

tesseract_motion_planners
/trajopt/include/tesseract
_motion_planners/trajopt/deserialize.h

```
graph BT; A["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C["tesseract_motion_planners  
/trajopt/include/tesseract  
_motion_planners/trajopt/deserialize.h"]; B["tesseract_motion_planners  
/trajopt/src/deserialize.cpp"] --> C;
```

The diagram illustrates a file dependency structure. At the top is a gray box representing a header file: `tesseract_motion_planners/trajopt/include/tesseract_motion_planners/trajopt/deserialize.h`. Below it are two white boxes representing source files. The left box is `tesseract_motion_planners/test/serialize_test.cpp` and the right box is `tesseract_motion_planners/trajopt/src/deserialize.cpp`. Two blue arrows point from these source files up to the header file, indicating that both source files include this header.

tesseract_motion_planners
/test/serialize_test.cpp

tesseract_motion_planners
/trajopt/src/deserialize.cpp