Table 1: Success Rate Heatmap: Color-coded Success Rates Across All Optimizer-Problem Combinations

Problem	Adam	Adam-AMSGrad	Adam-Fast	Adam-Robust	Adam-WeightDecay	GD	GD-AdaptiveMomentum	GD-Momentum	GD-Nesterov	GD-WeightDecay	LBFGS	L-BFGS-Aggressive	L-BFGS-Conservative	L-BFGS-Limited	L-BFGS-MoreThuente	QQN-Bisection-1	QQN-Bisection-2	QQN-CubicQuadraticInterpolation	QQN-GoldenSection	QQN-Strong Wolfe	Trust Region-Adaptive	Trust Region-Aggressive	Trust Region-Conservative	Trust Region-Precise	Trust Region-Standard
Sphere_2D	40%	0%	30%	0%	100%	100%	60%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	35%	30%	100%	55%	10%
Sphere_10D Rosenbrock_2D	95% 0%		0% 60%		100%	100%	60% 25%	75%	65%	100%	100%	100%	100% 100%	100%	100%	100%	100% 30%	100% 40%	100%	100%	30%	0% 0%	35% 0%	65%	15% 0%
Rosenbrock_5D	0%		5%		60%	0%	0%		10%	60%			20%	45%	95% 70%	85%	55%	70%	10% 55%	35% 100%					0%
Rosenbrock_10D	90%	100%	45%		100%	75%		55%	100%	100%			100%	100%	95%	100%	100%	100%	100%	100%		30%			0%
Michalewicz_2D_m10	50%	30%	40%		0%	0%		0%	10%	0%	10%		0%	25%	25%	0%	0%	0%	0%	0%		0%			0%
Michalewicz_5D_m10	80%	55%	65%	10%	10%	45%							30%			20%	35%			25%					0%
Michalewicz_10D_m10 Rastrigin_2D	20% 55%	30% 55%	35% 0%	0% 15%	50%	0% 5%							0% 75%	0% 70%	0% 55%	65%	5% 30%	0% 80%	5% 55%	5% 65%	0% 15%	0% 0%		0% 10%	0% 1 0%
Rastrigin_5D	30%	40%	40%	55%	55%	30%	65%	5%	45%	50%			40%	35%	50%	25%	15%	50%	35%	40%	60%	50%		35%	45%
Rastrigin_10D	30%	55%	30%	30%	35%	35%	40%	10%	25%	45%			20%	50%	65%	45%	15%	60%	50%	40%	40%	45%		0%	25%
Ackley_2D_a20_b0.2_c6.28e0	0%										50%	20%	0%	15%	45%	60%	40%	40%	35%	15%					0%
Ackley_5D_a20_b0.2_c6.28e0 Ackley_10D_a20_b0.2_c6.28e0	0%										25% 15%	20%			10%	30% 10%	35% 20%								0% 0%
StyblinskiTang_2D	0%		35%		80%	65%		15%	10%	35%	50%		90%	70%	70%	70%	75%	70%	90%	65%	70%	20%			40%
StyblinskiTang_5D	0%		55%		65%	50%	10%	15%	30%	60%	30%		65%	50%	50%	60%	60%	45%	70%	40%	65%	45%			55%
StyblinskiTang_10D	0%		30%		35%	25%	20%	15%	30%	45%	45%		30%	35%	35%	30%	35%	15%	45%	15%		50%		0%	40%
Beale_2D Levi_2D	0% 0%				100%	100%	80% 0%	5% 0%	100%	100%	65% 15%		100% 0%	100% 25%	100% 15%	95% 15%	70% 20%	95% 40%	100% 45%	90% 25%				45% 0%	0% 0%
GoldsteinPrice_2D	0%										5%			0%	5%	20%	5%	15%	35%	15%					0%
Matyas_2D	100%	100%	100%	100%	100%	100%	95%	100%	100%	100%	100%	95%	100%	100%	100%	100%	100%	100%	100%	100%					0%
Himmelblau_2D Booth_2D	0%				100%	100%			40%	75%	35%		100%	100%	100%	100%	100%	100%	100%	100%	100%	25%			80%
Griewank_2D	0% 0%				100%	100%				15% 0%	100%		100%	100%	100%	100%	100%	100%	100%	100%	90%	0%			0% 0%
Griewank_5D	0%																								0%
Griewank_10D	0%																			0%					0%
Schwefel_2D Schwefel_5D	0% 0%																			50% 50%					0% 0%
Schwefel_10D	0%																			50%					0%
