

SHM Formulae

Potential energy,

$$E_p = \frac{1}{2} kx^2$$

Here, spring constant, $k = \omega^2 m$

x = displacement

(Potential energy maximum at amplitude)

(Potential energy minimum (0) at equilibrium point)

Kinetic energy,

$$E_k = \frac{1}{2} mv^2$$
$$v = \omega \sqrt{A^2 - x^2}$$

(Kinetic energy maximum at equilibrium point)

(Kinetic energy minimum (0) at amplitude)

Total energy/mechanical energy,

$$E = E_p + E_k = \frac{1}{2} kA^2$$

Total energy/mechanical energy is always constant

1. A block attached to a spring is suspended vertically. If the block is pushed 7 cm upward from the equilibrium position and released at $t = 0$. The mass of the block is 5 kg and the spring constant is $k = 22 \text{ N/m}$. i) Calculate the potential energy at $x = 3 \text{ cm}$. ii) Calculate the kinetic energy at the same position.

i) We know,
Potential energy,

$$\begin{aligned} P.E &= \frac{1}{2} kx^2 \\ &= \frac{1}{2} \times 22 \times (0.03)^2 \\ &= 0.0099 \text{ J} \end{aligned}$$

\therefore Potential energy is 0.0099 J.

ii) Velocity at x ,

$$\begin{aligned} v &= \pm \omega \sqrt{A^2 - x^2} \\ \text{or, } v^2 &= \omega^2 (A^2 - x^2) \\ \text{or, } v^2 &= \frac{k}{m} (A^2 - x^2) \\ \text{or, } v^2 &= \frac{22}{5} \times [(0.07)^2 - (0.03)^2] \\ \therefore v^2 &= 0.0176 \text{ m s}^{-1} \end{aligned}$$

\therefore Kinetic energy at x ,

$$\begin{aligned} K.E &= \frac{1}{2} mv^2 \\ &= \frac{1}{2} \times 5 \times 0.0176 \\ &= 0.044 \text{ J} \end{aligned}$$

Here,

$$A = 7 \text{ cm} = 0.07 \text{ m}$$

$$m = 5 \text{ kg}$$

$$k = 22 \text{ N m}^{-1}$$

$$x = 3 \text{ cm} = 0.03 \text{ m}$$

$$P.E = ?$$

$$K.E = ?$$

2. Suppose a spring block-system starts moving from the equilibrium as we apply force on it. The block has mass $m = 6.4 \text{ kg}$ and is designed to oscillate with angular frequency $\omega = 56 \text{ rads}^{-1}$ with amplitude 15 cm .

Calculate: i) the kinetic energy at $x = 14 \text{ cm}$ from the equilibrium point, ii) mathematically calculate the position where the kinetic energy is 0.

i) We know,

Kinetic energy,

$$\begin{aligned} K.E &= \frac{1}{2}mv^2 \\ &= \frac{1}{2}m\omega^2(A^2 - x^2) \\ &= \frac{1}{2} \times 6.4 \times (56)^2 \times [(0.15)^2 - (0.14)^2] \\ &= 28.102 \text{ J} \end{aligned}$$

\therefore Kinetic energy at $x = 14 \text{ cm}$ is 28.102 J .

ii) Let, kinetic energy will be 0 at position x .

Now,

$$\begin{aligned} K.E &= 0 \\ \text{or, } \frac{1}{2}mv^2 &= 0 \\ \text{or, } \frac{1}{2}m\omega^2(A^2 - x^2) &= 0 \\ \text{or, } A^2 - x^2 &= 0 \\ \text{or, } x^2 &= A^2 \\ \therefore x &= A \end{aligned}$$

\therefore Kinetic energy will be 0 when our displacement will be equal to amplitude.

Here,

$$m = 6.4 \text{ kg}$$

$$\omega = 56 \text{ rad s}^{-1}$$

$$A = 15 \text{ cm} = 0.15 \text{ m}$$

$$x = 14 \text{ cm} = 0.14 \text{ m}$$

$$K.E = ?$$

3. A particle with mass 50 g executes simple harmonic motion given by the equation $y = \sin \left(10t - \frac{\pi}{4} \right)$. Calculate the i) velocity and acceleration at $t = 5 \text{ s}$ ii) total energy at $t = 3 \text{ s}$.

