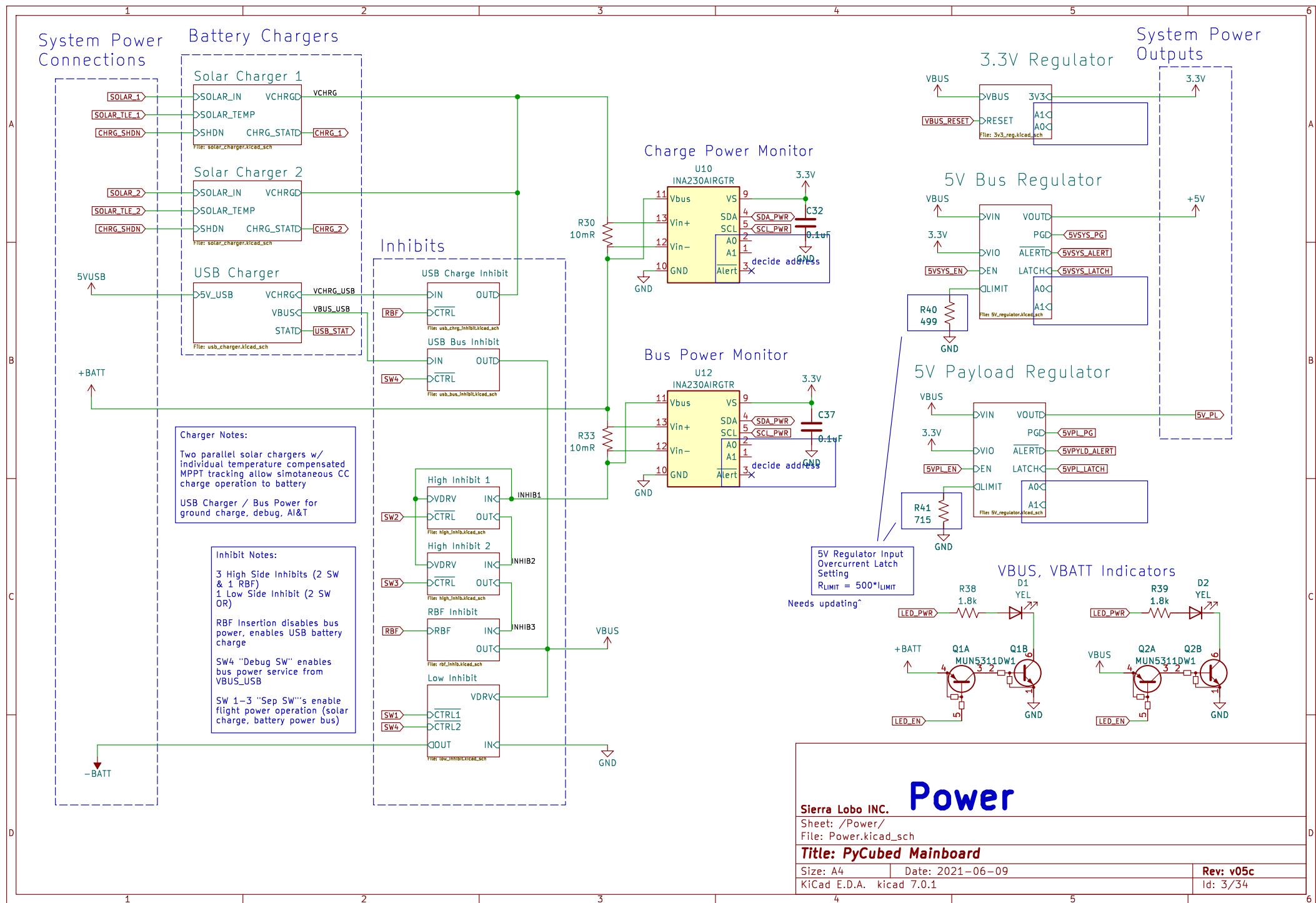


Avionics



1 2 3 4 5 6

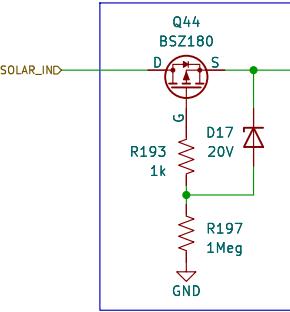
PARAMETERS

INPUT:
 Solar Panel: 9-24V 400mA (i.e. 7S Pumpkin Cell)
 Panel Temperature: Lm35 cathode ($10\text{mV}/\text{degK}$ absolute temperature sensor)

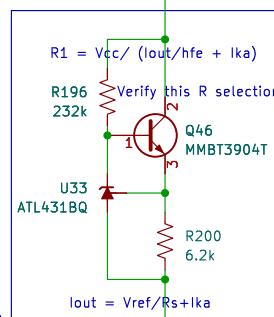
OUTPUT:
 8.4Vfloat, 0.8A (6.7W)

A

Input "Diode"
 Notice zener, V_{GS} may potentially exceed rating with margin applied.



LM35 Bias CC Source
 450 μA source provides constant Z_{IN} to temperature compensation
 10% margin on LM35 minimum current.



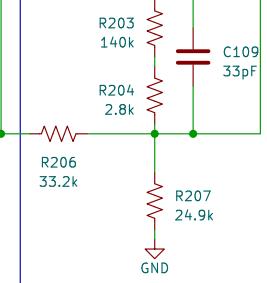
B

Input Voltage Regulation Programming

Temperature Sensor Input
 LM335 Temperature sensor on solar panels.
 $10\text{mV}/\text{degK}$ absolute sensitivity
 400 μA min current

ATL431 CC Source, set to 440 μA , 10% above LM335 functional minimum

SOLAR_TEMPD



V_{IN_REG} : Input Voltage Regulation Reference.
 Maximum charge current is reduced when this pin is below 2.7V.

LT3652HV serves the maximum charge current required to maintain the programmed operational V_{IN} voltage, through maintaining the voltage on V_{IN_REG} at or above 2.7V.

$$\text{Goal: } V_{MP}(T) = V_{IN}(T)$$

$$V_{IN}(T) = [(2.7/R_{VIN_REG_2} - (V_{TLE}(T) - 2.7)R_{TLE})] * R_{VIN_REG_1}$$

$$V_{MP} = m_{MP}(T) + b_{MP}$$

$$V_{TLE} = m_{TLE}(T) + b_{TLE}$$

$$\Rightarrow R_{VIN_REG_1} = (-m_{MP})/(m_{TLE})/(R_3)$$

$$\Rightarrow R_{VIN_REG_2} = (R_1)(V_{REF})....$$

C

Sheet: /Power/Solar Charger 1/
 File: solar_charger.kicad_sch

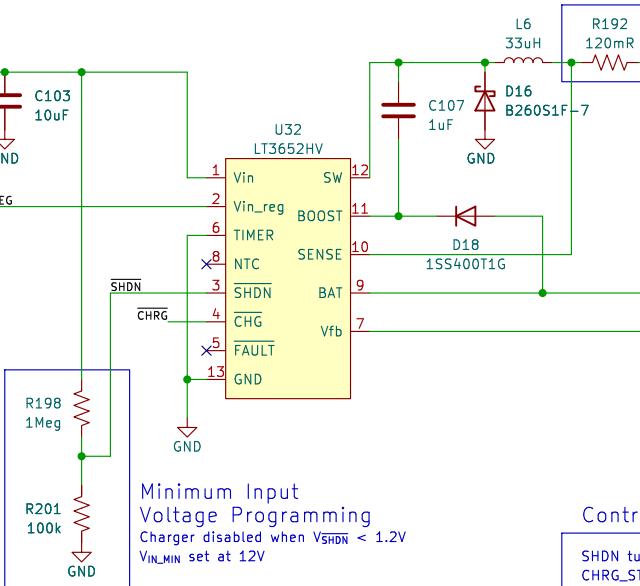
Title:

Size: A4 | Date:
 KiCad E.D.A. kicad 7.0.1

Rev:
 Id: 4/34

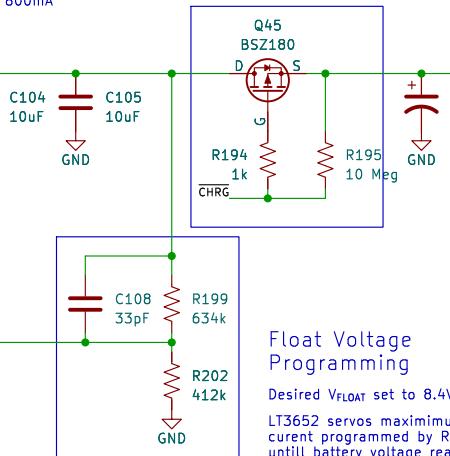
3

Charge Current Limit Programming
 Desired I_{CHRG} set to 800mA



Minimum Input Voltage Programming
 Charger disabled when $V_{SHDN} < 1.2\text{V}$
 V_{IN_MIN} set at 12V

Output Switch
 Prevents backflow when not charging ($CHRG$ low)
 Good idea when paralleling charging circuits...

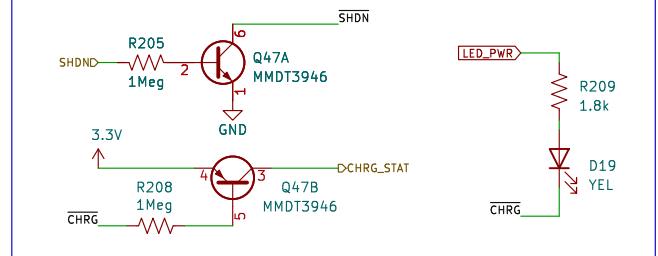


Float Voltage Programming

Desired V_{FLOAT} set to 8.4V
 LT3652 serves maximum charge current programmed by R_{SEN} until battery voltage reaches V_{FLOAT}

Control Signals

$SHDN$ turns off/on charger. Programmed V_{IN_MIN} takes precedence.
 $CHRG_STAT$ is high when charging.



1	2	3	4	5	6
1	2	3	4	5	6

1 2 3 4 5 6

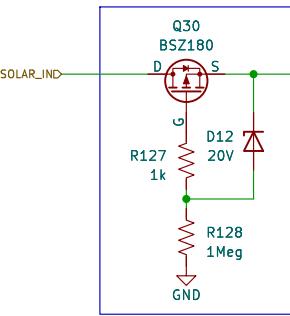
PARAMETERS

INPUT:
 Solar Panel: 9-24V 400mA (i.e. 7S Pumpkin Cell)
 Panel Temperature: Lm35 cathode ($10\text{mV}/\text{degK}$ absolute temperature sensor)

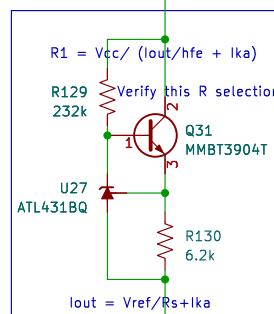
OUTPUT:
 8.4Vfloat, 0.8A (6.7W)

A

Input "Diode"
 Notice zener, V_{GS} may potentially exceed rating with margin applied.

