

ompl::base::StateValidity
Checker



```
graph BT; A[tesseract_planning::StateCollisionValidator] --> B[ompl::base::StateValidityChecker];
```

The diagram illustrates an inheritance relationship between two C++ classes. At the bottom is a gray-shaded box representing the base class, `tesseract_planning::StateCollisionValidator`. A blue arrow points vertically upwards from this box to a white box at the top, which represents the derived class, `ompl::base::StateValidityChecker`. This indicates that `tesseract_planning::StateCollisionValidator` inherits from `ompl::base::StateValidityChecker`.

tesseract_planning
::StateCollisionValidator