

tesseract\_motion\_planners  
/ompl/include/tesseract  
\_motion\_planners/ompl/serialize.h

```
graph BT; A["tesseract_motion_planners /ompl/src/serialize.cpp"] --> C["tesseract_motion_planners /ompl/include/tesseract _motion_planners/ompl/serialize.h"]; B["tesseract_motion_planners /test/serialize_test.cpp"] --> C;
```

The diagram illustrates a file dependency structure. At the top is a header file box (shaded gray) containing the path `tesseract_motion_planners /ompl/include/tesseract _motion_planners/ompl/serialize.h`. Below it are two source file boxes. The left box contains `tesseract_motion_planners /ompl/src/serialize.cpp` and the right box contains `tesseract_motion_planners /test/serialize_test.cpp`. Blue arrows point from each source file box up to the header file box, indicating that both source files include the header file.

tesseract\_motion\_planners  
/ompl/src/serialize.cpp

tesseract\_motion\_planners  
/test/serialize\_test.cpp