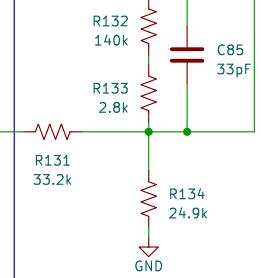


LM35 Bias CC Source
 450 μA source provides constant Z_{IN} to temperature compensation
 10% margin on LM35 minimum current.



B

Input Voltage Regulation Programming



V_{IN_REG} : Input Voltage Regulation Reference.
 Maximum charge current is reduced when this pin is below 2.7V.

LT3652HV serves the maximum charge current required to maintain the programmed operational V_{IN} voltage, through maintaining the voltage on V_{IN_REG} at or above 2.7V.

$$\text{Goal: } V_{MP}(T) = V_{IN}(T)$$

$$V_{IN}(T) = [(2.7/R_{VIN_REG_2} - (V_{TLE}(T) - 2.7)R_{TLE})] * R_{VIN_REG_1}$$

$$V_{MP} = m_{MP}(T) + b_{MP}$$

$$V_{TLE} = m_{TLE}(T) + b_{TLE}$$

$$\Rightarrow R_{VIN_REG_1} = (-m_{MP})/(m_{TLE})/(R_3)$$

$$\Rightarrow R_{VIN_REG_2} = (R_1)(V_{REF})....$$

C

Temperature Sensor Input

LM335 Temperature sensor on solar panels.
 10mV/degK absolute sensitivity
 400 μA min current
 ATL431 CC Source, set to 440 μA , 10% above LM335 functional minimum

SOLAR_TEMPD

D

1

2

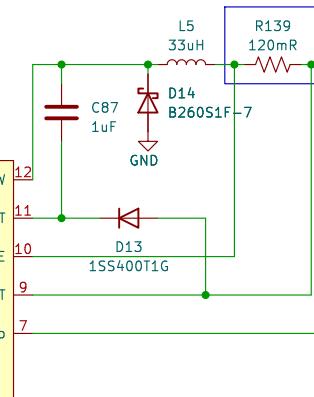
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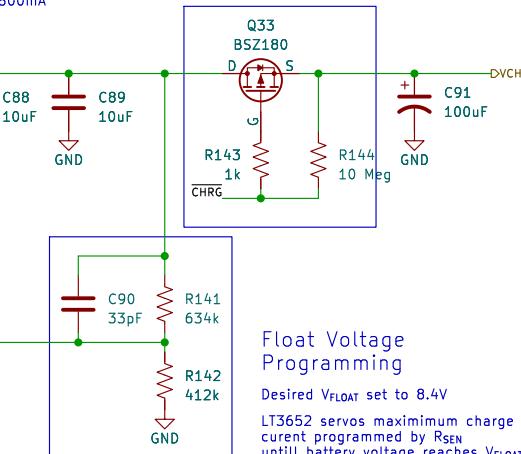
6

Charge Current Limit Programming
 Desired I_{CHRG} set to 800mA



Output Switch

Prevents backflow when not charging ($CHRG$ low)
 Good idea when paralleling charging circuits...

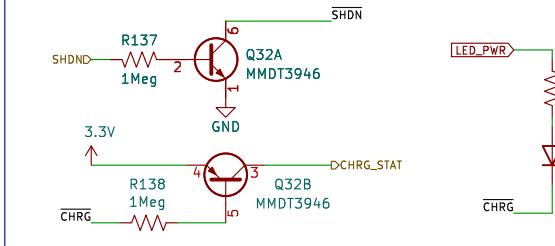


Float Voltage Programming

Desired V_{FLOAT} set to 8.4V
 LT3652 serves maximum charge current programmed by R_{SEN} until battery voltage reaches V_{FLOAT}

Control Signals

SHDN turns off/on charger. Programmed V_{IN_MIN} takes precedence.
 $CHRG_STAT$ is high when charging.



Sheet: /Power/Solar Charger 2/
 File: solar_charger.kicad_sch

Title:

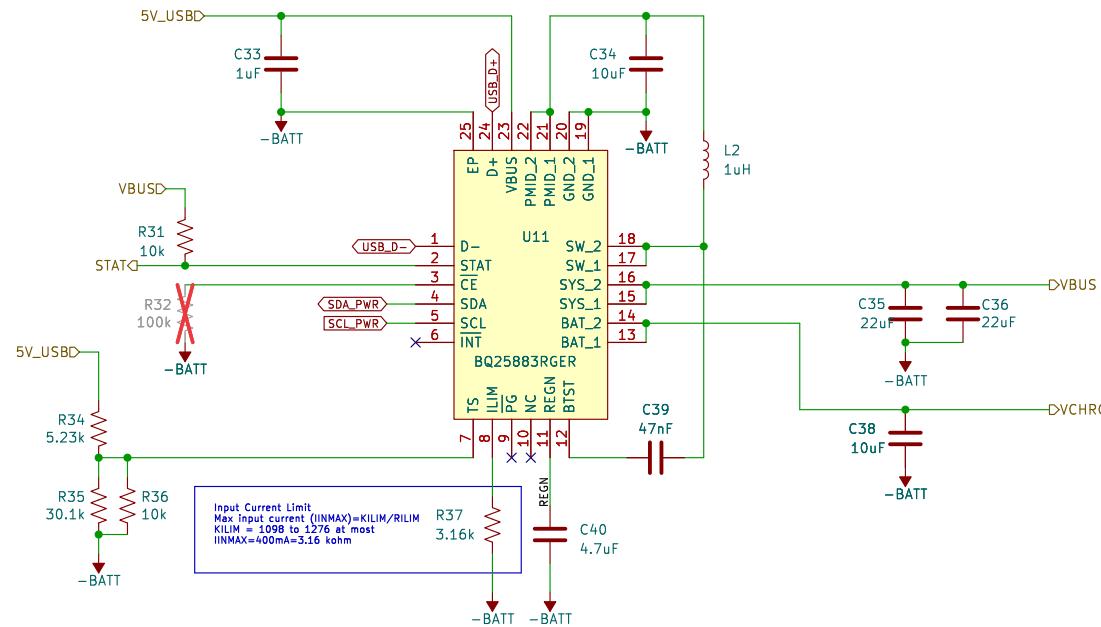
Size: A4 | Date:
 KiCad E.D.A. kicad 7.0.1

Rev:
 Id: 5/34

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USB (Boost) Charging for 2-cell Li-ion



Sheet: /Power/USB Charger/
File: usb_charger.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 6/34

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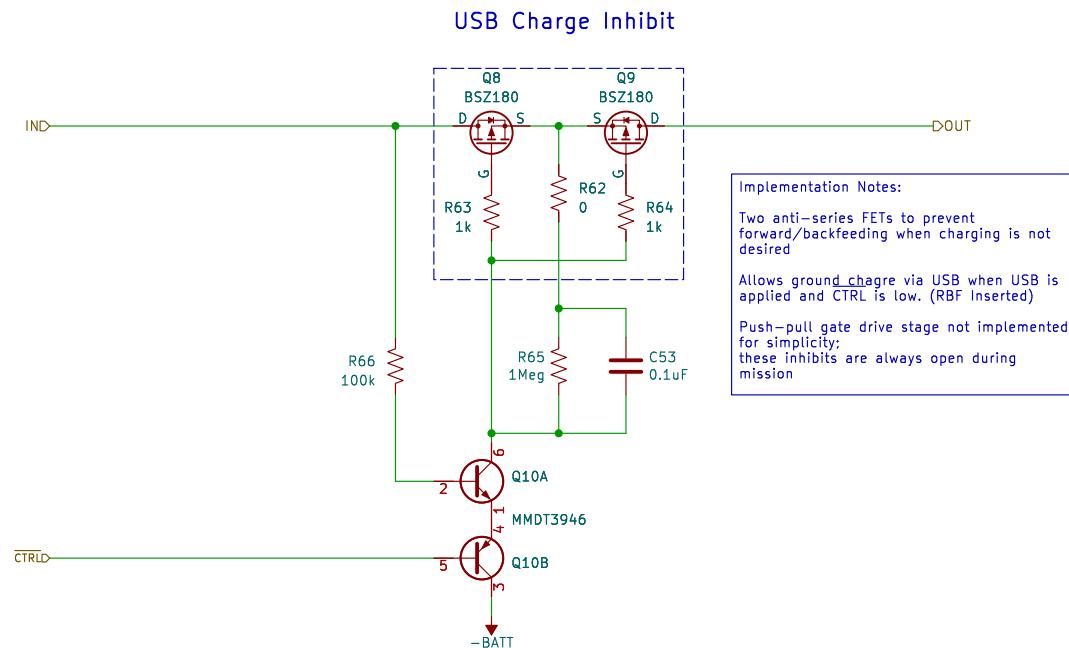
B

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Sheet: /Power/USB Charge Inhibit/
File: usb_chrg_inhibit.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 7/34

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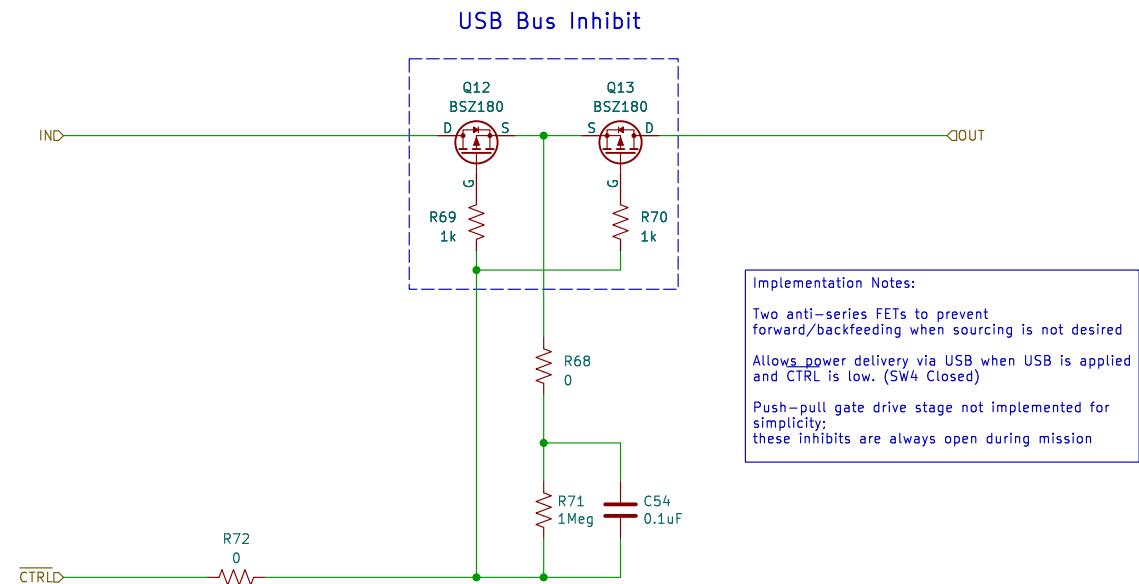
B

