

Homework: Expert System

Knowledge Engineering



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ESI-SBA

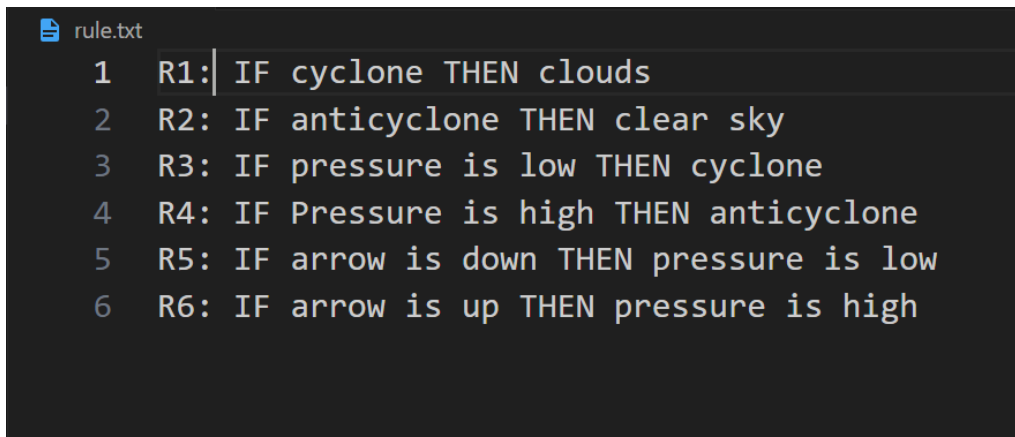
1. Objective

The objective of this lab is to study and implement an expert system that operates using both forward chaining and backward chaining. The system will be designed to enrich a given fact base by applying rules from a rule base.

2. Code structure

2.1 Rule base

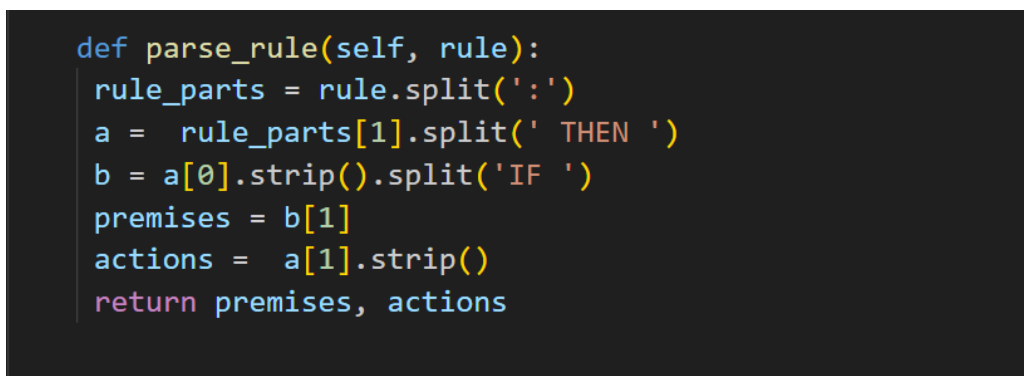
The rule base is represented by a set of rules loaded from a file. Each rule follows a specific structure: “R1: IF (List of premises) THEN (List of actions)”



```
rule.txt
1  R1: IF cyclone THEN clouds
2  R2: IF anticyclone THEN clear sky
3  R3: IF pressure is low THEN cyclone
4  R4: IF Pressure is high THEN anticyclone
5  R5: IF arrow is down THEN pressure is low
6  R6: IF arrow is up THEN pressure is high
```

Figure 1: Rule base screenshot

Function which determines actions and premises:



```
def parse_rule(self, rule):
    rule_parts = rule.split(':')
    a = rule_parts[1].split(' THEN ')
    b = a[0].strip().split('IF ')
    premises = b[1]
    actions = a[1].strip()
    return premises, actions
```

Figure 2: Rule function screenshot

2.2 Expert System class

- Represents the main expert system.
- Initialized with a rule base file and an initial fact base.
- Load the rule base file to create a list of Rule objects.

```
class ExpertSystem:

    def __init__(self, rule_file , initial_facts):
        self.rule_base = self.load_rules(rule_file)
        self.fact_base =initial_facts

    def load_rules(self, rule_file):
        with open(rule_file, 'r') as file:
            rule_lines = file.readlines()

        rule_base = []
        for line in rule_lines:
            rule_base.append(line.strip())

        return rule_base
```

Figure 3: Expert system class screenshot

2.3 Forward chaining

The forward chaining process involves:

