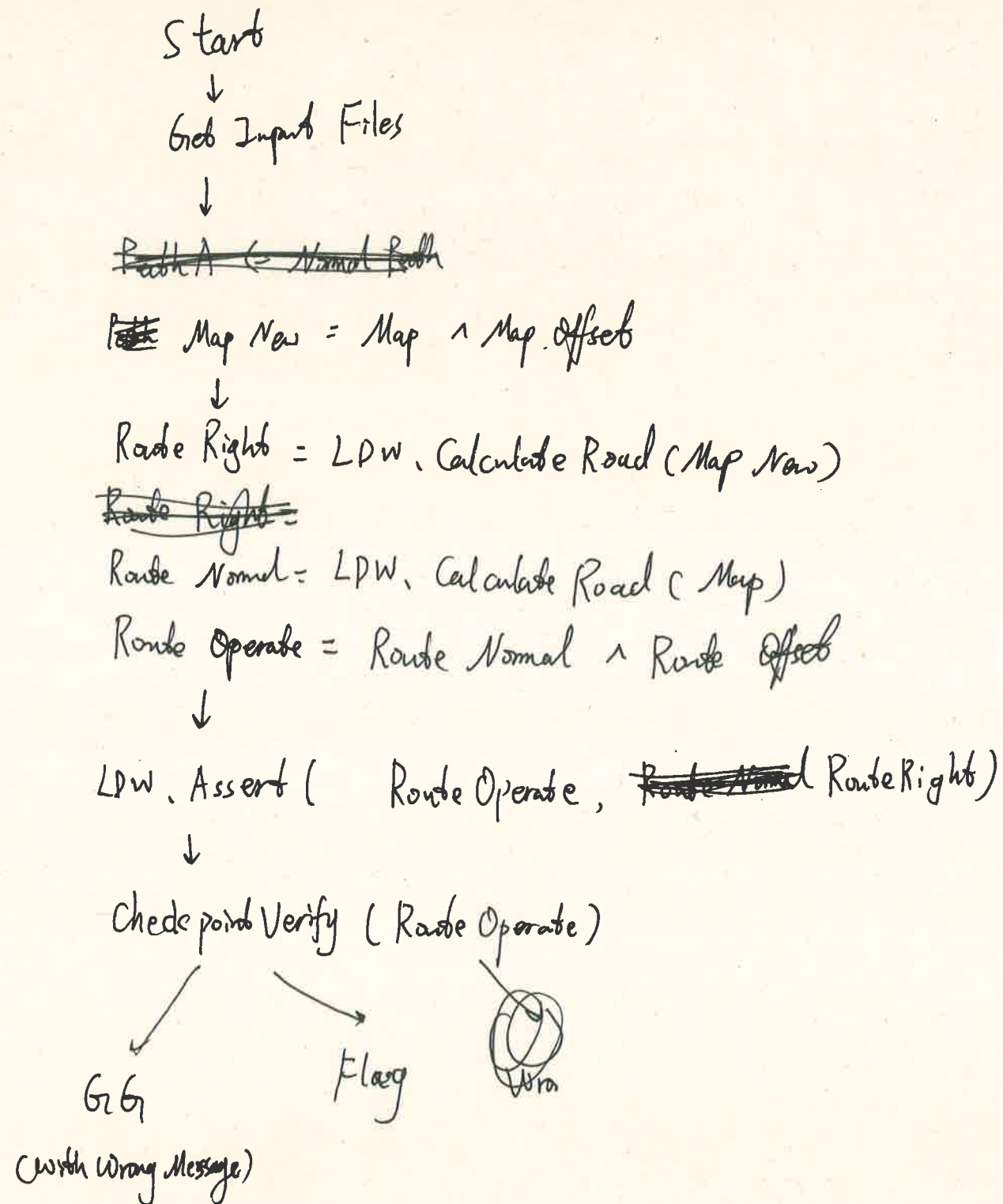


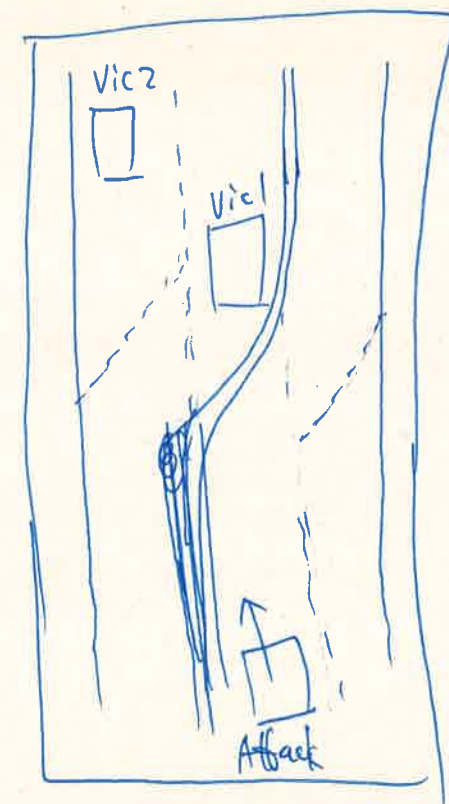
Workflow V2:

