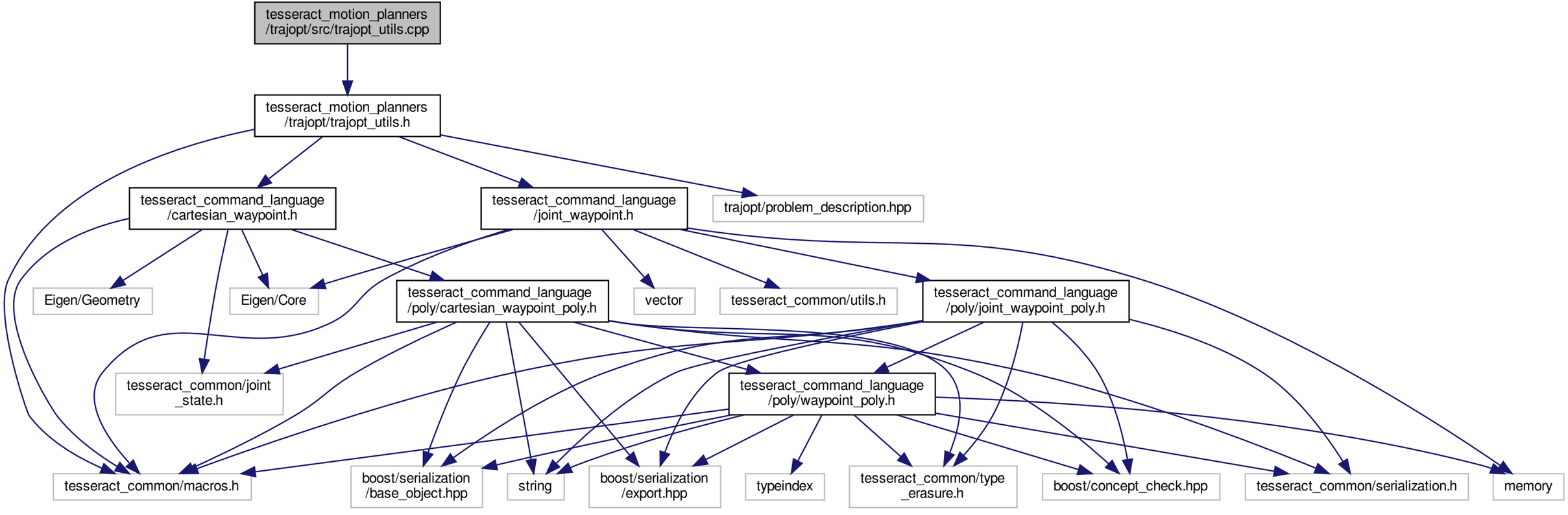
tesseract_motion_planners
/trajopt/src/trajopt_utils.cpp
tesseract_motion_planners
/trajopt/trajopt_utils.h
tesseract_command_language
/cartesian_waypoint.h
tesseract_command_language
/joint_waypoint.h
trajopt/problem_description.hpp
Eigen/Geometry
Eigen/Core
tesseract_command_language
/poly/cartesian_waypoint_poly.h
vector
tesseract_common/utils.h
tesseract_command_language
/poly/joint_waypoint_poly.h
tesseract_common/joint
_state.h
tesseract_command_language
/poly/waypoint_poly.h
tesseract_common/macros.h
boost/serialization
/base_object.hpp
string
boost/serialization
/export.hpp
typeindex
tesseract_common/type
_erasure.h
boost/concept_check.hpp
tesseract_common/serialization.h
memory