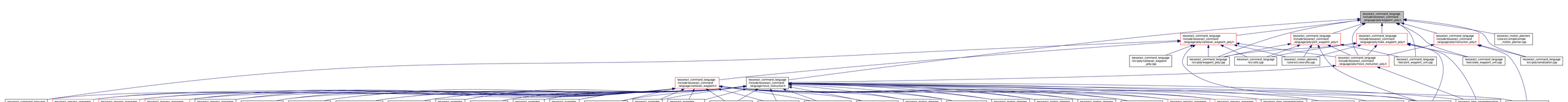
tessaract_command_language /include/tessaract_command_language/poly/waypoint_poly.h
tessaract_command_language /include/tessaract_command_language/poly/joint_waypoint_poly.h
tessaract_command_language /include/tessaract_command_language/poly/cartesian_waypoint_poly.h
tessaract_command_language /include/tessaract_command_language/poly/state_waypoint_poly.h
tessaract_command_language /include/tessaract_command_language/poly/instruction_poly.h
tessaract_motion_planners /core/src/simple/simple_motion_planner.cpp
tessaract_command_language /include/tessaract_command_language/poly/move_instruction_poly.h
tessaract_command_language /include/tessaract_command_language/cartesian_waypoint.h
tessaract_command_language /include/tessaract_command_language/move_instruction.h
tessaract_command_language /test/cartesian_waypoint_unit.cpp
tessaract_process_managers /examples/raster_example_program.h
tessaract_process_managers /examples/raster_waad_dt_example_program.h
tessaract_process_managers /examples/raster_waad_example_program.h
tessaract_process_managers /test/fix_state_bounds_task_generator_unit.cpp
tessaract_command_language /test/move_instruction.cpp
tessaract_command_language /test/serialize_test.cpp
tessaract_command_language /test/fpe_erasure_benchmark.cpp
tessaract_command_language /test/utils_test.cpp
tessaract_examples /src/basic_cartesian_example.cpp
tessaract_examples /src/car_steel_example.cpp
tessaract_examples /src/freespace_hybrid_example.cpp
tessaract_examples /src/freespace_ompl_example.cpp
tessaract_examples /src/glass_upright_example.cpp
tessaract_examples /src/pick_and_place_example.cpp
tessaract_examples /src/puzzle_piece_auxiliary_axis_example.cpp
tessaract_examples /src/puzzle_piece_example.cpp
tessaract_motion_planners /examples/chain_example.cpp
tessaract_motion_planners /examples/freespace_example.cpp
tessaract_motion_planners /examples/raster_example.cpp
tessaract_motion_planners /test/descartes_planner_tests.cpp
tessaract_motion_planners /test/ompl_planner_tests.cpp
tessaract_motion_planners /test/simple_planner_fixed_size_assign_position.cpp
tessaract_motion_planners /test/simple_planner_fixed_size_interpolation.cpp
tessaract_motion_planners /test/simple_planner_lvs_interpolation.cpp
tessaract_motion_planners /test/trajopt_planner_tests.cpp
tessaract_process_managers /examples/freespace_example_program.h
tessaract_process_managers /examples/raster_dt_example_program.h
tessaract_time_parameterization /test/ruckig_trajectory_smoothing_tests.cpp
tessaract_command_language /src/complexity_instruction.cpp
tessaract_time_parameterization /test/iterative_spline_tests.cpp
tessaract_command_language /test/waypoint_unit.cpp
tessaract_time_parameterization /test/time_optimal_trajectory_generation_tests.cpp
tessaract_command_language /test/move_instruction_unit.cpp
tessaract_command_language /src/poly/cartesian_waypoint_poly.cpp
tessaract_command_language /src/poly/waypoint_poly.cpp
tessaract_command_language /src/utils.cpp
tessaract_motion_planners /core/src/core/utils.cpp
tessaract_command_language /test/joint_waypoint_unit.cpp
tessaract_command_language /test/state_waypoint_unit.cpp
tessaract_command_language /src/poly/serialization.cpp