# Adaptive and integrated neighborhooddependent approach for nonlinear enhancement of color images

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School of Electrical Engineering and Computer Science Kyungpook National Univ.



## **Abstract**

# ◆ Objective

Enhancement of digital image captured under low illumination conditions

# Proposed algorithm

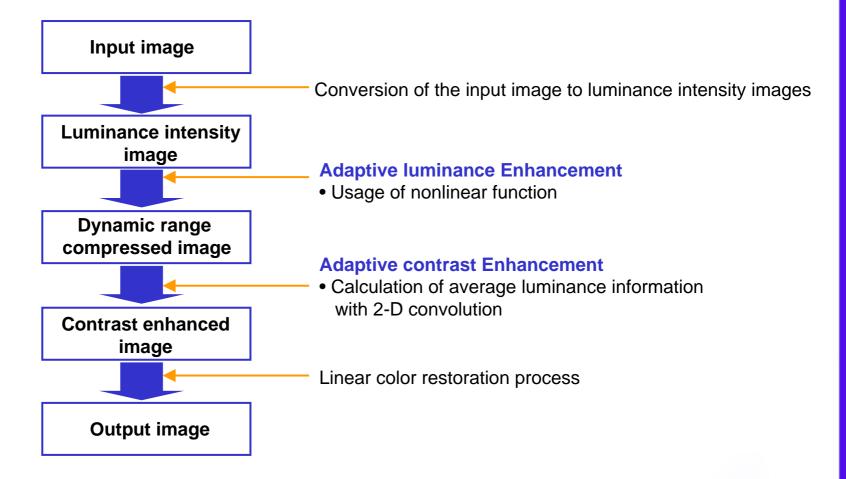
- Adaptive and integrated neighborhood dependent approach for nonlinear enhancement (AINDANE)
  - Adaptive luminance enhancement
    - Global intensity transformation with nonlinear transfer function (dynamic range compression)
  - Adaptive contrast enhancement
    - Tune of the intensity of each pixel with neighbor pixels
- Two procedure for flexibility and easier control

# Introduction

- ◆ Better performance of human vision
  - Perception of more than six order magnitude
  - Accommodation of different levels of radiance by controlling the size of pupils
  - Dynamic range compression via the lateral processing at the retinex level
  - Dynamic range processing with the visual cortex
- Method for modeling of human visual system (HVS)
  - Dynamic range compression

- ◆ Adaptive and integrated neighborhood dependent approach for nonlinear enhancement (AINDANE)
  - Two independent procedure
    - Adaptive luminance enhancement
      - Treatment of luminance information
      - Dynamic range compression
    - Adaptive contrast enhancement
      - Preservation of details
      - Approximation of the tonality with the original image
  - Properties
    - Flexibility and capability to turn and control of the image enhancement

### Diagram of the whole procedure



## Related work

- ◆ Retinex-based algorithms
  - Properties
    - Management of dynamic range compression and color constancy
    - Computational complexity
  - MSRCR (Multi-scale retinex for color restoration)
    - Logarithmic compression and spatial convolution
    - Time consuming, nonlinear color restoration causing the unnatural image result, and artifacts at the boundaries
  - LDNE (Luma-dependent nonlinear enhancement)
    - Luminance based multi-scale retinex algorithm for time reducing

- Histogram equalization (HE) algorithms
  - Histogram equalization
    - Poor result image with bimodal histogram
  - AHE (Adaptive histogram equalization)
    - HE within a window
    - Noise enhancement and ring artifacts
  - Contrast limiting AHE
    - Clip of histogram level
    - Undesired noise amplification and boundary artifacts
  - Multi-scale AHE
  - Wavelet-based MAHE
    - Adaptively based on spatial-frequency properties

# ◆ Tone reproduction operators

- Histogram adjustment
  - Usage of population of local adaptation of luminance
  - Lack of contrast enhancement
- Tone mapping with neighborhood dependent
  - Similar with MSRCR
  - Halo artifacts
- Low-curvature image simplifier (LCIS)
  - Overemphasis of details, computational complexity, and many parameters

# **AINDANE Algorithm**

- ◆ Adaptive luminance enhancement
  - Conversion of the luminance information
    - Method in standard NTSC (National Television Standards Committee)

$$I(x,y) = \frac{76.245 I_R(x,y) + 19.685 I_G(x,y) + 29.071 I_B(x,y)}{255}$$
(1)

where  $I_R(x, y)$ ,  $I_G(x, y)$ , and  $I_R(x, y)$  are R, G, and B value (8-bit)

Normalization

$$I_n(x,y) = \frac{I(x,y)}{255}$$
 (2)

- Enhancement of luminance intensity
  - Dynamic range compression

$$I_n' = \frac{I_n^{(0.75z+0.25)} + (1 - I_n)0.4(1-z) + I_n^{(2-z)}}{2}$$
(3)

where z is the image dependent parameter , and L is the intensity level corresponding to a CDF of 0.1

$$z = \begin{cases} 0 & \text{for } L \le 50 \\ \frac{L - 50}{100} & \text{for } 50 < L \le 150 \\ 1 & \text{for } L > 150 \end{cases}$$

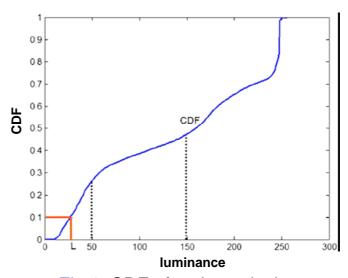


Fig 1. CDF of an intensity image

#### Property of the transfer function

- Large enhancement of low luminance
- Appropriate dynamic range compression
- Various form depended on the parameter, z

$$I_n' = \frac{I_n^{(0.75z+0.25)} + (1 - I_n)0.4(1-z) + I_n^{(2-z)}}{2}$$

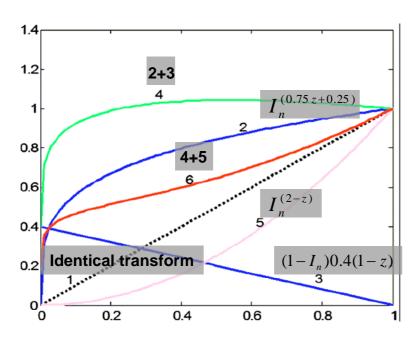


Fig 2. Nonlinear transfer function

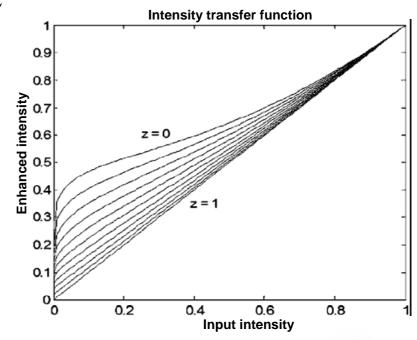


Fig 3. Nonlinear transfer function with z



# Adaptive contrast enhancement

- Necessity
  - Gray out of the image during enhancement of luminance intensity
- Disadvantage of normal contrast enhancement technique
  - Significantly expanded
  - Poor result between pixels which have small difference
- Surrounding pixel (neighborhood) dependent contrast enhancement technique
  - Enhancement of picture contrast and fine details with preserving image quality
  - Different output with pixels which have the same value
    - Booster with darker surround
    - Lower with brighter surround

#### Procedure

- Gaussian kernel
  - Closeness with HVS

$$G(x, y) = K \exp\left[\frac{-(x^2 + y^2)}{c^2}\right]$$
(4)

where c is the scale or Gaussian surround space constant, and

$$\iint K \exp\left[\frac{-(x^2 + y^2)}{c^2}\right] dxdy = 1 \tag{5}$$

- 2-D discrete spatial convolution
  - Average of neighborhood

$$I_{conv}(x,y) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} I(m,n)G(m+x,n+y)$$
 (6)

- Center-surround contrast enhancement
  - Contents
    - » Comparison between center pixel value and convolution result
    - » Pull up with higher center pixel value than average and vice versa
  - Pixel intensity after contrast enhancement

$$S(x,y) = 255 I_n(x,y)^{E(x,y)}$$
(7)

$$E(x,y) = r(x,y)^p = \left\lceil \frac{I_{conv}(x,y)}{I(x,y)} \right\rceil^p$$
 (8)

where r(x, y) is the ratio, and

 $p\,$  is an image dependent parameter to tune the contrast process,

$$p = \begin{cases} \frac{3}{27 - 2\sigma} & \textit{for } \sigma \leq 3\\ \frac{27 - 2\sigma}{7} & \textit{for } 3 < \sigma < 3\\ 1 & \textit{for } \sigma \geq 3 \end{cases}$$
 where  $\sigma$  is the global standard deviation

- » Linear relationship between p and  $\sigma$  based on experiments
- » User set of p to adjust the contrast enhancement process
- »  $\sigma$  as the contrast level of the original intensity image

- Contrast enhancement curve with various E
  - » Larger  $I_n(x,y)^{E(x,y)}$  than  $I_n(x,y)$  if E(x,y) is less than 1 (r(x,y)<1)
  - » Smaller  $I_n(x,y)^{E(x,y)}$  than  $I_n(x,y)$  if E(x,y) is less than 1 (r(x,y)>1)

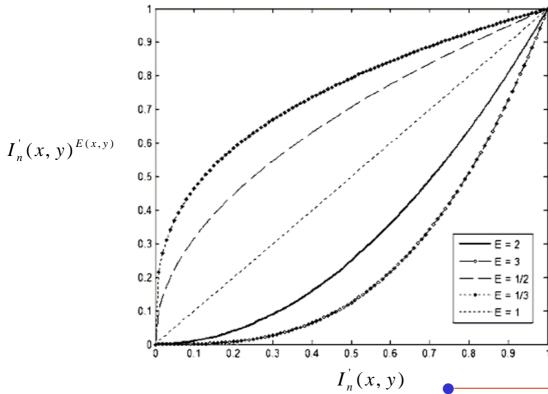


Fig 4. Intensity transformation for contrast enhancement of a IMAGING LA

- Multi-scale convolution for better perfermance
  - Same conception as MSR
    - Small scale for nearest neighbor pixel luminance information
      - » Local contrast or fine details
      - » 1 to 5% of the image size
    - Large scale for the whole luminance information in an image
      - » Smooth and natural looking
      - » 25 to 45% of the image size
    - Medium scale for both luminance information
      - » 10 to 15
  - Properties
    - Calculation of more complete information on the luminance
    - Time consuming with computational complexity

#### Equations for Multi-scale convolution

$$G_i(x, y) = K \exp\left[\frac{-(x^2 + y^2)}{c_i^2}\right]$$
 (9)

$$I_{conv,i}(x,y) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} I(m,n)G_i(m+x,n+y)$$
(10)

$$E_i(x,y) = r_i(x,y)^p = \left\lceil \frac{I_{conv,i}(x,y)}{I(x,y)} \right\rceil^p$$
(11)

$$S_i(x, y) = 255 I_n(x, y)^{E_i(x, y)}$$
 (12)

$$S(x, y) = \sum_{i} w_i S_i(x, y)$$
(13)

where  $c_i$  (i=0,1,2,...) is the different scales, and  $w_i$  is the weight factor for each output  $w_i=1/n,\ i=1,2,...n,$ 

n is the number of scales

### ◆ Color restoration

- Linear color restoration process for the enhanced color image
  - Based on the chromatic information of input image

$$S_{j}(x,y) = S(x,y) \frac{I_{j}(x,y)}{I(x,y)} \lambda_{j}$$
(14)

where j=r,g,b represents the R, G, B spectral band, and  $S_r,S_g$ , and  $S_b$  are the RGB values of the enhanced color image

- Usage of  $\lambda$ 
  - Manual adjustment of the color hue of the enhanced color image
  - Constant, and smaller than but close to 1

# **Experimental results and discussion**

lacktriangle Result depending on the parameters, (z, c, p)



(a) Original

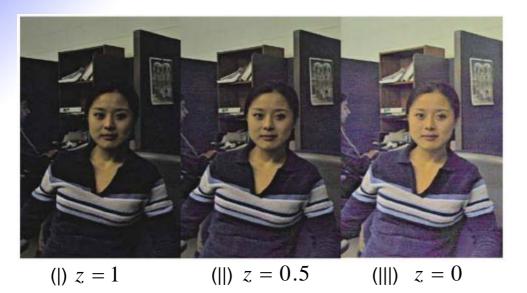
(||) c = 20

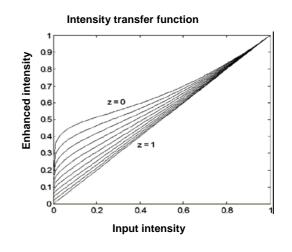
(|) c = 5

(b) Result images (consideration of local luminance range),  $z=0,\,p=1$ 

Fig 5-1. Result images depending on parameter c

(|||) c = 240





(d) Result images (consideration of degree of luminance enhancement), p=1, c=multiscale



$$S(x, y) = 255 I_n(x, y)^{E(x,y)}$$

$$E(x, y) = r(x, y)^{p} = \left[\frac{I_{conv}(x, y)}{I(x, y)}\right]^{p}$$

(|) 
$$p = 1$$

(||) 
$$p = 2$$

(|||) 
$$p = 3$$

(d) Result images (consideration of degree of contrast enhancement), z = 0, c = multiscale

Fig 5-2. Result images depending on parameter

# Results with comparison of INDANE and AINDANE







(a) Original

(b) INDANE (z = 0)

(c) AINDANE (  $z \neq 0$ )

Fig 6. Result images depending on parameter z (luminance control)







(a) Original

(b) INDANE (p = 1)

(c) AINDANE (  $p \neq 1$ )

Fig 7. Result images depending on parameter *p* (contrast control)

# Results with comparison of other methods



artifact



Dimmer face than right person

Dimmer face than right person





A lot of noise and not sufficient luminance enhancement

**Color constancy problems** 

(a) Original

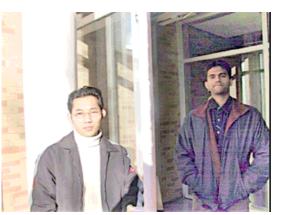
(b) AHE

(c) retinex

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**Insufficient luminance enhancement** 



**Higher quality** 



Problem in highlighted area

(d) MSRCR



(e) INDANE

**Higher quality** 

(f) AINDANE

Fig 8-2. Image enhancement comparison.

# Results with comparison with other images









(a) Original

Strong contrast enhancement and poor luminance enhancement

(b) MSRCR









Incorrect colors (cloud color) and insufficient luminance enhancement

(c) Retinex

(d) AINDANE

## ◆ Results of AINDANE

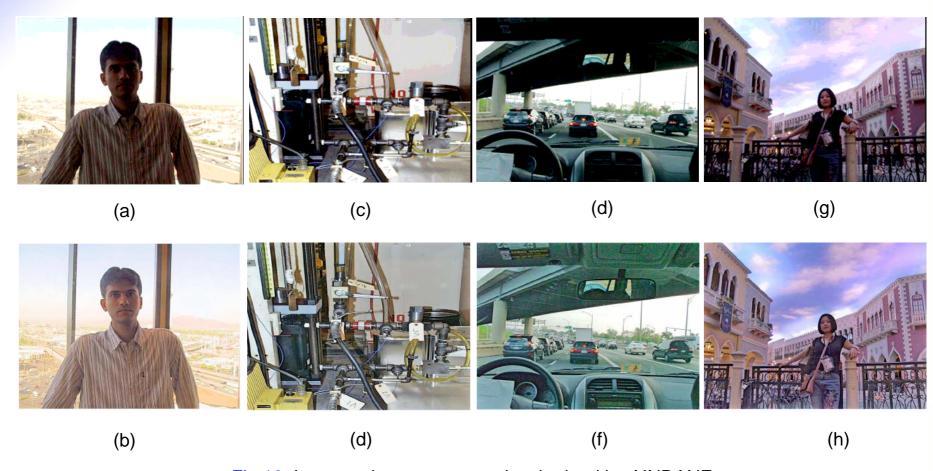


Fig 10. Image enhancement results obtained by AINDANE

### Results of Robust evolution

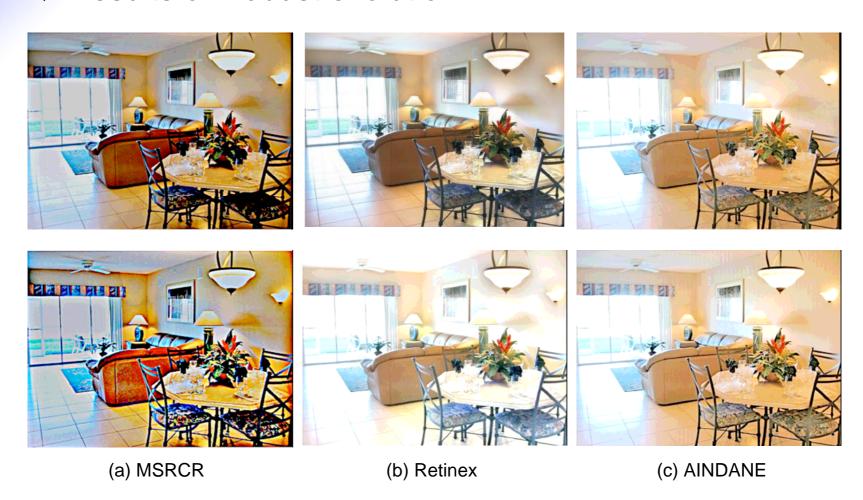


Fig 11. Robust evolution: Left image is the first enhanced image, and right image is the second enhanced image.

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### Results of statistical method

- Usage of image mean and the mean of zonal standard deviation with blocks
  - Obtainment of overall lightness from image mean
  - Obtainment of overall contrast from the mean of standard deviations

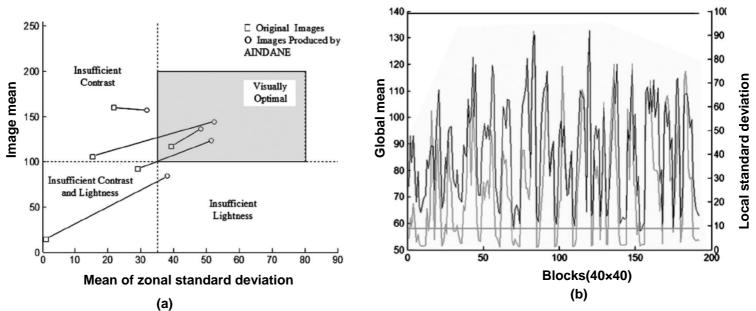


Fig 12. Nonlinear transfer function with z

# **Computational speed**

- ◆ Computational speed of AINDANE
  - Devices
    - 3.06GHz CPU and 1 Gbyte of memory
  - Coding
    - PhotoFlair version 2.0 for MSRCR and ,C++ for AINDANE
  - 30% processing time from MSRCR
    - Only one channel FFT computation for AINDANCE compared with 3 channel FFT computation for MSRCR

Table 1. Comparison of AINDANE and MSRCR in processing time

| Image Size (pixels) | Processing Time by<br>AINDANE (s) | Processing Time by<br>MSRCR (s) |
|---------------------|-----------------------------------|---------------------------------|
| 360×240             | 0.25                              | 1.2                             |
| 640×480             | 1.4                               | 4                               |
| 1024×768            | 2.8                               | 8                               |
| 2000×1312           | 6.7                               | 18                              |

## **Conclusion**

### ◆ AINDANE

- Improvement of visual quality of digital images captured under insufficient or non uniform lighting conditions
- Two procedure for flexibility and easier control
  - Adaptive luminance enhancement
  - Adaptive contrast enhancement
- Better performance for visual quality and colors
- Faster speed compared with MSRCR

### ◆ Multi-scale Retinex

### Retinex output

$$MR_i(x, y) =$$

$$\sum_{s=0}^{nn-1} w_s \times (\log_t I(x, y) - \log\{F(x, y) *_t I(x, y)\})$$
 (4)

$$F_s(x,y) = K_s e^{-(x^2 + y^2)/c_s^2}$$
 (5)

$$\iint F_s(x, y) dx dy = 1 \tag{6}$$

Where nn is the number of scales, and  $w_s$  is the weight coefficient associated with output by SSR with the scale  $c_s$ .

### Compensation

$$MR_{i}(x, y) =$$

$$MR_i \cdot (1 + C \cdot \frac{I_i(x, y)}{\sum I_i(x, y)}), \quad C = 125$$
 (7)

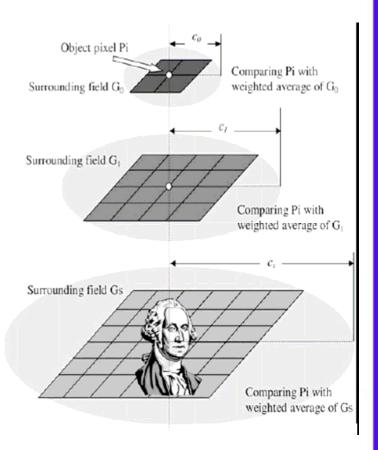


Fig. 3. Diagram expanded in to MSR Technique

- A visibility matching tone reproduction operator for high dynamic range scenes
  - Naive Histogram equalization

$$B_{de} = \log(L_{d\min}) + [\log(L_{d\max}) - \log(L_{d\min})] \cdot P(B_w)$$

Where  $L_d$  is display luminance, and  $B_w = \log L_d$  is display brightness.

- Histogram adjustment with a linear ceiling
  - Limitation of the contrast

$$\frac{dL_d}{dL_w} \le \frac{L_d}{L_w}$$

Ceiling of

$$f(b) \le \frac{f(b)}{\log(L_{d \max}) - \log(L_{d \min})}$$

Where T is the total pixel number, and  $\Delta b = (L_{d\max} - L_{d\min})/T$  is interval of bins.

- Tolerance for truncation
  - 2.5% of histogram total

