

Probabilistic Tracking using Stereo Cameras

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Chapter 1

Data Structure Documentation

1.1 annotatePosPose Class Reference

Class for annotating both positions and poses of the people in the images.

Data Structures

- struct [ANNOTATION](#)
A structure that stores annotations.

Public Types

- enum [POSE](#) { [SITTING](#), [STANDING](#), [BENDING](#), [ORIENTATION](#) }
All considered poses.

Static Public Member Functions

- static void [mouseHandlerAnn](#) (int event, int x, int y, int flags, void *param)
Mouse handler for annotating people's positions and poses.
- static void [showMenu](#) (cv::Point center)
Draws the "menu" of possible poses for the current position.
- static int [runAnn](#) (int argc, char **argv)
Starts the annotation of the images.
- static void [trackbar_callback](#) (int position, void *param)
The "on change" handler for the track-bars.
- static void [trackBarHandleFct](#) (int position, void *param)
A function that starts a new thread which handles the track-bar event.

1.2 `annotatePosPose::ANNOTATION` Struct Reference

A structure that stores annotations.

Data Fields

- `cv::Point` **location**
- `vector< unsigned int >` **poses**

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