

The numerical code used in: Modelling the penetration of subsonic rigid projectile probes into granular materials using the cavity expansion theory

Mechanical Properties and Coefficients

Volcanic ash (Change the properties for other target medium here)

In[1]:=

```

ρ = 1620;
ηs = 0.13;
Ee = 3.192 × 109;
k = 2 × 109;
ν =  $\frac{3k - Ee}{6k}$ ;
Coh = 4.74342 × 106;
ϕf = 25.3769 π / 180; (*Y = - $\frac{6(Coh \cos[\phi f])}{-3 + \sin[\phi f]}$ ); *)
Y = 2 Coh;

```

In[3]:=

```

cd =  $\sqrt{\frac{Ee(1-\nu)}{(1+\nu)(1-2\nu)\rho}}$ ; (*cd=ce:elastic wave speed*)

β[c_] :=  $\frac{c}{\sqrt{\frac{Ee}{\rho}}}$ ; ρ0 = ρ;

W =  $\frac{12 Coh \cos[\phi f]}{Ee(-3 + \sin[\phi f])}$ ; X =  $\frac{3 - \sin[\phi f]}{3k + 3k \sin[\phi f]}$ ;
term = .01; (*define the acceptable error |cp2-cp1|<term*)
NR = 1000;
(*define the step-size in the Runge-Kutta method*)

```

Equation 17 a & 17 b

$$\begin{aligned} \text{In[7]:= } A[c_] &:= - \left(\frac{4 c^3 \text{Coh}(1 + \nu) (-1 + 2 \nu) \text{Cos}[\phi f]}{(c - cd) Ee} \right. \\ &\quad \left. \frac{3 cd (c + cd) (-1 + 2 \nu) + (cd^2 (1 - 2 \nu) + 4 c^2 (1 + \nu) + c (cd - 2 cd \nu)) \text{Sin}[\phi f]}{(c - cd) Ee} \right); \\ B[c_] &:= \left(\frac{6 cd \text{Coh}(1 + \nu) (-1 + 2 \nu) \text{Cos}[\phi f]}{(c - cd) Ee} \right. \\ &\quad \left. \frac{3 cd (c + cd) (-1 + 2 \nu) + (cd^2 (1 - 2 \nu) + 4 c^2 (1 + \nu) + c (cd - 2 cd \nu)) \text{Sin}[\phi f]}{(c - cd) Ee} \right); \end{aligned}$$

Assumption 1 : c_p and S_r (hydrostat plastic region)

Solving Equation 30a & 30b

$$\begin{aligned} \text{In[9]:= } \text{Cph} &= \text{Function}[\{\eta, V, \phi, \text{term}\}, \\ &\quad \text{clear[out]; error = 1;} \\ &\quad c = \frac{V}{\left(\eta - \frac{2 \text{Coh}(-1 + \eta) (1 + \nu)}{Ee} \right)^{1/3}}; \\ &\quad \text{If}[\phi == 0, \text{out} = c, \text{While}[\text{Abs}[\text{error}] > \text{term}, \text{out} = \frac{V}{(-B[c] (c - cd) (c + cd) (-1 + \eta) + \eta)^{1/3}}]; \\ &\quad \quad \text{error} = \text{out} - c; \\ &\quad \quad c = \text{out}]; \\ &\quad \text{out}]; \end{aligned}$$

Solving Equation 24 & 25

S_0 : Equation 31 & 32

```

In[10]:= Sh = Function[{η, V, ϕ, c, ξ}, ψ = V / c;

If[ϕ ≠ 0, S0 = (1 + B[c] (-c² + cd²))² β[c]² η +  $\frac{3 A[c] (1 + \nu) + 2 B[c] (cd² (1 - 2 \nu) + 3 c² \nu)}{3 (-1 + \nu + 2 \nu²)}$  +

 $\frac{\text{Coh Cot}[\phi f]}{Ee} - \frac{\beta[c]² \psi⁶ (1 + \text{Sin}[\phi f])}{2 (-1 + \eta)} - \frac{2 \beta[c]² \psi³ (1 + \text{Sin}[\phi f])}{(-1 + \eta) (-1 + 3 \text{Sin}[\phi f])}$ ,

S0 = (1 + B[c] (-c² + cd²))² β[c]² η +  $\frac{3 A[c] (1 + \nu) + 2 B[c] (cd² (1 - 2 \nu) + 3 c² \nu)}{3 (-1 + \nu + 2 \nu²)}$  -

 $\frac{\beta[c]² \psi³ (-4 + \psi³)}{2 (-1 + \eta)}$ ];

If[ϕ ≠ 0, Shy = S0 ξ  $^{-\frac{4 \text{Sin}[\phi f]}{1 + \text{Sin}[\phi f]}}$  -  $\frac{\text{Coh} (\text{Cos}[\phi f] + \text{Cot}[\phi f])}{Ee (1 + \text{Sin}[\phi f])}$  +  $\frac{\beta[c]² \psi⁶ (1 + \text{Sin}[\phi f])}{2 \xi⁴ (-1 + \eta)}$  +

 $\frac{2 \beta[c]² \psi³ (1 + \text{Sin}[\phi f])}{\xi (-1 + \eta) (-1 + 3 \text{Sin}[\phi f])}$ , Shy =  $\frac{\beta[c]² \psi³ (-4 \xi³ + \psi³)}{2 \xi⁴ (-1 + \eta)}$  + S0 -  $\frac{4 \text{Coh Log}[\xi]}{Ee}$ ];

Shy];

```

Assumption 1 :

Incompressible Elastic

Equation 33a & 33b

```

In[11]:= CpIn = Function[{η, V, ϕ, term},
  Clear[out, out1]; error = 1;
  c = 
$$\frac{V}{\left(\frac{3 \text{Coh} - 3 \text{Coh} \eta + \text{Ee} \eta}{\text{Ee}}\right)^{1/3}};$$

  ceta =
    - 
$$\frac{2 V^3 \rho \tan[\phi]}{3 \text{Coh}} + (12 \times 2^{1/3} V^6 \rho^2 \tan[\phi]^2) / \left( \text{Coh}^2 \left( \frac{6561 \text{Ee} V^3 \sec[\phi]}{\text{Coh}} - \frac{2187 \text{Ee} V^3 \tan[\phi]}{\text{Coh}} - \frac{11664 V^9 \rho^3 \tan[\phi]^3}{\text{Coh}^3} + \sqrt{\left( -\frac{136048896 V^{18} \rho^6 \tan[\phi]^6}{\text{Coh}^6} + \left( \frac{6561 \text{Ee} V^3 \sec[\phi]}{\text{Coh}} - \frac{2187 \text{Ee} V^3 \tan[\phi]}{\text{Coh}} - \frac{11664 V^9 \rho^3 \tan[\phi]^3}{\text{Coh}^3} \right)^2} \right)^{1/3}} \right) + \right. \\
    \frac{1}{27 \times 2^{1/3}} \left( \frac{6561 \text{Ee} V^3 \sec[\phi]}{\text{Coh}} - \frac{2187 \text{Ee} V^3 \tan[\phi]}{\text{Coh}} - \frac{11664 V^9 \rho^3 \tan[\phi]^3}{\text{Coh}^3} + \sqrt{\left( -\frac{136048896 V^{18} \rho^6 \tan[\phi]^6}{\text{Coh}^6} + \left( \frac{6561 \text{Ee} V^3 \sec[\phi]}{\text{Coh}} - \frac{2187 \text{Ee} V^3 \tan[\phi]}{\text{Coh}} - \frac{11664 V^9 \rho^3 \tan[\phi]^3}{\text{Coh}^3} \right)^2} \right)^{1/3}} \right); \\
  If[\phi == 0, out = c, If[\eta == 0, out = ceta]];
  If[\phi != 0, If[\eta != 0, While[Abs[error] > term, out = 
$$\frac{V}{\left(\eta + \frac{9 \text{Coh} (-1+\eta) \cos[\phi]}{-3 \text{Ee} + (\text{Ee} + 18 c^2 \rho) \sin[\phi]}\right)^{1/3}};$$

    error = out - c;
    c = out]]];
  out];$$

