

tesseract\_planning  
::MotionPlanner



```
graph BT; A[tesseract_planning::TrajOptMotionPlanner] --> B[tesseract_planning::MotionPlanner];
```

A diagram illustrating inheritance. A light gray box at the bottom contains the text 'tesseract\_planning' and '::TrajOptMotionPlanner'. A blue arrow points upwards from this box to a white box at the top. The white box contains the text 'tesseract\_planning' and '::MotionPlanner'.

tesseract\_planning  
::TrajOptMotionPlanner