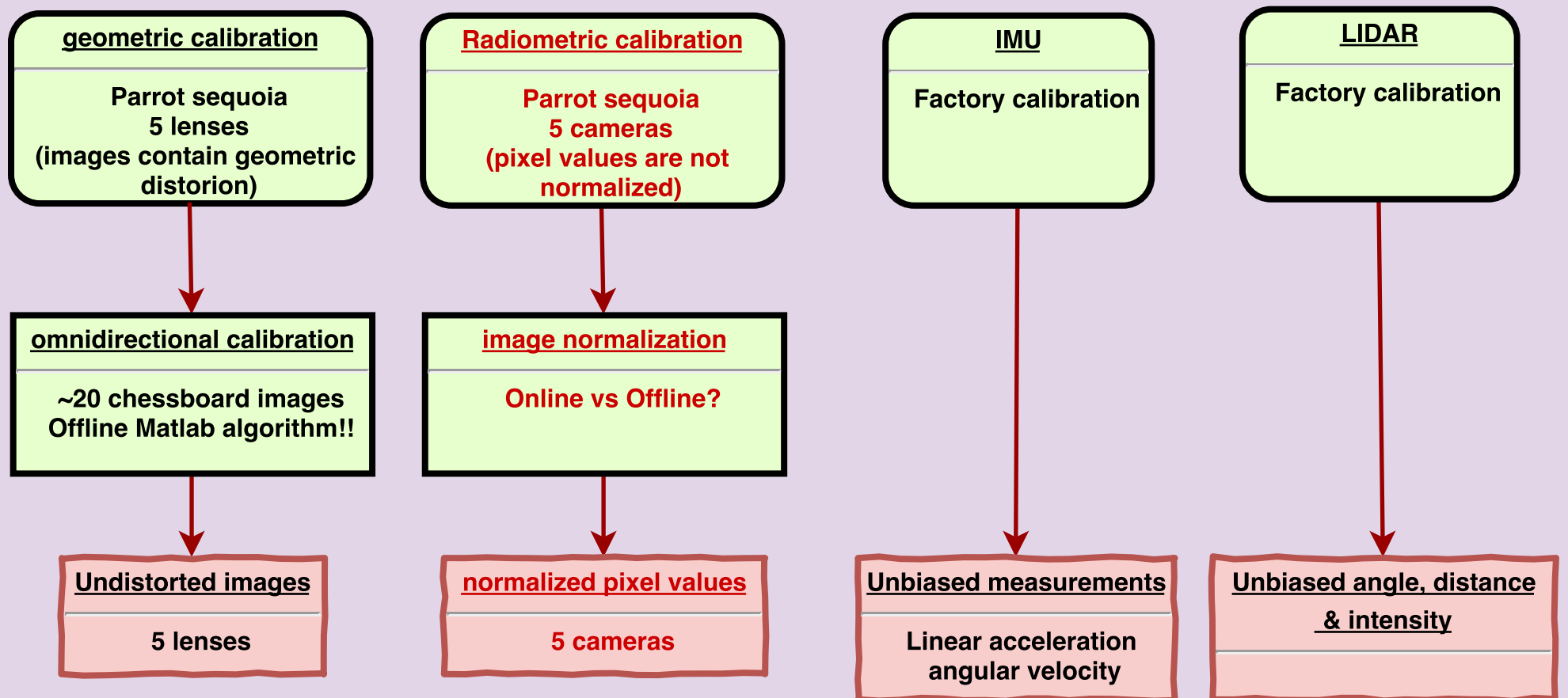


SLAM - calibration

Intrinsic calibration



Extrinsic calibration