```

Solving Equation 24 & 25; S₀: Equation 34 & 35

```

In[12]:= SIn = Function[{η, V, ϕ, c, ξ}, ψ = V / c;
  If[\phi != 0, S0 = 
$$\frac{\text{Coh} \cot[\phi]}{\text{Ee}} - \frac{2 \text{Coh} (2 \text{Ee} + 9 c^2 \rho) \cos[\phi]}{\text{Ee} (-3 \text{Ee} + (\text{Ee} + 18 c^2 \rho) \sin[\phi])} - \frac{\beta[c]^2 \psi^3 (1 + \sin[\phi]) (4 - \psi^3 + 3 \psi^3 \sin[\phi])}{2 (-1 + \eta) (-1 + 3 \sin[\phi])} + \eta \left( \beta[c] + \frac{9 \text{Coh} \beta[c] \cos[\phi]}{-3 \text{Ee} + (\text{Ee} + 18 c^2 \rho) \sin[\phi]} \right)^2,$$

    S0 = 
$$\left( \beta[c] - \frac{3 \text{Coh} \beta[c]}{\text{Ee}} \right)^2 \eta + \frac{2 \text{Coh} (2 \text{Ee} + 9 c^2 \rho)}{3 \text{Ee}^2} - \frac{\beta[c]^2 \psi^3 (-4 + \psi^3)}{2 (-1 + \eta)}];$$

  If[\phi != 0, Sinco = S0 ξ 
$$^{-\frac{4 \sin[\phi]}{1 + \sin[\phi]}} - \frac{\text{Coh} (\cos[\phi] + \cot[\phi])}{\text{Ee} (1 + \sin[\phi])} + \frac{\beta[c]^2 \psi^6 (1 + \sin[\phi])}{2 \xi^4 (-1 + \eta)} + \frac{2 \beta[c]^2 \psi^3 (1 + \sin[\phi])}{\xi (-1 + \eta) (-1 + 3 \sin[\phi])},$$

    Sinco = 
$$\frac{\beta[c]^2 \psi^3 (-4 \xi^3 + \psi^3)}{2 \xi^4 (-1 + \eta)} + S0 - \frac{4 \text{Coh} \log[\xi]}{\text{Ee}}];$$

  Sinco];

```

Assumption 2 :

Linear Strain

(for linear pressure –
volumetric
strain assumption)

Solving Equation 43

```
In[13]:= CpLinV = Function[{V},
  Clear[out];
  out = FindRoot[(-Ee^2 W (-1 + c^2 X ρ) (-1 + V^2 X ρ) ArcTanh[c √X √ρ] (3 cd (c + cd) (-1 + 2 v) +
    (cd^2 (1 - 2 v) + 4 c^2 (1 + v) + c (cd - 2 cd v)) Sin[ϕf]) + Ee^2 W (-1 + c^2 X ρ)
    (-1 + V^2 X ρ) ArcTanh[V √X √ρ] (3 cd (c + cd) (-1 + 2 v) + (cd^2 (1 - 2 v) + 4 c^2 (1 + v) +
    c (cd - 2 cd v)) Sin[ϕf]) + √X √ρ (12 c^3 cd (c + cd) Coh (-1 + v + 2 v^2) ρ
    (-1 + V^2 X ρ) Cos[ϕf] + Ee (Ee (c - V) W + V (2 V^2 + c Ee (c - V) W X) ρ - 2 c^2 V^3 X ρ^2)
    (3 cd (c + cd) (-1 + 2 v) + (cd^2 (1 - 2 v) + 4 c^2 (1 + v) + c (cd - 2 cd v)) Sin[ϕf])) ==
    0, {c,  $\frac{V + cd}{2}$ }, AccuracyGoal → 10, PrecisionGoal → 20][[1, 2]];
  out];
```

Equation 18a & 42d & 41b

$$\begin{aligned}
\ln[14] := \text{SrE}[c_ , \xi_] &:= \frac{3 A[c] \xi^3 (1 + \nu) + 2 B[c] (cd^2 (1 - 2 \nu) + 3 c^2 \xi^2 \nu)}{3 \xi^3 (-1 + \nu + 2 \nu^2)}; \\
\text{SrPL0}[c_ , \xi_] &:= \frac{3 A[c] (1 + \nu) + 2 B[c] (cd^2 (1 - 2 \nu) + 3 c^2 \nu)}{3 (-1 + \nu + 2 \nu^2)} + \\
&\quad \frac{2 B[c] Ee \beta[c]^4 - (W + 2 B[c] cd^2 \beta[c]^2) \rho}{(-1 + Ee X \beta[c]^2) \rho} - \frac{1}{2} W \text{Log}\left[\frac{1}{1 - Ee X \beta[c]^2}\right]; \\
\text{SrPL}[c_ , \xi_] &:= \frac{W + 2 B[c] (-c^2 + cd^2) \beta[c]^2}{(-1 + Ee X \beta[c]^2) \xi} + \text{SrPL0}[c, \xi] + \\
&\quad \left(W \left(2 \text{ArcTanh}\left[\sqrt{Ee X} \beta[c]\right] - 2 \text{ArcTanh}\left[\sqrt{Ee X} \beta[c] \xi\right] + \right. \right. \\
&\quad \left. \left. \sqrt{Ee X} \beta[c] \xi \text{Log}\left[\frac{\xi^2}{1 - Ee X \beta[c]^2 \xi^2}\right] \right) \right) / (2 \sqrt{Ee X} \beta[c] \xi);
\end{aligned}$$

Assumption 2 :

Non – Linear Sloution

Solving Equation 44a & 44b with Runge–Kutta method (RK4)

```

In[17]:= Rungekutta = Function[{V, c, zetaend, zetabeg, NR, y0, y00},
Clear[out];
dydt1[ξ_, u_, s_] := (2 (4 Coh Cos[φf] + Ee s (-3 + Sin[φf]) + 3 k (1 + Sin[φf]))
(6 k X ξ (Coh Cos[φf] + Ee s Sin[φf]) +
u (2 Coh (2 - 3 k X) Cos[φf] + 3 k (1 + Sin[φf]) + Ee s (-3 + Sin[φf] - 6 k X Sin[φf])))) /
(ξ (-Ee² s² (-3 + Sin[φf])² - 2 Ee s (-3 + Sin[φf]) (4 Coh Cos[φf] + 3 k (1 + Sin[φf])) +
(1 + Sin[φf]) (-16 Coh² + 9 k² (-1 + c² X ξ² ρo) - 24 Coh k Cos[φf] +
(16 Coh² + 9 k² (-1 + c² X ξ² ρo)) Sin[φf] - 9 c² k² u X (-u + 2 ξ) ρo (1 + Sin[φf]))));
dydt2[ξ_, u_, s_] := -((2 (4 Coh Cos[φf] + Ee s (-3 + Sin[φf]) + 3 k (1 + Sin[φf]))
(-Ee² s² (-1 + Cos[2 φf] + 6 Sin[φf]) + (1 + Sin[φf])
(2 Coh (3 k Cos[φf] - 4 Coh (-1 + Sin[φf])) + 3 c² k u (-u + ξ) ρo (1 + Sin[φf])) +
Ee s (3 k - 6 Coh Cos[φf] - 3 k Cos[2 φf] + 6 k Sin[φf] + 5 Coh Sin[2 φf])))) /
(Ee ξ (1 + Sin[φf]) (Ee² s² (-3 + Sin[φf])² + 2 Ee s (-3 + Sin[φf])
(4 Coh Cos[φf] + 3 k (1 + Sin[φf])) +
(1 + Sin[φf]) (16 Coh² - 9 k² (-1 + c² X ξ² ρo) + 24 Coh k Cos[φf] + (-16 Coh² -
9 k² (-1 + c² X ξ² ρo)) Sin[φf] + 9 c² k² u X (-u + 2 ξ) ρo (1 + Sin[φf]))));
h = (zetabeg - zetaend) / NR;
ans = {{zetaend, y0, y00}};
Do[
k1 = {{dydt1[zeta, ans[[1, 2]], ans[[1, 3]]], dydt2[zeta, ans[[1, 2]], ans[[1, 3]]]}};
k2 = {{dydt1[zeta + h/2, ans[[1, 2]] + h/2 k1[[1, 1]], ans[[1, 3]] + h/2 k1[[1, 2]]],
dydt2[zeta + h/2, ans[[1, 2]] + h/2 k1[[1, 1]], ans[[1, 3]] + h/2 k1[[1, 2]]]}};
k3 = {{dydt1[zeta + h/2, ans[[1, 2]] + h/2 k2[[1, 1]], ans[[1, 3]] + h/2 k2[[1, 2]]],
dydt2[zeta + h/2, ans[[1, 2]] + h/2 k2[[1, 1]], ans[[1, 3]] + h/2 k2[[1, 2]]]}};
k4 = {{dydt1[zeta + h, ans[[1, 2]] + h k3[[1, 1]], ans[[1, 3]] + h k3[[1, 2]]],
dydt2[zeta + h, ans[[1, 2]] + h k3[[1, 1]], ans[[1, 3]] + h k3[[1, 2]]]}};
ynp1 = {{ans[[1, 2]], ans[[1, 3]]} + h/6 (k1 + 2 k2 + 2 k3 + k4);
ans = Prepend[ans, {zeta, ynp1[[1, 1]], ynp1[[1, 2]]}], {zeta, zetaend + h, zetabeg, h}];

ans];