(i)

$$\text{Displacement, } y = \sin \left(10t - \frac{\pi}{4} \right)$$

$$\therefore \text{Velocity, } v = \frac{dy}{dt} = \frac{d}{dt} \left[\sin \left(10t - \frac{\pi}{4} \right) \right] \\ = 10 \cos \left(10t - \frac{\pi}{4} \right)$$

$$\therefore \text{Acceleration, } a = \frac{dv}{dt} = \frac{d}{dt} \left[10 \cos \left(10t - \frac{\pi}{4} \right) \right] \\ = -10 \times 10 \sin \left(10t - \frac{\pi}{4} \right) \\ = -100 \sin \left(10t - \frac{\pi}{4} \right)$$

$$\begin{array}{l} \text{Here,} \\ m = 50 \text{ g} = 0.05 \text{ kg} \\ \omega = 10 \text{ rad s}^{-1} \\ v(5) = ? \\ a(5) = ? \\ E(3) = ? \end{array}$$

\therefore Velocity at $t = 5 \text{ s}$,

$$v(5) = 10 \cos \left(10 \times 5 - \frac{\pi}{4} \right) \\ = 4.968 \text{ m s}^{-1}$$

\therefore Acceleration at $t = 5 \text{ s}$,

$$a(5) = -300 \sin \left(10 \times 5 - \frac{\pi}{4} \right) \\ = 86.786 \text{ m s}^{-2}$$

$$\text{(ii) } E = \frac{1}{2} k A^2 = \frac{1}{2} \omega^2 m A = \frac{1}{2} \times 10^2 \times 0.05 \times 1 = 2.5 \text{ J}$$

4. Suppose a spring block-system move between top and bottom point of a tall building as a moving mass. The block has mass $m = 5.7 \times 10^3 \text{ kg}$ and designed to oscillate at frequency $f = 50 \text{ Hz}$ with amplitude $A = 15 \text{ cm}$.

Calculate: i) the potential energy at the equilibrium point, ii) the block speed as it passes through the equilibrium point, iii) the maximum acceleration of the spring block-system.

i) We know,

At equilibrium position, $x = 0$

\therefore Potential energy,

$$P.E = \frac{1}{2} kx^2 = \frac{1}{2} k(0)^2 = 0$$

ii) We know,

At equilibrium position, SHM oscillation have its maximum speed.

\therefore Maximum velocity,

$$\begin{aligned} v_{max} &= A\omega \\ &= A2\pi f \quad [\because \omega = 2\pi f] \\ &= 0.15 \times 2\pi \times 50 \\ &= 47.12 \text{ m s}^{-1} \end{aligned}$$

Here,

$$m = 5.7 \times 10^3 \text{ kg}$$

$$f = 50 \text{ Hz}$$

$$A = x_{max} = 15 \text{ cm} = 0.15 \text{ m}$$

$$P.E = ?$$

$$v_{max} = ?$$

$$a_{max} = ?$$

iii) We know,

Maximum acceleration,

$$\begin{aligned} a &= -A\omega^2 \\ &= -A(2\pi f)^2 \quad [\because \omega = 2\pi f] \\ &= -0.15 \times (2\pi \times 50)^2 \\ &= 14804.48 \text{ m s}^{-2} \end{aligned}$$

5. A body of mass 300 gm is attached with a spring of spring constant 5000 dynes/cm. The body is displaced by 7 cm from its equilibrium position and released. Then the body executes SHM. Calculate the i) frequency, ii) angular frequency, iii) total energy of the mass spring system.

- i) We know,
Frequency,

$$\begin{aligned} f &= \frac{\omega}{2\pi} \\ &= \frac{1}{2\pi} \times \sqrt{\frac{k}{m}} \\ &= \frac{1}{2\pi} \times \sqrt{\frac{5000}{300}} \\ &= 0.65 \text{ Hz} \end{aligned}$$

- ii) We know,
Angular frequency,

$$\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{5000}{300}} = 4.082 \text{ rad s}^{-1}$$

- iii) We know,
Total energy,

$$\begin{aligned} E &= \frac{1}{2} k A^2 \\ &= \frac{1}{2} \times 5000 \times (7)^2 \\ &= -0.15 \times (2\pi \times 50)^2 \\ &= 122500 \text{ erg} \end{aligned}$$

Here,

$$m = 300 \text{ g}$$

$$k = 5000 \text{ dynes cm}^{-1}$$

$$A = 7 \text{ cm}$$

$$f = ?$$

$$\omega = ?$$

$$E = ?$$

6. Suppose the block has $m=2.75 \times 10^5 \text{ kg}$ and is designed to oscillate at frequency $f=10.0 \text{ Hz}$ and amplitude $A=20.0 \text{ cm}$. i) What is the total energy E of the spring-block system? ii) What is the KE and PE at $x=10 \text{ cm}$ iii) At what position $KE=PE$?

| | |
|---|---|
| <p>Total energy,</p> $E = \frac{1}{2} kA^2$ $= \frac{1}{2} \times 1.086 \times 10^9 \times (0.2)^2$ $= 2.172 \times 10^7 \text{ J}$ | $\omega = 2\pi f$ $= 2\pi \times 10$ $= 62.83 \text{ rad s}^{-1}$ $k = m\omega^2$ $= 2.75 \times 10^5 \times (62.83)^2$ $= 1.086 \times 10^9 \text{ N m}^{-1}$ |
| <p>ii) Velocity when $x = 10 \text{ cm} = 0.1 \text{ m}$,</p> $v = \pm \omega \sqrt{A^2 - x^2}$ <p>or, $v^2 = \omega^2 (A^2 - x^2)$</p> <p>or, $v^2 = (62.83)^2 [(0.2)^2 - (0.1)^2]$</p> $\therefore v^2 = 118.43 \text{ m s}^{-1}$ <p>Kinetic energy at $x = 10 \text{ cm}$,</p> $KE = \frac{1}{2} mv^2$ $= \frac{1}{2} \times 2.75 \times 10^5 \times 118.43$ $= 1.628 \times 10^7 \text{ J}$ | <p>Potential energy at $x = 10 \text{ cm}$,</p> $PE = \frac{1}{2} kx^2$ $= \frac{1}{2} \times 1.086 \times 10^9 \times (0.1)^2$ $= 5.43 \times 10^6 \text{ J}$ |

- iii) Let, KE will equal to PE at displacement x .
Now,

$$KE = PE$$

$$\text{or, } \frac{1}{2} mv^2 = \frac{1}{2} kx^2$$

$$\text{or, } \frac{1}{2} m\omega^2 (A^2 - x^2) = \frac{1}{2} kx^2$$

$$[\because v^2 = \omega^2 (A^2 - x^2)]$$

$$\text{or, } \frac{1}{2} k (A^2 - x^2) = \frac{1}{2} kx^2 \quad [\because k = m\omega^2]$$

$$\text{or, } A^2 - x^2 = x^2$$

$$\text{or, } A^2 = 2x^2$$

$$\text{or, } x = \sqrt{\frac{A^2}{2}}$$

$$\text{or, } x = \sqrt{\frac{(0.2)^2}{2}}$$

$$\therefore x = 0.14 \text{ m}$$

7. An oscillating block has kinetic energy equal to potential energy of 25 J ($KE=PE= 25 \text{ J}$) when the block is at $x=+0.50 \text{ m}$. i) What is the amplitude of oscillation? ii) What is the kinetic energy when the block is $x=0$?

| | |
|---|--|
| <p>i) Given, Potential energy at $x = 0.5 \text{ m}$,</p> $PE = \frac{1}{2}kx^2$ $\text{or, } 25 = \frac{1}{2}k(0.5)^2$ $\text{or, } 25 \times 2 = k \times \frac{1}{4}$ $\therefore k = 200 \text{ N m}^{-1}$ | <p>Total energy,</p> $E = PE + KE$ $\text{or, } \frac{1}{2}kA^2 = 25 + 25$ $\text{or, } \frac{1}{2} \times 200 \times A^2 = 50$ $\text{or, } 100 \times A^2 = 50$ $\text{or, } A = \sqrt{\frac{50}{100}}$ $\therefore A = 0.707 \text{ m}$ |
|---|--|

- ii. We know, At $x=0$, potential energy is 0 and kinetic energy is equal to total energy = $25 \text{ J} + 25 \text{ J} = 50 \text{ J}$

8. An oscillator consists of a block attached to a spring ($k=400 \text{ N/m}$). At some time t , the position, velocity, and acceleration of the block are $x = 0.100 \text{ m}$, $v = -13.6 \text{ m/s}$, and $a = -123 \text{ m/s}^2$. Calculate a) the mass of the block and b) the amplitude of the motion.

a) We know,

$$\begin{aligned} F &= -kx \\ \text{or, } ma &= -kx \\ \text{or, } m &= -\frac{kx}{a} \\ \text{or, } m &= -\frac{400 \times 0.1}{-123} \\ \therefore m &= 0.325 \text{ kg} \end{aligned}$$

b) We know,

$$\begin{aligned} v &= \pm \omega \sqrt{A^2 - x^2} \\ \text{or, } v^2 &= \omega^2 (A^2 - x^2) \\ \text{or, } \frac{v^2}{\omega^2} &= A^2 - x^2 \\ \text{or, } \frac{v^2}{\frac{k}{m}} + x^2 &= A^2 \\ \text{or, } A &= \sqrt{v^2 \times \frac{m}{k} + x^2} \\ \text{or, } A &= \sqrt{(-13.6)^2 \times \frac{0.325}{400} + (0.1)^2} \\ \text{or, } A &= \sqrt{(-13.6)^2 \times \frac{0.325}{400} + (0.1)^2} \\ \therefore A &= 0.400 \text{ m} \end{aligned}$$

Here,

$$k = 400 \text{ N m}^{-1}$$

$$x = 0.1 \text{ m}$$

$$v = -13.6 \text{ m s}^{-1}$$

$$a = -123 \text{ m s}^{-2}$$

$$m = ?$$

$$A = ?$$

9. Show that for a particle executing SHM, the instantaneous velocity is $v = \omega\sqrt{A^2 - x^2}$ and the maximum velocity is $\sqrt{\frac{2E}{m}}$, where symbols have their usual meanings.

$$\begin{aligned}
 v &= \frac{dx}{dt} \\
 v &= \frac{d}{dt} [A \cos(\omega t + \phi)] \\
 &= -A \sin(\omega t + \phi) \frac{d}{dt} (\omega t + \phi) \\
 &= -\omega A \sin(\omega t + \phi) \\
 &= -\omega \sqrt{A^2 \sin^2(\omega t + \phi)} \\
 &= -\omega \sqrt{A^2 [1 - \cos^2(\omega t + \phi)]} \\
 &= -\omega \sqrt{A^2 - A^2 \cos^2(\omega t + \phi)} \\
 v &= \pm \omega \sqrt{A^2 - x^2}
 \end{aligned}$$

We know,

We got maximum velocity, v_{max} at $x = 0$.

And, potential energy, PE is 0 at $x = 0$.

Now,

$$\begin{aligned}
 E &= PE + KE \\
 \text{or, } E &= 0 + \frac{1}{2} m v_{max}^2 \quad [\because PE = 0] \\
 \text{or, } 2E &= m v_{max}^2 \\
 \text{or, } \frac{2E}{m} &= v_{max}^2 \\
 \therefore v_{max} &= \sqrt{\frac{2E}{m}} \quad (\text{Showed})
 \end{aligned}$$

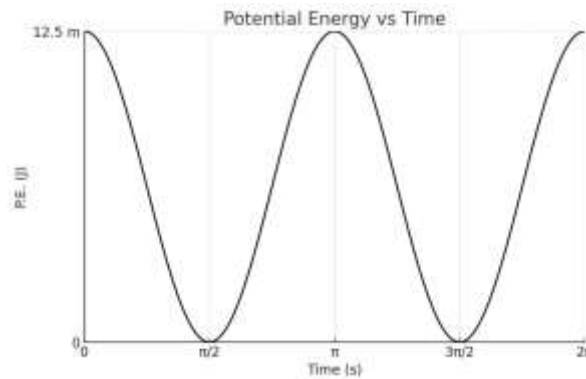
10. Show that, for a mass spring system with the equation of displacement $x = 5\cos t$, the potential and kinetic energy depends on time while total energy is time independent. [Use equations and graphical figures to justify your answer]

From the given equation with $x = A\cos \omega t$ implies, $\omega = 1 \text{ rad/s}$

$$\text{Potential energy, } E_p = \frac{1}{2}kx^2 = \frac{1}{2}k(5\cos t)^2 = \frac{1}{2}25k\cos^2 t$$

$$= \frac{1}{2}25\omega^2 m\cos^2 t = \frac{1}{2}25 \times 1^2 \times m\cos^2 t$$

$$= \frac{1}{2}25m\cos^2 t$$

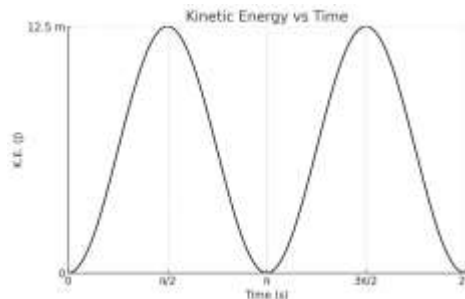


$$v = \frac{dy}{dx} = -5\sin t$$

$$\text{Kinetic energy, } E_k = \frac{1}{2}mv^2$$

$$= \frac{1}{2}25m\sin^2 t$$

This indicates K.E. depends on time.



$$\text{Total energy, } E = \text{P.E.} + \text{K.E.} = \frac{1}{2}25m\cos^2 t + \frac{1}{2}25m\sin^2 t = \frac{1}{2}25m(\cos^2 t + \sin^2 t) = \frac{1}{2}25m$$

This shows that total energy time-independent.

