

tesseract\_motion\_planners  
/trajopt/include/tesseract  
\_motion\_planners/trajopt/serialize.h

```
graph BT; A["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C["tesseract_motion_planners  
/trajopt/include/tesseract  
_motion_planners/trajopt/serialize.h"]; B["tesseract_motion_planners  
/trajopt/src/serialize.cpp"] --> C;
```

The diagram illustrates a dependency relationship. At the top is a grey box representing a header file: `tesseract_motion_planners/trajopt/include/tesseract_motion_planners/trajopt/serialize.h`. Below it are two white boxes representing source files. The left box is `tesseract_motion_planners/test/serialize_test.cpp` and the right box is `tesseract_motion_planners/trajopt/src/serialize.cpp`. Blue arrows point from each source file box up to the header file box, indicating that both source files include or depend on the header file.

tesseract\_motion\_planners  
/test/serialize\_test.cpp

tesseract\_motion\_planners  
/trajopt/src/serialize.cpp