```

Probe

S_r and c_p for different assumptions

```

In[18]:=  $\eta_{se} = \eta_s$ ;
listCph = {}; (*cp: Assumption 1*)
listCpInE = {}; (*cp: Assumption 1 incompressible elastic*)
listCpLinV = {}; (*cp: Assumption 2: Linear*)
listCpFV = {}; (*cp: Assumption 2: Non-Linear*)
listSh = {}; (*Sr: Assumption 1*)
listSInE = {}; (*Sr: Assumption 1 incompressible elastic*)
listSLinV = {}; (*Sr: Assumption 2: Linear*)
listSFV = {}; (*Sr: Assumption 2: Non-Linear*)

Do[ $V_i = i \sqrt{\frac{Y}{\rho}}$ ;  $c = CpLinV[V_i]$ ;

listCpLinV = Append[listCpLinV, { $V_i \sqrt{\frac{\rho}{Y}}$ ,  $c \sqrt{\frac{\rho}{Y}}$  }];

listSLinV = Append[listSLinV, { $V_i \sqrt{\frac{\rho}{Y}}$ ,  $SrPL[c, \frac{V_i}{c}] \frac{Ee}{Y}$  }];

err = 1; If[ArrayDepth[listCpFV] > 5, c = cp]; errlist = {};
While[Abs[err] > term,  $y_0 = B[c] (c - cd) (c + cd)$ ;
 $y_{00} = \frac{3 A[c] (1 + \nu) + 2 B[c] (cd^2 (1 - 2 \nu) + 3 c^2 \nu)}{3 (-1 + \nu + 2 \nu^2)}$ ;

zetaend = 1;
zetabeg =  $\frac{V_i}{c}$ ;
ansFR = Rungekutta[V_i, c, zetaend, zetabeg, NR,  $y_0$ ,  $y_{00}$ ];
 $cp = 0.01 \frac{V_i}{ansFR[[1, 2]]} + 0.99 c$ ;
err =  $c - \frac{V_i}{ansFR[[1, 2]]}$ ;
errlist = Append[errlist, {err, c}];
If[Length[errlist] > 2, errlistf = Interpolation[errlist, InterpolationOrder -> 1];
cp = errlistf[0];
c = cp];

listCpFV = Append[listCpFV, { $V_i \sqrt{\frac{\rho}{Y}}$ ,  $cp \sqrt{\frac{\rho}{Y}}$  }];

```



```

listSFV = Append[listSFV, {Vi  $\sqrt{\frac{\rho}{Y}}$ , ansFR[[1, 3]]  $\frac{Ee}{Y}$  }];

errh = 1;
While[Abs[errh] > term, c = Cph[ $\eta_s$ , Vi,  $\phi_f$ , term];
   $\sigma_r$  = Sh[ $\eta_s$ , Vi,  $\phi_f$ , c,  $\frac{Vi}{c}$ ] Ee;
   $p = \frac{3 \sigma_r - 4 Coh \cos[\phi_f] - \sigma_r \sin[\phi_f]}{3 + 3 \sin[\phi_f]}$ ;
   $\eta_{sm} = \frac{p}{k}$ ;
  errh =  $\frac{\eta_{sm} - \eta_s}{\eta_s} 100$ ;
   $\eta_s = \eta_{sm}$ ];
If[ $\eta_s < 0.12$ ,  $\eta_s = \eta_{sm}$ ,  $\eta_s = 0.12$ ]; c = Cph[ $\eta_s$ , Vi,  $\phi_f$ , term];

listCph = Append[listCph, {Vi  $\sqrt{\frac{\rho}{Y}}$ , c  $\sqrt{\frac{\rho}{Y}}$  }];

listSh = Append[listSh, {Vi  $\sqrt{\frac{\rho}{Y}}$ , Sh[ $\eta_s$ , Vi,  $\phi_f$ , c,  $\frac{Vi}{c}$ ]  $\frac{Ee}{Y}$  }];

errhE = 1;
While[Abs[errhE] > term, c = CpIn[ $\eta_{se}$ , Vi,  $\phi_f$ , term];
   $\sigma_r$  = SIn[ $\eta_{se}$ , Vi,  $\phi_f$ , c,  $\frac{Vi}{c}$ ] Ee;
   $p = \frac{3 \sigma_r - 4 Coh \cos[\phi_f] - \sigma_r \sin[\phi_f]}{3 + 3 \sin[\phi_f]}$ ;
   $\eta_{sme} = \frac{p}{k}$ ;
  errhE =  $\frac{\eta_{sme} - \eta_{se}}{\eta_{se}} 100$ ;
   $\eta_{se} = \eta_{sme}$ ];
If[ $\eta_{se} < 0.12$ ,  $\eta_{se} = \eta_{sme}$ ,  $\eta_{se} = 0.12$ ];
Print["i=", i, "      Assumption I  $\eta$ =",
   $\eta_s$ , "      Assumption I: Incompressible Elastic  $\eta$ =",  $\eta_{se}$ ];
c = CpIn[ $\eta_{se}$ , Vi,  $\phi_f$ , term];

listCpInE = Append[listCpInE, {Vi  $\sqrt{\frac{\rho}{Y}}$ , c  $\sqrt{\frac{\rho}{Y}}$  }];

listSInE = Append[listSInE, {Vi  $\sqrt{\frac{\rho}{Y}}$ , SIn[ $\eta_{se}$ , Vi,  $\phi_f$ , c,  $\frac{Vi}{c}$ ]  $\frac{Ee}{Y}$  }, {i, 0.01, 5.01, .1}]

```

... **InterpolatingFunction**: Input value {0} lies outside the range of data in the interpolating function. Extrapolation will be used.

i=0.01 Assumption I $\eta=0.0180708$ Assumption I: Incompressible Elastic $\eta=0.017831$

... **FindRoot**: The line search decreased the step size to within tolerance specified by AccuracyGoal and PrecisionGoal but was unable to find a sufficient decrease in the merit function. You may need more than MachinePrecision digits of working precision to meet these tolerances.

