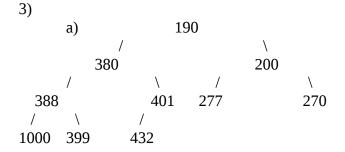
Simon Chen N10013388 sc4900 Homework 11

1) O(nlogn + klogn) nlogn is to build the heap from the array klogn is thhe time it takes to get the min and

insert(x) : O(1) amortized
deleteMin(x) : O(ln)
findMin(x) : O(n)



The 197 will get swapped with the parent until it is less than the parent.

The array will change as followed:

| Sentinel | 190 | 380 | 200 | 388 | 401 | 277 | 270 | 1000 | 399 | 432 | 197 |

197 swapped: with the parent, 401
| Sentinel | 190 | 380 | 200 | 388 | 197 | 277 | 270 | 1000 | 399 | 432 | 401 |

197 swapped: with the parent, 380
| Sentinel | 190 | 197 | 200 | 388 | 380 | 277 | 270 | 1000 | 399 | 432 | 401 |

Done with swapping. Tree is now:

}

```
190
                                   200
           197
                                           \
  388
                    380
                           277
                                           270
1000 399
                 432
                       401
4)
a)
              2 | 3 | 4 | 6 | 8 | 70 | 5 | 9 | 7 | 19 | 27 |
| Sentinel |
b)
Root is removed:
                     3
           6
                                    4
  7
                    8
                           70
                                            5
               19
       27
5)
template <class Comparable>
void BinaryHeap<Comparable>::insert( const Comparable & x)
{
       if (theSize + 1 == array.size()){
              array.resize( array.size() * 2 + 1);
       }
       int hole = ++theSize;
       for (; x < array[hole/2] \&\& hole > 0; hole /= 2)
              array[hole] = move(array[hole/2])
       array[hole] = x;
```

6)

The results of using the linear-time algorithm is to first insert the tree then make the tree follow the order of a binary tree heap.

The array will be | Sentinel | 10 | 12 | 1 | 14 | 6 | 5 | 8 | 15 | 3 | 7 | 4 | 11 | 10 | 0 |

The tree will be

Now percolate up to make it have the heap order while swapping. The end result will be.

The array will be | Sentinel | 0 | 3 | 1 | 12 | 4 | 5 | 8 | 15 | 14 | 7 | 6 | 11 | 10 | 10 |

$$G \rightarrow F \rightarrow E \rightarrow D \rightarrow C$$

8)
Adj. List
$$A \rightarrow (D,3) \rightarrow (B,6) \rightarrow (E,1)$$

$$B \rightarrow (A,6) \rightarrow (D,0) \rightarrow (C,5)$$

$$C \rightarrow (D,12) \rightarrow (B,5) \rightarrow (E,18) \rightarrow (G,5)$$

$$D \rightarrow (A,3) \rightarrow (B,0) \rightarrow (C,12) \rightarrow (F,3)$$

$$E \rightarrow (A,1) \rightarrow (C,18) \rightarrow (G,19)$$

$$F \rightarrow (D,3) \rightarrow (G,14)$$

$$G \rightarrow (E,19) \rightarrow (C,5) \rightarrow (F,14)$$

Adj. Matrix

A	В	C	D	E	F	G
	6		3	1		
6		5	0			
	5		12	18		5
3	0	12			3	
1		18				19
			3			14
		5		19	14	

9)									
phase	distance/pre						Visit	Discovered	
	A	В	C	D	\mathbf{E}	F	G		
init	0								A
1	0	6/A		3/A	1/A			A	B D E
2	0	6/A	19/E	3/A	1/A		20/E	E	B D C G
3	0	3/A	15/E	3/A	1/A	6/D	20/E	D	B C G F
4	0	3/D	8/B	3/A	1/A	6/D	20/E	В	C G F
5	0	3/D	8/B	3/A	1/A	6/D	20/E	F	C G
5	0	3/D	8/B	3/A	1/A	6/D	13/E	С	G
5	0	3/D	8/B	3/A	1/A	6/D	13/E	G	

Dijkstra's algorithm will close off the path to C and ignore that the shortest weighted path to C is A B C

11) You can modify Dijstra's algorithm to keep track of all the paths so that when the path is the same value as the closed path it will count that as an alternative path.

DFS Starting from the Top to Bottom

 $A \rightarrow D \rightarrow G \rightarrow C \rightarrow B \rightarrow A$

 $A \rightarrow B$ (already discovered)

 $A \rightarrow E$

(everything is discovered now)

BFS Starting from Top to Bottom

 $A \rightarrow D$

 $A \rightarrow B$

 $A \rightarrow E$

 $D\,\to\, F$

 $B \rightarrow C$

 $E \rightarrow C$ (Already discovered)

 $F \rightarrow G$

 $C \rightarrow G(Already discovered)$

 $G \rightarrow C(Already discovered)$

 $G \rightarrow E(Already discovered)$

13)

