```
5.C Eigenspaces and Diagonal Matrices
  Friday 17 May 2024 01:46
definition: suppose TEL(V), LEF then the eigenspace E(L,T) of T corresponding to L is
                        E(\lambda,T):=\ker(T-\lambda I)
                     it is the set of all eigenvectors of T corresponding to \lambda + 0 vector
                      T-\lambda I \in L(V) \Rightarrow \ker(T-\lambda I) < V \text{ and } T|_{EQ,T} = \lambda I
proposition: V is finite dimensional and Te L(V), him we distinct eigenvalues of T then
                 E(J_1,T)+\cdots+E(J_m,T) is a direct sum
                 also,
                  dim(E(U,T)) +...+dim(E(U,T)) \le dim(V)
proof; suppose 3 some U; EEU; T) S.t. MIT. +Um=0
           as eigenvectors with distinct cisenvalues are linearly independent, U; =0 4;
           => U,+...+Um where U; EE(A; T) has unique representation.
            also, dim(EU,T)+...+dim(E(h,T))=dim(EU,T)\D.--\DE(h,T)) \le dim(V)
theorem: conditions equivalent to diagonalisability
            suppose TEL(V) where dim(V)=n, {\lambda}, ief1, m]} is distinct eigenvalues of T
            then the following ove equivalent:
             (a) T is diagonisable
             (b) V has basis consisting of Cigarvectors of T
             (c) ] I timensimal U_1,...,U_n < V , each invariant under T st. V = U_1 \oplus \cdots \oplus U_n
             (d) V = E(\lambda, T) \oplus \cdots \oplus E(\lambda_n, T)
             (e) din(V) = \sum_{i=1}^{m} din(E(\lambda_{i},T))
  proof: Wab:
            Tv = 1; v \Leftrightarrow M(T) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}
            let EV; je[I, N]} busy of V is also eigenvectors of T.
             > span(v;) is 1-dimentional subspace invovient under T
             v = $ c; v; c; eff \ v \ v \ is unique representation and c; v; e spancy)
             ⇒ V = span(v,) @ ··· · · · · · span(v,)
            let v, EU, v, to as U, is invariant under T, v, is eigenvector of T
            ⇒ cjvj∈Uj, cj∈# so direct sum ⇒ V=$ gv; is unique > {\varphi}: j∈[\lambda m]} is basis of V
           .°. (N) ←>(b) ←>(c)
           છ ⇒લે)∶
           let {V; : j ∈ [1, n]} busis of V is also eigenvectors of T.
           FICELIMI S.E. V; EE(\lambda_i,T) \JEILINI > V E[\lambda_i,T) + ···+E(\lambda_i,T) \VeV
           aheady shown by dimensionality of direct sum
           let {v,··}, he a basis of E(1,1). U{v··} has length in c=(e)
           re-lable the vanion of all basis of E(\lambda_i,T) as \{v_j:j\in E(i,n)\}
           suppose a; v; = 0 where a = F, j = [1.n]
```

corollery; if TGL(V) has dim(V) distinct eigenvalues, T is diagonalisable

=> d; V;= = u eigenvectors with distinct eigenvelve one linearly independent ⇒ Ui = 0 ¥ i € [1, m] => ax Vx=0 se. Vx ∈ E(λi, T) and vx is major of E(λi, T) => dk=0+k=) aj=0+jeft,n] => {vj.jeft,n]} is limerly independent

let u; = a,v, st. v, E E(), 1)

. (a) <=> (b) <=> (v)