... **InterpolatingFunction:** Input value {0} lies outside the range of data in the interpolating function. Extrapolation will be used.

i=0.11 Assumption I $\eta=0.0181592$ Assumption I: Incompressible Elastic $\eta=0.0179296$

... **FindRoot:** The line search decreased the step size to within tolerance specified by AccuracyGoal and PrecisionGoal but was unable to find a sufficient decrease in the merit function. You may need more than MachinePrecision digits of working precision to meet these tolerances.

... **InterpolatingFunction:** Input value {0} lies outside the range of data in the interpolating function. Extrapolation will be used.

... **General:** Further output of InterpolatingFunction::dmval will be suppressed during this calculation.

i=0.21 Assumption I $\eta=0.0183953$ Assumption I: Incompressible Elastic $\eta=0.0181933$

i=0.31 Assumption I $\eta=0.0187748$ Assumption I: Incompressible Elastic $\eta=0.018618$

... **FindRoot:** The line search decreased the step size to within tolerance specified by AccuracyGoal and PrecisionGoal but was unable to find a sufficient decrease in the merit function. You may need more than MachinePrecision digits of working precision to meet these tolerances.

... **General:** Further output of FindRoot::lstol will be suppressed during this calculation.

i=0.41 Assumption I $\eta=0.0192986$ Assumption I: Incompressible Elastic $\eta=0.0192038$

i=0.51 Assumption I $\eta=0.0199641$ Assumption I: Incompressible Elastic $\eta=0.019947$

i=0.61 Assumption I $\eta=0.0207691$ Assumption I: Incompressible Elastic $\eta=0.020844$

i=0.71 Assumption I $\eta=0.0217111$ Assumption I: Incompressible Elastic $\eta=0.0218908$

i=0.81 Assumption I $\eta=0.0227872$ Assumption I: Incompressible Elastic $\eta=0.0230837$

i=0.91 Assumption I $\eta=0.0239946$ Assumption I: Incompressible Elastic $\eta=0.0244163$

i=1.01 Assumption I $\eta=0.0253299$ Assumption I: Incompressible Elastic $\eta=0.0258846$

i=1.11 Assumption I $\eta=0.0267898$ Assumption I: Incompressible Elastic $\eta=0.0274837$

i=1.21 Assumption I $\eta=0.0283706$ Assumption I: Incompressible Elastic $\eta=0.0292088$

i=1.31 Assumption I $\eta=0.0300687$ Assumption I: Incompressible Elastic $\eta=0.0310539$

i=1.41 Assumption I $\eta=0.0318803$ Assumption I: Incompressible Elastic $\eta=0.0330167$

i=1.51 Assumption I $\eta=0.0338017$ Assumption I: Incompressible Elastic $\eta=0.0350917$

i=1.61 Assumption I $\eta=0.0358293$ Assumption I: Incompressible Elastic $\eta=0.0372746$

i=1.71 Assumption I $\eta=0.0379592$ Assumption I: Incompressible Elastic $\eta=0.0395616$

i=1.81 Assumption I $\eta=0.0401881$ Assumption I: Incompressible Elastic $\eta=0.0419489$

i=1.91 Assumption I $\eta=0.0425124$ Assumption I: Incompressible Elastic $\eta=0.0444329$

i=2.01 Assumption I $\eta=0.0449303$ Assumption I: Incompressible Elastic $\eta=0.0470103$

i=2.11 Assumption I $\eta=0.0474357$ Assumption I: Incompressible Elastic $\eta=0.0496782$

i=2.21 Assumption I $\eta=0.050027$ Assumption I: Incompressible Elastic $\eta=0.0524335$

i=2.31 Assumption I $\eta=0.0527014$ Assumption I: Incompressible Elastic $\eta=0.0552737$

i=2.41 Assumption I $\eta=0.055456$ Assumption I: Incompressible Elastic $\eta=0.0581963$

i=2.51 Assumption I $\eta=0.0582883$ Assumption I: Incompressible Elastic $\eta=0.0611991$

i=2.61 Assumption I $\eta=0.0611959$ Assumption I: Incompressible Elastic $\eta=0.0642799$

i=2.71 Assumption I $\eta=0.0641763$ Assumption I: Incompressible Elastic $\eta=0.0674367$

i=2.81	Assumption I $\eta=0.0672274$	Assumption I: Incompressible Elastic $\eta=0.070668$
i=2.91	Assumption I $\eta=0.0703472$	Assumption I: Incompressible Elastic $\eta=0.073972$
i=3.01	Assumption I $\eta=0.0735336$	Assumption I: Incompressible Elastic $\eta=0.0773472$
i=3.11	Assumption I $\eta=0.0767847$	Assumption I: Incompressible Elastic $\eta=0.0807924$
i=3.21	Assumption I $\eta=0.0800988$	Assumption I: Incompressible Elastic $\eta=0.0843063$
i=3.31	Assumption I $\eta=0.0834743$	Assumption I: Incompressible Elastic $\eta=0.087888$
i=3.41	Assumption I $\eta=0.0869096$	Assumption I: Incompressible Elastic $\eta=0.0915365$
i=3.51	Assumption I $\eta=0.0904031$	Assumption I: Incompressible Elastic $\eta=0.0952512$
i=3.61	Assumption I $\eta=0.0939534$	Assumption I: Incompressible Elastic $\eta=0.0990353$
i=3.71	Assumption I $\eta=0.0975593$	Assumption I: Incompressible Elastic $\eta=0.102881$
i=3.81	Assumption I $\eta=0.101219$	Assumption I: Incompressible Elastic $\eta=0.106791$
i=3.91	Assumption I $\eta=0.104932$	Assumption I: Incompressible Elastic $\eta=0.110766$
i=4.01	Assumption I $\eta=0.108697$	Assumption I: Incompressible Elastic $\eta=0.114805$
i=4.11	Assumption I $\eta=0.112513$	Assumption I: Incompressible Elastic $\eta=0.118909$
i=4.21	Assumption I $\eta=0.116378$	Assumption I: Incompressible Elastic $\eta=0.12$
i=4.31	Assumption I $\eta=0.12$	Assumption I: Incompressible Elastic $\eta=0.12$
i=4.41	Assumption I $\eta=0.12$	Assumption I: Incompressible Elastic $\eta=0.12$
i=4.51	Assumption I $\eta=0.12$	Assumption I: Incompressible Elastic $\eta=0.12$
i=4.61	Assumption I $\eta=0.12$	Assumption I: Incompressible Elastic $\eta=0.12$
i=4.71	Assumption I $\eta=0.12$	Assumption I: Incompressible Elastic $\eta=0.12$
i=4.81	Assumption I $\eta=0.12$	Assumption I: Incompressible Elastic $\eta=0.12$
i=4.91	Assumption I $\eta=0.12$	Assumption I: Incompressible Elastic $\eta=0.12$
i=5.01	Assumption I $\eta=0.12$	Assumption I: Incompressible Elastic $\eta=0.12$

