

tesseract_planning
::OMPLPlannerConfigurator



```
graph BT; A[tesseract_planning::TRRTConfigurator] --> B[tesseract_planning::OMPLPlannerConfigurator];
```

A diagram showing two class boxes. The top box is white with a black border and contains the text 'tesseract_planning' and '::OMPLPlannerConfigurator'. The bottom box is gray with a black border and contains the text 'tesseract_planning' and '::TRRTConfigurator'. A blue arrow points from the top of the gray box to the bottom of the white box, indicating an inheritance relationship.

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::TRRTConfigurator