

tesseract_planning
::TrajectoryContainer

std::vector< std::reference
_wrapper< tesseract_planning
::InstructionPoly > >

tesseract_planning
::InstructionsTrajectory

trajectory_

```
graph LR; IT[tesseract_planning::InstructionsTrajectory] --> TC[tesseract_planning::TrajectoryContainer]; IT -.->|trajectory_| V[std::vector< std::reference_wrapper< tesseract_planning::InstructionPoly > >];
```