

tesseract_planning
::TaskInfo



```
graph BT; A[tesseract_planning::CheckInputTaskInfo] --> B[tesseract_planning::TaskInfo];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray-shaded box labeled 'tesseract_planning::CheckInputTaskInfo'. A blue arrow points vertically upwards from this box to a white box at the top labeled 'tesseract_planning::TaskInfo'. Both boxes have a black border.

tesseract_planning
::CheckInputTaskInfo