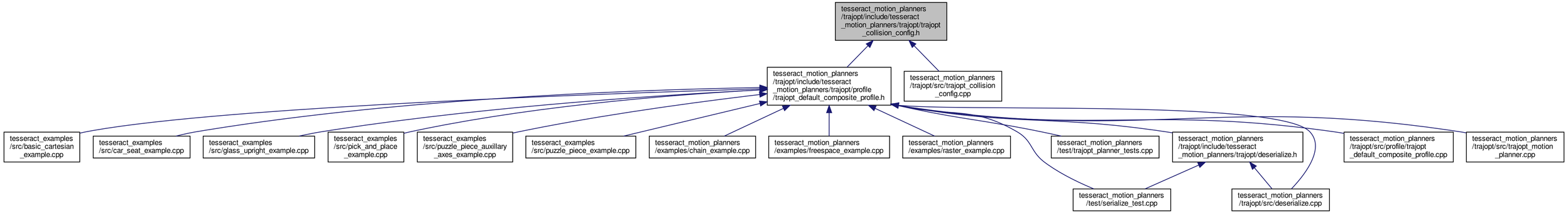
tesseract_motion_planners /trajopt/include/tesseract _motion_planners/trajopt/trajopt _collision_config.h
tesseract_motion_planners /trajopt/include/tesseract _motion_planners/trajopt/profile /trajopt_default_composite_profile.h
tesseract_motion_planners /trajopt/src/trajopt_collision _config.cpp
tesseract_examples /src/basic_cartesian _example.cpp
tesseract_examples /src/car_seat_example.cpp
tesseract_examples /src/glass_upright_example.cpp
tesseract_examples /src/pick_and_place _example.cpp
tesseract_examples /src/puzzle_piece_auxillary _axes_example.cpp
tesseract_examples /src/puzzle_piece_example.cpp
tesseract_motion_planners /examples/chain_example.cpp
tesseract_motion_planners /examples/freespace_example.cpp
tesseract_motion_planners /examples/raster_example.cpp
tesseract_motion_planners /test/trajopt_planner_tests.cpp
tesseract_motion_planners /trajopt/include/tesseract _motion_planners/trajopt/deserialize.h
tesseract_motion_planners /trajopt/src/profile/trajopt _default_composite_profile.cpp
tesseract_motion_planners /trajopt/src/trajopt_motion _planner.cpp
tesseract_motion_planners /test/serialize_test.cpp
tesseract_motion_planners /trajopt/src/deserialize.cpp