

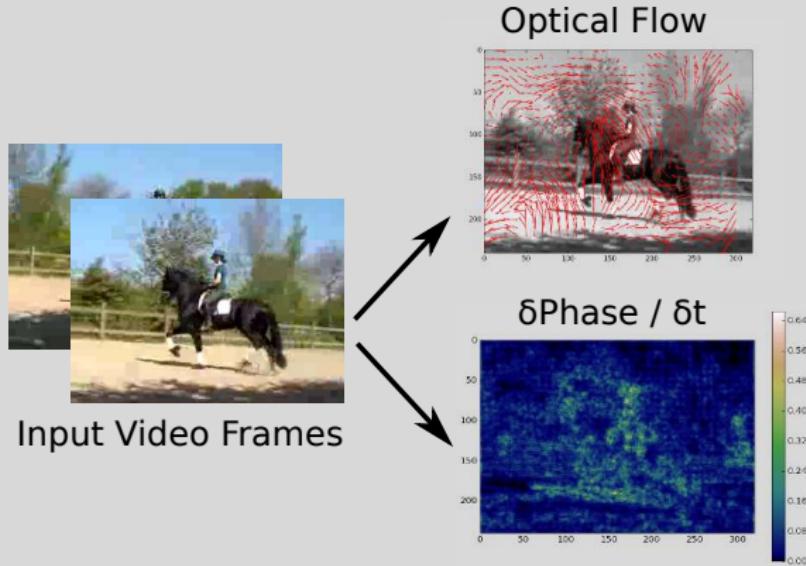


## Making a Case for Learning Motion Representations with Phase

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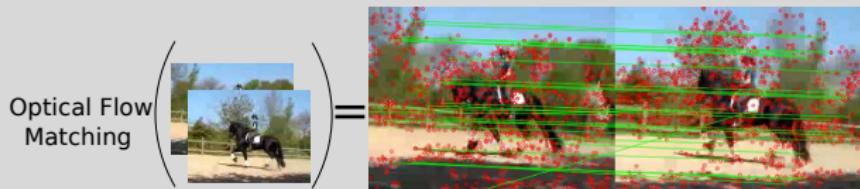
# Eulerian versus Lagrangian Motion



- ▶ Lagrangian motion (optical flow) estimates the changes in position over time
  - match points/patches.
- ▶ Eulerian approach (phase variations over time) flux statistics over time
  - number of measurements stays constant.

## Gains of Eulerian Motion

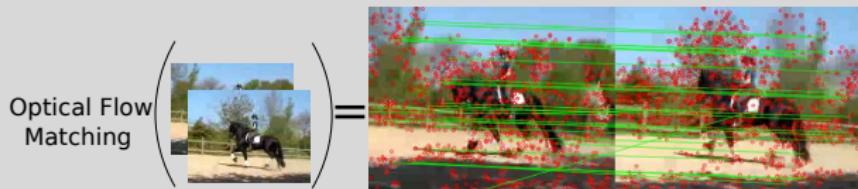
- ▶ **No feature extraction and matching** of patches between frames.
- ▶ **No missing correspondences**, rotating objects, occlusion.



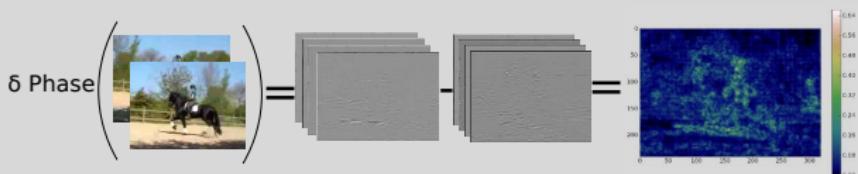
We focus on phase-based motion [Wadhwa et. al., SIGGRAPH, 2013].

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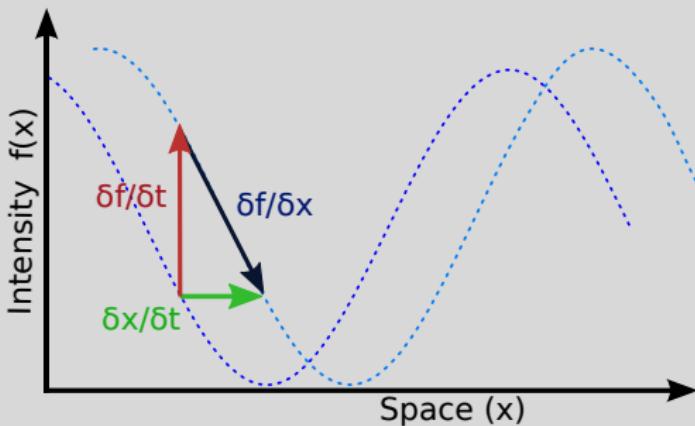


- ▶ **Constant number of measurements** over time.
- ▶ Phase information is **innate** to the image.



