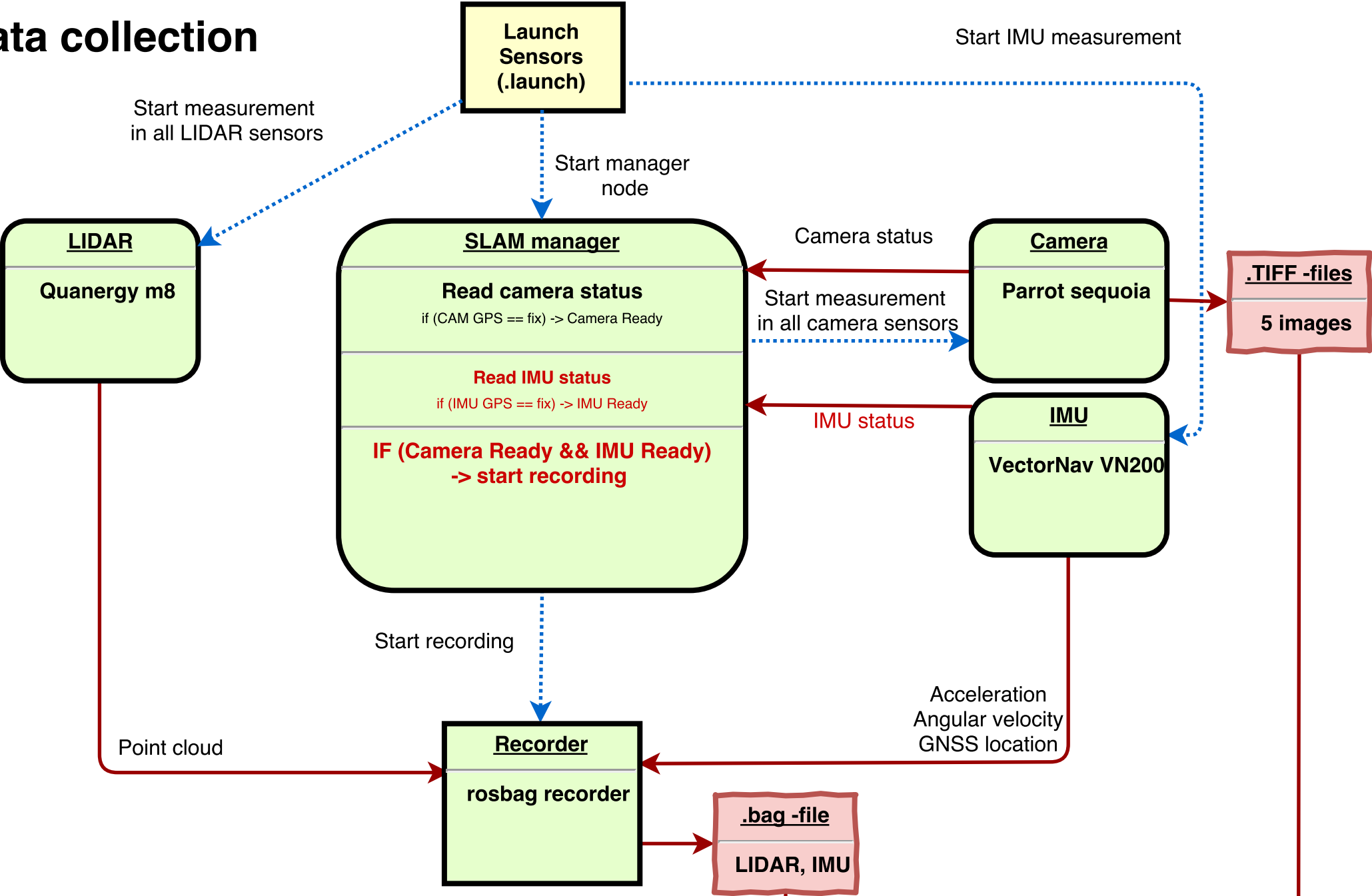
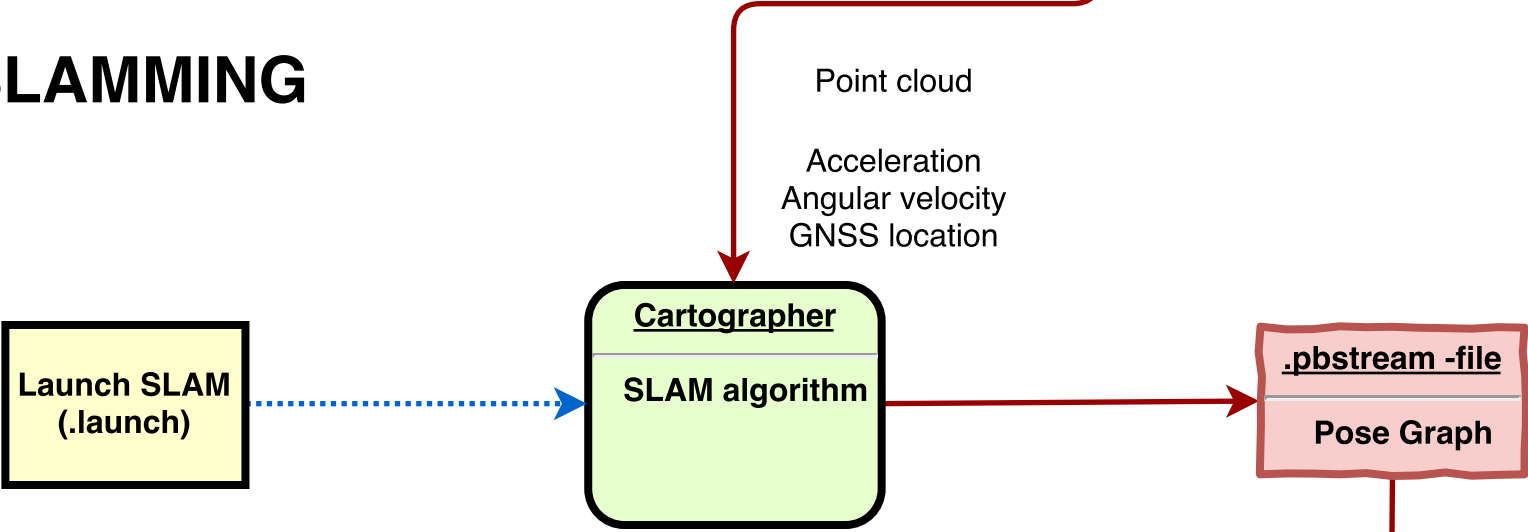


# SLAM - process in ROS

## Data collection



## SLAMMING



## Point cloud extraction

