Table 1: Success Rate Heatmap: Color-coded Success Rates Across All Optimizer-Problem Combinations

Problem	Adam	Adam-AMSGrad	Adam-Fast	Adam-Robust	Adam-WeightDecay	ŒD	GD-AdaptiveMomentum	GD-Momentum	GD-Nesterov	GD-Weight Decay	L-BFGS	L-BFGS-Aggressive	L-BFGS-Conservative	L-BFGS-Limited	L-BFGS-MoreThuente	QQN-Bisection-1	QQN-Bisection-2	QQN-CubicQuadraticInterpolation	QQN-GoldenSection	QQN-StrongWolfe	Trust Region-Adaptive	Trust Region-Aggressive	Trust Region-Conservative	Trust Region-Precise	Trust Region-Standard
Sphere_2D	40%	0%	30%	0%	100%	100%	60%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	35%	30%	100%	55%	10%
Sphere_10D	95%		0%		100%	100%	60%	75%	65%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	30%		35%	65%	15%
Rosenbrock 2D Rosenbrock 5D	0%		60%		60%		25%		10%	60%			100%	0% 45%	95% 70%	5% 85%	30% 55%	40% 70%	10% 55%	35% 100%					0%
Rosenbrock_5D Rosenbrock_10D	90%	100%	5% 45%		100%	75%		55%	100%	100%			100%	45% 100%	95%	100%	100%	100%	100%	100%		30%			0%
Michalewicz_2D_m10	50%	30%	40%		0%	0%		0%	10%	0%	10%		0%	25%	25%	0%	0%	0%	0%	0%		0%			0%
Michalewicz_5D_m10	80%	55%	65%	10%	10%	45%			5%		0%		30%	0%	5%	20%	35%			25%					0%
Michalewicz_10D_m10	20%	30%	35%																						0%
Rastrigin_2D	55%	55%	0%	15%	50%		0%	0%	5%	5%			75%	70%	55%	65%	30%	80%	55%	65%	15%	0%		10%	0%
Rastrigin_5D Rastrigin_10D	30%	40%	40% 30%	55%	55%	30% 35%	65% 40%	5%	45% 25%	50%			40% 20%	35% 50%	50% 65%	25% 45%	15% 15%	50% 60%	35% 50%	40% 40%	60%	50%		35%	45% 25%
Ackley_2D_a20_b0.2_c6.28e0	30% 0%	55% 0%	30% 0%	30% 0%	35% 0%	35% 0%	0%	10% 0%	25% 0%	45% 0%	50%	20%	0%	15%	45%	60%	40%	40%	35%	40% 15%	40% 5%	45% 0%			0%
Ackley_5D_a20_b0.2_c6.28e0	0%										25%	20%	0%	0%	10%	30%	35%	5%	5%	5%					0%
Ackley_10D_a20_b0.2_c6.28e0	0%										15%	5%			5%	10%	20%								0%
StyblinskiTang_2D	0%		35%		80%	65%	5%	15%	10%	35%	50%		90%	70%	70%	70%	75%	70%	90%	65%	70%	20%			40%
StyblinskiTang_5D	0%		55%		65% 35%	50%	10%	15%	30% 30%	60%	30%		65% 30%	50% 35%	50%	60%	60%	45% 15%	70% 45%	40% 15%	65%	45%			55% 40%
StyblinskiTang_10D Beale_2D	0%		30% 0%		100%	25% 100%	20% 80%	15% 5%	100%	45% 100%	45% 65%		100%	100%	35% 100%	30% 95%	35% 70%	95%	100%	90%		50%		45%	0%
Levi_2D	0%				0%	0%	0%	0%	0%	0%	15%		0%	25%	15%	15%	20%	40%	45%	25%				0%	0%
GoldsteinPrice_2D	0%										5%			0%	5%	20%		15%	35%	15%					0%
Matyas_2D	100%	100%	100%	100%	100%	100%	95%	100%	100%	100%	100%	95%	100%	100%	100%	100%	100%	100%	100%	100%					0%
Himmelblau_2D	0%				100%	100%			40%	75%	35%		100%	100%	100%	100%	100%	100%	100%	100%	100%	25%			80%
Booth_2D Griewank_2D	0% 0%				100%	100%				15% 0%	100%		100%	100%	100%	100%	100%	100%	100%	100%	90%	0% 0%			0% 0%
Griewank_5D	0%																								0%
Griewank_10D	0%																								0%
Schwefel_2D	0%																			50%					0%
Schwefel_5D	0%																			50%					0%
