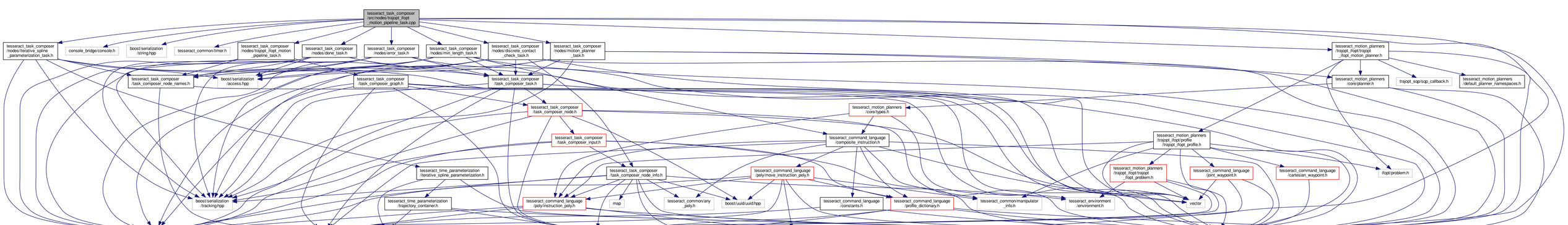
tesseract_task_composer/src/nodes/trajopt_ifopt/motion_pipeline_task.cpp
tesseract_task_composer/nodes/iterative_spline_parameterization_task.h
console_bridge/console.h
boost/serialization/string.hpp
tesseract_common/timer.h
tesseract_task_composer/nodes/trajopt_ifopt/motion_pipeline_task.h
tesseract_task_composer/nodes/done_task.h
tesseract_task_composer/nodes/error_task.h
tesseract_task_composer/nodes/min_length_task.h
tesseract_task_composer/nodes/discrete_contact_check_task.h
tesseract_task_composer/nodes/motion_planner_task.h
tesseract_motion_planners/trajopt_ifopt/trajopt_ifopt_motion_planner.h
tesseract_task_composer/task_composer_node_names.h
boost/serialization/access.hpp
tesseract_task_composer/task_composer_graph.h
tesseract_task_composer/task_composer_task.h
tesseract_motion_planners/core/planner.h
trajopt_sqp/sqp_callback.h
tesseract_motion_planners/default_planner_namespaces.h
tesseract_task_composer/task_composer_node.h
tesseract_motion_planners/core/types.h
tesseract_task_composer/task_composer_input.h
tesseract_command_language/composite_instruction.h
tesseract_motion_planners/trajopt_ifopt/profile/trajopt_ifopt_profile.h
tesseract_time_parameterization/iterative_spline_parameterization.h
tesseract_task_composer/task_composer_node_info.h
tesseract_command_language/poly/move_instruction_poly.h
tesseract_motion_planners/trajopt_ifopt/trajopt_ifopt_problem.h
tesseract_command_language/joint_waypoint.h
tesseract_command_language/cartesian_waypoint.h
ifopt/problem.h
boost/serialization/tracking.hpp
tesseract_time_parameterization/trajectory_container.h
tesseract_command_language/poly/instruction_poly.h
map
tesseract_common/any_poly.h
boost/uuid/uuid.hpp
tesseract_command_language/constants.h
tesseract_command_language/profile_dictionary.h
tesseract_common/manipulator_info.h
tesseract_environment/environment.h
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boost/serialization/export.hpp
string
Eigen/Eigen
memory
shared_mutex
tesseract_common/serialization.h
tesseract_common/macros.h
unordered_map