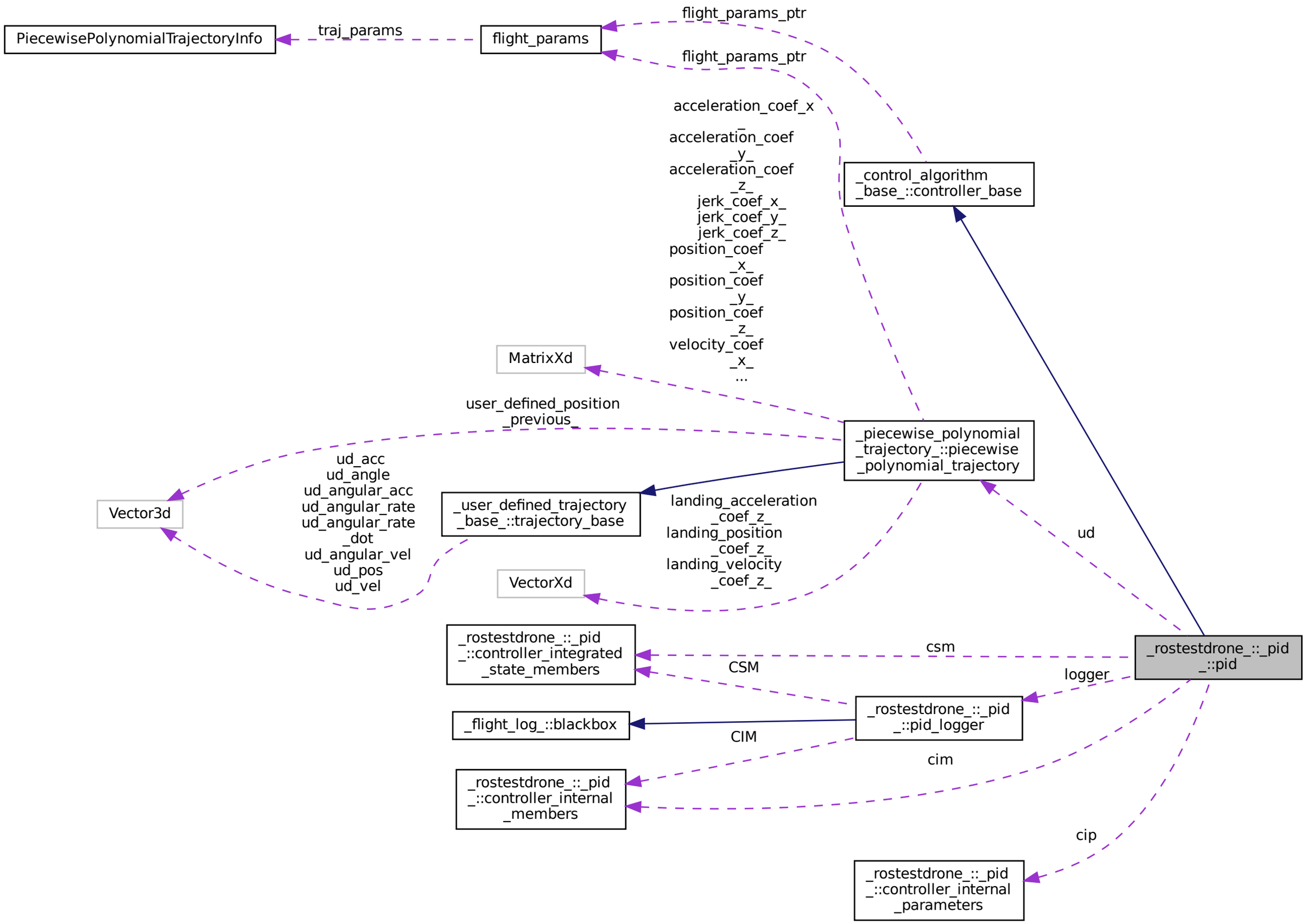
PiecewisePolynomialTrajectoryInfo
traj_params
flight_params
flight_params_ptr
flight_params_ptr
acceleration_coef_x_
acceleration_coef_y_
acceleration_coef_z_
jerk_coef_x_
jerk_coef_y_
jerk_coef_z_
position_coef_x_
position_coef_y_
position_coef_z_
velocity_coef_x_
...
_control_algorithm_base_::controller_base
MatrixXd
user_defined_position_previous_
_piecewise_polynomial_trajectory_::piecewise_polynomial_trajectory
Vector3d
ud_acc
ud_angle
ud_angular_acc
ud_angular_rate
ud_angular_rate_dot
ud_angular_vel
ud_pos
ud_vel
_user_defined_trajectory_base_::trajectory_base
landing_acceleration_coef_z_
landing_position_coef_z_
landing_velocity_coef_z_
ud
VectorXd
rostestdrone::_pid_::controller_integrated_state_members
csm
CSM
rostestdrone::_pid_::pid
logger
rostestdrone::_pid_::pid_logger
_flight_log_::blackbox
CIM
cim
rostestdrone::_pid_::controller_internal_members
cip
rostestdrone::_pid_::controller_internal_parameters