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D

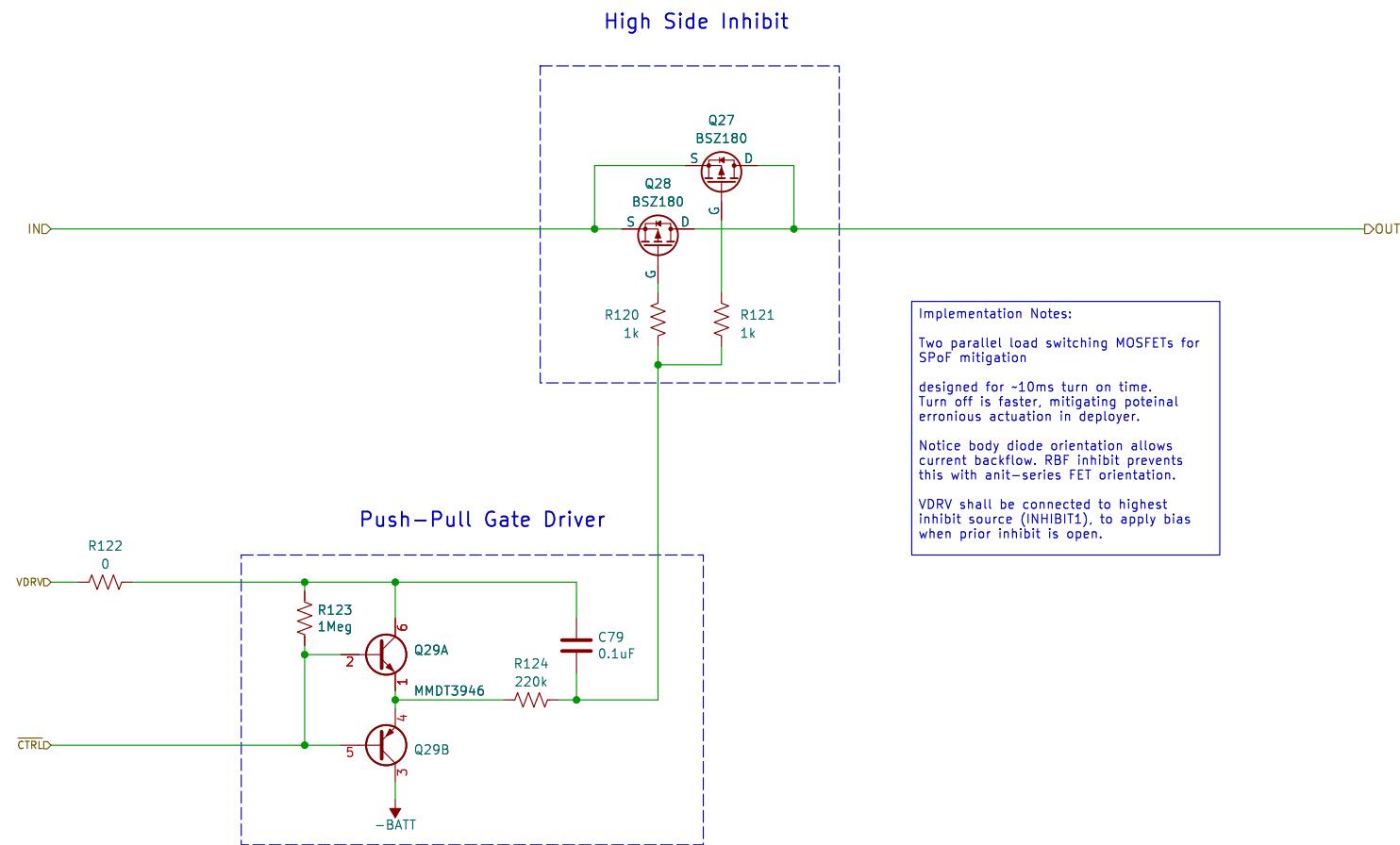


Sheet: /Power/USB Bus Inhibit/
File: usb_bus_inhibit.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 8/34



Sheet: /Power/High Inhibit 1/
File: high_inhib.kicad_sch

Title:

Size: A4 Date:
KiCad E.D.A. kicad 7.0.1

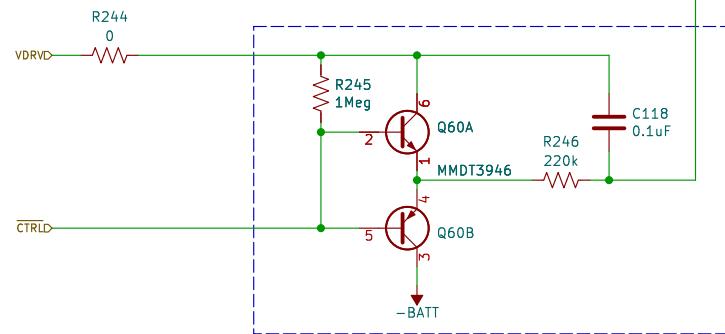
Rev:
Id: 9/34

A

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High Side Inhibit

Implementation Notes:
 Two parallel load switching MOSFETs for SPoF mitigation
 designed for ~10ms turn on time.
 Turn off is faster, mitigating potential erroneous actuation in deployer.
 Notice body diode orientation allows current backflow. RBF inhibit prevents this with anit-series FET orientation.
 VDRV shall be connected to highest inhibit source (INHIBIT1), to apply bias when prior inhibit is open.

Push-Pull Gate Driver

Sheet: /Power/High Inhibit 2/
 File: high_inhib.kicad_sch

Title:

Size: A4 | Date:
 KiCad E.D.A. kicad 7.0.1

Rev:
 Id: 10/34

B

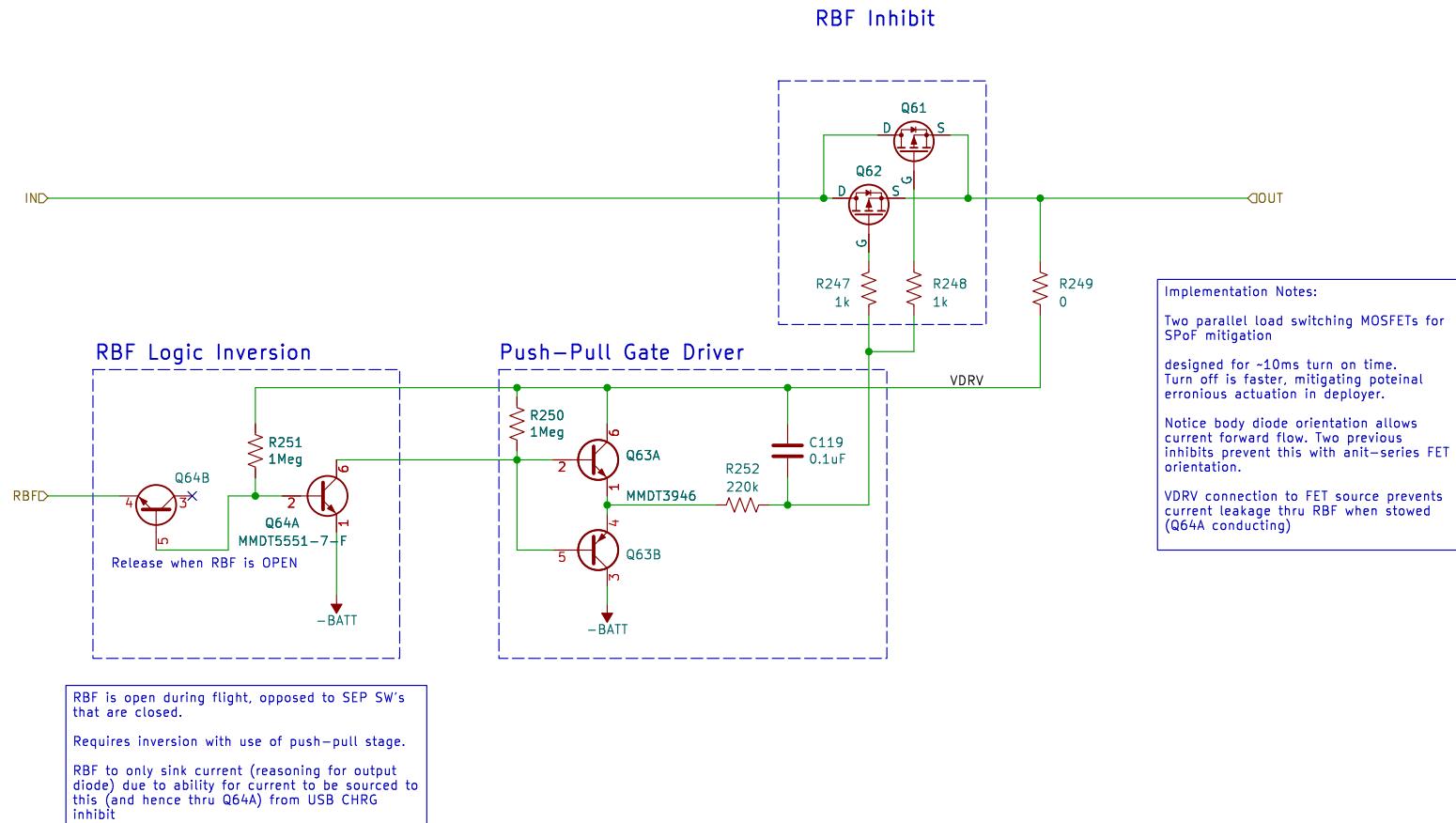
B

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D



Sheet: /Power/RBF Inhibit/
File: rbf_inhib.kicad_sch

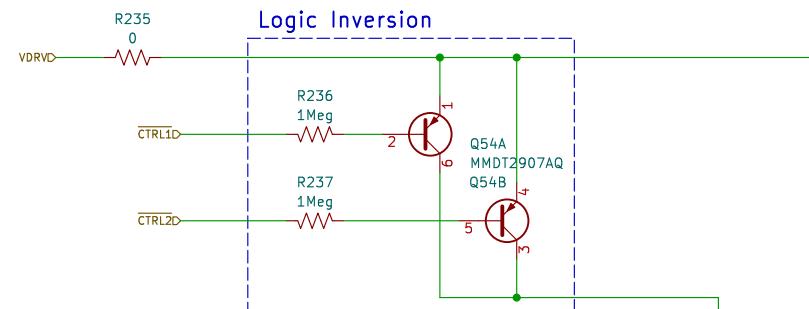
Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 11/34

1 2 3 4 5 6

A



Logic Inversion

SEP SW's are closed during flight, but low side inhibit is open when low.
Input to inverting push-pull stage requires inversion.

Implementation Notes:

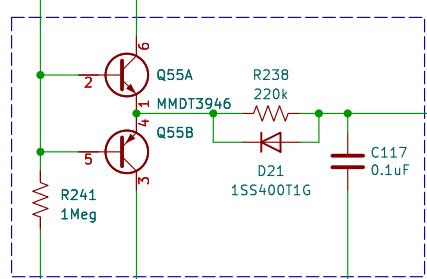
Two parallel load switching MOSFETs for SPoF mitigation
designed for ~10ms turn on time.

Turn off is faster, mitigating potential erroneous actuation in deployer.