In[22]:=

```

CPLinV =
  ListPlot[listCpLinV, PlotLegends → Placed[{"Assumption 2: Linear"}, {Left, Top}],
  LabelStyle → (FontFamily → "Cambria"), Joined → True,
  PlotRange → {{0, 5}, {0, 15}}, GridLines → Automatic, AspectRatio → .5,
  Frame → {{True, True}, {True, True}}, PlotStyle → {Black, Dashed, Thick},
  FrameLabel → {{ $\sqrt{\frac{\rho_0}{\gamma}} c_p$ ", None}, { $\sqrt{\frac{\rho_0}{\gamma}} V$ ", None}}, PlotMarkers → {"●", Medium}];

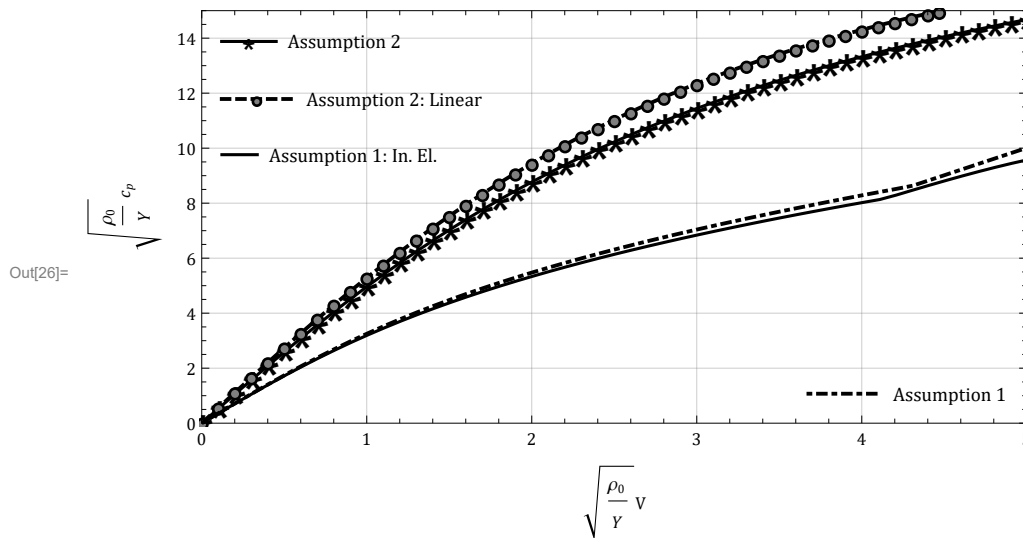
CPFV = ListPlot[listCpFV, PlotLegends → Placed[{"Assumption 2"}, {Left, Top}],
  LabelStyle → (FontFamily → "Cambria"), Joined → True,
  PlotRange → {{0, 5}, {0, 15}}, GridLines → Automatic, AspectRatio → .5,
  Frame → {{True, True}, {True, True}}, PlotStyle → Black,
  FrameLabel → {{ $\sqrt{\frac{\rho_0}{\gamma}} c_p$ ", None}, { $\sqrt{\frac{\rho_0}{\gamma}} V$ ", None}}, PlotMarkers → {"*", Large}];

CPH = ListPlot[listCpH, PlotLegends → Placed[{"Assumption 1"}, {Right, Bottom}],
  LabelStyle → (FontFamily → "Cambria"), Joined → True,
  PlotRange → {{0, 5}, {0, 15}}, GridLines → Automatic, AspectRatio → .5,
  Frame → {{True, True}, {True, True}}, PlotStyle → {Black, DotDashed, Thick},
  FrameLabel → {{ $\sqrt{\frac{\rho_0}{\gamma}} c_p$ ", None}, { $\sqrt{\frac{\rho_0}{\gamma}} V$ ", None}}];

CPHINE = ListPlot[listCpInE, PlotLegends → Placed[{"Assumption 1: In. El."},
  {Left, Top}], LabelStyle → (FontFamily → "Cambria"), Joined → True,
  PlotRange → {{0, 5}, {0, 15}}, GridLines → Automatic, AspectRatio → .5,
  Frame → {{True, True}, {True, True}}, PlotStyle → Black,
  FrameLabel → {{ $\sqrt{\frac{\rho_0}{\gamma}} c_p$ ", None}, { $\sqrt{\frac{\rho_0}{\gamma}} V$ ", None}}];

Show[CPFV, CPLinV, CPH, CPHINE]

```



In[27]:=

```

SLinV = ListPlot[listSLinV, PlotLegends → Placed[{"Assumption 2: Linear"}, {Left, Top}],
  LabelStyle → (FontFamily → "Cambria"), Joined → True,
  PlotRange → {{0, 5}, {0, 70}}, GridLines → Automatic, AspectRatio → .5,
  Frame → {{True, True}, {True, True}}, PlotStyle → {Black, Dashed, Thick},
  FrameLabel → {{ $\frac{\sigma_r}{2 C_{oh}}$ , None}, { $\sqrt{\frac{\rho_\theta}{2 C_{oh}}} c_p$ , None}}, PlotMarkers → {"○", Medium}];

SFV = ListPlot[listSFV, PlotLegends → Placed[{"Assumption 2"}, {Left, Top}],
  LabelStyle → (FontFamily → "Cambria"), Joined → True,
  PlotRange → {{0, 5}, {0, 70}}, GridLines → Automatic, AspectRatio → .5,
  Frame → {{True, True}, {True, True}}, PlotStyle → Black,
  FrameLabel → {{ $\frac{\sigma_r}{2 C_{oh}}$ , None}, { $\sqrt{\frac{\rho_\theta}{2 C_{oh}}} c_p$ , None}}, PlotMarkers → {"*", Large}];

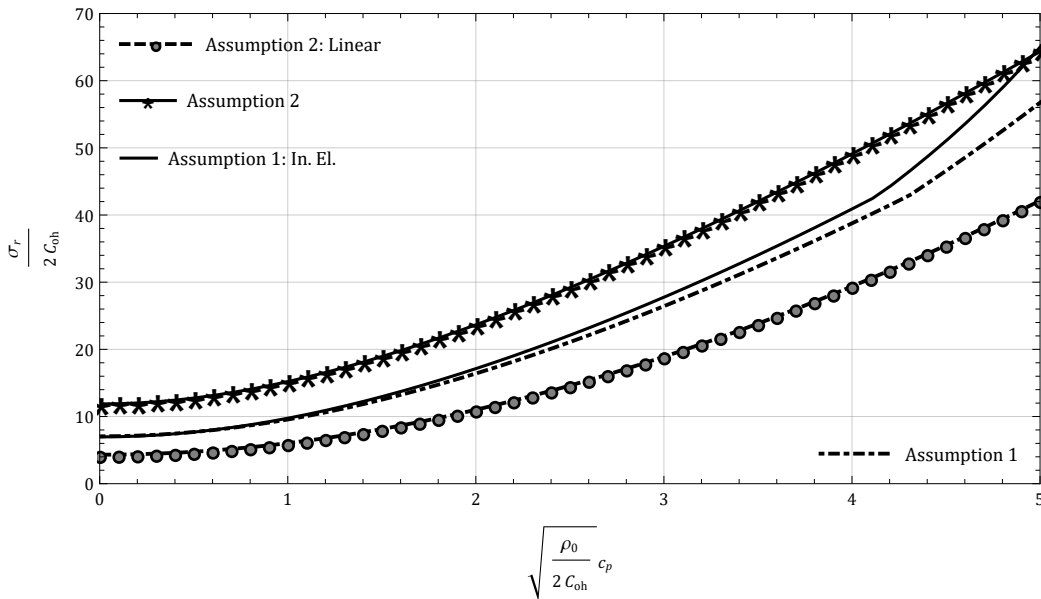
SH = ListPlot[listSh, PlotLegends → Placed[{"Assumption 1"}, {Right, Bottom}],
  LabelStyle → (FontFamily → "Cambria"), Joined → True,
  PlotRange → {{0, 5}, {0, 70}}, GridLines → Automatic, AspectRatio → .5,
  Frame → {{True, True}, {True, True}}, PlotStyle → {Black, DotDashed, Thick},
  FrameLabel → {{ $\frac{\sigma_r}{2 C_{oh}}$ , None}, { $\sqrt{\frac{\rho_\theta}{2 C_{oh}}} c_p$ , None}}];

SHINE = ListPlot[listSInE, PlotLegends → Placed[{"Assumption 1: In. El."}, {Left, Top}],
  LabelStyle → (FontFamily → "Cambria"), Joined → True, PlotRange → {{0, 5}, {0, 70}},
  GridLines → Automatic, AspectRatio → .5, Frame → {{True, True}, {True, True}},
  PlotStyle → Black, FrameLabel → {{ $\frac{\sigma_r}{2 C_{oh}}$ , None}, { $\sqrt{\frac{\rho_\theta}{2 C_{oh}}} c_p$ , None}}];

Show[SLinV, SFV, SH, SHINE]

