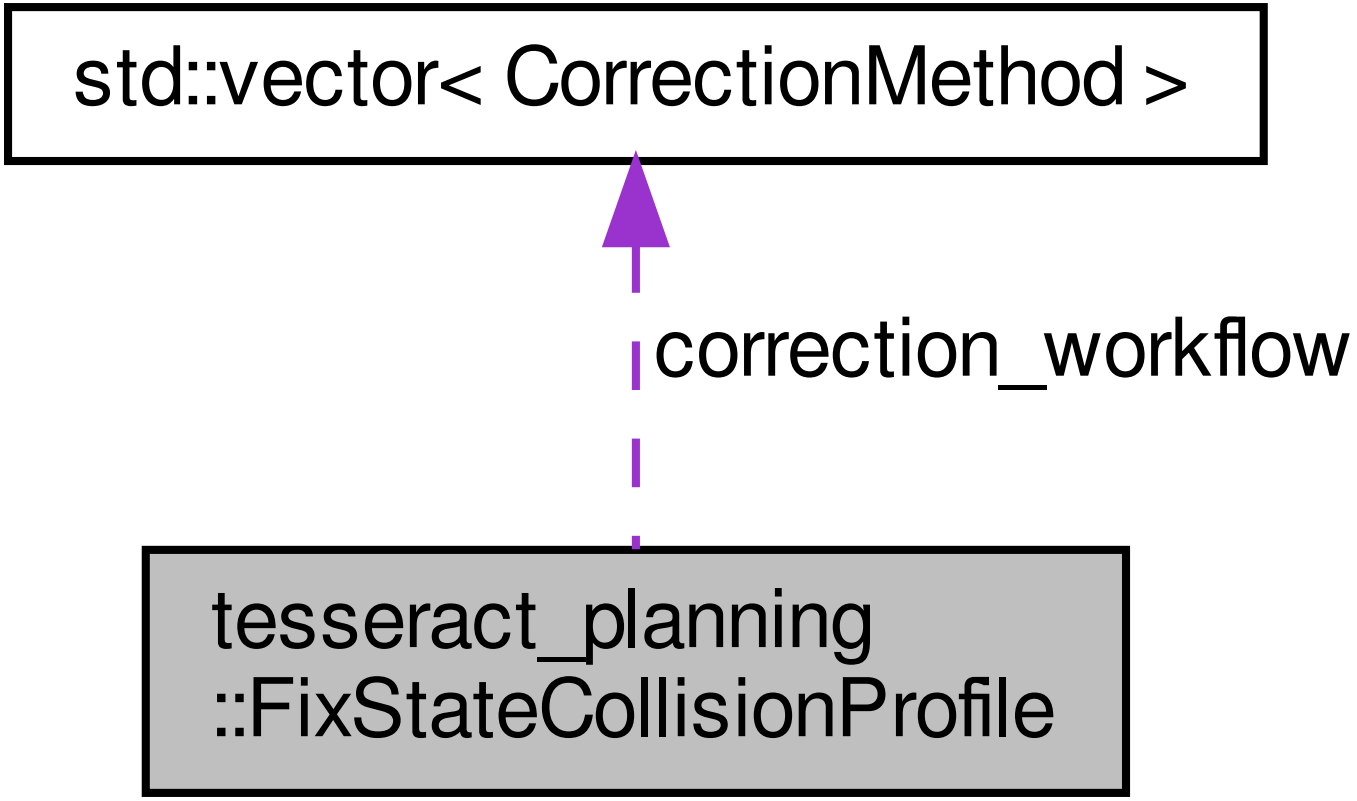
std::vector< CorrectionMethod >
correction_workflow
tesseract_planning
::FixStateCollisionProfile