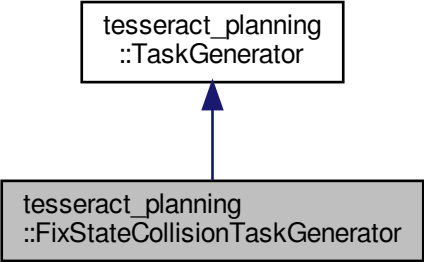


tesseract\_planning  
::TaskGenerator



tesseract\_planning  
::FixStateCollisionTaskGenerator