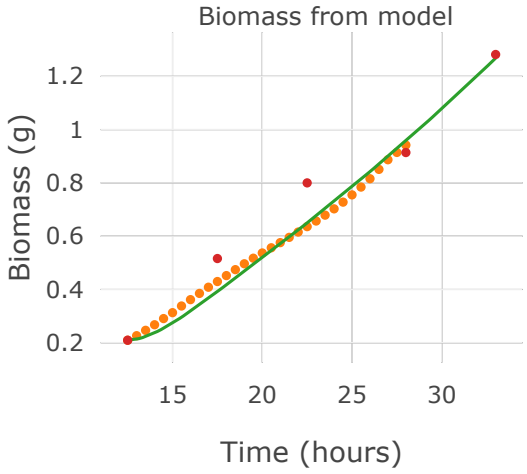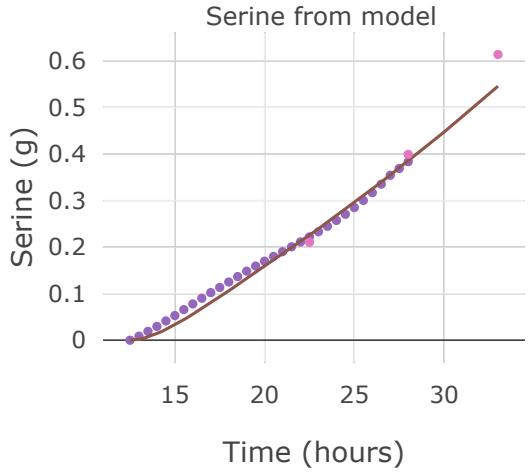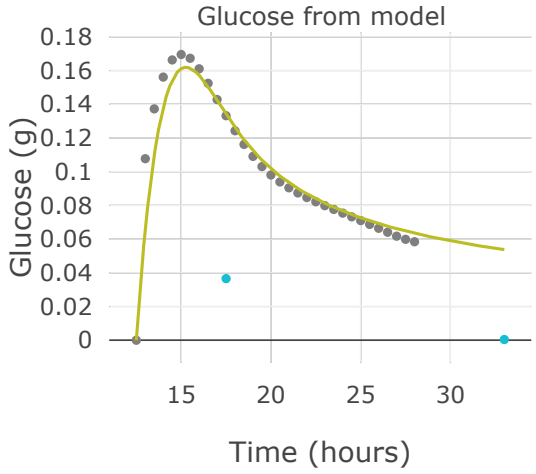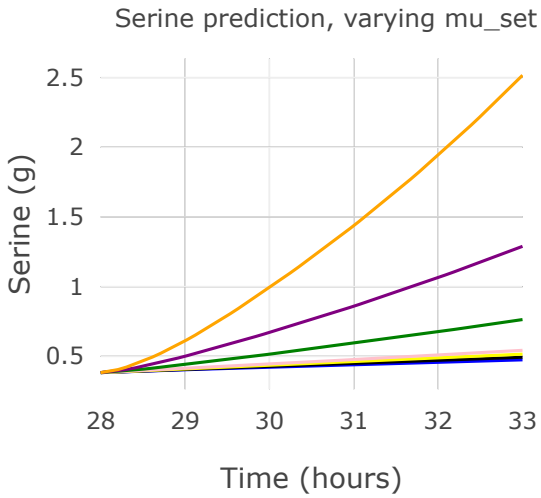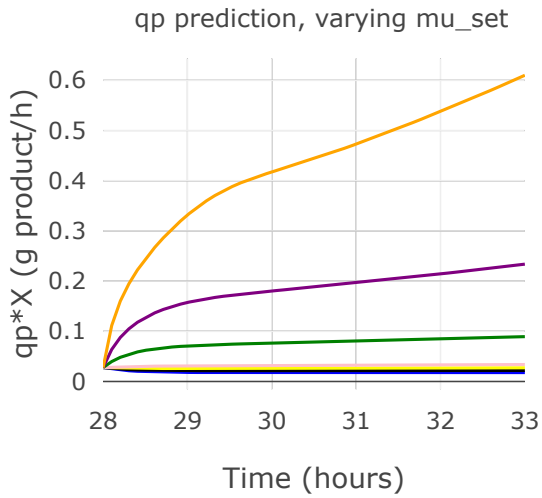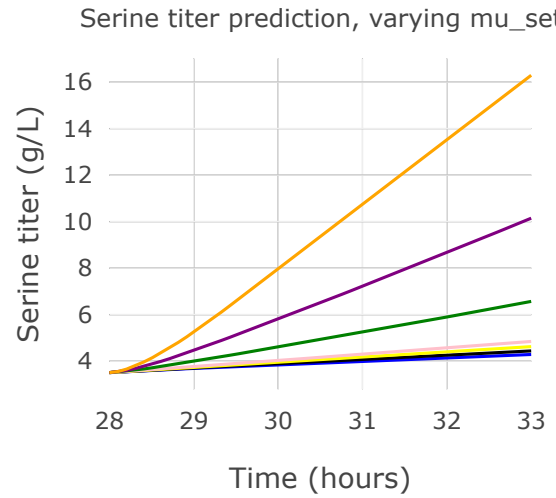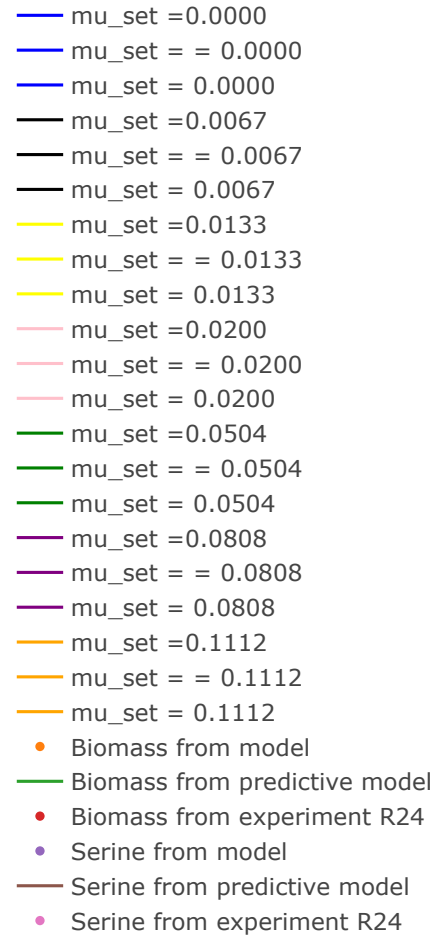Model prediction control