- Detecting rules with verified premises (filtering).
- Selecting a rule to apply.
- Applying the rule and disabling it.
- Repeating until no more applicable rules.

```
def apply_forward_chaining(self, rules_used,fact, base):

    while True:
        rule_applied = False
        for rule in base:
            premise, action = self.parse_rule(rule)
            if premise in fact:
                rules_used.append(rule.split(':')[0])
                fact.append(action)
                base.remove(rule)
                rule_applied = True

        if not rule_applied:
            break

    self.print_system_status(fact,rules_used)
```

Figure 4: forward chaining function screenshot

2.4 Backward chaining

The backward chaining process involves:

- Placing the initial goal at the top of a stack. => (init_goal)
- Detecting rules that conclude this goal. => (find_rules_for_goal)
- Resolving conflicts (if they exist). => (selected_rule)
- Applying the rule, where the elements of the premises become sub-goals to achieve.
- Stopping when the stack is empty or no applicable rules remain.

```
def apply_backward_chaining(self, goal , rules_used ,fact , base):
    rules = self.find_rules_for_goal(goal)
    if not rules:
        print(f"Goal cannot be achieved.")
        return

    selected_rule = rules[0]
    rules_used.append(selected_rule)
    self.apply_rule_backward(selected_rule, rules_used,fact, base )

def find_rules_for_goal(self, goal):
    rules_for_goal = []
    for rule in self.rule_base:
        _, actions = self.parse_rule(rule)

        if goal in actions:
            rules_for_goal.append(rule)
    return rules_for_goal

def apply_rule_backward(self, rule ,rules_used ,fact, base):
    premises, actions = self.parse_rule(rule)
    fact.append(actions)
    if (premises in self.fact_base) :
        for_rules_used = []
        for i in rules_used :
            r=i.split(':')
            for_rules_used.append(r[0])
            self.print_system_status(fact,for_rules_used[::-1])
    else :
        base.remove(rule)
        self.apply_backward_chaining(premises ,rules_used ,fact, base)
```

Figure 5: backward chaining functions screenshot

3. Output

```
##### main code #####
initial_facts= ['pressure is low']
rule_file = 'C:/Users/ayama/OneDrive/Bureau/IC/tp2/rule.txt'
system = ExpertSystem(rule_file , initial_facts)
goal = 'clouds'

rules_used = []
print("*****Backward chaining*****\n")
print(f"the goal is :"+ str(goal)+"\n")
system.apply_backward_chaining(goal ,rules_used ,system.fact_base.copy(), system.rule_base.copy())

rules_used = []
print("*****forward chaining*****\n")
system.apply_forward_chaining(rules_used, system.fact_base.copy(), system.rule_base.copy())
```

Figure 5: main code screenshot

```
*****Backward chaining*****

the goal is :clouds

New Fact Base: ['pressure is low', 'clouds', 'cyclone']

Rules order :['R3', 'R1']

*****forward chaining*****

New Fact Base: ['pressure is low', 'cyclone', 'clouds']

Rules order :['R3', 'R1']
```

Figure 6: output screenshot

4. Explanation

4.1 Forward chaining

- Facts base: ['pressure is low', 'cyclone', 'clouds']
 - The expert system started with the initial fact base, which was "pressure is low."
 - By applying rules iteratively, it derived new facts, including "cyclone" and "clouds."
 - The final fact base after forward chaining consists of 'pressure is low', 'cyclone', and 'clouds.'
- Rule order: [R3, R1]

- The system applied two rules during forward chaining.
- Rule 3 was applied first, resulting in the addition of 'cyclone' to the fact base.
- Rule 1 was then applied, leading to the inclusion of 'clouds' in the fact base.

4.2 Backword chaining

- New Fact base: ['pressure is low', 'cyclone', 'clouds']
 - The backward chaining process started with a specific goal, in this case, "clouds."
 - By working backward from the goal, the system identified that 'cyclone' was needed.
 - The process continued until the system reached the initial fact base.
 - The final fact base after backward chaining is the same as the one after forward chaining.
- Rule order: [R3, R1]
 - Similar to forward chaining, the backward chaining process applied Rule 3 first and then Rule 1.
 - The order of rule application during backward chaining matches that of forward chaining.

5. Conclusion

This lab focused on the implementation of an expert system capable of both forward and backward chaining. The rule base was read from a file and modeled appropriately. The system successfully demonstrated the ability to enrich a fact base by applying rules, and the output included the set of rules used and the updated fact base.