Levy_2D	0%				100%					100%	80%	70%	85%	95%	95%	100%	100%	100%	100%	100%					0%
Levy_5D	0%				60%	0%		10%	25%	100%	80%	75%	100%	70%	100%	100%	100%	100%	100%	100%					0%
Levy_10D Zakharov_2D	0% 0%				100%	100%				100% 25%	80% 60%	25% 70%	100% 75%	80% 90%	100% 100%	100%	100% 100%	100% 100%	100% 100%	100% 100%					0% 0%
Zakharov_5D	0%				60%	100%				25%	0%	0%	100%	95%	100%	100%	100%	100%	100%	100%					0%
Zakharov_10D	0%				0%	10%				30%			0%	55%	0%	100%	100%	100%	100%	95%					0%
IllConditionedRosenbrock_2D_alpha100	0%												80%		65%	5%	25%	35%	0%	20%					0%
IllConditionedRosenbrock_5D_alpha100 IllConditionedRosenbrock_10D_alpha100	0%														20%	80% 65%	15%	65% 75%	35% 0%	100% 70%					0% 0%
Trigonometric_2D	100%	85%	5%		75%	100%				85%	90%	80%	100%	90%	100%	100%	100%	100%	95%	100%					0%
Trigonometric_5D	85%	35%	0%	20%	70%	100%				75%	0%	0%	90%	95%	75%	90%	80%	100%	100%	90%					0%
Trigonometric_10D	35%			10%	70%	55%				85%			25%		60%	85%	75%	100%	80%	100%					0%
PenaltyI_2D_alpha1e6 PenaltyI_5D_alpha1e6	0% 0%																								0% 0%
PenaltyI_10D_alpha1e6	0%																								0%
Barrier_2D_mu0.1	0%																								0%
Barrier_5D_mu0.1 Barrier_10D_mu0.1	0% 0%																								0% 0%
NoisySphere_2D_sigma0.01	0%		35%			35%	30%	35%	25%	25%	40%		80%	45%	15%	35%				60%					0%
NoisySphere_5D_sigma0.01	0%		10%			20%	15%	25%	30%	25%	20%		85%	55%	25%	45%			10%	45%					0%
NoisySphere_10D_sigma0.01	0%		15%			10%	35%	10%	15%		20%		85%	45%	10%	45%		0%		25%					0%
SparseRosenbrock_4D SparseRosenbrock_10D	0% 0%														20%	15% 20%		45% 55%	5% 5%	25% 45%					0% 0%
SparseQuadratic_5D_pattern[1, 3]	0%				100%	100%				100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%					0%
SparseQuadratic_10D_pattern[1, 3]	0%				100%	100%				100%	90%	100%	100%	100%	100%	100%	100%	100%	100%	100%					0%
LogisticRegression_100samples_5features_reg0.01	0%																								0%
LogisticRegression_200samples_10features_reg0.01 LinearRegression_100samples_5features_reg0.01	0%																								0% 0%
LinearRegression_100samples_5teatures_reg0.01 LinearRegression_200samples_10features_reg0.01	0%		20%			100%				100%	90%	100%	100%	100%	100%	100%	100%	100%	100%	100%					0%
NeuralNetwork_100samples_layers_5_10_3	0%		85%		85%	0%				0%	10%	15%	30%	40%	0%	90%	85%	90%	85%	60%					0%
NeuralNetwork_100samples_layers_10_20_5	15%	0%	40%	0%	100%	0%				0%	0%	0%	20%	0%	0%	90%	95%	100%	70%	55%					0%
SVM_100samples_5features_C1 SVM_200samples_10features_C1	100%	90%	0%	50%	100%	100%				100%	100%	100%	100%	90%	100%	100%	100%	100%	90%	100%					0%
SVM_200samples_10features_C1	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%

Legend: 90-100% Excellent, 50-89% Good, 10-49% Poor, 0-9% Very Poor, N/A No Data. Quickly identifies which optimizers work on which problem types.