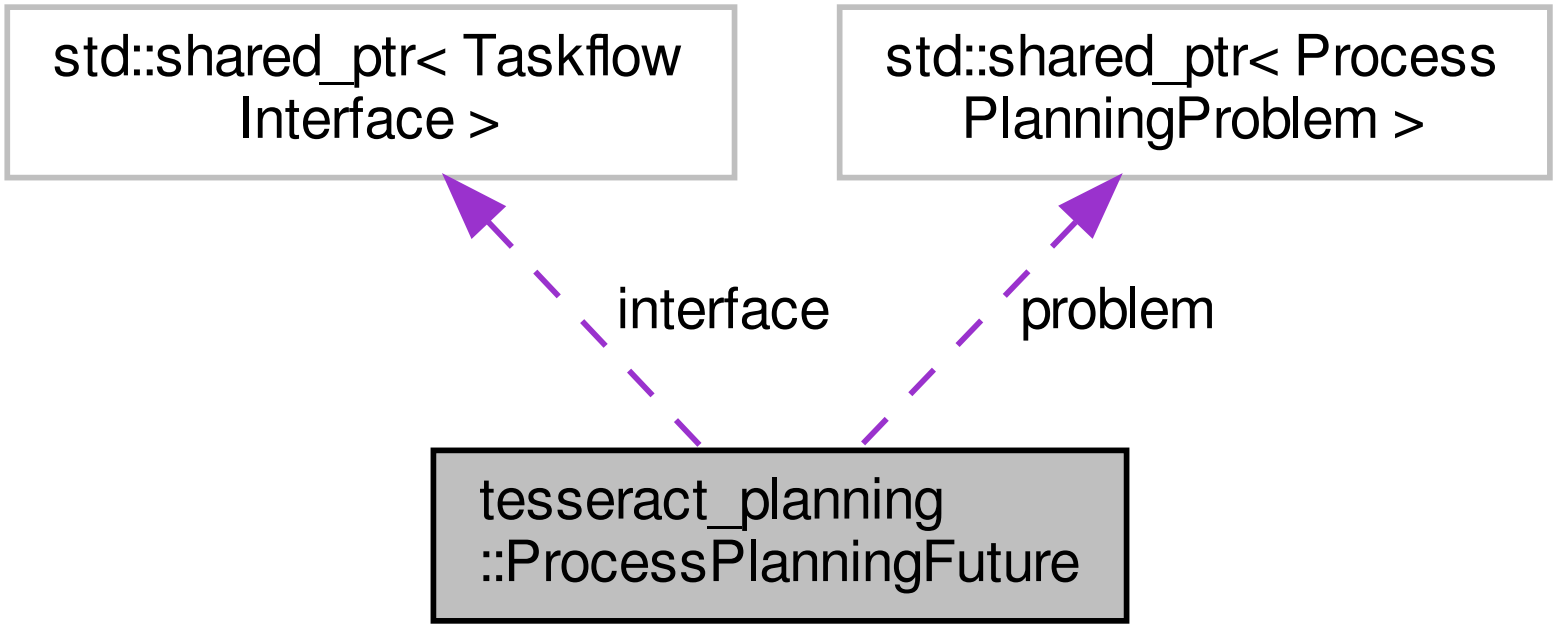
std::shared_ptr< Taskflow Interface >
std::shared_ptr< Process PlanningProblem >
interface
problem
tesseract_planning ::ProcessPlanningFuture