view\_frames Result Recorded at time: 1550169560.84 world Broadcaster: /robot\_state\_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1550169560.78 Oldest transform: 1550169555.88 Broadcaster: /robot\_state\_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1550169560.78 Oldest transform: 1550169555.88 12 Broadcaster: /robot\_state\_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1550169560.78 Oldest transform: 1550169555.88 skiff Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.0 Average rate: 10.204 Average rate: 10.204 Average rate: 10.204 Buffer length: 4.9 Buffer length: 4.9 Buffer length: 4.9 Buffer length: 0.0 Most recent transform: 1550169560.78 Most recent transform: 1550169560.78 Most recent transform: 1550169560.78 Most recent transform: 0.0 Oldest transform: 1550169555.88 Oldest transform: 1550169555.88 Oldest transform: 1550169555.88 Oldest transform: 0.0 port\_rowlock\_l starboard\_rowlock\_1 footplate seat Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1550169560.78 Oldest transform: 1550169555.88 upperleg\_2 starboard\_oar\_1 back\_low port\_oar\_1 lowerleg Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1550169560.78 Oldest transform: 1550169555.88 upperleg\_1 back\_high starboard\_blade\_1 handle\_left\_11 port\_blade\_l Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.204 Average rate: 10000.0 Buffer length: 4.9 Buffer length: 0.0 Most recent transform: 1550169560.78 Most recent transform: 0.0 Oldest transform: 1550169555.88 Oldest transform: 0.0 handle\_left\_12 shoulder\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.204 Average rate: 10.204 Average rate: 10000.0 Average rate: 10.204 Buffer length: 4.9 Buffer length: 4.9 Buffer length: 0.0 Buffer length: 4.9 Most recent transform: 1550169560.78 Most recent transform: 1550169560.78 Most recent transform: 0.0 Most recent transform: 1550169560.78 Oldest transform: 1550169555.88 Oldest transform: 1550169555.88 Oldest transform: 0.0 Oldest transform: 1550169555.88 left\_shoulder\_xx\_link arm\_l\_lower\_2 right\_shoulder\_psi\_link head Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.204 Average rate: 10.204 Average rate: 10000.0 Buffer length: 0.0 Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 0.0 Most recent transform: 1550169560.78 Most recent transform: 1550169560.78 Oldest transform: 0.0 Oldest transform: 1550169555.88 Oldest transform: 1550169555.88 dummy\_link\_2 left\_shoulder\_psi\_link arm\_r\_upper Broadcaster: /robot\_state\_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1550169560.78 Oldest transform: 1550169555.88 arm\_l\_upper Broadcaster: /robot\_state\_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1550169560.78 Oldest transform: 1550169555.88 left\_elbow\_psi\_link Broadcaster: /robot\_state\_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1550169560.78 Oldest transform: 1550169555.88 arm\_l\_lower\_1 Broadcaster: /robot\_state\_publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 dummy\_link\_1