9003 - val_loss: 1.4816 - val_accuracy: 0.6520
  Epoch 198/200
  0.8976 - val_loss: 1.4784 - val_accuracy: 0.6595
  Epoch 199/200
  0.8995 - val_loss: 1.4029 - val_accuracy: 0.6615
  Epoch 200/200
  0.9038 - val_loss: 1.4537 - val_accuracy: 0.6770
[]: # Check if there is still a big difference in accuracy for original and rotated \Box
   ⇔test images
   # Evaluate the trained model on original test set
```

Epoch 187/200

Test loss: 1.4951 Test accuracy: 0.6685 Test loss: 4.2030 Test accuracy: 0.3345

[]: # Plot the history from the training run plot_results(history6)





1.25 Part 20: Plot misclassified images

Lets plot some images where the CNN performed badly, these cells are already finished.

```
[]: # Find misclassified images
y_pred=model6.predict(Xtest)
y_pred=np.argmax(y_pred,axis=1)

y_correct = np.argmax(Ytest,axis=-1)

miss = np.flatnonzero(y_correct != y_pred)
```

63/63 [==============] - 1s 6ms/step



1.26 Part 21: Testing on another size

Question 25: This CNN has been trained on 32 x 32 images, can it be applied to images of another size? If not, why is this the case?

Question 26: Is it possible to design a CNN that can be trained on images of one size, and then applied to an image of any size? How?

Question 25: No, this is beacuse the model is end with a fully connected network, so it requires a fixed input size due to the flattening operation that maps it to a 1D vector.

Question 26: Yes, this can be doing using only a fully convolutional network i.e without any dense layers

1.27 Part 22: Pre-trained 2D CNNs

There are many deep 2D CNNs that have been pre-trained using the large ImageNet database (several million images, 1000 classes). Import a pre-trained ResNet50 network from Keras applications. Show the network using model.summary()

Question 27: How many convolutional layers does ResNet50 have?

Question 28: How many trainable parameters does the ResNet50 network have?

Question 29: What is the size of the images that ResNet50 expects as input?

Question 30: Using the answer to question 28, explain why the second derivative is seldom used when training deep networks.

Apply the pre-trained CNN to 5 random color images that you download and copy to the cloud machine or your own computer. Are the predictions correct? How certain is the network of each image class?

These pre-trained networks can be fine tuned to your specific data, and normally only the last layers need to be re-trained, but it will still be too time consuming to do in this laboration.

See https://keras.io/api/applications/ and https://keras.io/api/applications/resnet/#resnet50-function

Useful functions

image.load_img in tensorflow.keras.preprocessing

```
ResNet50 in tensorflow.keras.applications.resnet50
    preprocess_input in tensorflow.keras.applications.resnet50
    decode_predictions in tensorflow.keras.applications.resnet50
    expand dims in numpy
    Question 27: 50 convolutional layers
    Question 28: 25583592 trainable parameters
    Question 29: (224, 224, 3)
    Question 30: We don't use second derivative to learn cause to do it we need the hessian matrix
    which for 25583592 trainable parameter for examples will be 25583592 x 25583592 matrix and that
    is too big to store in memory.
[]: from google.colab import drive
     drive.mount('/content/drive')
    Mounted at /content/drive
[]: # Your code for using pre-trained ResNet 50 on 5 color images of your choice.
     # The preprocessing should transform the image to a size that is expected by \Box
      \hookrightarrow the CNN.
     from keras.applications import ResNet50
     from tensorflow.keras.preprocessing.image import load_img, img_to_array
     from tensorflow.keras.applications.resnet50 import preprocess input
      ⇔decode predictions
     model7 = ResNet50()
     #model7.summary()
     %cd "/content/drive/MyDrive/"
    /content/drive/MyDrive
    Image-1: Iron Man
    Image-2: Apple
    Image-3: Surfing
    Image-4: Sun
    Image-5: Rocket
[]: image1 = load_img("iron-man.webp", target_size = (224,224))
     image1=image1.resize((224,224))
```

image.img_to_array in tensorflow.keras.preprocessing

```
input_arr_1 = img_to_array(image1)
    input_arr_1 = np.expand_dims(input_arr_1,axis = 0)
    image2 = load_img("apple.webp", target_size = (224,224))
    image2=image2.resize((224,224))
    input_arr_2 = img_to_array(image2)
    input_arr_2 = np.expand_dims(input_arr_2,axis = 0)
    image3 = load_img("surf.webp", target_size = (224,224))
    image3=image3.resize((224,224))
    input_arr_3 = img_to_array(image3)
    input_arr_3 = np.expand_dims(input_arr_3,axis = 0)
    image4 = load_img("sun.jpeg", target_size = (224,224))
    image4=image4.resize((224,224))
    input_arr_4 = img_to_array(image4)
    input_arr_4 = np.expand_dims(input_arr_4,axis = 0)
    image5 = load_img("rocket.webp", target_size = (224,224))
    image5=image5.resize((224,224))
    input arr 5 = img to array(image5)
     input_arr_5 = np.expand_dims(input_arr_5,axis = 0)
[]: score1 = model7.predict(input_arr_1)
    decode_predictions(score1) #Image-1
    1/1 [======= ] - 1s 847ms/step
[]: [[('n03146219', 'cuirass', 0.80024636),
      ('n02895154', 'breastplate', 0.18907034),
      ('n03000247', 'chain mail', 0.003918813),
      ('n04192698', 'shield', 0.0021846096),
      ('n03379051', 'football_helmet', 0.0019023493)]]
[]: score2 = model7.predict(input_arr_2)
    decode_predictions(score2) #Image-2
    1/1 [======] - 0s 22ms/step
[]: [[('n07749582', 'lemon', 0.27165836),
      ('n07742313', 'Granny_Smith', 0.26778814),
      ('n07747607', 'orange', 0.10203416),
      ('n07745940', 'strawberry', 0.051424935),
      ('n04522168', 'vase', 0.04739114)]]
```

```
[]: score3 = model7.predict(input_arr_3)
    decode_predictions(score3) #Image-3
    1/1 [======= ] - Os 21ms/step
[]: [[('n04456115', 'torch', 0.36744487),
      ('n03729826', 'matchstick', 0.21474075),
      ('n03929660', 'pick', 0.07949964),
      ('n03388043', 'fountain', 0.06841073),
      ('n03666591', 'lighter', 0.044225983)]]
[]: score4 = model7.predict(input_arr_4)
    decode predictions(score4) #Image-4
    1/1 [=======] - Os 22ms/step
[]: [[('n06874185', 'traffic_light', 0.503199),
      ('n04009552', 'projector', 0.3440176),
      ('n04286575', 'spotlight', 0.1258798),
      ('n01930112', 'nematode', 0.008039685),
      ('n03782006', 'monitor', 0.0029325872)]]
[]: score5 = model7.predict(input_arr_5)
    decode_predictions(score5) #Image-5
    1/1 [=======] - 0s 22ms/step
[]: [[('n02783161', 'ballpoint', 0.6085586),
      ('n03773504', 'missile', 0.07037285),
      ('n04008634', 'projectile', 0.046716996),
      ('n04116512', 'rubber_eraser', 0.04079768),
      ('n04367480', 'swab', 0.019980296)]]
```

The model doesn't give an exactly right prediction for all the 5 images but it gives similar kind of guess based on the image.

The model is not that certain with the prediction with only image-1, image-4 and image-5 having more than 50%. And among that only image-1 being around 80%.