tesseract\_task\_composer /include/tesseract\_task \_composer/nodes/trajopt \_ifopt\_motion\_planner\_task.h

tesseract\_task\_composer /include/tesseract\_task \_composer/nodes/trajopt ifopt motion pipeline task.h

tesseract\_task\_composer /src/nodes/trajopt\_ifopt \_motion\_planner\_task.cpp

tesseract\_examples /src/basic\_cartesian example.cpp

tesseract\_examples /src/glass\_upright\_example.cpp tesseract\_task\_composer /src/nodes/trajopt\_ifopt \_motion\_pipeline\_task.cpp