

Vector3d

Matrix3d

angular_velocity_error_ref
inner_loop_D
inner_loop_I
inner_loop_P
inner_loop_dynamic_inversion
omega_cmd_dot_rotational
omega_cmd_rotational
omega_ref_dot_rotational
outer_loop_D
outer_loop_I
...

jacobian_matrix
jacobian_matrix_dot

MRAC::ControllerSpecific
InternalMembers

