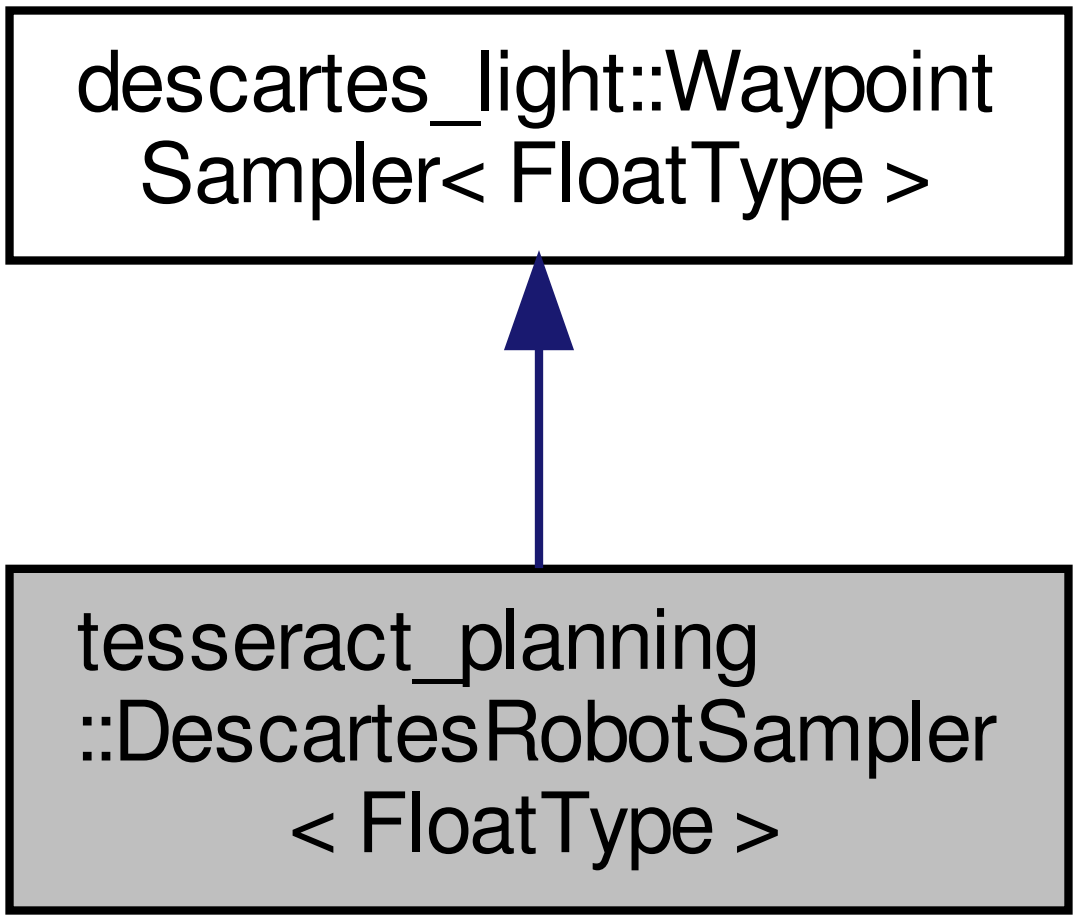
descartes_light::WaypointSampler< FloatType >
tesseract_planning::DescartesRobotSampler< FloatType >