

tesseract\_planning  
::TrajectoryContainer

std::vector< std::reference  
\_wrapper< tesseract\_planning  
::InstructionPoly > >

tesseract\_planning  
::InstructionsTrajectory

trajectory\_

```
graph LR; IT[tesseract_planning::InstructionsTrajectory] --> TC[tesseract_planning::TrajectoryContainer]; IT -.->|trajectory_| V[std::vector< std::reference_wrapper< tesseract_planning::InstructionPoly > >];
```