We focus on phase-based motion [Wadhwa et. al., SIGGRAPH, 2013].

## Phase-based Motion



[Fleet et. al., IJCV, 1990] show that the temporal gradient of the phase over a spatially band-passed video over time directly relates to the motion field.

## Phase-based Motion

- ▶ Local motion  $\leftrightarrow$  local edges with different orientations.
- ▶ Using a steerable pyramid [Simoncelli, Trans. on Info. Theory, 1992] we decompose the image into localized subbands.
- ▶ The local-phase variations over time, give the local motion.

$$(G_\sigma^\theta + iH_\sigma^\theta) \otimes I(x, y) = A_\sigma^\theta(x, y) e^{i\phi_\sigma^\theta(x, y)}$$

↑  
Image  
Channels

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Complex Filters  
scale -  $\sigma$   
orientation -  $\theta$

Image  
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Image Channels

Amplitude

Phase

The diagram illustrates the decomposition of an image  $I(x, y)$  using complex filters. The expression  $(G_\sigma^\theta + iH_\sigma^\theta) \otimes I(x, y)$  is shown in a horizontal bar. Four red ovals highlight specific parts of the equation, each with a corresponding label below it:

- The first oval covers  $(G_\sigma^\theta + iH_\sigma^\theta)$ , labeled "Complex Filters scale -  $\sigma$  orientation -  $\theta$ ".
- The second oval covers  $I(x, y)$ , labeled "Image Channels".
- The third oval covers  $A_\sigma^\theta(x, y)$ , labeled "Amplitude".
- The fourth oval covers  $e^{i\phi_\sigma^\theta(x, y)}$ , labeled "Phase".

## 4 Phase Applications

1. Action Recognition
  - Starting point: Two stream network [Simonyan et. al., CVPR, 2014].
2. Motion Prediction in Static Images
  - Starting point: RCNNs [Liang et. al., CVPR 2015], [Pinheiro et.al., ICML 2014].
3. \*Motion Transfer in Static Images
  - Starting point: Artistic style transfer [Gatys et. al., 2015].
4. \*Motion Transfer in Videos
  - Starting point: Artistic style transfer in videos [Ruder et. al., 2016]

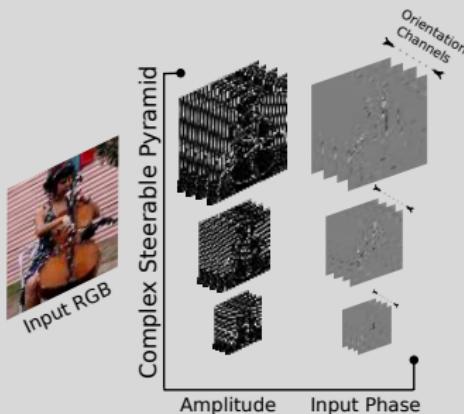
## 4 Phase Applications

- ▶ Convolve the input frame/image with the steerable complex filters.



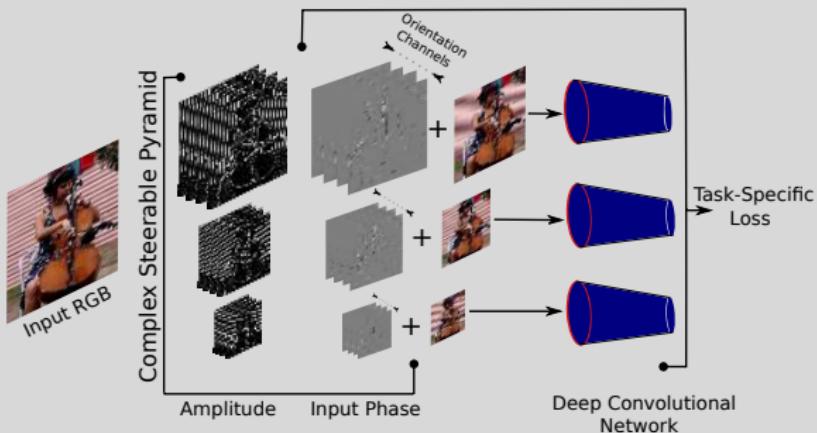
## 4 Phase Applications

- Get oriented amplitude and phase at different scales.