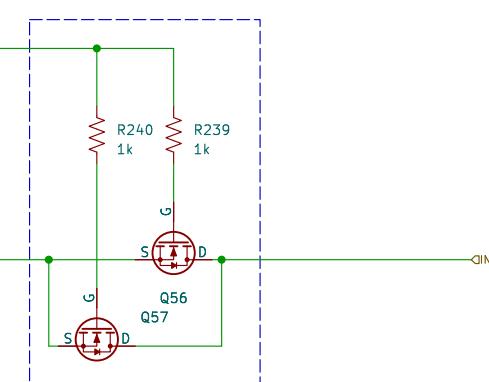
CTRL1 OR CTRL2 can turn this inhibit on,
CTRL2 shall be connected to SW4 "Debug SW" for easier debug, AI&T

VDRV shall be connected to VBUS (disables leakage when stowed).

Push-Pull Gate Driver



Low Side Inhibit



B

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A

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D

Sheet: /Power/Low_Inhibit/
File: low_inhibit.kicad_sch

Title:

Size: A4 Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 12/34

1 2 3

4 5 6

PARAMETERS

INPUT:
VBUS 5–8.4VOUTPUT:
5V, 2A (max, 10W)

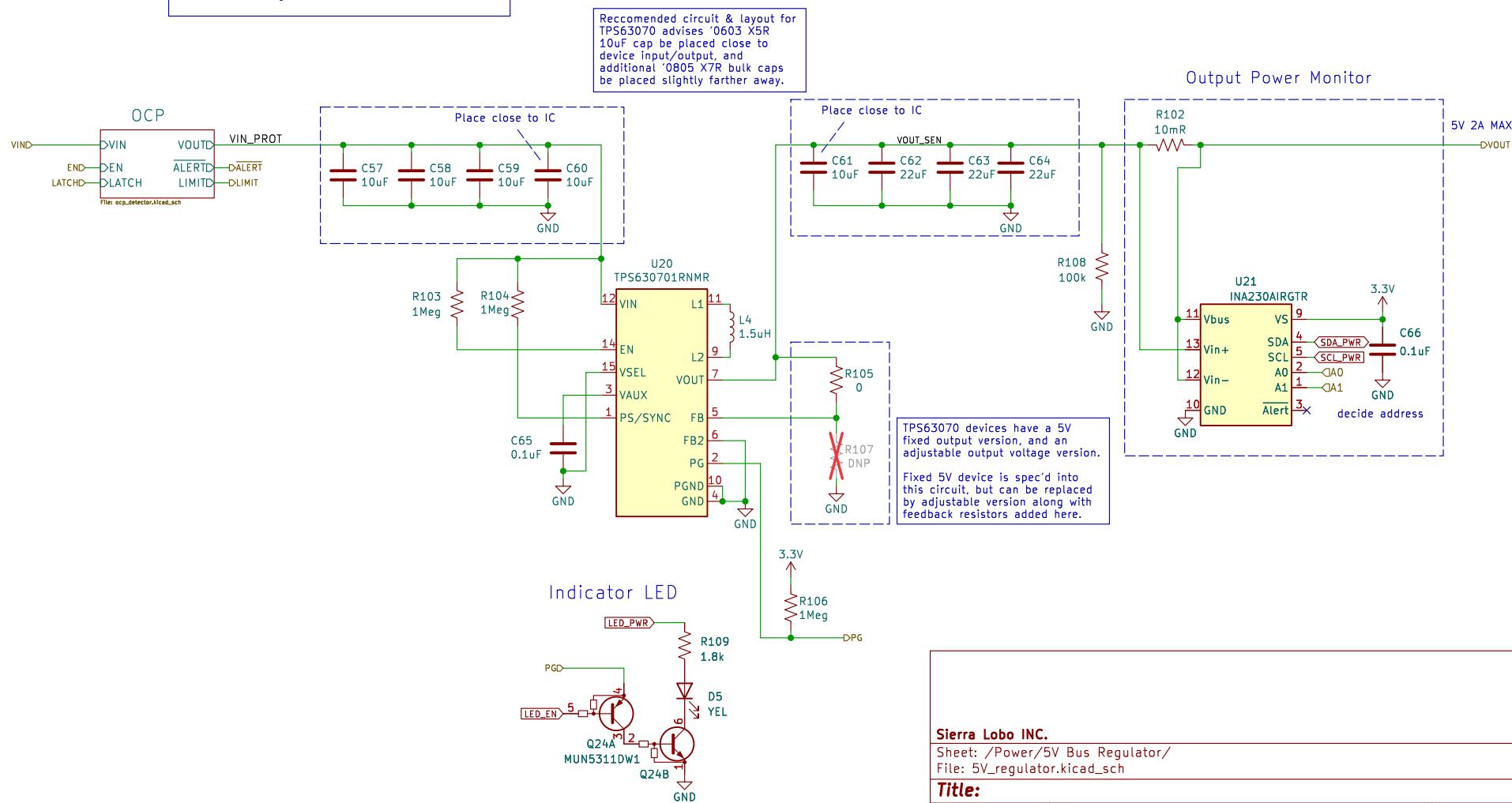
Implementation Notes:

based from TI WebBench Design.

No heritage for TPS63070, failure of device has potential to cause catastrophic upstream fault.
 OCL protection circuit will disable power to device when input current exceeds threshold set by LIMIT resistor. LIMIT resistor shall be calculated such that OCL will only trip when current surpasses extreme operational bounds (i.e. 40% margin at 80% conversion efficiency).

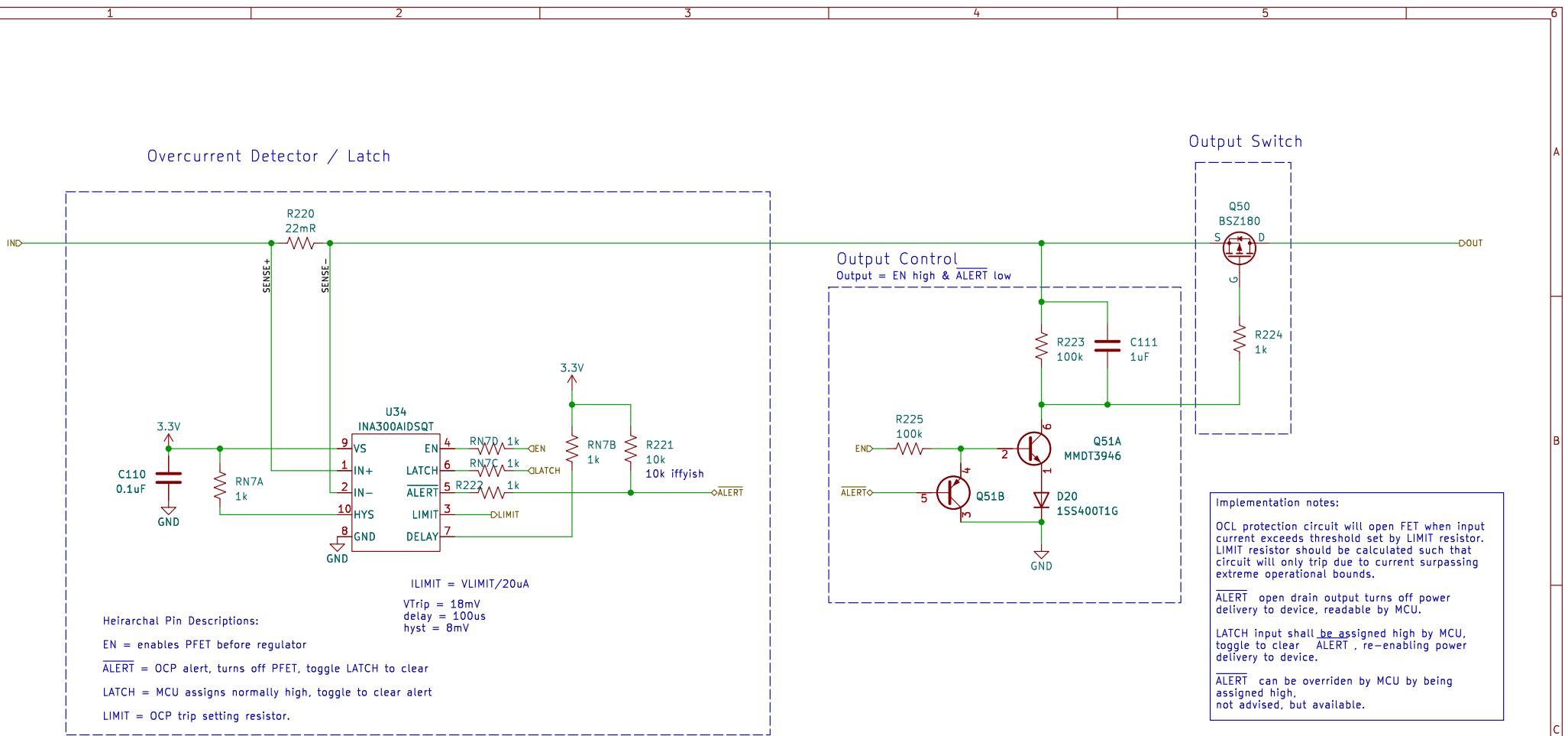
Low input capacitance & device soft start will limit inrush when turned on, but current will still spike as device &/ downstream devices are used.

OCP circuit trips after 100μS of a sustained trip current additionally mitigating nuisance trips, but users should still be cognizant of such.



Sierra Lobo INC.