Schwefel_10D Levy_2D	0% 0%				0% 100%					0% 100%	0% 80%	0% 70%	0% 85%	0% 95%	0% 95%	0% 100%	0% 100%	0% 100%	0% 100%	50% 100%					0% 0%
Levy_5D	0%				60%			10%	25%	100%	80%	75%	100%	70%	100%	100%	100%	100%	100%	100%					0%
Levy_10D	0%				0%			0%	0%	100%	80%	25%	100%	80%	100%	100%	100%	100%	100%	100%					0%
Zakharov_2D	0%				100%	100%				25%	60%	70%	75%	90%	100%	100%	100%	100%	100%	100%					0%
Zakharov_5D	0%				60%	100%				25%			100%	95%	100%	100%	100%	100%	100%	100%					0%
Zakharov_10D IllConditionedRosenbrock_2D_alpha100	0% 0%					10%				30% 0%			80%	55%	65%	100%	100% 25%	100% 35%	100%	95% 20%					0% 0%
IllConditionedRosenbrock_5D_alpha100	0%												0%		20%	80%	15%	65%	35%	100%					0%
IllConditionedRosenbrock_10D_alpha100	0%														0%	65%	5%	75%	0%	70%					0%
Trigonometric_2D	100%	85%	5%		75%	100%				85%	90%	80%	100%	90%	100%	100%	100%	100%	95%	100%					0%
Trigonometric_5D	85%	35%	0%	20%	70%	100%				75%			90%	95%	75%	90%	80%	100%	100%	90%					0%
Trigonometric_10D PenaltyI_2D_alpha1e6	35% 0%			10%	70%	55% 0%				85%			25% 0%		60% 0%	85% 0%	75% 0%	100%	80% 0%	100%					0% 0%
PenaltyI_5D_alpha1e6	0%																								0%
PenaltyI_10D_alpha1e6	0%																								0%
Barrier_2D_mu0.1	0%																								0%
Barrier_5D_mu0.1	0%																								0%
Barrier_10D_mu0.1 NoisySphere_2D_sigma0.01	0% 0%		0% 35%			0% 35%	30%	35%	0% 25%	25%	40%		80%	45%	15%	35%				60%					0% 0%
NoisySphere_5D_sigma0.01	0%		10%			20%	15%	25%	30%	25%	20%		85%	55%	25%	45%			10%	45%					0%
NoisySphere_10D_sigma0.01	0%		15%			10%	35%	10%	15%	5%	20%		85%	45%	10%	45%			5%	25%					0%
SparseRosenbrock_4D	0%		0%			0%	0%	0%	0%		0%		0%	0%	20%	15%		45%		25%					0%
SparseRosenbrock_10D	0%				0%	0%				0%	0%	0%	0%	0%	0%	20%	0%	55%	5%	45%					0%
SparseQuadratic_5D_pattern[1, 3] SparseQuadratic_10D_pattern[1, 3]	0%				100% 100%	100% 100%				100% 100%	100% 90%	100% 100%	100%	100%	100% 100%	100%	100% 100%	100% 100%	100% 100%	100% 100%					0% 0%
SparseQuadratic_10D_pattern[1, 3] LogisticRegression_100samples_5features_reg0.01	0%				0%	0%				0%	0%	0%	100%	100%	0%	100%	0%	100%	0%	0%					0%
LogisticRegression_200samples_10features_reg0.01	0%																								0%
LinearRegression_100samples_5features_reg0.01	0%					0%													0%						0%
LinearRegression_200samples_10features_reg0.01	0%		20%		0%	100%				100%	90%	100%	100%	100%	100%	100%	100%	100%	100%	100%					0%
NeuralNetwork_100samples_layers_5_10_3 NeuralNetwork_100samples_layers_10_20_5	10% 10%		60% 50%		85% 100%								45% 20%	45%	15%	95% 100%	90% 100%	80% 100%	75% 85%	45% 70%					0% 0%
SVM_100samples_5features_C1	100%	90%	0%	50%	100%	100%				100%	100%	100%	100%	90%	100%	100%	100%	100%	90%	100%					0%
SVM_200samples_10features_C1	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%

**Legend:** 90-100% Excellent, 50-89% Good, 10-49% Poor, 0-9% Very Poor, N/A No Data. Quickly identifies which optimizers work on which problem types.