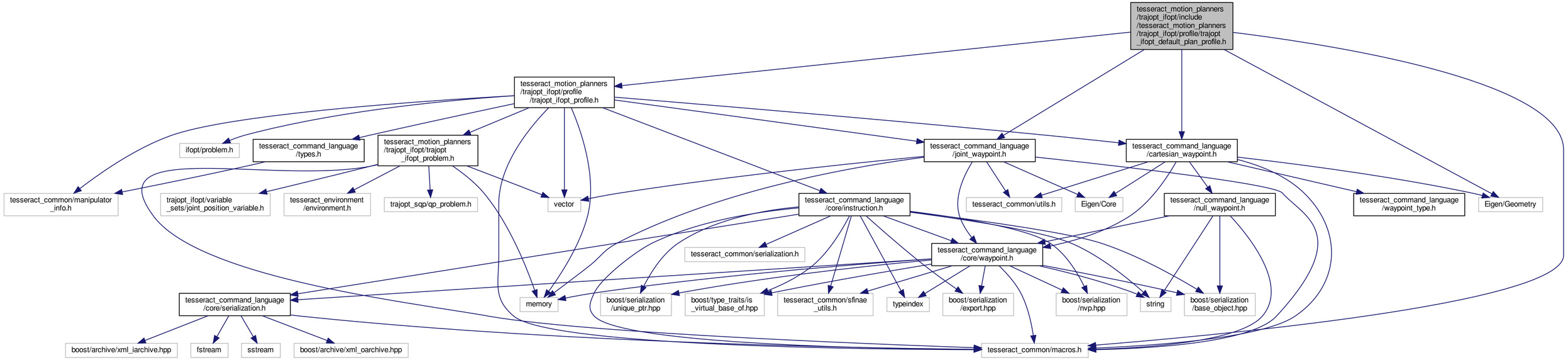
tesseract_motion_planners /trajopt_ifopt/include /tesseract_motion_planners /trajopt_ifopt/profile/trajopt _ifopt_default_plan_profile.h
tesseract_motion_planners /trajopt_ifopt/profile /trajopt_ifopt_profile.h
ifopt/problem.h
tesseract_command_language /types.h
tesseract_motion_planners /trajopt_ifopt/trajopt _ifopt_problem.h
tesseract_command_language /joint_waypoint.h
tesseract_command_language /cartesian_waypoint.h
tesseract_common/manipulator _info.h
trajopt_ifopt/variable _sets/joint_position_variable.h
tesseract_environment /environment.h
trajopt_sqp/qp_problem.h
vector
tesseract_command_language /core/instruction.h
tesseract_common/utils.h
Eigen/Core
tesseract_command_language /null_waypoint.h
tesseract_command_language /waypoint_type.h
Eigen/Geometry
tesseract_common/serialization.h
tesseract_command_language /core/waypoint.h
tesseract_command_language /core/serialization.h
memory
boost/serialization /unique_ptr.hpp
boost/type_traits/is _virtual_base_of.hpp
tesseract_common/sfinae _utils.h
typeindex
boost/serialization /export.hpp
boost/serialization /nvp.hpp
string
boost/serialization /base_object.hpp
boost/archive/xml_iarchive.hpp
fstream
sstream
boost/archive/xml_oarchive.hpp
tesseract_common/macros.h