

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/compound
_state_validator.h

```
graph BT; A["tesseract_motion_planners/ompl/src/compound_state_validator.cpp"] --> C["tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/compound_state_validator.h"]; B["tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp"] --> C;
```

This diagram illustrates the relationship between two source files and a common header file. The header file, located at `tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/compound_state_validator.h`, is included by both `compound_state_validator.cpp` and `default_plan_profile.cpp`. The source files are located in the `src` directory, while the header file is in the `include` directory.

tesseract_motion_planners
/ompl/src/compound_state
_validator.cpp

tesseract_motion_planners
/ompl/src/profile/ompl
_default_plan_profile.cpp