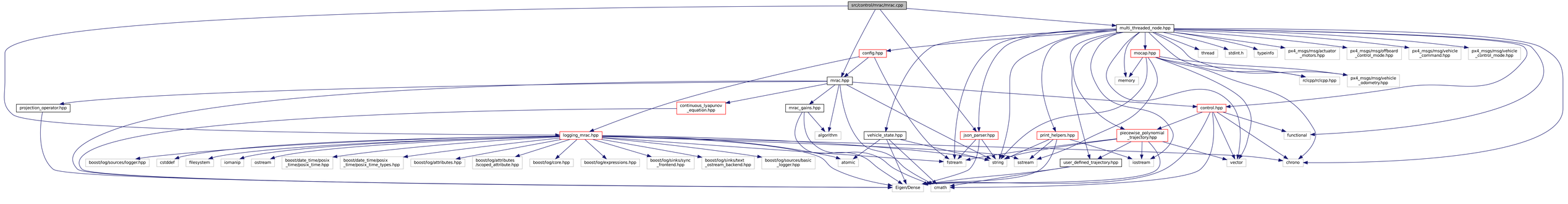
src/control/mrac/mrac.cpp
multi_threaded_node.hpp
config.hpp
mocap.hpp
thread
stdint.h
typeinfo
px4_msgs/msg/actuator_motors.hpp
px4_msgs/msg/offboard_control_mode.hpp
px4_msgs/msg/vehicle_command.hpp
px4_msgs/msg/vehicle_control_mode.hpp
memory
rclcpp/rclcpp.hpp
px4_msgs/msg/vehicle_odometry.hpp
mrac.hpp
projection_operator.hpp
continuous_lyapunov_equation.hpp
mrac_gains.hpp
control.hpp
algorithm
vehicle_state.hpp
json_parser.hpp
print_helpers.hpp
piecewise_polynomial_trajectory.hpp
functional
logging_mrac.hpp
boost/log/sources/logger.hpp
cstddef
filesystem
iomanip
ostream
boost/date_time/posix_time/posix_time.hpp
boost/date_time/posix_time/posix_time_types.hpp
boost/log/attributes.hpp
boost/log/attributes/scoped_attribute.hpp
boost/log/core.hpp
boost/log/expressions.hpp
boost/log/sinks/sync_frontend.hpp
boost/log/sinks/text_ostream_backend.hpp
boost/log/sources/basic_logger.hpp
atomic
fstream
string
sstream
user_defined_trajectory.hpp
iostream
vector
chrono
Eigen/Dense
cmath