

tesseract_motion_planners
/trajopt/include/tesseract
_motion_planners/trajopt/deserialize.h

```
graph BT; A["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C["tesseract_motion_planners  
/trajopt/include/tesseract  
_motion_planners/trajopt/deserialize.h"]; B["tesseract_motion_planners  
/trajopt/src/deserialize.cpp"] --> C;
```

The diagram illustrates the relationship between three files in the tesseract_motion_planners package. At the top is a header file, deserialize.h, located in the trajopt/include directory. Below it are two source files: serialize_test.cpp in the test directory and deserialize.cpp in the trajopt/src directory. Blue arrows point from each source file to the header file, indicating that both source files include this header.

tesseract_motion_planners
/test/serialize_test.cpp

tesseract_motion_planners
/trajopt/src/deserialize.cpp