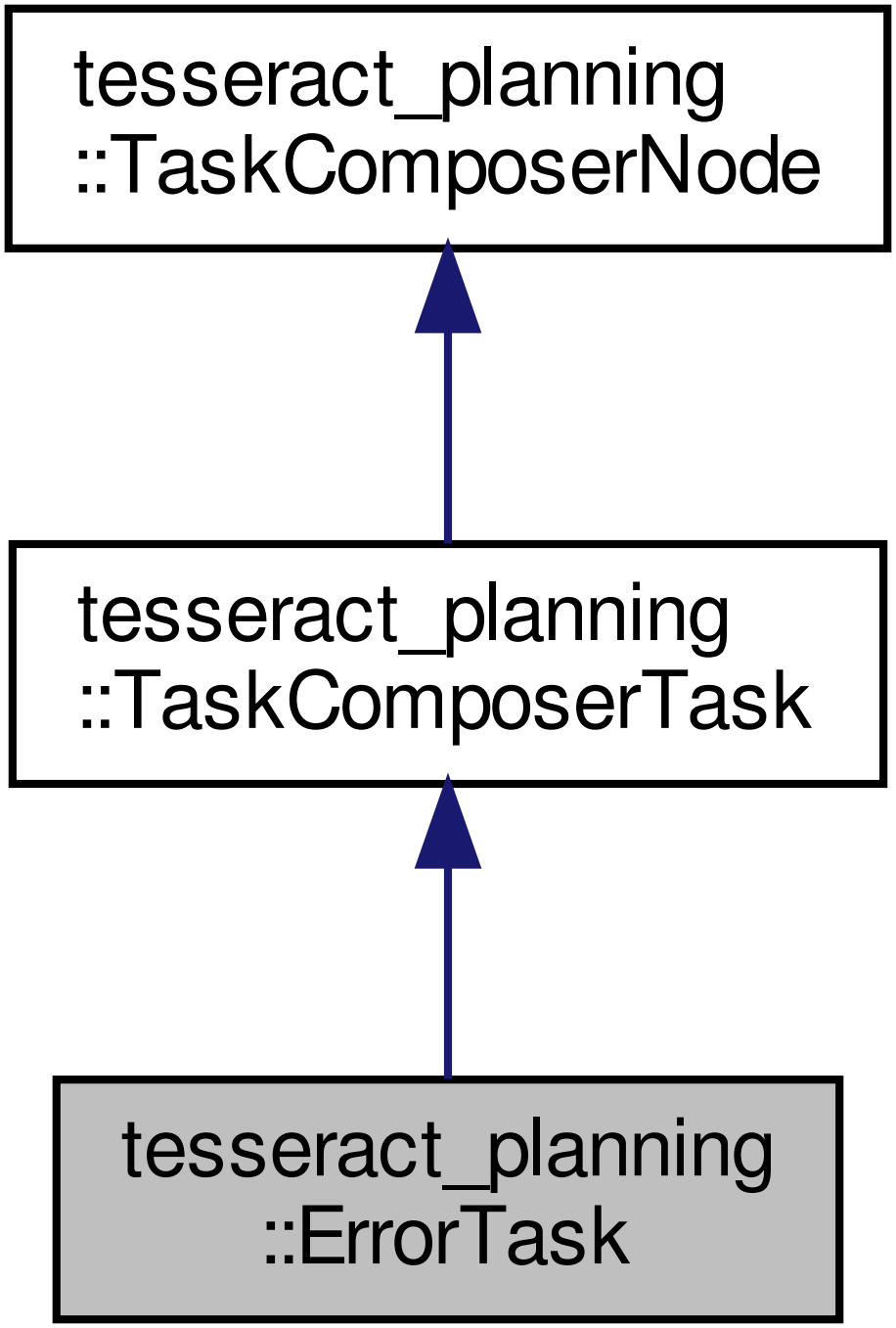
tesseract_planning
::TaskComposerNode
tesseract_planning
::TaskComposerTask
tesseract_planning
::ErrorTask