```

Out[31]=



Penetration

Geometry of the probe

```
In[32]:= a =  $\frac{0.156}{2}$ ; (*M= 162+55.3;*); M = 162;
Vp = 520;  $\mu = 0$ ;
CRH = 6;
s = 2 a CRH;
 $\theta_0 = \text{ArcSin}\left[\frac{s - a}{s}\right];$ 
```

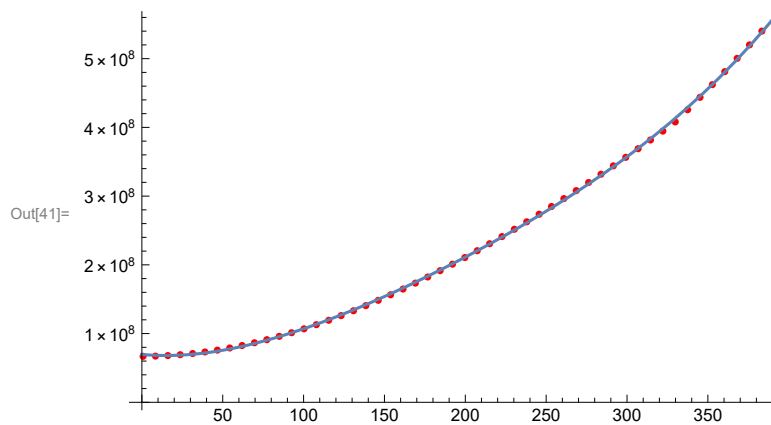
Assumption I

Curve fitting for Assumption 1 (Hydrostat model)

In[36]:=

```
listSh2 = listSh;
listSh2[[All, 1]] =  $\frac{\text{listSh2}[[\text{All}, 1]]}{\sqrt{\frac{\rho}{Y}}}$ ;

listSh2[[All, 2]] = listSh2[[All, 2]] Y;
fith = Fit[listSh2, {1, x, x^2, x^3, x^4}, x];
g[x_] := fith
Show[ListPlot[listSh2, PlotStyle -> Red], Plot[g[x], {x, 0, 500}]]
SIGMAFh[vp_, phi_] := fith /. x -> vp Cos[phi]; (*V=vp Cos[phi]*)
```



Curve fitting maximum error and coefficient of determination

In[43]:=

```
R2 = 0;
sstot = 0;
ssres = 0;
sum = 0;
error = {};
Do[sum = sum + listSh2[[i, 2]], {i, 1, Dimensions[listSh2][[1]]}];
ave =  $\frac{\text{sum}}{\text{Dimensions[listSh2][[1]]}}$ ;
Do[sstot = sstot + (listSh2[[i, 2]] - ave)^2;
  val = (fith /. x -> listSh2[[i, 1]]);
  error = Append[error,  $\frac{\text{Abs[listSh2[[i, 2]] - val]}{\text{Abs[listSh2[[i, 2]]]}}$ ];
  ssres = ssres + (listSh2[[i, 2]] - val)^2, {i, 1, Dimensions[listSh2][[1]]}];
R2 = 1 -  $\frac{\text{ssres}}{\text{sstot}}$ ;
maxerror = Max[error] 100;
Print["coefficient of determination=", R2, "      Maximum Error=", maxerror, "%"]
```

coefficient of determination=0.999867 Maximum Error=3.86776%

Penetration Time (Tf) and Penetration depth (Zf) without the pusher plate with different friction

In[47]:=

```

M = 162; Clear[μ];
Do[dah =  $\frac{-\text{SIGMAFh}[\text{vp}, \phi]}{M} (\mu \sin[\phi] + \cos[\phi]) \left( \sin[\phi] - \frac{s-a}{s} \right) 2\pi s^2$  // FullSimplify;
  (*Equation 50*)
  azh = Integrate[dah, {φ, φ0,  $\frac{\pi}{2}$ }] /. φ0 → 0 // Simplify; (*Equation 51*)
  azhy[v_] := azh /. vp → v;
  dzh =  $\frac{\text{vp}}{\text{azhy}[\text{vp}]}$  // Simplify;
  Zhvp = Integrate[dzh, {vp, Vp0, Vph}, Assumptions → 1000 > Vp0 > Vph > 0];
  Zh[v_, v0_] := Zhvp /. Vph → v /. Vp0 → v0;
  tvp = Integrate[ $\frac{1}{\text{azhy}[\text{vp}]}$ , {vp, Vp0, Vph}, Assumptions → 1000 > Vp0 > Vph > 0];
  th[v_, v0_] := tvp /. Vph → v /. Vp0 → v0;
  tfhy = th[0, Vp];
  zfhy = Zh[0, Vp];
  Print["μ=", μ, "      Tf=", Round[1000 tfhy, 0.1],
    "ms", "      Zf=", Round[zfhy, 0.01], "m"], {μ, 0, .1, 0.01}]

```

μ=0.	Tf=53.1ms	Zf=12.39m
μ=0.01	Tf=50.1ms	Zf=11.71m
μ=0.02	Tf=47.4ms	Zf=11.1m
μ=0.03	Tf=44.9ms	Zf=10.55m
μ=0.04	Tf=42.8ms	Zf=10.06m
μ=0.05	Tf=40.8ms	Zf=9.61m
μ=0.06	Tf=39.ms	Zf=9.19m
μ=0.07	Tf=37.3ms	Zf=8.82m
μ=0.08	Tf=35.8ms	Zf=8.47m
μ=0.09	Tf=34.4ms	Zf=8.14m
μ=0.1	Tf=33.1ms	Zf=7.85m

Adding effects of the pushing plate between t = 0 to 0.003 s

In[49]:=

```

M = 162 + 55.3;
Do[dah =  $\frac{-\text{SIGMAFh}[vp, \phi]}{M} (\mu \sin[\phi] + \cos[\phi]) \left( \sin[\phi] - \frac{s-a}{s} \right) 2\pi s^2$  // FullSimplify;

azh = Integrate[dah, { $\phi, \phi_0, \frac{\pi}{2}$ }] /.  $\phi_0 \rightarrow 0$  // Simplify;

azhy[v_] := azh /. vp -> v;
dzh =  $\frac{vp}{azhy[vp]}$  // Simplify;

tvp = Integrate[ $\frac{1}{azhy[vp]}$ , {vp, Vp0, Vph}, Assumptions -> 1000 > Vp0 > Vph > 0];

th[v_, v0_] := tvp /. Vph -> v /. Vp0 -> v0;
v3ms = FindRoot[th[vv, Vp] - 0.003, {vv, Vp}][[1, 2]];
Zhvp = Integrate[dzh, {vp, Vp0, Vph}, Assumptions -> 1000 > Vp0 > Vph > 0];
Zh[v_, v0_] := Zhvp /. Vph -> v /. Vp0 -> v0;

tfhy =  $\frac{th[0, v3ms]}{162 + 55.3} (162) + 0.003$ ;

zfhy = Zh[v3ms, Vp] + Zh[0, v3ms]  $\frac{162}{162 + 55.3}$ ;

Print[" $\mu$ =",  $\mu$ , " Tf=", Round[1000 tfhy, 0.1],
      "ms", " Zf=", Round[zfhy, 0.01], "m"], { $\mu$ , 0, .1, 0.01}]

```

$\mu=0.$	Tf=53.8ms	Zf=12.77m
$\mu=0.01$	Tf=50.8ms	Zf=12.09m
$\mu=0.02$	Tf=48.1ms	Zf=11.49m
$\mu=0.03$	Tf=45.7ms	Zf=10.94m
$\mu=0.04$	Tf=43.5ms	Zf=10.44m
$\mu=0.05$	Tf=41.5ms	Zf=9.99m
$\mu=0.06$	Tf=39.7ms	Zf=9.57m
$\mu=0.07$	Tf=38.1ms	Zf=9.2m
$\mu=0.08$	Tf=36.6ms	Zf=8.85m
$\mu=0.09$	Tf=35.2ms	Zf=8.52m
$\mu=0.1$	Tf=33.9ms	Zf=8.22m

