cmu-gpr-dataset	
├─ time_s-time_ns-loc-cmu-gpr	
	# Ground truth positions
gpr_meas.csv	# GPR measurements
	# IMU measurements
	# Wheel encoder measurements
	ong # RGB camera image
└	
(a)	
Measurement Type	Measurement CSV Value
	$[t_{\text{stamp}}, amp_1,, amp_{201}]$
GPR Measurement:	Amplitude of 1D Trace
[t _{stamp} , a _x , a _y , a _{z1} , g _x , g _y , g _{z1} , w, x, y, z]	
IMU Measurement:	t stamp, dx, dy, dz, Sx, Sy, Sz, W, X, Y, Z
intermediation.	Accelerometer Gyroscope Magnetometer $\frac{[m/s^2]}{[rad/s]}$
Wheel Encoder Measurement:	$[t_{\mathrm{stamp}}, dist_{\mathrm{x}}]$
	Signed distance traversed [m]
	U

 $[~t_{stamp},~p_x,~p_y,~p_z]$

(b)

Ground truth position [m]

Total Station Measurement: