

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/serialize.h

```
graph BT; A["tesseract_motion_planners  
/ompl/src/serialize.cpp"] --> C["tesseract_motion_planners  
/ompl/include/tesseract  
_motion_planners/ompl/serialize.h"]; B["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C;
```

The diagram illustrates the relationship between three source files in the tesseract_motion_planners project. At the top, a gray box represents the header file: tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/serialize.h. Below it, two white boxes represent source files. The left box is tesseract_motion_planners/ompl/src/serialize.cpp, and the right box is tesseract_motion_planners/test/serialize_test.cpp. Two blue arrows point from these source files up to the header file, indicating that both source files include this header.

tesseract_motion_planners
/ompl/src/serialize.cpp

tesseract_motion_planners
/test/serialize_test.cpp