

tesseract\_planning  
::TaskInfo



```
classDiagram
    class tesseract_planning_FixStateCollisionTaskInfo["tesseract_planning::FixStateCollisionTaskInfo"]
    class tesseract_planning_TaskInfo["tesseract_planning::TaskInfo"]
    tesseract_planning_FixStateCollisionTaskInfo --|> tesseract_planning_TaskInfo
```

The diagram consists of two rectangular boxes. The top box is white with a black border and contains the text 'tesseract\_planning' followed by '::TaskInfo' on the next line. The bottom box is gray with a black border and contains the text 'tesseract\_planning' followed by '::FixStateCollisionTaskInfo' on the next line. A blue arrow points vertically from the top edge of the bottom box to the bottom edge of the top box, indicating an inheritance relationship.

tesseract\_planning  
::FixStateCollisionTaskInfo