Assumption 1: Incompressible Elastic Assumption

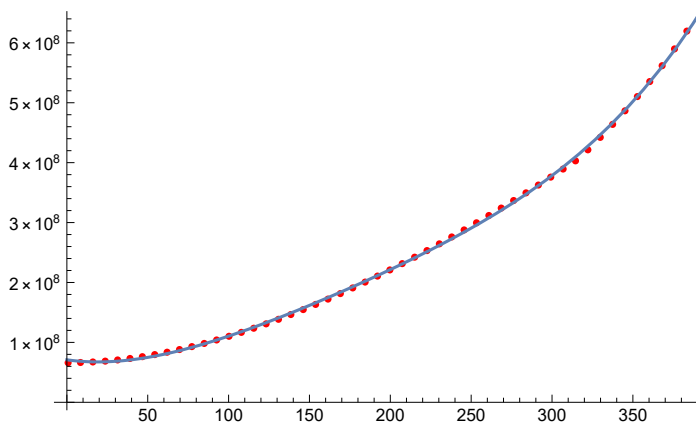
Curve fitting for Assumption 1 (incompressible elastic)

In[51]:=

```
listSInE2 = listSInE;
listSInE2[[All, 1]] =  $\frac{\text{listSInE2}[[\text{All}, 1]]}{\sqrt{\frac{\rho}{\gamma}}}$ ;

listSInE2[[All, 2]] = listSInE2[[All, 2]]  $\gamma$ ;
fitInE = Fit[listSInE2, {1, x, x2, x3, x4}, x];
gInE[x_] := fitInE
Show[ListPlot[listSInE2, PlotStyle → Red], Plot[gInE[x], {x, 0, 500}]]
SIGMAFInE[vp_,  $\phi$ _] := fitInE /. x → vp Cos[ $\phi$ ]; (*V=vp Cos[ $\phi$ ]*)
```

Out[56]=



Curve fitting maximum error and coefficient of determination

In[58]:=

```
R2 = 0;
sstot = 0;
ssres = 0;
sum = 0;
error = {};
Do[sum = sum + listSInE2[[i, 2]], {i, 1, Dimensions[listSInE2][[1]]}];
ave =  $\frac{\text{sum}}{\text{Dimensions[listSInE2][[1]]}}$ ;
Do[sstot = sstot + (listSInE2[[i, 2]] - ave)2;
  val = (fitInE /. x → listSInE2[[i, 1]]);
  error = Append[error,  $\frac{\text{Abs[listSInE2}[[i, 2]] - \text{val}}{\text{Abs[listSInE2}[[i, 2]]}}$ ];
  ssres = ssres + (listSInE2[[i, 2]] - val)2, {i, 1, Dimensions[listSInE2][[1]]}];
R2 = 1 -  $\frac{\text{ssres}}{\text{sstot}}$ ;
maxerror = Max[error] 100;
Print["coefficient of determination=", R2, "      Maximum Error=", maxerror, "%"]
```

coefficient of determination=0.999733 Maximum Error=6.85462%

Penetration Time (Tf) and Penetration depth (Zf) without the pusher plate with different friction

In[62]:=

```

M = 162; Clear[μ];
Do[daInE =  $\frac{-\text{SIGMAFInE}[vp, \phi]}{M} (\mu \sin[\phi] + \cos[\phi]) \left( \sin[\phi] - \frac{s-a}{s} \right) 2 \pi s^2$  // FullSimplify;
(*Equation 50*)
azInE = Integrate[daInE, {ϕ, ϕ0,  $\frac{\pi}{2}$ }] /. ϕ0 → 0 // Simplify;
(*Equation 51*)
azIncE[v_] := azInE /. vp → v; dzIncE =  $\frac{vp}{azIncE[vp]}$  // Simplify;
ZIncEvp = Integrate[dzIncE, {vp, Vp0, Vph}, Assumptions → 1000 > Vp0 > Vph > 0];
ZIncE[v_, v0_] := ZIncEvp /. Vph → v /. Vp0 → v0;
tIncE = Integrate[ $\frac{1}{azIncE[vp]}$ , {vp, Vp0, Vph}, Assumptions → 1000 > Vp0 > Vph > 0];
tFtIncE[v_, v0_] := tIncE /. Vph → v /. Vp0 → v0;
tfFInE = tFtIncE[0, Vp]; zfFInE = ZIncE[0, Vp];
Print["μ=", μ, " Tf=", Round[1000 tfFInE, 0.1],
      "ms", " Zf=", Round[zfFInE, 0.01], "m"], {μ, 0, .1, 0.01}]

```

μ=0.	Tf=52.8ms	Zf=12.23m
μ=0.01	Tf=49.8ms	Zf=11.56m
μ=0.02	Tf=47.1ms	Zf=10.96m
μ=0.03	Tf=44.7ms	Zf=10.42m
μ=0.04	Tf=42.5ms	Zf=9.94m
μ=0.05	Tf=40.6ms	Zf=9.49m
μ=0.06	Tf=38.8ms	Zf=9.09m
μ=0.07	Tf=37.1ms	Zf=8.71m
μ=0.08	Tf=35.6ms	Zf=8.37m
μ=0.09	Tf=34.2ms	Zf=8.05m
μ=0.1	Tf=32.9ms	Zf=7.76m

Adding effects of the pushing plate between t = 0 to 0.003 s

In[64]:=

```

M = 162 + 55.3;
Do[daInE =  $\frac{-\text{SIGMAFInE}[vp, \phi]}{M} (\mu \sin[\phi] + \cos[\phi]) \left( \sin[\phi] - \frac{s-a}{s} \right) 2\pi s^2$  // FullSimplify;

azInE = Integrate[daInE, { $\phi$ ,  $\phi_0$ ,  $\frac{\pi}{2}$ }] /.  $\phi_0 \rightarrow 0$  // Simplify;

azIncE[v_] := azInE /. vp  $\rightarrow$  v; dzIncE =  $\frac{vp}{azIncE[vp]}$  // Simplify;

tIncE = Integrate[ $\frac{1}{azIncE[vp]}$ , {vp, Vp0, Vph}, Assumptions  $\rightarrow 1000 > Vp0 > Vph > 0$ ];

tFtIncE[v_, v0_] := tIncE /. Vph  $\rightarrow$  v /. Vp0  $\rightarrow$  v0;
v3ms = FindRoot[tFtIncE[vv, Vp] - 0.003, {vv, Vp}][[1, 2]];
ZIncEvp = Integrate[dzIncE, {vp, Vp0, Vph}, Assumptions  $\rightarrow 1000 > Vp0 > Vph > 0$ ];
ZIncE[v_, v0_] := ZIncEvp /. Vph  $\rightarrow$  v /. Vp0  $\rightarrow$  v0;

tfFInE =  $\frac{tFtIncE[0, v3ms]}{162 + 55.3} (162) + 0.003$ ;

zfFInE = ZIncE[v3ms, Vp] + ZIncE[0, v3ms]  $\frac{162}{162 + 55.3}$ ;

Print[" $\mu$ =",  $\mu$ , "    Tf=", Round[1000 tfFInE, 0.1],
      "ms", "    Zf=", Round[zfFInE, 0.01], "m"], { $\mu$ , 0, .1, 0.01}]

```

$\mu=0.$	Tf=53.5ms	Zf=12.61m
$\mu=0.01$	Tf=50.5ms	Zf=11.94m
$\mu=0.02$	Tf=47.9ms	Zf=11.34m
$\mu=0.03$	Tf=45.5ms	Zf=10.81m
$\mu=0.04$	Tf=43.3ms	Zf=10.32m
$\mu=0.05$	Tf=41.3ms	Zf=9.87m
$\mu=0.06$	Tf=39.5ms	Zf=9.47m
$\mu=0.07$	Tf=37.9ms	Zf=9.09m
$\mu=0.08$	Tf=36.4ms	Zf=8.75m
$\mu=0.09$	Tf=35.ms	Zf=8.43m
$\mu=0.1$	Tf=33.7ms	Zf=8.14m

