

tesseract_planning
::MotionPlanner



```
graph BT; OMPL[tesseract_planning::OMPLMotionPlanner] --> MP[tesseract_planning::MotionPlanner];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray box representing the base class, `tesseract_planning::OMPLMotionPlanner`. A blue arrow points upwards from this box to a white box at the top, which represents the derived class, `tesseract_planning::MotionPlanner`. This indicates that `OMPLMotionPlanner` inherits from `MotionPlanner`.

tesseract_planning
::OMPLMotionPlanner