

tesseract\_motion\_planners  
/ompl/include/tesseract  
\_motion\_planners/ompl/deserialize.h

```
graph BT; A["tesseract_motion_planners /ompl/src/deserialize.cpp"] --> C["tesseract_motion_planners /ompl/include/tesseract _motion_planners/ompl/deserialize.h"]; B["tesseract_motion_planners /test/serialize_test.cpp"] --> C;
```

The diagram illustrates a dependency structure. At the top is a grey box representing a header file: `tesseract_motion_planners /ompl/include/tesseract _motion_planners/ompl/deserialize.h`. Below it are two white boxes representing source files. The left box is `tesseract_motion_planners /ompl/src/deserialize.cpp` and the right box is `tesseract_motion_planners /test/serialize_test.cpp`. Blue arrows point from each source file box up to the header file box, indicating that both source files include or depend on the header file.

tesseract\_motion\_planners  
/ompl/src/deserialize.cpp

tesseract\_motion\_planners  
/test/serialize\_test.cpp