

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/serialize.h

```
graph BT; A["tesseract_motion_planners  
/ompl/src/serialize.cpp"] --> C["tesseract_motion_planners  
/ompl/include/tesseract  
_motion_planners/ompl/serialize.h"]; B["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C;
```

The diagram illustrates the relationship between three source files. At the top, a gray-shaded box contains the header file path: `tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/serialize.h`. Below this, on the left, is a white box with the source file path: `tesseract_motion_planners/ompl/src/serialize.cpp`. On the right is another white box with the test file path: `tesseract_motion_planners/test/serialize_test.cpp`. Two blue arrows point from the bottom of each white box to the bottom of the gray box, indicating that both source files include the header file.

tesseract_motion_planners
/ompl/src/serialize.cpp

tesseract_motion_planners
/test/serialize_test.cpp