

Vector3d

Matrix3d

angular\_velocity\_error\_ref  
inner\_loop\_D  
inner\_loop\_I  
inner\_loop\_P  
inner\_loop\_dynamic\_inversion  
omega\_cmd\_dot\_rotational  
omega\_cmd\_rotational  
omega\_ref\_dot\_rotational  
outer\_loop\_D  
outer\_loop\_I  
...

jacobian\_matrix  
jacobian\_matrix\_dot

MRAC::ControllerSpecific  
InternalMembers

