

tesseract\_planning  
::MotionPlanner



```
classDiagram
    class tesseract_planning_MotionPlanner["tesseract_planning::MotionPlanner"]
    class tesseract_planning_TrajOptMotionPlanner["tesseract_planning::TrajOptMotionPlanner"]
    tesseract_planning_TrajOptMotionPlanner --|> tesseract_planning_MotionPlanner
```

The diagram illustrates a class hierarchy. At the top is a white box with a black border representing the base class 'tesseract\_planning::MotionPlanner'. Below it is a gray box with a black border representing the derived class 'tesseract\_planning::TrajOptMotionPlanner'. A blue arrow points from the top of the gray box to the bottom of the white box, indicating that 'TrajOptMotionPlanner' inherits from 'MotionPlanner'.

tesseract\_planning  
::TrajOptMotionPlanner