

tesseract_planning
::TaskflowGenerator



```
graph BT; A[tesseract_planning::RasterGlobalTaskflow] --> B[tesseract_planning::TaskflowGenerator];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray box labeled 'tesseract_planning::RasterGlobalTaskflow'. A blue arrow points upwards from this box to a white box at the top labeled 'tesseract_planning::TaskflowGenerator', indicating that 'RasterGlobalTaskflow' inherits from 'TaskflowGenerator'.

tesseract_planning
::RasterGlobalTaskflow