

tesseract_motion_planners
/descartes/include/tesseract
_motion_planners/descartes
/deserialize.h

```
graph BT; A["tesseract_motion_planners  
/descartes/src/deserialize.cpp"] --> C["tesseract_motion_planners  
/descartes/include/tesseract  
_motion_planners/descartes  
/deserialize.h"]; B["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C;
```

The diagram illustrates a dependency structure. At the top is a grey box representing a header file: `tesseract_motion_planners/descartes/include/tesseract_motion_planners/descartes/deserialize.h`. Below it are two white boxes representing source files. The left box is `tesseract_motion_planners/descartes/src/deserialize.cpp` and the right box is `tesseract_motion_planners/test/serialize_test.cpp`. Blue arrows point from each source file box up to the header file box, indicating that both source files include or depend on the header file.

tesseract_motion_planners
/descartes/src/deserialize.cpp

tesseract_motion_planners
/test/serialize_test.cpp