

tesseract\_planning  
::MotionPlanner



```
graph BT; A[tesseract_planning::OMPLMotionPlanner] --> B[tesseract_planning::MotionPlanner];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray-shaded box representing the base class, `tesseract_planning::OMPLMotionPlanner`. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white box above it. The white box represents the derived class, `tesseract_planning::MotionPlanner`.

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