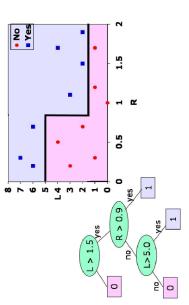
Linear Classifiers I: Perceptron

E.g. Decision Tree Boundary Classification as Boundary:



Linear Hypothesis Class

- Line equation (assume 2D first): $w_2x_2+w_1x_1+b=0$

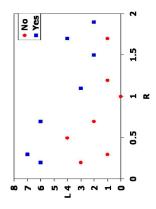
Fact1: All points (x_1, x_2) lying on the line make the equation true.

- Fact2: The line separates the plane in two half-planes.
- **Fact3**: The points (x_1, x_2) in one half-plane give us an inequality with respect to 0, which has the same direction for each of the points in the half-plane.
- **Fact4**: The points (x_1, x_2) in the other half-plane give us the reverse inequality with respect to 0.

Bankruptcy example

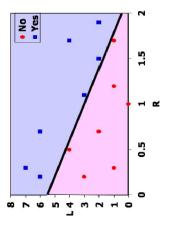
 \boldsymbol{R} is the ratio of earnings to expenses \boldsymbol{L} is the number of late payments on credit cards over the past year.

We would like to draw a linear separator, and thus get a classifier.



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Simple Linear Boundary



Fact 3 proof

 $w_2x_2+w_1x_1+b=0$

We can write it as:

$$x_2 = -\frac{w_1}{w_2} x_1 - \frac{b}{w_2}$$

(p,r) is on the line so:

 \overline{q}

9 For q < r, so we have: $q < r = -\frac{w_1}{m}p$ $r = -\frac{w_1}{w_2} \, p - \frac{b}{w_2}$

i.e.

$$w_2q + w_1p + b < 0$$
 if w_2

$$w_2q + w_1p + b < 0$$
 if $w_2 > 0$
 $w_2q + w_1p + b > 0$ if $w_2 < 0$

Since (p,q) was an arbitrary point in the half-plane, we say that the same direction of inequality holds for any other point of the half-plane. Fact 4 is similar.

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2

Linear classifier

One small change

$$h(\mathbf{x}, \mathbf{w}, b) = sign(\mathbf{w} \cdot \mathbf{x} + b)$$

Which outputs
$$+1$$
 or -1 .

+1 corresponds to blue, and

-1 to red, or vice versa.

Learning Algorithm

Start with random w's

Training tuples

 $\mathbf{x}^1, \mathbf{y}^1$ $\mathbf{x}^2, \mathbf{y}^2$

 $\mathbf{x}^n, \mathcal{Y}^n$

It can be shown that if the data is linearly separable, and we repeat this procedure many times, we will get a line that separates the training tuples.

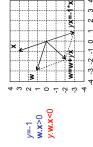
$h(\mathbf{x}, \mathbf{w}) = \operatorname{sign}\left(\left(\sum_{i=1}^{m} w_i x_i\right) + w_0\right)$ $\mathbf{w} = \left[w_0, w_1, ..., w_m\right]$ $h(\mathbf{x}, \mathbf{w}) = \operatorname{sign}\left(\sum_{i=0}^{m} w_i x_i\right)$ $= \operatorname{sign}(\mathbf{w}^T \mathbf{x})$ $= sign(\mathbf{w} \cdot \mathbf{x})$ $\mathbf{x} = \begin{bmatrix} 1, x_1, ..., x_m \end{bmatrix}$ $h(\mathbf{x}, \mathbf{w}, b) = \operatorname{sign}\left(\left(\sum_{i=1}^{m} w_i x_i\right) + b\right)$

Recall the dot product

$$A \cdot B = \sum_{i} A_i B_i$$
$$= ||A|| * ||B|| * cos(\theta)$$

- $\|A\|$ and $\|B\|$ can only be positive $\cos(\theta)$ is negative when the angle is between ½ pi and 3/2 pi that is, when the angle is obtuse

y=+1 w.x<0 y.w.x<0



For each misclassified training tuple, e.g. Well, why is this a good rule? $sign(\mathbf{w}^T \mathbf{x}^k) \neq y^k$ $\mathbf{w} = \mathbf{w} + \eta \cdot y^k \mathbf{x}^k$ $h(\mathbf{x}, \mathbf{w}) = \operatorname{sign}(\mathbf{w}^T \mathbf{x})$ Update w

Sign of dot product and misclassification