

tesseract\_planning  
::TrajectoryContainer



```
graph BT; A[tesseract_planning::TesseractCommonTrajectory] --> B[tesseract_planning::TrajectoryContainer];
```

The diagram illustrates an inheritance relationship between two C++ classes. At the bottom is a gray box representing the base class, `tesseract_planning::TesseractCommonTrajectory`. A blue arrow points upwards from this box to a white box at the top, which represents the derived class, `tesseract_planning::TrajectoryContainer`. This indicates that `TesseractCommonTrajectory` inherits from `TrajectoryContainer`.

tesseract\_planning  
::TesseractCommonTrajectory