

tesseract\_planning  
::MotionPlanner



```
graph BT; A[tesseract_planning::OMPLMotionPlanner] --> B[tesseract_planning::MotionPlanner];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray rectangular box containing the text 'tesseract\_planning' followed by '::OMPLMotionPlanner' on the next line. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white rectangular box above it. The white box contains the text 'tesseract\_planning' followed by '::MotionPlanner' on the next line. Both boxes have a thin black border.

tesseract\_planning  
::OMPLMotionPlanner