

ompl::base::StateValidity
Checker



```
graph BT; A[tesseract_planning::StateCollisionValidator] --> B[ompl::base::StateValidityChecker];
```

The diagram illustrates an inheritance relationship. A light gray box at the bottom contains the text 'tesseract_planning::StateCollisionValidator'. A blue arrow points vertically upwards from this box to a white box at the top. The white box contains the text 'ompl::base::StateValidityChecker'.

tesseract_planning
::StateCollisionValidator