



Ecuación principal

$$\rightarrow F_a(t) = F_z(t) + F_L(t) = F_c(t) + F_R(t)$$

$$\rightarrow F_z(t) = \frac{P_a(t) - P_p(t)}{Z}$$

$$\rightarrow F_L(t) = \frac{1}{L} \int [P_a(t) - P_p(t)] dt$$

$$\rightarrow F_c(t) = \frac{C d P_p(t)}{dt}$$

$$\rightarrow F_R(t) = \frac{P_p(t)}{R}$$

Procedimiento algebraico

$$\frac{P_a(t)}{Z} - \frac{P_p(t)}{Z} + \frac{1}{L} \int [P_a(t) - P_p(t)] dt = \frac{C d P_p(t)}{dt} + \frac{P_p(t)}{R}$$

$$\frac{P_a(s)}{Z} - \frac{P_p(s)}{Z} + \frac{P_a(s) - P_p(s)}{LS} = CS P_p(s) + \frac{P_p(s)}{R}$$

$$\left(\frac{1}{Z} + \frac{1}{LS} \right) P_a(s) = \left(CS + \frac{1}{R} + \frac{1}{Z} + \frac{1}{LS} \right) P_p(s)$$

$$\frac{LS+Z}{LZS} P_d(s) = \frac{CLS^2 + LZS + RLS + RZ + CLZS^2}{RLZS}$$

$$\frac{P_p(s)}{P_d(s)} = \frac{\frac{LS+Z}{LZS}}{\frac{CLS^2 + (LZ + RL)S + RZ}{RLZS}}$$

$$\frac{P_p(s)}{P_d(s)} = \frac{RLS + RZ}{CLRZS^2 + (LZ + RL)S + RZ}$$

Error en estado estacionario

$$e(s) = \lim_{s \rightarrow 0} s P_d(s) \left[1 - \frac{P_p(s)}{P_d(s)} \right]$$

$$= \lim_{s \rightarrow 0} \cancel{s} \cdot \frac{1}{\cancel{s}} \left[1 - \frac{RLS + RZ}{CLRZS^2 + (LZ + RL)S + RZ} \right]$$

$$= 1 - \frac{RZ}{RZ} = 0V$$

Estabilidad en lazo abierto

$$\lambda_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$\begin{aligned} a &= CLRZ \\ b &= LZ + RL \\ c &= RZ \end{aligned}$$

$$\lambda_{1,2} = \frac{-(LZ + RL) \pm \sqrt{(LZ + RL)^2 - 4CLRZ^2}}{2CLRZ}$$

El sistema tiene una respuesta estable porque $\text{Re} \lambda_{1,2} < 0$

Modelo de ecuaciones integro-diferenciales

$$P_p(t) = \left(\frac{1}{R} + \frac{1}{Z} \right) = \frac{P_a(t)}{Z} + \frac{1}{L} \int [P_a(t) - P_p(t)] dt - \frac{cd}{dt} P_p(t)$$

$$P_p(t) = \left(\frac{P_a(t)}{Z} + \frac{1}{L} \int [P_a(t) - P_p(t)] dt - \frac{cd}{dt} P_p(t) \right) \frac{Z R}{Z + R}$$