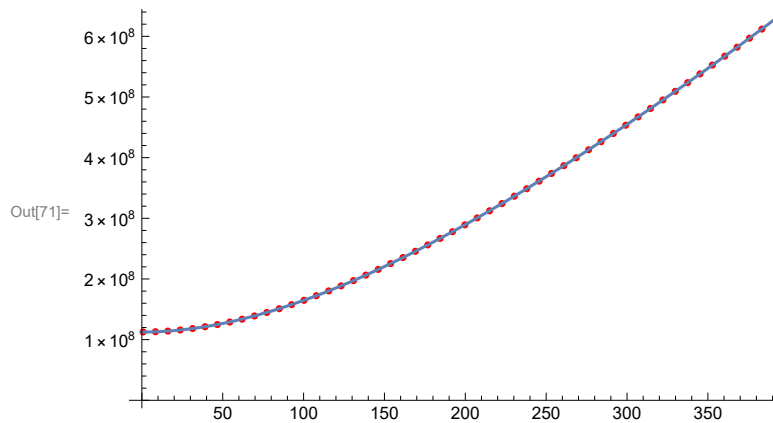
Assumption 2

Curve fitting for Linear Volumetric model

In[66]:=

```
listSFV2 = listSFV;
listSFV2[[A11, 1]] =  $\frac{\text{listSFV2}[[A11, 1]]}{\sqrt{\frac{\rho}{Y}}}$ ;

listSFV2[[A11, 2]] = listSFV2[[A11, 2]] Y;
fitFV = Fit[listSFV2, {1, x, x^2, x^3, x^4}, x];
gFV[x_] := fitFV
Show[ListPlot[listSFV2, PlotStyle -> Red], Plot[gFV[x], {x, 0, 500}]]
SIGMAFFV[vp_, phi_] := fitFV /. x -> vp Cos[phi]; (*V=vp Cos[phi]*)
```



Curve fitting maximum error and coefficient of determination

In[73]:=

```
R2 = 0;
sstot = 0;
ssres = 0;
sum = 0;
error = {};
Do[sum = sum + listSFV2[[i, 2]], {i, 1, Dimensions[listSFV2][[1]]}];
ave =  $\frac{\text{sum}}{\text{Dimensions[listSFV2][[1]]}}$ ;
Do[sstot = sstot + (listSFV2[[i, 2]] - ave)^2;
  val = (fitFV /. x -> listSFV2[[i, 1]]);
  error = Append[error,  $\frac{\text{Abs[listSFV2[[i, 2]] - val]}}{\text{Abs[listSFV2[[i, 2]]]}}$ ];
  ssres = ssres + (listSFV2[[i, 2]] - val)^2, {i, 1, Dimensions[listSFV2][[1]]}];
R2 = 1 -  $\frac{\text{ssres}}{\text{sstot}}$ ;
maxerror = Max[error] 100;
Print["coefficient of determination=", R2, "      Maximum Error=", maxerror, "%"]
```

coefficient of determination=1. Maximum Error=0.106333%

Penetration Time (Tf) and Penetration depth (Zf) without the pusher plate with different friction

In[77]:=

```

M = 162; Clear[μ];
Do[daFV =  $\frac{-\text{SIGMAFFV}[\text{vp}, \phi]}{M} (\mu \sin[\phi] + \cos[\phi]) \left( \sin[\phi] - \frac{s-a}{s} \right) 2 \pi s^2$  // FullSimplify;
(*Equation 50*)
azFV = Integrate[daFV, {φ, φ0,  $\frac{\pi}{2}$ }] /. φ0 → 0 // Simplify;
(*Equation 51*)
azFVN[v_] := azFV /. vp → v; dzFV =  $\frac{\text{vp}}{\text{azFVN}[\text{vp}]}$  // Simplify;
ZFV = Integrate[dzFV, {vp, vp0, vph}, Assumptions → 1000 > vp0 > vph > 0];
ZFVN[v_, v0_] := ZFV /. Vph → v /. vp0 → v0;
tfV = Integrate[ $\frac{1}{\text{azFVN}[\text{vp}]}$ , {vp, vp0, vph}, Assumptions → 1000 > vp0 > vph > 0];
tfVN[v_, v0_] := tfV /. Vph → v /. vp0 → v0;
tfFV = tfVN[0, vp]; zfFV = ZFVN[0, vp];
Print["μ=", μ, " Tf=", Round[1000 tfFV, 0.1],
      "ms", " Zf=", Round[zfFV, 0.01], "m"], {μ, 0, .1, 0.01}]

```

μ=0.	Tf=32.7ms	Zf=7.79m
μ=0.01	Tf=30.9ms	Zf=7.36m
μ=0.02	Tf=29.2ms	Zf=6.97m
μ=0.03	Tf=27.7ms	Zf=6.62m
μ=0.04	Tf=26.3ms	Zf=6.31m
μ=0.05	Tf=25.1ms	Zf=6.02m
μ=0.06	Tf=24.ms	Zf=5.76m
μ=0.07	Tf=23.ms	Zf=5.52m
μ=0.08	Tf=22.ms	Zf=5.3m
μ=0.09	Tf=21.2ms	Zf=5.09m
μ=0.1	Tf=20.4ms	Zf=4.9m

Adding effects of the pushing plate between t = 0 to 0.003 s

In[79]:=

```

M = 162 + 55.3;
Do[daFV =  $\frac{-\text{SIGMAFFV}[\text{vp}, \phi]}{M} (\mu \sin[\phi] + \cos[\phi]) \left( \sin[\phi] - \frac{s-a}{s} \right) 2 \pi s^2$  // FullSimplify;

azFV = Integrate[daFV, {\phi, \phi0,  $\frac{\pi}{2}$ }] /. \phi0 \to \theta0 // Simplify;

azFVN[v_] := azFV /. vp \to v;
dzFV =  $\frac{vp}{azFVN[vp]}$  // Simplify;

tFV = Integrate[ $\frac{1}{azFVN[vp]}$ , {vp, Vp0, Vph}, Assumptions \to 1000 > Vp0 > Vph > 0];

tFVN[v_, v0_] := tFV /. Vph \to v /. Vp0 \to v0;
v3ms = FindRoot[tFVN[vv, Vp] - 0.003, {vv, Vp}][[1, 2]];
ZFV = Integrate[dzFV, {vp, Vp0, Vph}, Assumptions \to 1000 > Vp0 > Vph > 0];
ZFVN[v_, v0_] := ZFV /. Vph \to v /. Vp0 \to v0;

tfFV =  $\frac{tFVN[0, v3ms]}{162 + 55.3} (162) + 0.003$ ;

zfFV = ZFVN[v3ms, Vp] + ZFVN[0, v3ms]  $\frac{162}{162 + 55.3}$ ;

Print["\mu=", \mu, "      Tf=", Round[1000 tfFV, 0.1],
      "ms", "      Zf=", Round[zfFV, 0.01], "m"], {\mu, 0, .1, 0.01}]

```

$\mu=0.$	Tf=33.5ms	Zf=8.17m
$\mu=0.01$	Tf=31.6ms	Zf=7.73m
$\mu=0.02$	Tf=30.ms	Zf=7.35m
$\mu=0.03$	Tf=28.5ms	Zf=7.m
$\mu=0.04$	Tf=27.1ms	Zf=6.68m
$\mu=0.05$	Tf=25.9ms	Zf=6.39m
$\mu=0.06$	Tf=24.8ms	Zf=6.13m
$\mu=0.07$	Tf=23.7ms	Zf=5.89m
$\mu=0.08$	Tf=22.8ms	Zf=5.67m
$\mu=0.09$	Tf=21.9ms	Zf=5.46m
$\mu=0.1$	Tf=21.1ms	Zf=5.27m