

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/compound
_state_validator.h

```
graph BT; A["tesseract_motion_planners/ompl/src/compound_state_validator.cpp"] --> C["tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/compound_state_validator.h"]; B["tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp"] --> C;
```

This diagram illustrates the relationship between two source files and a header file. The header file, `tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/compound_state_validator.h`, is located in a grey box at the top. Below it, two source files are shown in white boxes: `tesseract_motion_planners/ompl/src/compound_state_validator.cpp` on the left and `tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp` on the right. Blue arrows point from each source file to the header file, indicating that both source files include this header.

tesseract_motion_planners
/ompl/src/compound_state
_validator.cpp

tesseract_motion_planners
/ompl/src/profile/ompl
_default_plan_profile.cpp