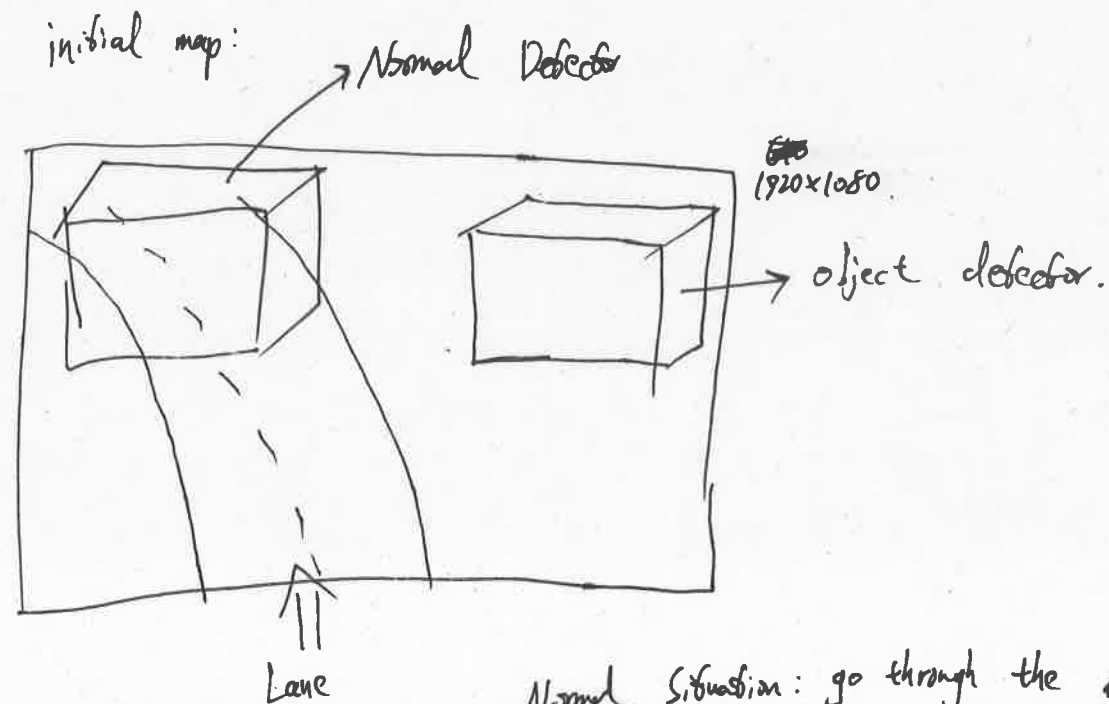
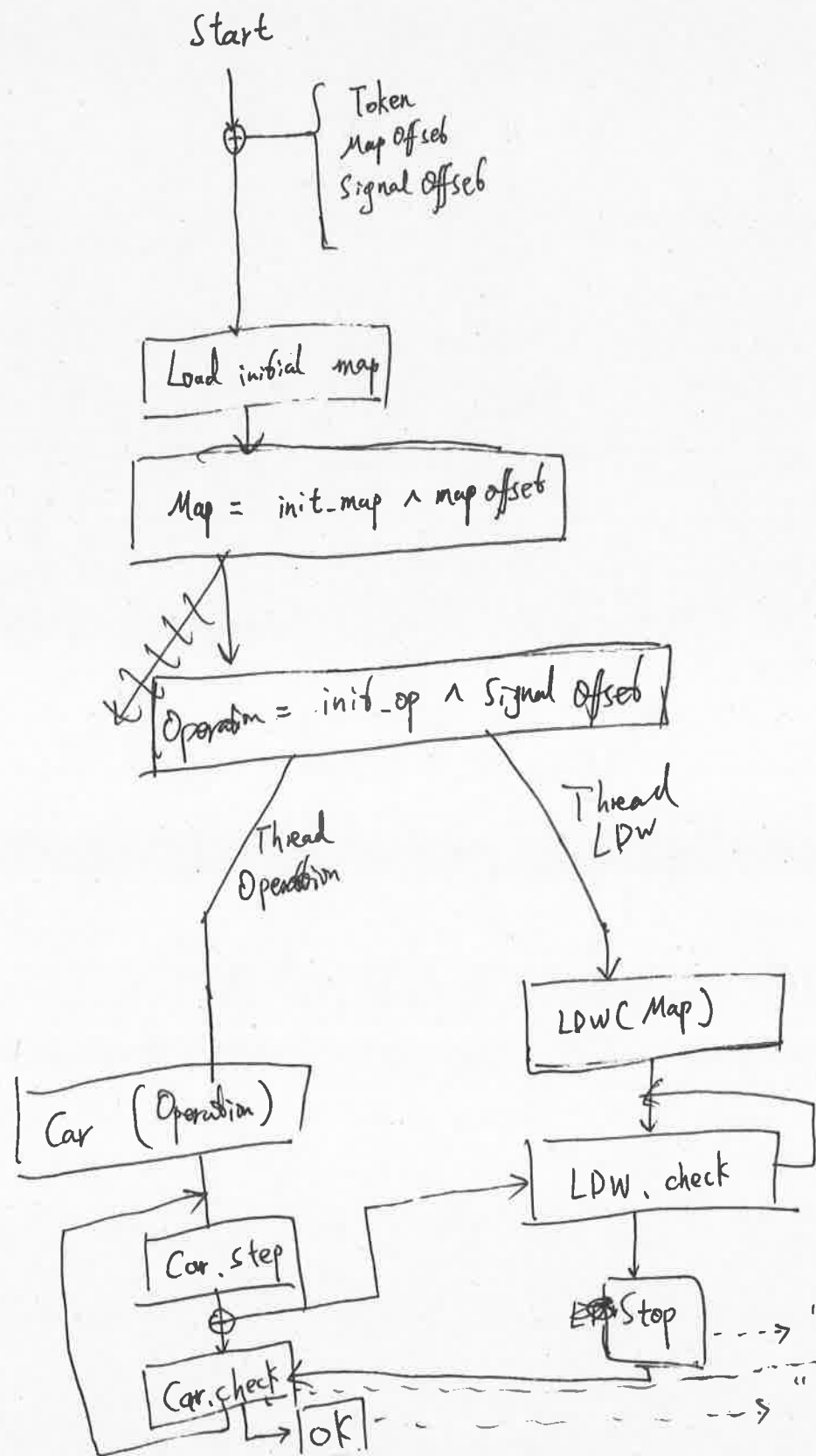


Possible V3:

Use a irregular map.

New Map?





Normal Situation: go through the normal detector
 Right Situation: go through the object detector
 Required: Monitored & Stopped by LDW
 Lane Departure Warning

"Not a good Driver!"

"Good Driver but too good to be true"

Flag is { }