Sheet: /Power/5V Bus Regulator/
File: 5V_regulator.kicad_sch**Title:**Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1Rev:
Id: 13/34



Overcurrent Protection

Sheet: /Power/5V Bus Regulator/OCP/
File: ocp_detector.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 14/34

PARAMETERS

INPUT:
VBUS 5–8.4VOUTPUT:
5V, 2A (max, 10W)

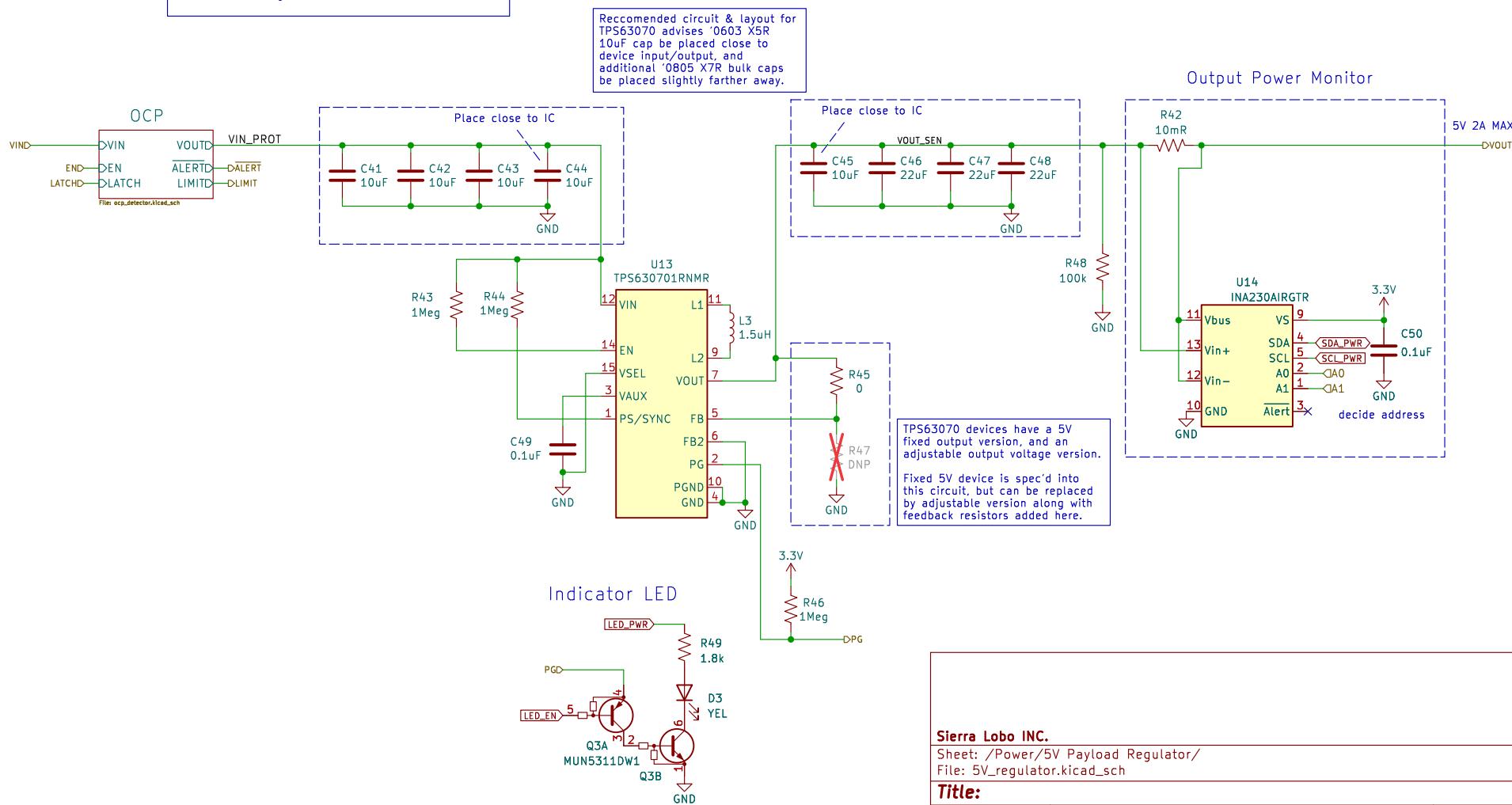
Implementation Notes:

based from TI WebBench Design.

No heritage for TPS63070, failure of device has potential to cause catastrophic upstream fault.
 OCL protection circuit will disable power to device when input current exceeds threshold set by LIMIT resistor. LIMIT resistor shall be calculated such that OCL will only trip when current surpasses extreme operational bounds (i.e. 40% margin at 80% conversion efficiency).

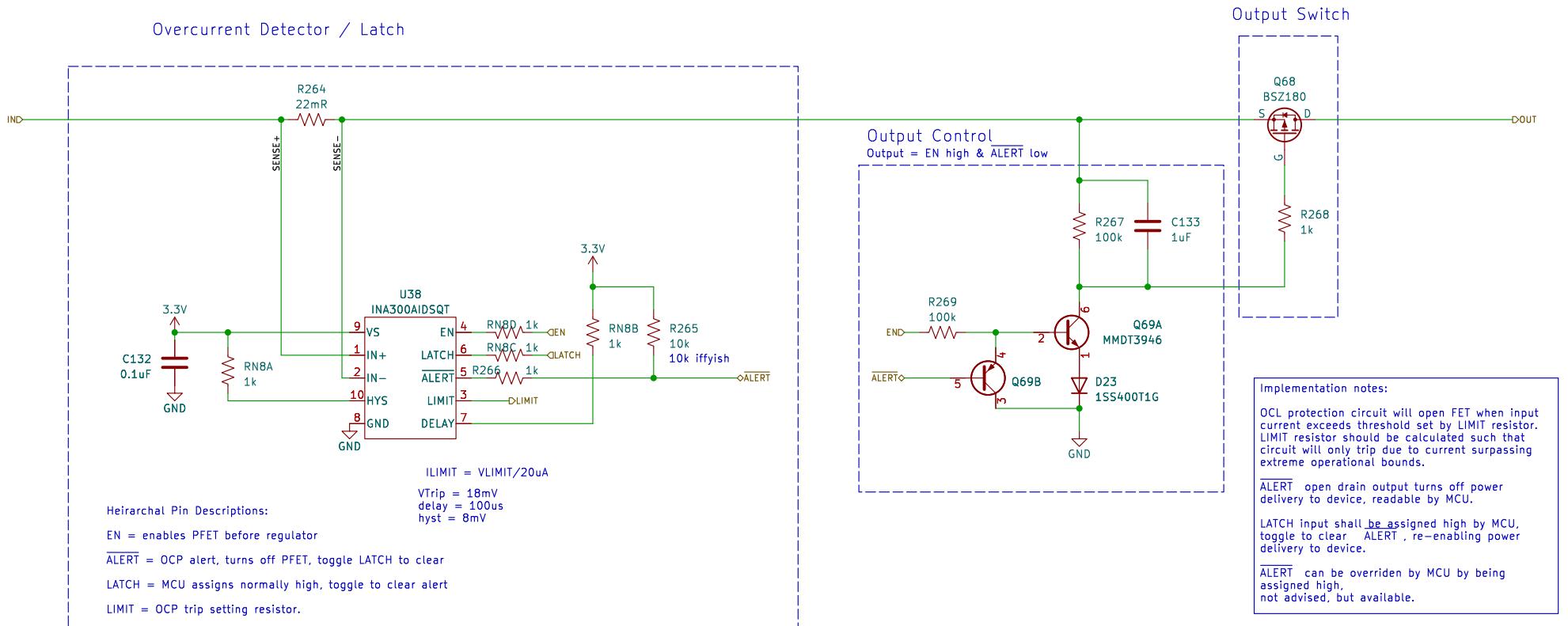
Low input capacitance & device soft start will limit inrush when turned on, but current will still spike as device &/ downstream devices are used.

OCP circuit trips after 100μS of a sustained trip current additionally mitigating nuisance trips, but users should still be cognizant of such.



Sierra Lobo INC.

Sheet: /Power/5V Payload Regulator/
File: 5V_regulator.kicad_sch**Title:**Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1Rev:
Id: 15/34



Overcurrent Protection

Sheet: /Power/5V Payload Regulator/OCP/
File: ocp_detector.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 16/34

1 2 3 4 5 6

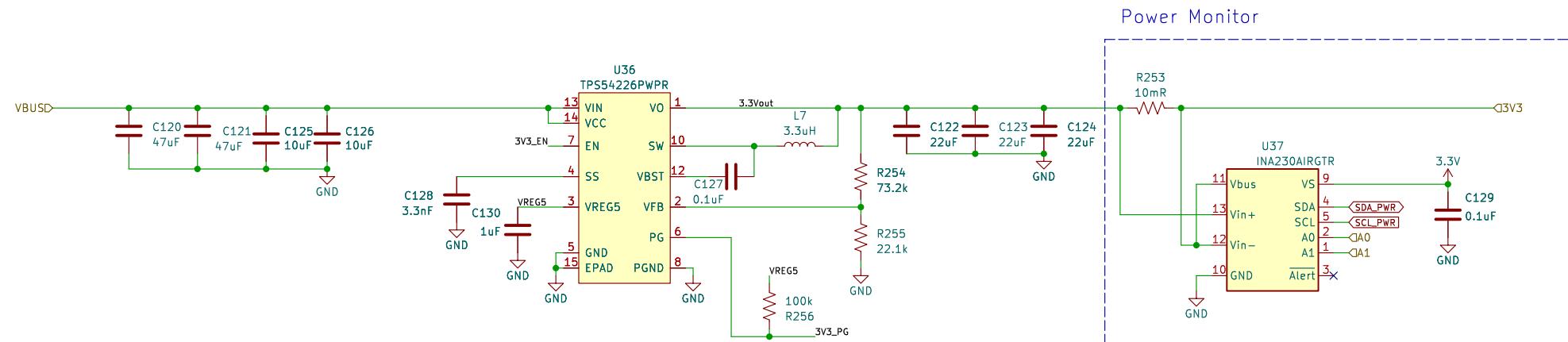
PARAMETERS

INPUT:
VBUS 4.5–18V

OUTPUT:
3.3V, ~1.5A (OCP)
~1.5A OCP (See datasheet p8 for more information.)

A

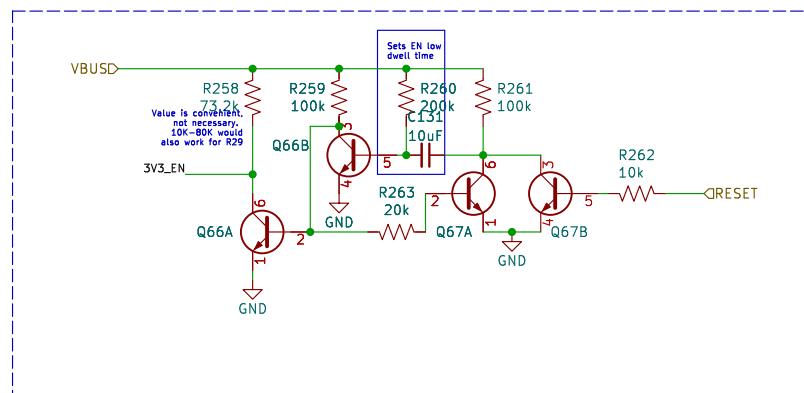
A



B

B

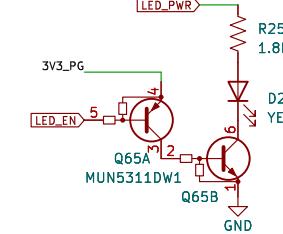
"One Shot" Regulator Reset



C

C

Indicator LED



Sheet: /Power/3.3V Regulator/
File: 3v3_reg.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

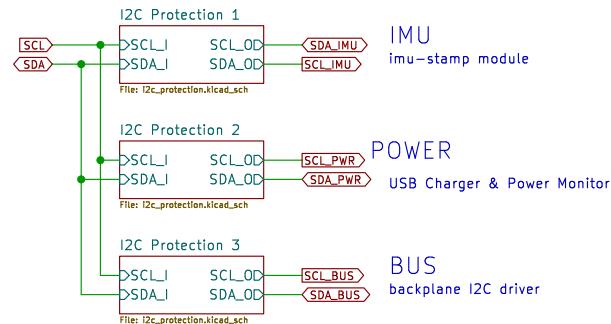
Rev:
Id: 17/34

1 2 3 4 5 6

A

A

I2C Bus Protection



B

B

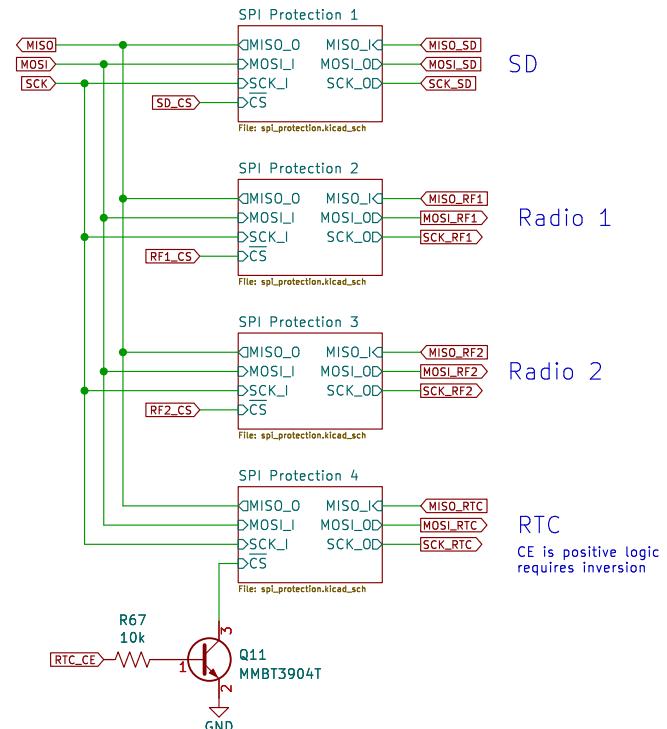
NOTE

These novel bus protection circuits prevent traditional I2C/SPI failure modes where a single slave failure can disable the entire bus.

