

tesseract_motion_planners
/trajopt_ifopt/include
/tesseract_motion_planners
/trajopt_ifopt/trajopt_ifopt
_motion_planner.h

```
graph BT; A["tesseract_motion_planners  
/trajopt_ifopt/src/trajopt_ifopt_motion_planner.cpp"] --> C["tesseract_motion_planners  
/trajopt_ifopt/include  
/tesseract_motion_planners  
/trajopt_ifopt/trajopt_ifopt  
_motion_planner.h"]; B["tesseract_task_composer  
/src/task_composer_task_plugin_factory.cpp"] --> C;
```

tesseract_motion_planners
/trajopt_ifopt/src/trajopt
_ifopt_motion_planner.cpp

tesseract_task_composer
/src/task_composer_task
_plugin_factory.cpp