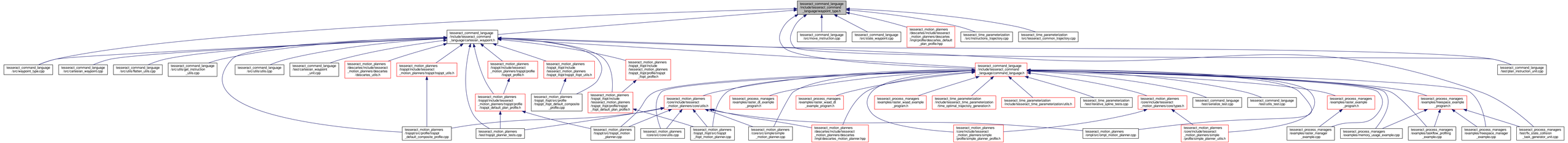
tesseract_command_language /include/tesseract_command_language/waypoint_type.h
tesseract_command_language /include/tesseract_command_language/cartesian_waypoint.h
tesseract_command_language /include/tesseract_command_language/command_language.h
tesseract_command_language /src/move_instruction.cpp
tesseract_command_language /src/state_waypoint.cpp
tesseract_motion_planners /descartes/include/tesseract_motion_planners/descartes/impl/profile/descartes_default_plan_profile.hpp
tesseract_time_parameterization /src/instructions_trajectory.cpp
tesseract_time_parameterization /src/tesseract_common_trajectory.cpp
tesseract_command_language /src/waypoint_type.cpp
tesseract_command_language /src/cartesian_waypoint.cpp
tesseract_command_language /src/utils/flatten_utils.cpp
tesseract_command_language /src/utils/get_instruction_utils.cpp
tesseract_command_language /src/utils/utils.cpp
tesseract_command_language /test/cartesian_waypoint_unit.cpp
tesseract_motion_planners /descartes/include/tesseract_motion_planners/descartes/descartes_utils.h
tesseract_motion_planners /trajopt/include/tesseract_motion_planners/trajopt/trajopt_utils.h
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tesseract_motion_planners /trajopt_ifopt/src/profile/trajopt_ifopt_default_composite_profile.cpp
tesseract_motion_planners /core/include/tesseract_motion_planners/core/utils.h
tesseract_process_managers /examples/raster_dt_example_program.h
tesseract_process_managers /examples/raster_waad_dt_example_program.h
tesseract_process_managers /examples/raster_waad_example_program.h
tesseract_time_parameterization /include/tesseract_time_parameterization/time_optimal_trajectory_generation.h
tesseract_time_parameterization /include/tesseract_time_parameterization/utils.h
tesseract_time_parameterization /test/iterative_spline_tests.cpp
tesseract_motion_planners /core/include/tesseract_motion_planners/core/types.h
tesseract_command_language /test/serialize_test.cpp
tesseract_command_language /test/utils_test.cpp
tesseract_process_managers /examples/raster_example_program.h
tesseract_process_managers /examples/freespace_example_program.h
tesseract_motion_planners /trajopt/src/profile/trajopt_default_composite_profile.cpp
tesseract_motion_planners /test/trajopt_planner_tests.cpp
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tesseract_motion_planners /core/src/core/utils.cpp
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tesseract_motion_planners /core/src/simple/simple_motion_planner.cpp
tesseract_motion_planners /descartes/include/tesseract_motion_planners/descartes/impl/descartes_motion_planner.hpp
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tesseract_motion_planners /ompl/src/ompl_motion_planner.cpp
tesseract_motion_planners /core/include/tesseract_motion_planners/simple/profile/simple_planner_utils.h
tesseract_process_managers /examples/raster_manager_example.cpp
tesseract_process_managers /examples/memory_usage_example.cpp
tesseract_process_managers /examples/task/flow_profiling_example.cpp
tesseract_process_managers /examples/freespace_manager_example.cpp
tesseract_process_managers /test/fix_state_collision_task_generator_unit.cpp
tesseract_command_language /test/plan_instruction_unit.cpp