

ompl::base::StateValidity
Checker



```
graph BT; A[tesseract_planning::StateCollisionValidator] --> B[ompl::base::StateValidityChecker];
```

The diagram illustrates an inheritance relationship between two C++ classes. At the bottom is a gray rectangular box containing the text 'tesseract_planning::StateCollisionValidator'. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white rectangular box above it. The white box contains the text 'ompl::base::StateValidityChecker'.

tesseract_planning
::StateCollisionValidator