Learn more:
<https://doi.org/10.36227/techrxiv.15166620>

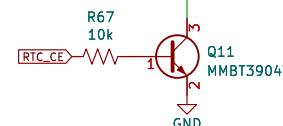
By default, slave clock and/or data lines can be held low and the Master (SAMD51) will still be able to communicate with the remainder of the bus.

They can individually be bypassed by removing the transistor(s) and soldering the 0ohm jumpers below.



C

C



D

Bus Protection

Sierra Lobo INC.

Sheet: /Bus Protection/
 File: Bus_Protection.kicad_sch

Title: PyCubed Mainboard

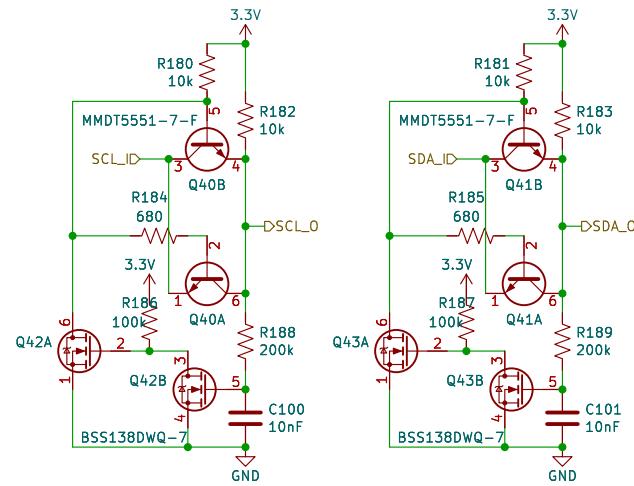
Size: A4 Date: 2021-06-09
 KiCad E.D.A. kicad 7.0.1

Rev: v05c
 Id: 18/34

A

A

Bus Protection



NOTE

These novel bus protection circuits prevent traditional I₂C/SPI failure modes where a single slave failure can disable the entire bus.

Learn more:
<https://doi.org/10.36227/techrxiv.15166620>

By default, slave clock and/or data lines can be held low and the Master (SAMD51) will still be able to communicate with the remainder of the bus.

They can individually be bypassed by removing the transistor(s) and soldering the 0ohm jumpers below.

I₂C Protection – Bypass Jumpers



Sheet: /Bus Protection/I₂C Protection 1/
File: i2c_protection.kicad_sch

Title:

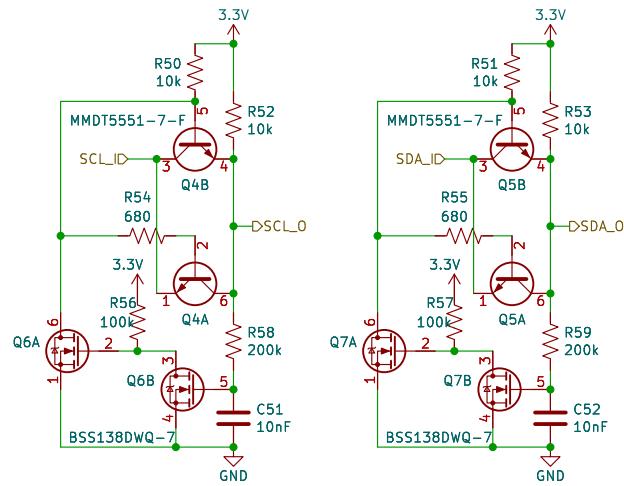
Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 19/34

A

A

Bus Protection



NOTE

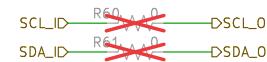
These novel bus protection circuits prevent traditional I₂C/SPI failure modes where a single slave failure can disable the entire bus.

Learn more:
<https://doi.org/10.36227/techrxiv.15166620>

By default, slave clock and/or data lines can be held low and the Master (SAMD51) will still be able to communicate with the remainder of the bus.

They can individually be bypassed by removing the transistor(s) and soldering the 0Ω jumpers below.

I₂C Protection – Bypass Jumpers



Sheet: /Bus Protection/I₂C Protection 2/
File: i2c_protection.kicad_sch

Title:

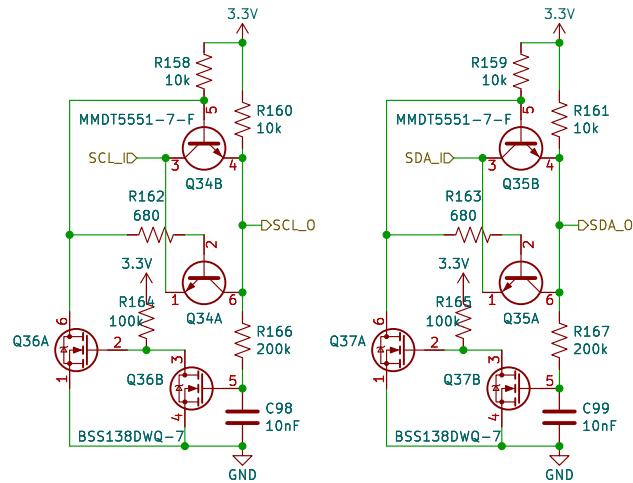
Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 20/34

A

A

Bus Protection



NOTE

These novel bus protection circuits prevent traditional I₂C/SPI failure modes where a single slave failure can disable the entire bus.

Learn more:
<https://doi.org/10.36227/techrxiv.15166620>

By default, slave clock and/or data lines can be held low and the Master (SAMD51) will still be able to communicate with the remainder of the bus.

They can individually be bypassed by removing the transistor(s) and soldering the 0Ω jumpers below.

I₂C Protection – Bypass Jumpers



Sheet: /Bus Protection/I₂C Protection 3/
File: i2c_protection.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 21/34

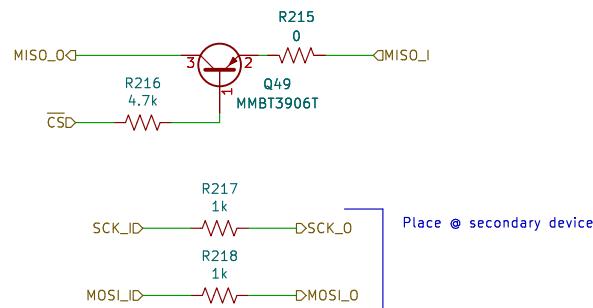
NOTE

These novel bus protection circuits prevent traditional I₂C/SPI failure modes where a single slave failure can disable the entire bus.

Learn more:
<https://doi.org/10.36227/techriv.15166620>

By default, slave clock and/or data lines can be held low and the Master (SAMD51) will still be able to communicate with the remainder of the bus.

They can individually be bypassed by removing the transistor(s) and soldering the 0ohm the jumpers below.

SPI Bus Protection**Bypass Jumper**

Jumper Bypass N/R for MOSI
 Inline 1k resistors @ destination offer passive protection



Sheet: /Bus Protection/SPI Protection 1/
 File: spi_protection.kicad_sch

Title:

Size: A4 | Date:
 KiCad E.D.A. kicad 7.0.1

Rev:
 Id: 22/34

NOTE

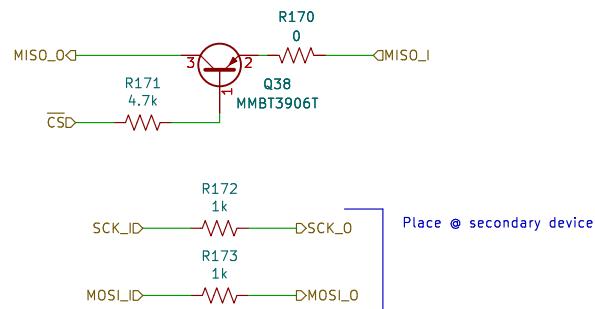
These novel bus protection circuits prevent traditional I²C/SPI failure modes where a single slave failure can disable the entire bus.

Learn more:

<https://doi.org/10.36227/techriv.15166620>

By default, slave clock and/or data lines can be held low and the Master (SAMD51) will still be able to communicate with the remainder of the bus.

They can individually be bypassed by removing the transistor(s) and soldering the 0ohm the jumpers below.

SPI Bus Protection**Bypass Jumper**

Jumper Bypass N/R for MOSI
Inline 1k resistors @ destination offer passive protection



Sheet: /Bus Protection/SPI Protection 2/
File: spi_protection.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 23/34

NOTE

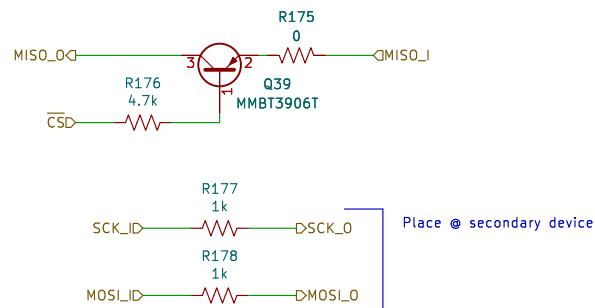
These novel bus protection circuits prevent traditional I²C/SPI failure modes where a single slave failure can disable the entire bus.

Learn more:

<https://doi.org/10.36227/techriv.15166620>

By default, slave clock and/or data lines can be held low and the Master (SAMD51) will still be able to communicate with the remainder of the bus.

They can individually be bypassed by removing the transistor(s) and soldering the 0ohm the jumpers below.

