

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/state
_collision_validator.h

```
graph BT; A["tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp"] --> C["tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/state_collision_validator.h"]; B["tesseract_motion_planners/ompl/src/state_collision_validator.cpp"] --> C;
```

A diagram illustrating the relationship between three files in the tesseract_motion_planners/ompl directory. At the top is a header file: tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/state_collision_validator.h. Below it are two source files. The left source file is tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp, and the right source file is tesseract_motion_planners/ompl/src/state_collision_validator.cpp. Blue arrows point from each source file to the header file, indicating that both source files include this header.

tesseract_motion_planners
/ompl/src/profile/ompl
_default_plan_profile.cpp

tesseract_motion_planners
/ompl/src/state_collision
_validator.cpp