

tesseract\_motion\_planners  
/descartes/include/tesseract  
\_motion\_planners/descartes  
/serialize.h

```
graph BT; A["tesseract_motion_planners  
/descartes/src/serialize.cpp"] --> C["tesseract_motion_planners  
/descartes/include/tesseract  
_motion_planners/descartes  
/serialize.h"]; B["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C;
```

The diagram illustrates a dependency structure where two source files, `serialize.cpp` and `serialize_test.cpp`, both include the header file `serialize.h`. The header file is located in the `include` directory, while the source files are in the `src` and `test` directories, respectively. All paths are relative to the `tesseract_motion_planners` directory.

tesseract\_motion\_planners  
/descartes/src/serialize.cpp

tesseract\_motion\_planners  
/test/serialize\_test.cpp