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RESEARCH AND TEACHING EXPERIENCE

Digital Twin Electric Grid

Robotics and Automation Lab, RUET

Undergraduate Thesis

06/2022 - present

Email: asifat331@gmail.com

- Case Study: Started with a case study and wrote a systematic review article.
- Conceptualization: Proposed a seven-layer conceptual framework developed with a systems engineering approach.
- Implementation: Implemented the proposed conceptual framework to a laboratory microgrid.
- Operations: Real-time bidirectional communication, sensory data management, control system, system modeling (ML), fault classification, autonomous and cloud supervisory control.

Development of RoboNurse

For remote nursing during Covid-19

09/2020 - 2022

- **Development**: Robot design (motion planning, automated medication, 4-DOF robotic arm), implementation, trajectory planning, iterative testing.
- o Operations: Routine checkup, medication, real-time cloud update, supervisory control via IoT cloud.

Physics and Mathematics Tutor

Self-employment

Supplementary teacher

08/2018 - Present

- o Task: I teach O and A-level students, prepare tests and evaluate their academic progress -12 hrs/week.
- $\circ \ \ \textbf{Topics} \hbox{:} \ \ \text{Calculus, probability, matrix, polynomials, mechanics, modern and classical physics, etc.}$

SKILLS

- Platforms: MATLAB, Simulink (ROS, Robotics system toolbox, Simscape, Lidar toolbox), Proteus, Solid Works, AutoCAD, Microchip Studio, LOGO! (PLC), MS Office, Logisim, Arduino.
- Programming languages: C, C++, Python, LATEX, Matlab, Ladder diagram (LD), Instruction list (IL).
- **Technical**: Testbed, sensor, actuator design, calibration, performance test, transnational and rotational mapping, trajectory planning, control system design, serial communication.
- **Soft skills**: Resourcefulness, adaptive development, time management, critical thinking, problem-solving, goal decomposition.

Publications

• Peer Reviewed

• Sifat, M. M. H., Choudhury, S. M., Das, S. K., Ahamed, M. H., Muyeen, S. M., Hasan, M. M., ... & Das, P. (2022). Towards electric digital twin grid: Technology and framework review. Energy and AI, 100213.

• Under Review

- Sifat, M. H., Das, S. K., & Choudhury, S. M. Design, Development, and Optimization of a Conceptual Framework of Digital Twin Electric Grid Using Systems Engineering Approach. Development, and Optimization of a Conceptual Framework of Digital Twin Electric Grid Using Systems Engineering Approach. (Preprint)
- Sifat, M. H., Choudhury, Das, S. K., Alam K. S., Sakib M. S. I., & Kaif A. M. A. D. Design and Experimental Implementation of a Digital-Twin Microgrid for Optimum Operation with Self-Healing Control Strategies—

 Journal: IEEE Transaction on Smart Grid.
- Sifat, M. H., & Das, S. K. Proactive and Reactive Maintenance Strategies for Self-Healing Digital Twin Islanded Microgrids using Fuzzy Logic Controllers and Machine Learning-Journal: IEEE Transactions of Power Systems

• In Process

 Sifat, M. H., Das, S. K., & Rokunuzzaman, M. IoT-Enabled RoboNurse for Effective Infectious Pandemic Management: A Systems Engineering Approach—Intended journal: IEEE Transactions on Medical Robotics and Bionics.

PROJECTS

• 3 - DOF Robotic Arm

- Developed a sorting robot based on product colors.
- Skills—Sensor calibration, Simulink modeling, ROS simulation, practical deployment and noise management, servo control, cascaded operation.

• Biped Walking Mechanism

- o Replicating human walking mechanism-a cost-effective approach
- Skills-Critical thinking, link, and joint state transition planning, custom servo mechanism, error optimization.

RESEARCH INTERESTS

• Robotics, mechatronic systems design, humanoid robots, UGVs, digital twin technology, smart grid control, management, and optimization.

EDUCATION

Rajshahi University of Engineering & Technology

Rajshahi-6204, Bangladesh

BSc in Mechatronics Engineering

2018 - Present

- \circ CGPA: : 3.51/4 (till 6th semester). Possible date of graduation September 2023
- Related Courses: : Robotics, Automation, HRI, Design of Mechatronic Systems, AI, ML Algorithms, DSP & Machine Vision, Embedded Systems, Hydraulic and Pneumatic Control, Control Systems, Numerical Analysis, and Statistics.