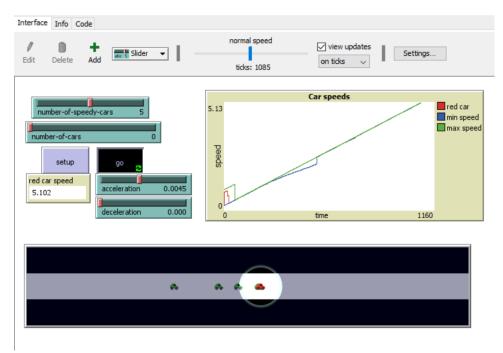
```
globals
 day
]
turtles-own
 walks-# ;; the amount of steps takenSSSSss
to setup
 clear-all
 reset-ticks
 create-turtles 20 [set xcor random 16 set ycor random 16]
 ask turtles [set walks-# 0]
end
to go
 ask turtles
   forward 1
   change-direction
   set walks-# walks-# + 1
   set label walks-#
  1
 tick
 if (remainder ticks 4 = 0) [set day day + 1]
end
to change-direction
    ifelse (random 100 < 50)
    [right 90]
    [left 90]
 end
```

Opdrachten:

1. Kernfunctionaliteit is autos op een weg te simuleren. Ik heb een nieuw soort auto toegevoegd. En een nieuwe slider. De nieuwe autos zijn speedy autos.



```
set-default-shape turtles "car"
create-turtles number-of-cars [
 set color blue
 set xcor random-xcor
 set heading 90
 ;; set initial speed to be in range 0.1 to 1.0
 set speed 0.1 + random-float 0.9
 set speed-limit 1
 set speed-min 0
 separate-cars
create-turtles number-of-speedy-cars [
 set color green
 set xcor random-xcor
 set heading 90
 ;; set initial speed to be in range 0.1 to 1.0
  set speed 0.1 + random-float 0.9
 set speed-limit 20
  set speed-min 0
 separate-cars
set sample-car one-of turtles
ask sample-car [ set color red ]
```