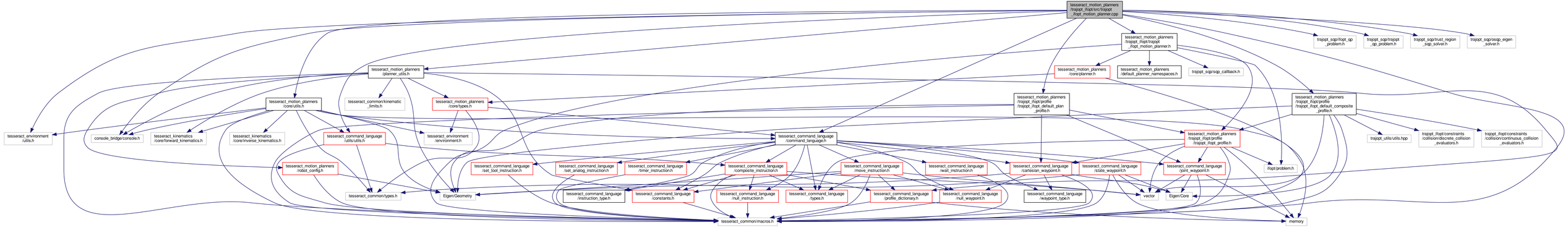
tesseract_motion_planners/trajopt_ifopt/src/trajopt_ifopt_motion_planner.cpp
tesseract_motion_planners/trajopt_ifopt/trajopt_ifopt_motion_planner.h
trajopt_sqp/ifopt_qp_problem.h
trajopt_sqp/trajopt_qp_problem.h
trajopt_sqp/trust_region_sqp_solver.h
trajopt_sqp/osqp_eigen_solver.h
tesseract_motion_planners/planner_utils.h
tesseract_motion_planners/core/planner.h
tesseract_motion_planners/default_planner_namespaces.h
trajopt_sqp/sqp_callback.h
tesseract_motion_planners/core/utils.h
tesseract_common/kinematic_limits.h
tesseract_motion_planners/core/types.h
tesseract_motion_planners/trajopt_ifopt/profile/trajopt_ifopt_default_plan_profile.h
tesseract_motion_planners/trajopt_ifopt/profile/trajopt_ifopt_default_composite_profile.h
tesseract_environment/utils.h
console_bridge/console.h
tesseract_kinematics/core/forward_kinematics.h
tesseract_kinematics/core/inverse_kinematics.h
tesseract_command_language/utils/utils.h
tesseract_environment/environment.h
tesseract_command_language/command_language.h
tesseract_motion_planners/trajopt_ifopt/profile/trajopt_ifopt_profile.h
trajopt_utils/utils.hpp
trajopt_ifopt/constraints/collision/discrete_collision_evaluators.h
trajopt_ifopt/constraints/collision/continuous_collision_evaluators.h
tesseract_motion_planners/robot_config.h
tesseract_command_language/set_tool_instruction.h
tesseract_command_language/set_analog_instruction.h
tesseract_command_language/timer_instruction.h
tesseract_command_language/composite_instruction.h
tesseract_command_language/move_instruction.h
tesseract_command_language/wait_instruction.h
tesseract_command_language/cartesian_waypoint.h
tesseract_command_language/state_waypoint.h
tesseract_command_language/joint_waypoint.h
ifopt/problem.h
tesseract_common/types.h
Eigen/Geometry
tesseract_command_language/instruction_type.h
tesseract_command_language/constants.h
tesseract_command_language/null_instruction.h
tesseract_command_language/types.h
tesseract_command_language/profile_dictionary.h
tesseract_command_language/null_waypoint.h
tesseract_command_language/waypoint_type.h
vector
Eigen/Core
tesseract_common/macros.h
memory