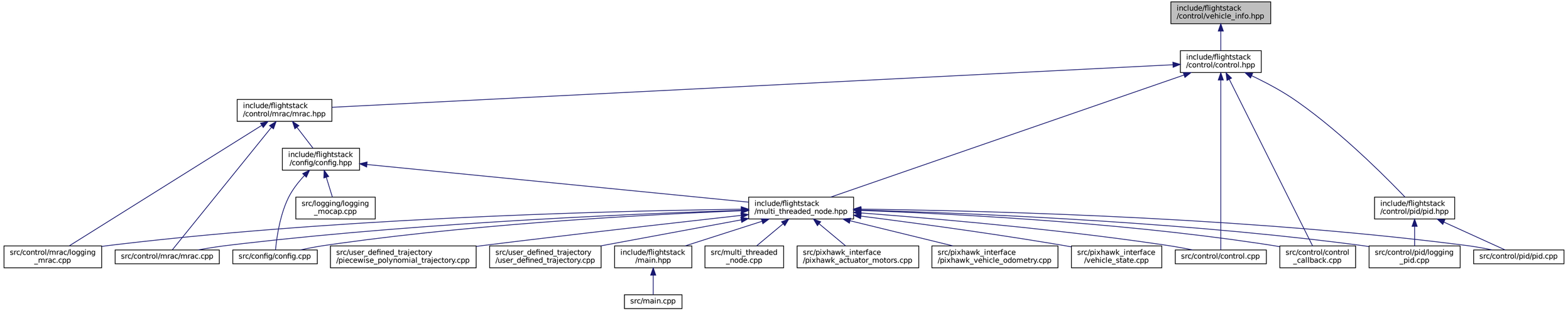
include/flightstack /control/vehicle_info.hpp
include/flightstack /control/control.hpp
include/flightstack /control/mrac/mrac.hpp
include/flightstack /config/config.hpp
src/logging/logging _mocap.cpp
include/flightstack /multi_threaded_node.hpp
include/flightstack /control/pid/pid.hpp
src/control/mrac/logging _mrac.cpp
src/control/mrac/mrac.cpp
src/config/config.cpp
src/user_defined_trajectory /piecewise_polynomial_trajectory.cpp
src/user_defined_trajectory /user_defined_trajectory.cpp
include/flightstack /main.hpp
src/multi_threaded _node.cpp
src/pixhawk_interface /pixhawk_actuator_motors.cpp
src/pixhawk_interface /pixhawk_vehicle_odometry.cpp
src/pixhawk_interface /vehicle_state.cpp
src/control/control.cpp
src/control/control _callback.cpp
src/control/pid/logging _pid.cpp
src/control/pid/pid.cpp
src/main.cpp