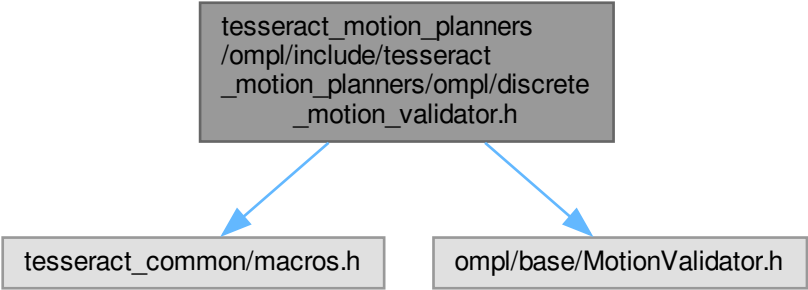


tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/discrete
_motion_validator.h



```
graph TD; A["tesseract_motion_planners /ompl/include/tesseract _motion_planners/ompl/discrete _motion_validator.h"] --> B["tesseract_common/macros.h"]; A --> C["ompl/base/MotionValidator.h"]
```

tesseract_common/macros.h

ompl/base/MotionValidator.h