SPI Bus Protection**Bypass Jumper**

Jumper Bypass N/R for MOSI
Inline 1k resistors @ destination offer passive protection



Sheet: /Bus Protection/SPI Protection 3/
File: spi_protection.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 24/34

NOTE

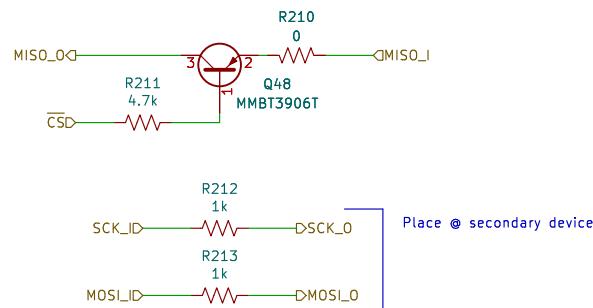
These novel bus protection circuits prevent traditional I²C/SPI failure modes where a single slave failure can disable the entire bus.

Learn more:

<https://doi.org/10.36227/techriv.15166620>

By default, slave clock and/or data lines can be held low and the Master (SAMD51) will still be able to communicate with the remainder of the bus.

They can individually be bypassed by removing the transistor(s) and soldering the 0ohm the jumpers below.

SPI Bus Protection**Bypass Jumper**

Jumper Bypass N/R for MOSI
Inline 1k resistors @ destination offer passive protection



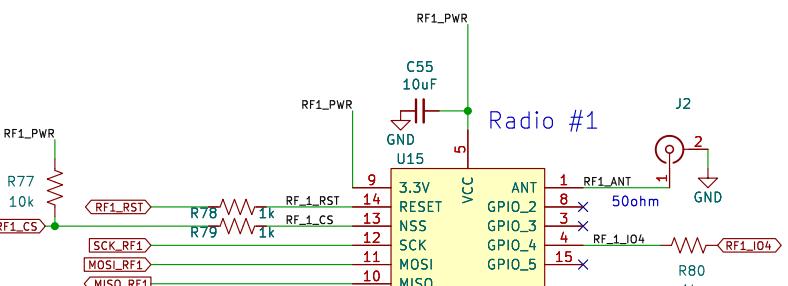
Sheet: /Bus Protection/SPI Protection 4/
File: spi_protection.kicad_sch

Title:

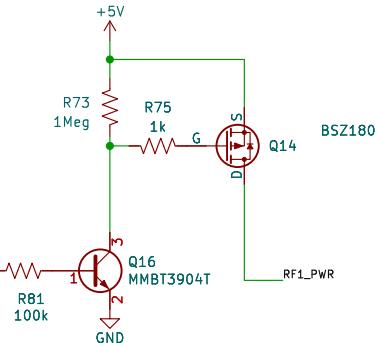
Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 25/34

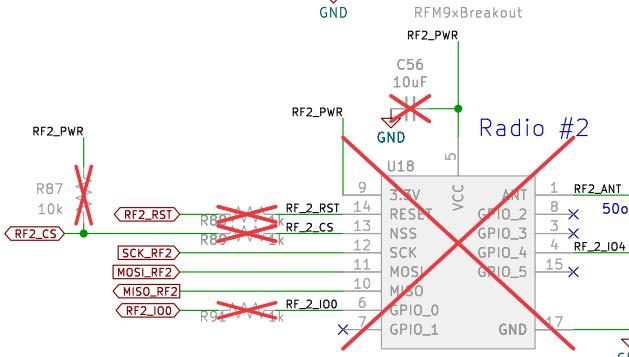
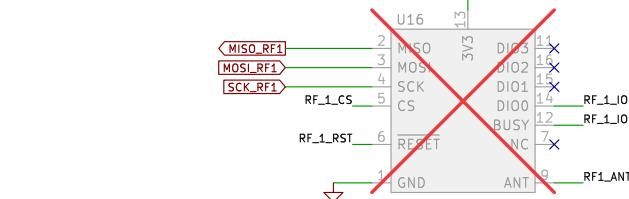
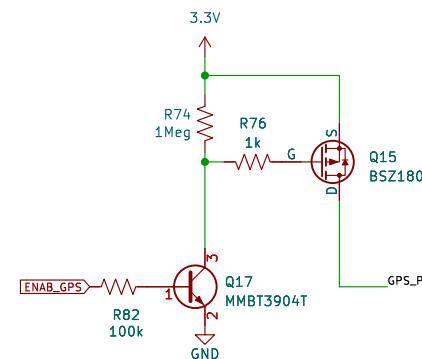
Modular Radios (HopeRF format)



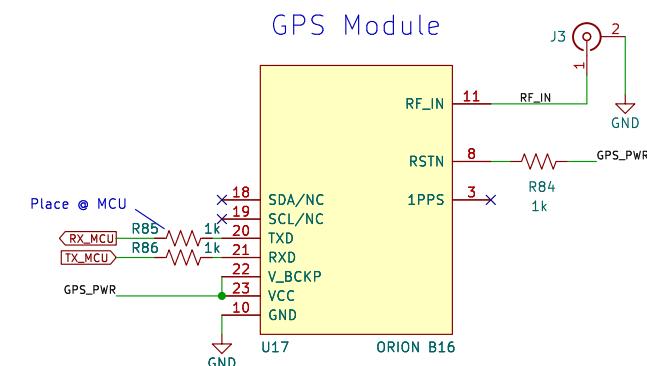
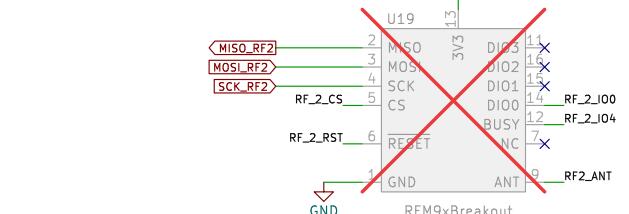
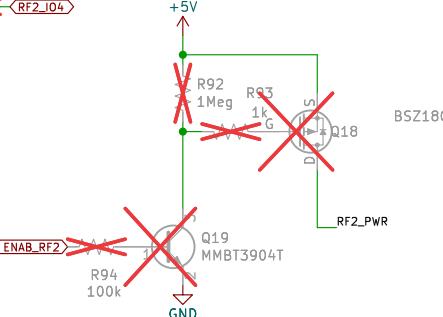
RF1 Power Switch



GPS Power Switch



RF2 Power Switch



NOTE: Components labeled "do not install" (DNI) are not populated by default

Radio, GPS, Payloads

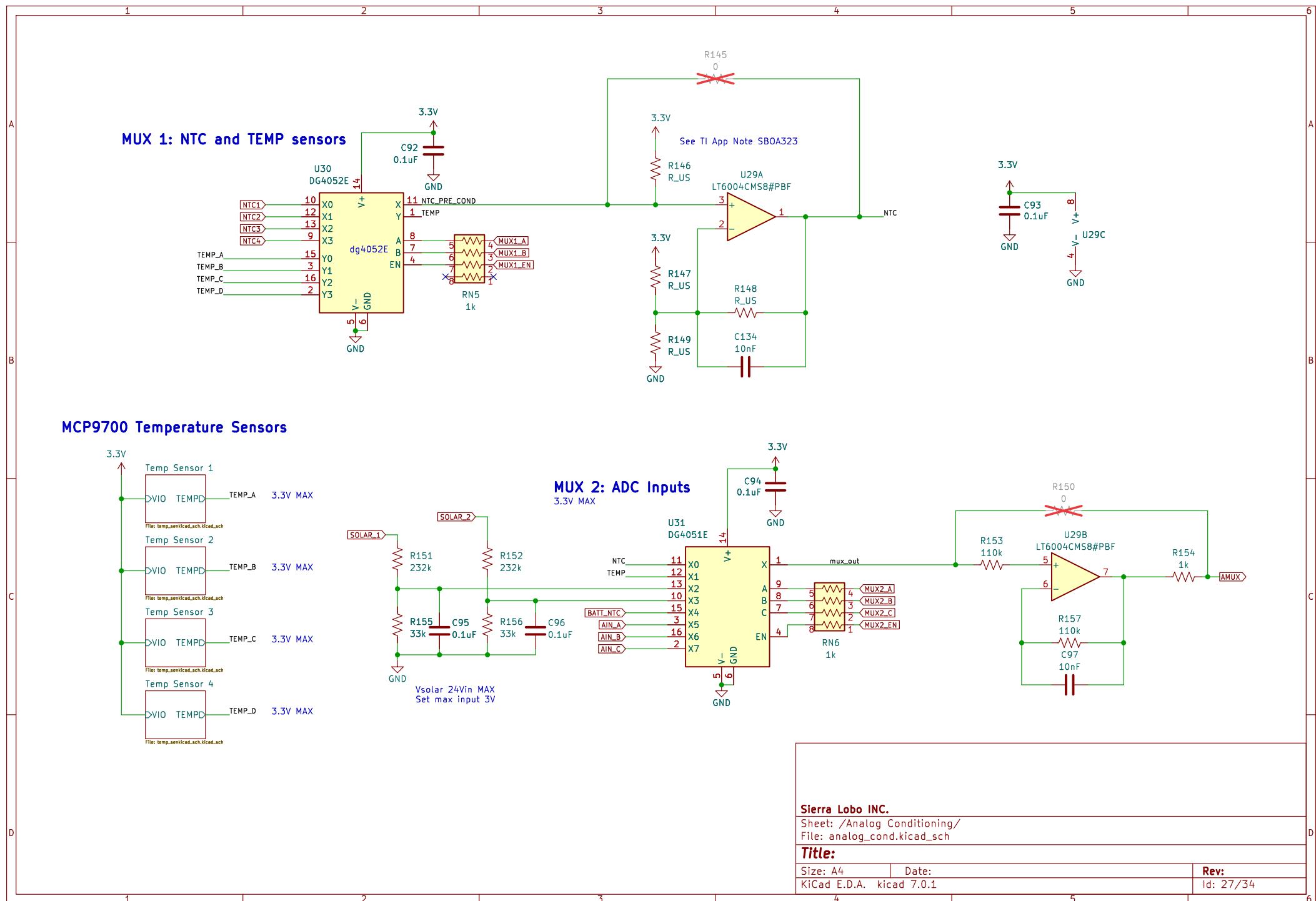
Sierra Lobo INC.

