

tesseract\_planning  
::MotionPlanner



```
graph BT; A[tesseract_planning::OMPLMotionPlanner] --> B[tesseract_planning::MotionPlanner];
```

The diagram consists of two rectangular boxes. The top box is white with a black border and contains the text 'tesseract\_planning' followed by '::MotionPlanner' on the next line. The bottom box is gray with a black border and contains the text 'tesseract\_planning' followed by '::OMPLMotionPlanner' on the next line. A blue arrow points vertically from the top of the gray box to the bottom of the white box, indicating an inheritance or specialization relationship.

tesseract\_planning  
::OMPLMotionPlanner