

# Potential Flow

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## Introduction

This document contains the derivation of a mathematical model used to solve for the airflow around a given aircraft geometry. It assumes potential flow and is accordingly limited in its applicability.

## 1 Problem statement

Given a finite time-invariant parametrized closed surface  $S \subset \mathbb{R}^3$  and sufficient far field boundary conditions, find the pressure distribution on  $S$  caused by and adiabatic inviscid irrotational flow given by

$$\vec{u} = \nabla \phi \quad (1)$$

where  $\vec{u} = \vec{u}(\vec{x}, t)$  is the flow velocity vector and  $\phi = \phi(\vec{x}, t)$  is the velocity potential at some position vector  $\vec{x} \in \mathbb{R}^3$  and time coordinate  $t \in \mathbb{R}$ .

### 1.1 Far field boundary conditions

Given a Cartesian coordinate system in  $\mathbb{R}^3$  centered near  $S$  with a position vector  $\vec{x}$ , we write the far field boundary conditions as

$$\lim_{|\vec{x}| \rightarrow \infty} p(\vec{x}) = p_\infty = \text{const.} \quad (2a)$$

$$\lim_{|\vec{x}| \rightarrow \infty} \rho(\vec{x}) = \rho_\infty = \text{const.} \quad (2b)$$

$$\lim_{|\vec{x}| \rightarrow \infty} \vec{u}(\vec{x}) = \vec{u}_\infty = \text{const.} \quad (2c)$$

### 1.2 Tangential flow

The tangential flow constraint requires that, for any normal vector  $\vec{n} = \vec{n}(\vec{x})$  to the surface  $S$ ,

$$\vec{n} \cdot \vec{u} = \vec{n} \cdot \nabla \phi = 0 \quad ; \quad \forall \vec{x} \in S \quad (3)$$

## 2 Solution

### 2.1 Helmholtz decomposition

Using Helmholtz decomposition, we get

$$\phi(\vec{x}, t) = \frac{1}{4\pi} \int_{\partial V_i} \hat{n}(\vec{x}') \cdot \frac{\nabla' \phi(\vec{x}', t)}{|\vec{x} - \vec{x}'|} dS' - \frac{1}{4\pi} \int_{V_i} \frac{\nabla'^2 \phi(\vec{x}', t)}{|\vec{x} - \vec{x}'|} dV' \quad ; \quad \forall \vec{x} \in V_i \quad (4)$$

for any compact domain  $V_i \subset \mathbb{R}^3$  with a piecewise smooth boundary  $\partial V_i$ , where the primed symbols above are with respect to the new  $\vec{x}'$  dummy variables and  $\hat{n}$  is the outward pointing unit normal vector to  $\partial V_i$ .

To extend this result to exterior domains, we define  $V_e = V - (V_i - \partial V_i)$  for some compact domain  $V \subset \mathbb{R}^3$  having a piecewise smooth boundary  $\partial V$  and then take the limit as  $V \rightarrow \mathbb{R}^3$ .

We first let  $V_e = V_{e1} \cup V_{e2}$ , where  $V_{e1} \cap V_{e2}$  is a single piecewise smooth surface containing exactly one hole and satisfying  $(V_{e1} \cap V_{e2}) \cap \partial V_i \neq \emptyset$ . Applying (4) to both  $V_{e1}$  and  $V_{e2}$  followed by summing the results leads to

$$\begin{aligned} \phi(\vec{x}, t) = & -\frac{1}{4\pi} \int_{\partial V_i} \hat{n}(\vec{x}') \cdot \frac{\nabla' \phi(\vec{x}', t)}{|\vec{x} - \vec{x}'|} dS' + \frac{1}{4\pi} \int_{\partial V} \hat{n}(\vec{x}') \cdot \frac{\nabla' \phi(\vec{x}', t)}{|\vec{x} - \vec{x}'|} dS' - \\ & - \frac{1}{4\pi} \int_{V_e} \frac{\nabla'^2 \phi(\vec{x}', t)}{|\vec{x} - \vec{x}'|} dV' \quad ; \quad \forall \vec{x} \in V_e \end{aligned}$$

We then note that applying (2c) on  $\partial V$  as  $V \rightarrow \mathbb{R}^3$  leads to

$$\begin{aligned} \frac{1}{4\pi} \int_{\partial V} \hat{n}(\vec{x}') \cdot \frac{\nabla' \phi(\vec{x}', t)}{|\vec{x} - \vec{x}'|} dS' = & -\frac{1}{4\pi} \int_{\partial V_i} \hat{n}(\vec{x}') \cdot \frac{(\vec{u}_\infty - \vec{u}_\infty)}{|\vec{x} - \vec{x}'|} dS' + \\ & + \frac{1}{4\pi} \int_{\partial V} \hat{n}(\vec{x}') \cdot \frac{\vec{u}_\infty}{|\vec{x} - \vec{x}'|} dS' - \frac{1}{4\pi} \int_{V_e} \frac{\nabla' \cdot \vec{u}_\infty}{|\vec{x} - \vec{x}'|} dV' \end{aligned}$$

since the divergence of a constant vector field is always zero, meaning that

$$\begin{aligned} \phi(\vec{x}, t) - \vec{u}_\infty \cdot \vec{x} = & -\frac{1}{4\pi} \int_{\partial V_i} \hat{n}(\vec{x}') \cdot \frac{\nabla' (\phi(\vec{x}', t) - \vec{u}_\infty \cdot \vec{x}')}{|\vec{x} - \vec{x}'|} dS' - \\ & - \frac{1}{4\pi} \int_{V_e} \frac{\nabla'^2 (\phi(\vec{x}', t) - \vec{u}_\infty \cdot \vec{x}')}{|\vec{x} - \vec{x}'|} dV' \quad ; \quad \forall \vec{x} \in V_e \quad (5) \end{aligned}$$

### 2.2 Incompressible flow

For an incompressible flow,

$$\nabla \cdot \vec{u} = \nabla \cdot \nabla \phi = \nabla^2 \phi = 0 \quad (6)$$

meaning that  $\phi$  satisfies Laplace's equation and is thereby harmonic. We note that (6), when combined with (3), (4), and (5), results in

$$\phi(\vec{x}, t) = 0 \quad ; \quad \forall \vec{x} \in V_i \quad (7)$$

and

$$\phi(\vec{x}, t) - \vec{u}_\infty \cdot \vec{x} = -\frac{1}{4\pi} \int_S \hat{n}(\vec{x}') \cdot \frac{\nabla' (\phi(\vec{x}', t) - \vec{u}_\infty \cdot \vec{x}')}{|\vec{x} - \vec{x}'|} dS' \quad ; \quad \forall \vec{x} \in V_e \quad (8)$$

Defining the source strength  $\sigma(\vec{x}, t) = \hat{n}(\vec{x}) \cdot \nabla (\phi(\vec{x}, t) - \vec{u}_\infty \cdot \vec{x})$ , allows us to write (8) as

$$\phi(\vec{x}, t) = \vec{u}_\infty \cdot \vec{x} - \frac{1}{4\pi} \int_S \frac{\sigma(\vec{x}', t)}{|\vec{x} - \vec{x}'|} dS' \quad ; \quad \forall \vec{x} \in V_e$$

For  $\phi$  to be single-valued and continuous, we equate (7) with (8) on  $V_e \cap V_i = S$  and simplify to get the condition

$$\frac{1}{4\pi} \int_S \frac{\sigma(\vec{x}', t)}{|\vec{x} - \vec{x}'|} dS' = \vec{u}_\infty \cdot \vec{x} \quad ; \quad \forall \vec{x} \in S$$