

tesseract_planning
::TrajectoryContainer



```
graph BT; A[tesseract_planning::TesseractCommonTrajectory] --> B[tesseract_planning::TrajectoryContainer];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray box representing the base class, and at the top is a white box representing the derived class. A blue arrow points from the base class box to the derived class box, indicating that the derived class inherits from the base class.

tesseract_planning
::TesseractCommonTrajectory