



Home automation

IOT

Automatic door
unlock




Problems and Solutions:

Ever wondered if you can open the door of a room while sitting in another room? Might as well give it a try!!

Well we can do it using one of the most common commodities of our life, our phone. Wanna know how?! Then just dive in!!!



Project objective



To help people open door locks sitting in another room, just for all the laziness we pack :P.

The project also helps in increasing security as it only opens using automated biometric lock of registered user and not using some manual lock and key system.



Project Working Overview

Note: This project will work with Android phones which support fingerprint scanning.

App scans the fingerprint.

It sends bluetooth signal to bluetooth module HC-05 and then accordingly rotates the servo motor which opens or closes the lock.

Biometric match is used by The Android app and a signal(True or False) is sent to the Arduino which rotates the motor to open the lock when the signal is True and keeps it locked or locks it again depending on the state it was in if the signal is False.

Android App controls output to servo motor

Tweaks:

Facial recognition can be added to the app.



Video demonstration:



The automated door lock would look something like this:





Components used:

- Arduino UNO
- Bluetooth module HC-05
- Servo motor
- Other necessities such as wires and battery
- A mobile phone with the android lock app installed



Integration overview:

The Bluetooth module is(HC 05) operated using 3.3 V DC Arduino output.

GND pin connected to arduino

RX of Arduino to TX of HC 05,TX of Arduino to RX of HC 05

Servo motor is connected using 5V DC supply

GND and ~9 pin connected with Arduino

Initial angle of motor-false(10 degree) and when true rotates to 180 degree


setup()- switches to false(10 degree)



Code overview

```
char t;  
|  
#include <Servo.h>  
Servo servo;  
int angle = 10; //initial angle is 10 degree  
  
void setup() {  
  
    servo.attach(9);  
    servo.write(angle);  
    //set initial angle to 10 degree each time regardless of last position  
  
    Serial.begin(9600);  
  
}
```

```
void loop() {  
  if (Serial.available()) {  
    //check if app is connected through bluetooth and ready to give output  
    t = Serial.read();  
    Serial.println(t);  
  }  
  
  if (t == 'w') {  
    //move forward(all motors rotate in forward direction)  
    // Serial.println("hello"); for debugging  
  
    for (angle = 10; angle < 180; angle++)  
    {  
      servo.write(angle);  
      delay(15);  
    }  
  }  
}
```



```
else if (t == 'a') {  
    //move reverse (all motors rotate in reverse direction)  
    // Serial.println("Bye");  for debugging  
  
    for (angle = 180; angle > 10; angle--)  
    {  
        servo.write(angle);  
        delay(15);  
    }  
}  
  
delay(100);  
}
```



Relevant links:

Git repo: https://github.com/Signior-X/iot_door_unlock

Drive Link: