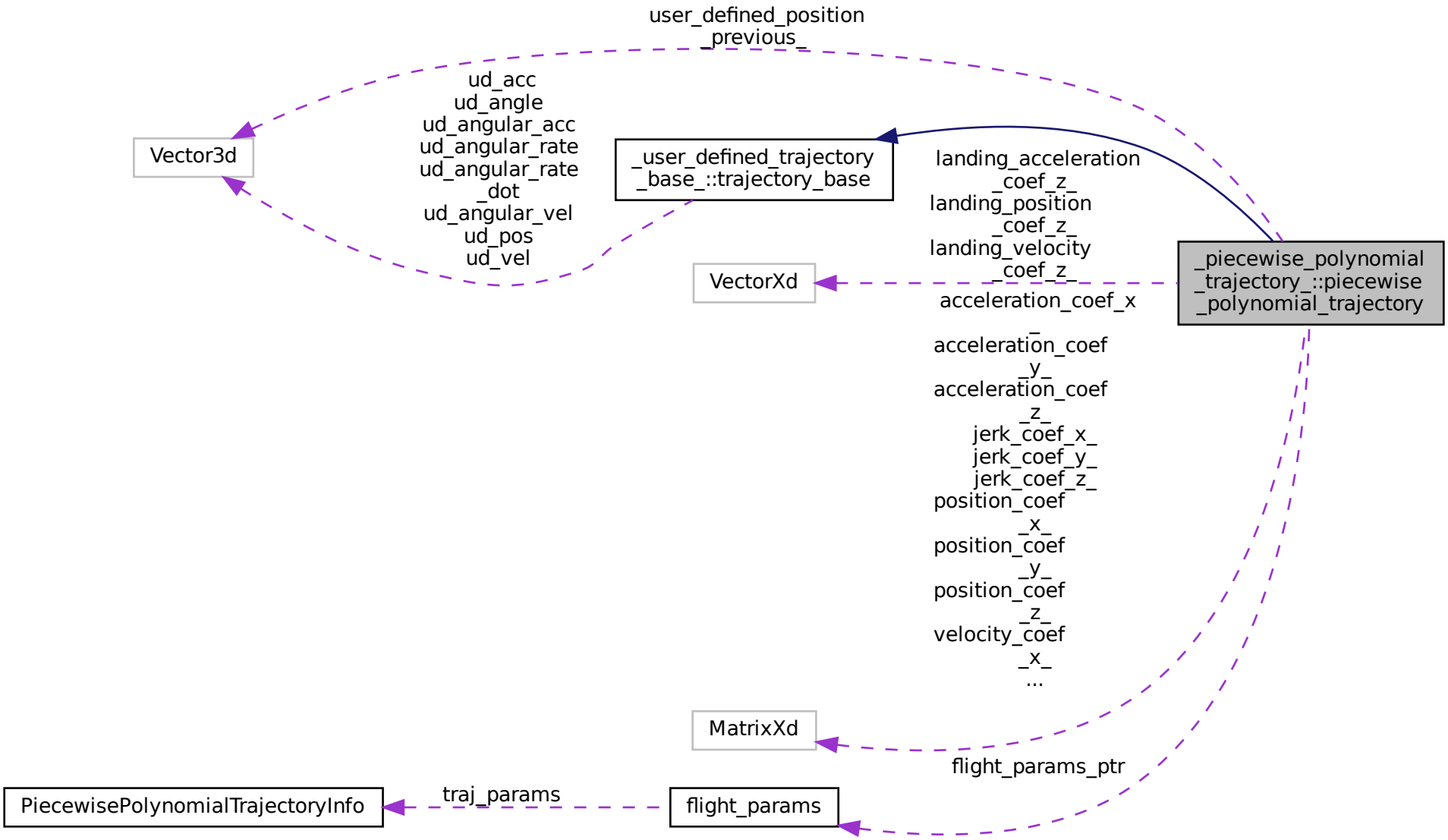
user_defined_position
previous
ud_acc
ud_angle
ud_angular_acc
ud_angular_rate
ud_angular_rate
_dot
ud_angular_vel
ud_pos
ud_vel
Vector3d
_user_defined_trajectory
base::trajectory_base
landing_acceleration
_coef_z_
landing_position
_coef_z_
landing_velocity
_coef_z_
acceleration_coef_x
_
acceleration_coef
_y_
acceleration_coef
_z_
jerk_coef_x_
jerk_coef_y_
jerk_coef_z_
position_coef
_x_
position_coef
_y_
position_coef
_z_
velocity_coef
_x_
...
VectorXd
_piecewise_polynomial
trajectory::piecewise
_polynomial_trajectory
MatrixXd
flight_params_ptr
PiecewisePolynomialTrajectoryInfo
traj_params
flight_params