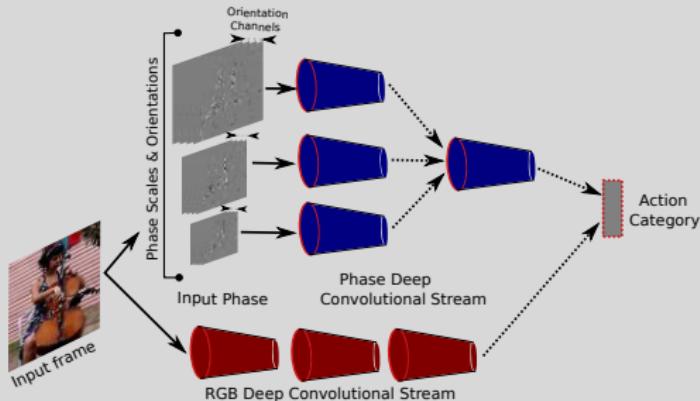


## 4 Phase Applications

- ▶ Add the image appearance info into a deep net formulation.



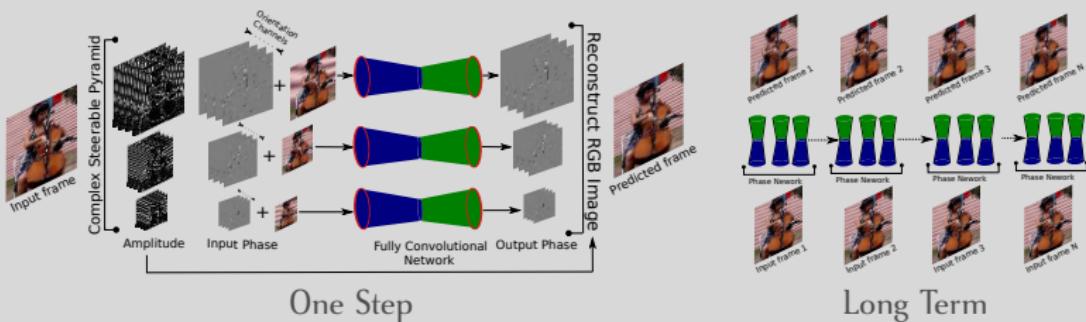
# Phase-based Action Recognition



## Experimental Setup:

- ▶ Compare against [Simonyan et. al., CVPR, 2014].
- ▶ Action Recognition datasets: HMDB51 and UCF101.

# Phase-based Motion Prediction in Static

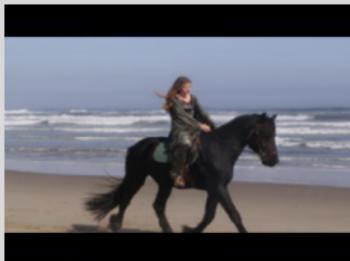


## Experimental Setup:

- ▶ Compare against optical-flow motion prediction [Walke, ICCV, 2015].
- ▶ Motion prediction datasets: HMDB51 and UCF101.

## Phase-based Motion Transfer in Static

Given an input **static image** transfer the style of a video motion.



Static

Video

Transferred

## Phase-based Motion Transfer

In static:

- ▶ Correctly aligning the parts of the objects that have similar motion is essential for the motion transfer task.
- ▶ We propose to add a weight pixels-wise correlation to the "style loss" of [Gatys et. al., 2015].

In video:

- ▶ Follow [Ruder et. al., 2016] and add a temporal constraint between the transferred frame phases.

## Conclusions

- ▶ We propose an Eulerian — phase-based — approach to motion representation learning.
- ▶ We argue for the intrinsic stability of the phase-based motion description.
- ▶ We explore a set of motion learning tasks in an Eulerian setting:
  - ▶ (a) action recognition,
  - ▶ (b) motion prediction in static images,
  - ▶ (c) motion transfer from a video to a static image and
  - ▶ (d) motion transfer in videos.

And we propose a phase-based approach.

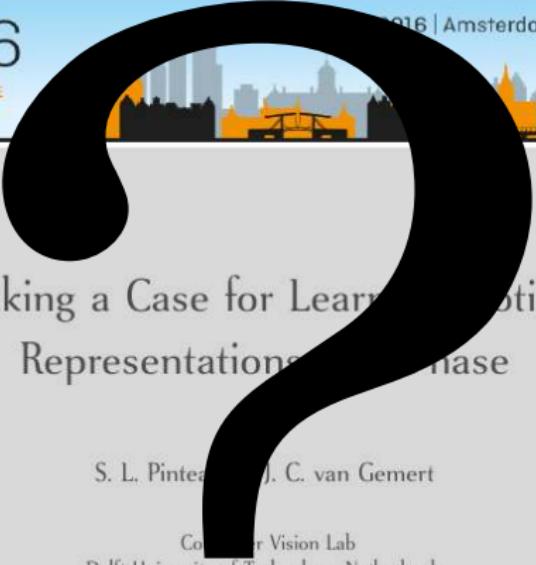
- ▶ We provide a small proof of concept.

Thank you

ECCV'16

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# Making a Case for Learning Motion Representations in a Sparse

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