

tesseract\_planning  
::TaskInfo



```
graph BT; A[tesseract_planning::MotionPlannerTaskInfo] --> B[tesseract_planning::TaskInfo];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray-shaded box representing the base class, `tesseract_planning::MotionPlannerTaskInfo`. A blue arrow points vertically upwards from this box to a white box above it, representing the derived class, `tesseract_planning::TaskInfo`. Both boxes have a black border and contain their respective class names in two lines.

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