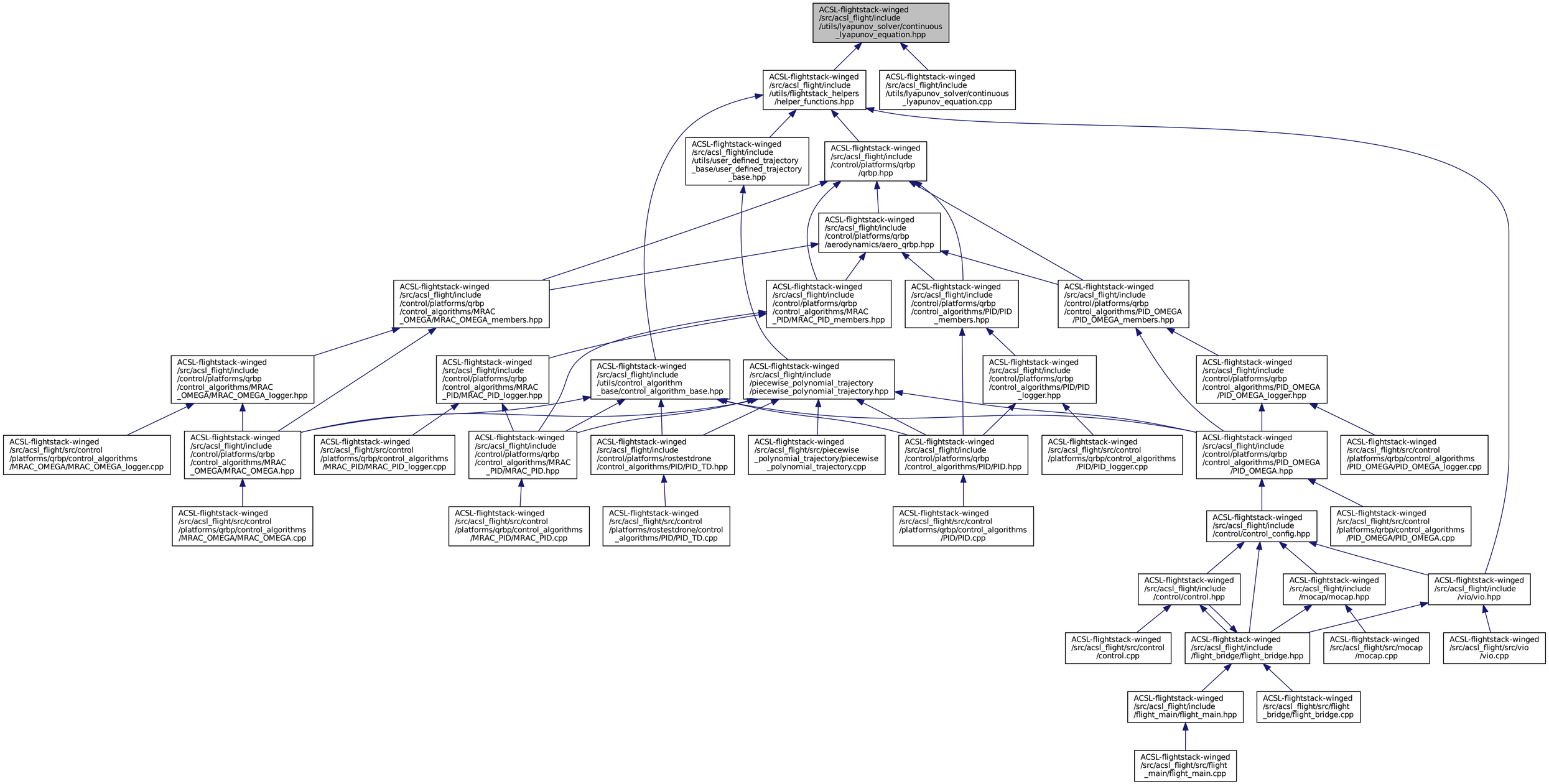
ACSL-flightstack-winged /src/acsl_flight/include /utils/lyapunov_solver/continuous _lyapunov_equation.hpp
ACSL-flightstack-winged /src/acsl_flight/include /utils/flightstack_helpers /helper_functions.hpp
ACSL-flightstack-winged /src/acsl_flight/include /utils/lyapunov_solver/continuous _lyapunov_equation.cpp
ACSL-flightstack-winged /src/acsl_flight/include /utils/user_defined_trajectory _base/user_defined_trajectory _base.hpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /qrbp.hpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /aerodynamics/aero_qrbp.hpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /control_algorithms/MRAC _OMEGA/MRAC_OMEGA_members.hpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /control_algorithms/MRAC _PID/MRAC_PID_members.hpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /control_algorithms/PID/PID _members.hpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /control_algorithms/PID_OMEGA /PID_OMEGA_members.hpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /control_algorithms/MRAC _OMEGA/MRAC_OMEGA_logger.hpp
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ACSL-flightstack-winged /src/acsl_flight/include /piecewise_polynomial_trajectory /piecewise_polynomial_trajectory.hpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /control_algorithms/PID/PID _logger.hpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /control_algorithms/PID_OMEGA /PID_OMEGA_logger.hpp
ACSL-flightstack-winged /src/acsl_flight/src/control /platforms/qrbp/control_algorithms /MRAC_OMEGA/MRAC_OMEGA_logger.cpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /control_algorithms/MRAC _OMEGA/MRAC_OMEGA.hpp
ACSL-flightstack-winged /src/acsl_flight/src/control /platforms/qrbp/control_algorithms /MRAC_PID/MRAC_PID_logger.cpp
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ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/rostestdrone /control_algorithms/PID/PID_TD.hpp
ACSL-flightstack-winged /src/acsl_flight/piecewise _polynomial_trajectory/piecewise _polynomial_trajectory.cpp
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ACSL-flightstack-winged /src/acsl_flight/src/control /platforms/qrbp/control_algorithms /PID/PID_logger.cpp
ACSL-flightstack-winged /src/acsl_flight/include /control/platforms/qrbp /control_algorithms/PID_OMEGA /PID_OMEGA.hpp
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ACSL-flightstack-winged /src/acsl_flight/include /mocap/mocap.hpp
ACSL-flightstack-winged /src/acsl_flight/include /vio/vio.hpp
ACSL-flightstack-winged /src/acsl_flight/src/control /control.cpp
ACSL-flightstack-winged /src/acsl_flight/include /flight_bridge/flight_bridge.hpp
ACSL-flightstack-winged /src/acsl_flight/src/mocap /mocap.cpp
ACSL-flightstack-winged /src/acsl_flight/src/vio /vio.cpp
ACSL-flightstack-winged /src/acsl_flight/include /flight_main/flight_main.hpp
ACSL-flightstack-winged /src/acsl_flight/src/flight _bridge/flight_bridge.cpp
ACSL-flightstack-winged /src/acsl_flight/src/flight _main/flight_main.cpp