Sheet: /RF and GPS/
File: RF_and_GPS.kicad_sch

Title: PyCubed Mainboard

Size: A4 Date: 2021-06-09
KiCad E.D.A. kicad 7.0.1

Rev: v05c
Id: 26/34



A

A

B

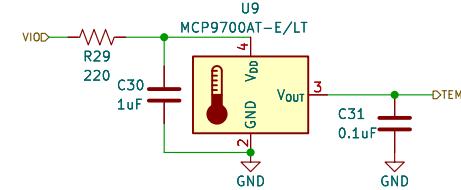
B

C

C

D

D



Sheet: /Analog Conditioning/Temp Sensor 1/
File: temp_senkicad_sch.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 28/34

A

A

B

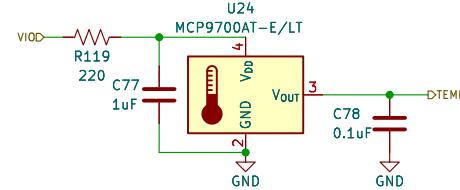
B

C

C

D

D



Sheet: /Analog Conditioning/Temp Sensor 2/
File: temp_senkicad_sch.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 29/34

A

A

B

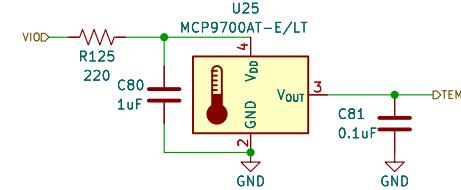
B

C

C

D

D



Sheet: /Analog Conditioning/Temp Sensor 3/
File: temp_senkicad_sch.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 30/34

A

A

B

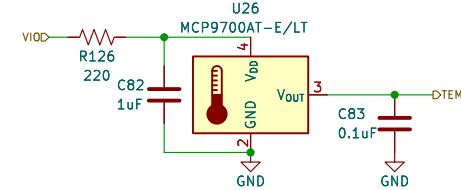
B

C

C

D

D



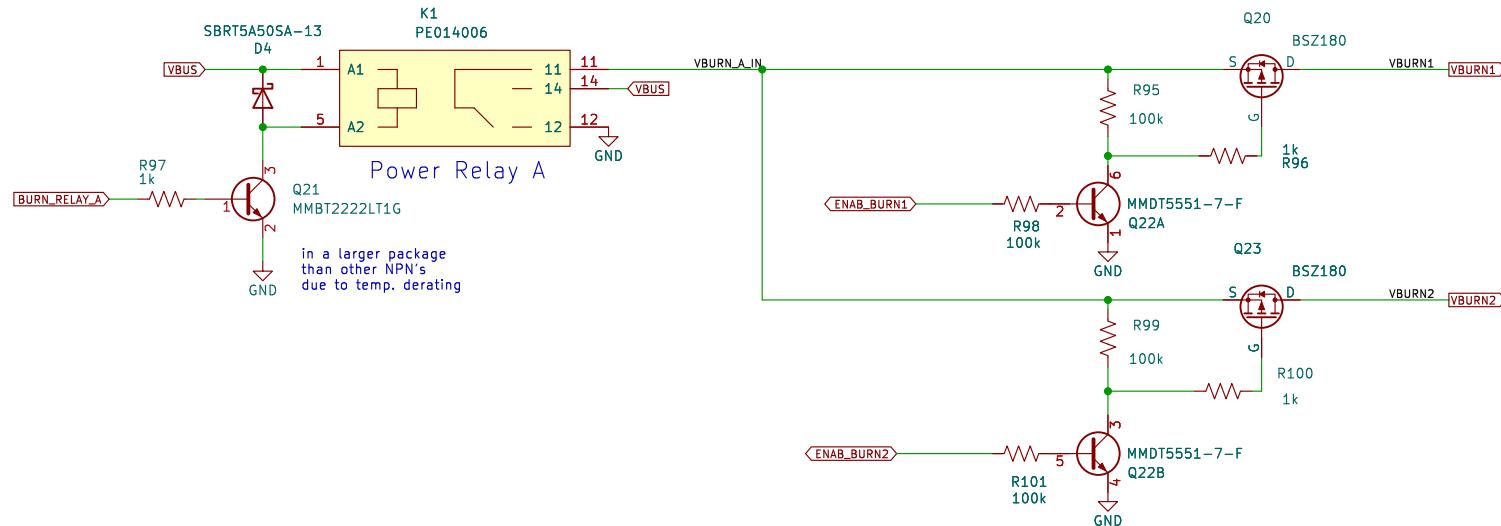
Sheet: /Analog Conditioning/Temp Sensor 4/
File: temp_senkicad_sch.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 31/34

Burn Wire Control (Antenna Deployment)



NOTE: Components labeled "do not install" (DNI) are not populated by default

Burn Wires

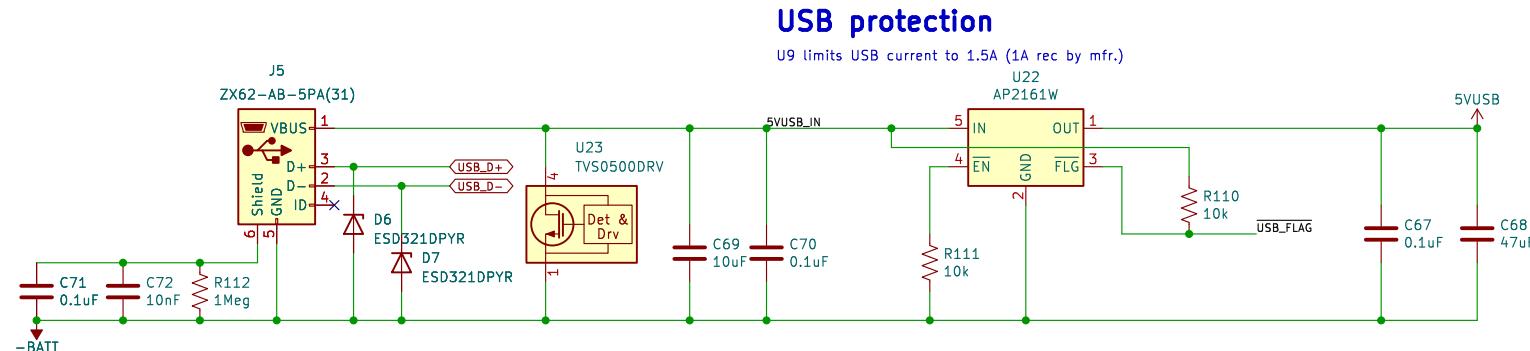
Sierra Lobo INC.

Sheet: /Burn_Wires/
File: Burn_Wires.kicad_sch

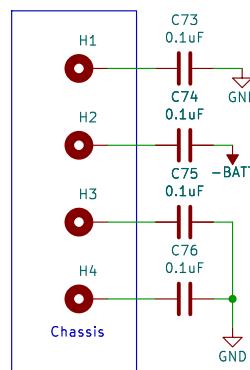
Title: PyCubed Mainboard

Size: A4 Date: 2021-06-09
KiCad E.D.A. kicad 7.0.1

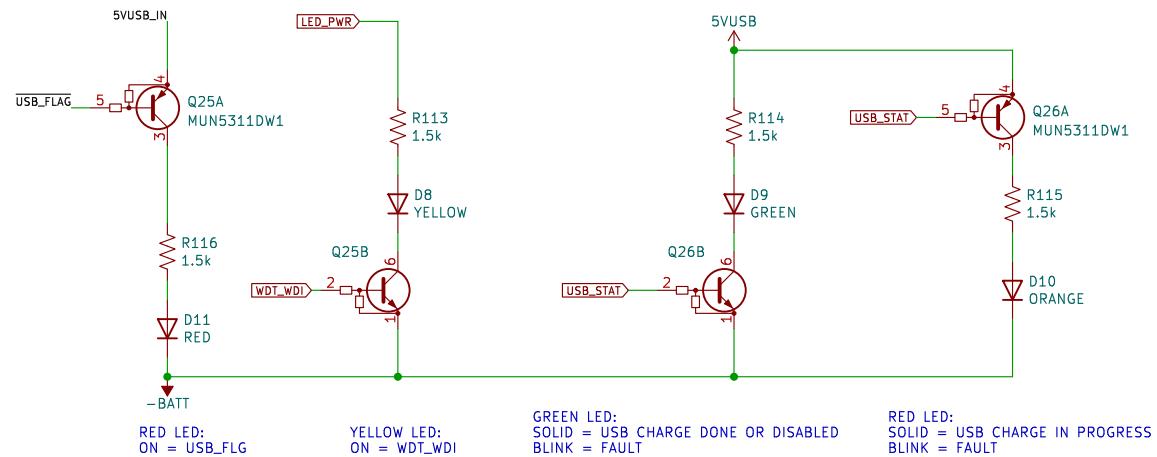
Rev: v05c
Id: 32/34



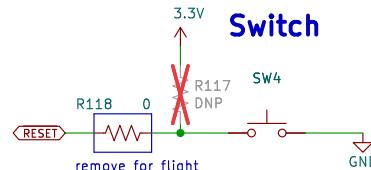
Mounting Holes



USB STATUS LEDs



Switch



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Sheet: /Backplane Interface/
File: Blank-Card-Default.kicad_sch

Title:

Size: A4 Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 33/34

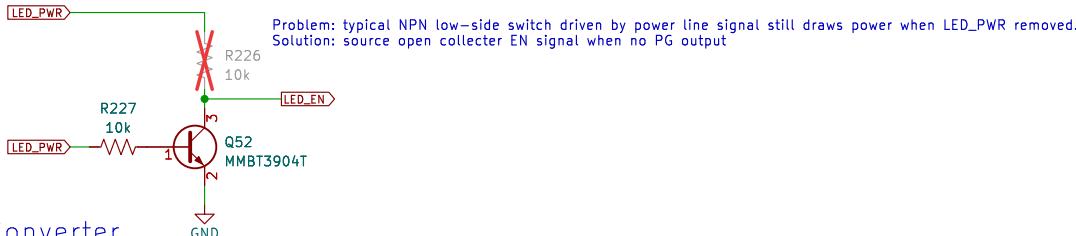
See LEDs also on backplane card interface, they're not here since they explicitly shine thru the backplane.

A

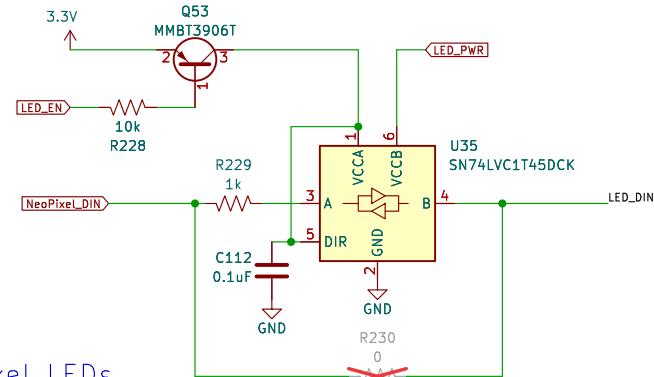
LED Jumper



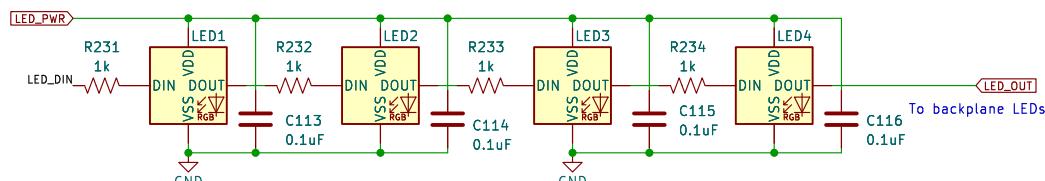
LED Open Collector Enable



3.3V → 5V Logic Converter



NeoPixel LEDs



Sheet: /Debug LEDs/
File: leds.kicad_sch

Title:

Size: A4 | Date:
KiCad E.D.A. kicad 7.0.1

Rev:
Id: 34/34