

A Supplementary Figures and Tables

Lemma 1. *If A and B are the adjacency matrices of simple graphs that are isomorphic to one another, then the minimum of rQAP is equal to the minimum of QAP.*

Proof. Because any feasible solution to GM is also a feasible solution to rQAP, we must only show that the optimal objective function value to rQAP can be no better than the optimal objective function value of QAP. Let $A = PBP^T$, so that $\langle A, PBP^T \rangle = 2m$, where m is the number of edges in A . If rQAP could achieve a lower objective value, then it must be that there exists a $D \in \mathcal{D}$ such that $\langle A, DBD^T \rangle > \langle A, PBP^T \rangle = 2m$ (remember that we are minimizing the negative Euclidean inner product). For that to be the case, it must be that $(DBD^T)_{uv} \geq 1$ for some (u, v) . That this is not so may be seen by the submultiplicativity of the norm induced by the ℓ_∞ norm: $\|Dx\|_\infty \leq \|D\|_{\infty, \infty} \|x\|_\infty$. Applying this twice (once for each doubly stochastic matrix multiplication) yields our result. \square

Linear Assignment Problems The standard way of writing a Linear Assignment Problem (LAP) is

$$\begin{aligned} & \text{minimize} && \sum_{u,v \in [n]} a_{u\pi(v)} b_{uv} \\ & \text{subject to} && P \in \mathcal{P}. \end{aligned}$$

The LAP objective function, like the QAP objective function, enjoys a number of equivalent formulations, including

$$\begin{aligned} \text{(LAP)} \quad & \text{minimize} && \langle P, AB^T \rangle \\ & \text{subject to} && P \in \mathcal{P}. \end{aligned} \tag{11}$$

The binary constraints of LAP—like those of QAP—make solving even this problem computationally tricky. Nonetheless, in the last several decades, there has been much progress in accelerating algorithms for solving LAPs, starting with exponential time, all the way down to $\mathcal{O}(n^3)$ for general LAPs, and even faster for certain special cases (e.g., sparse matrices) [24, 12].

To see that Eq. (7) is identical to Eq. (12), simply let $A = \nabla_P^{(i)}$ and $B = I$ (the $n \times n$ identity matrix).

To solve a LAP, consider a continuous relaxation of LAP, specifically, relaxing the permutation matrix constraint to a doubly stochastic matrix constraint:

$$\begin{aligned} \text{(rLAP)} \quad & \text{minimize} && \langle P, AB^T \rangle \\ & \text{subject to} && P \in \mathcal{D}. \end{aligned} \tag{12}$$

As it turns out, the minima of LAP and rLAP are equal to one another [12]. This relaxation motivates our approach to approximating QAP.

Pseudocode 1 FAQ for finding a local optimum of rQAP

Input: graphs A and B as well as stopping criteria

Output: \hat{P} , an estimated permutation matrix

- 1: Choose an initialization, $P^{(0)} = \mathbf{1}\mathbf{1}^T/n$
 - 2: **while** stopping criteria not met **do**
 - 3: Compute the gradient of f at the current point via Eq. (6)
 - 4: Compute the direction $Q^{(i)}$ by solving Eq. (7) via the Hungarian algorithm
 - 5: Compute the step size $\alpha^{(i)}$ by solving Eq. (8)
 - 6: Update $P^{(i)}$ according to Eq. (9)
 - 7: **end while**
 - 8: Obtain \hat{P} by solving Eq. (10) via the Hungarian algorithm.
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Table 1: Comparison of FAQ with optimal objective function value and previous state-of-the-art for directed graphs. The best (lowest) value is in **bold**. Asterisks indicate achievement of the global minimum. The number of vertices for each problem is the number in its name (second column).

| # | Problem | Optimal | FAQ | EPATH | GRAD |
|----|---------|----------|------------------|------------------|------------------|
| 1 | lipa20a | 3683 | 3791 | 3885 | 3909 |
| 2 | lipa20b | 27076 | 27076* | 32081 | 27076* |
| 3 | lipa30a | 13178 | 13571 | 13577 | 13668 |
| 4 | lipa30b | 151426 | 151426* | 151426* | 151426* |
| 5 | lipa40a | 31538 | 32109 | 32247 | 32590 |
| 6 | lipa40b | 476581 | 476581* | 476581* | 476581* |
| 7 | lipa50a | 62093 | 62962 | 63339 | 63730 |
| 8 | lipa50b | 1210244 | 1210244* | 1210244* | 1210244* |
| 9 | lipa60a | 107218 | 108488 | 109168 | 109809 |
| 10 | lipa60b | 2520135 | 2520135* | 2520135* | 2520135* |
| 11 | lipa70a | 169755 | 171820 | 172200 | 173172 |
| 12 | lipa70b | 4603200 | 4603200* | 4603200* | 4603200* |
| 13 | lipa80a | 253195 | 256073 | 256601 | 258218 |
| 14 | lipa80b | 7763962 | 7763962* | 7763962* | 7763962* |
| 15 | lipa90a | 360630 | 363937 | 365233 | 366743 |
| 16 | lipa90b | 12490441 | 12490441* | 12490441* | 12490441* |

Table 2: Comparison of FAQ with optimal objective function value and the best result on the undirected benchmarks. Note that FAQ restarted 100 times finds the optimal objective function value in 3 of 16 benchmarks, and that FAQ restarted 3 times finds a minimum better than the previous state-of-the-art on all 16 particularly difficult benchmarks.

| # | Problem | Optimal | FAQ_{100} | FAQ_3 | previous min |
|----|---------|---------|--------------------|----------------|--------------|
| 1 | chr12c | 11156 | 12176 | 13072 | 13072 |
| 2 | chr15a | 9896 | 9896* | 17272 | 19086 |
| 3 | chr15c | 9504 | 10960 | 14274 | 16206 |
| 4 | chr20b | 2298 | 2786 | 3068 | 3068 |
| 5 | chr22b | 6194 | 7218 | 7876 | 8482 |
| 6 | esc16b | 292 | 292* | 294 | 296 |
| 7 | rou12 | 235528 | 235528* | 238134 | 253684 |
| 8 | rou15 | 354210 | 356654 | 371458 | 371458 |
| 9 | rou20 | 725522 | 730614 | 743884 | 743884 |
| 10 | tai10a | 135028 | 135828 | 148970 | 152534 |
| 11 | tai15a | 388214 | 391522 | 397376 | 397376 |
| 12 | tai17a | 491812 | 496598 | 511574 | 529134 |
| 13 | tai20a | 703482 | 711840 | 721540 | 734276 |
| 14 | tai30a | 1818146 | 1844636 | 1890738 | 1894640 |
| 15 | tai35a | 2422002 | 2454292 | 2460940 | 2460940 |
| 16 | tai40a | 3139370 | 3187738 | 3194826 | 3227612 |