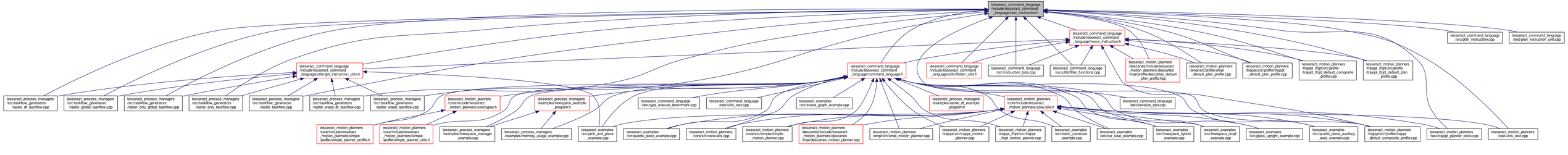
tesseract_command_language /include/tesseract_command_language/plan_instruction.h
tesseract_command_language /include/tesseract_command_language/move_instruction.h
tesseract_command_language /include/tesseract_command_language/utils/get_instruction_utils.h
tesseract_command_language /include/tesseract_command_language/command_language.h
tesseract_command_language /include/tesseract_command_language/utils/flatten_utils.h
tesseract_command_language /src/instruction_type.cpp
tesseract_command_language /src/utils/filter_functions.cpp
tesseract_motion_planners /descartes/include/tesseract_motion_planners/descartes/impl/profile/descartes_default_plan_profile.hpp
tesseract_motion_planners /ompl/src/profile/ompl_default_plan_profile.cpp
tesseract_motion_planners /trajopt/src/profile/trajopt_default_plan_profile.cpp
tesseract_motion_planners /trajopt_ifopt/src/profile/trajopt_ifopt_default_composite_profile.cpp
tesseract_motion_planners /trajopt_ifopt/src/profile/trajopt_ifopt_default_plan_profile.cpp
tesseract_command_language /src/plan_instruction.cpp
tesseract_command_language /test/plan_instruction_unit.cpp
tesseract_process_managers /src/task/flow_generators/raster_dt_task/flow.cpp
tesseract_process_managers /src/task/flow_generators/raster_global_task/flow.cpp
tesseract_process_managers /src/task/flow_generators/raster_only_global_task/flow.cpp
tesseract_process_managers /src/task/flow_generators/raster_only_task/flow.cpp
tesseract_process_managers /src/task/flow_generators/raster_task/flow.cpp
tesseract_process_managers /src/task/flow_generators/raster_waad_dt_task/flow.cpp
tesseract_process_managers /src/task/flow_generators/raster_waad_task/flow.cpp
tesseract_motion_planners /core/include/tesseract_motion_planners/core/types.h
tesseract_motion_planners /core/include/tesseract_motion_planners/simple/profile/simple_planner_profile.h
tesseract_motion_planners /core/include/tesseract_motion_planners/simple/profile/simple_planner_utils.h
tesseract_process_managers /examples/freespace_example/program.h
tesseract_process_managers /examples/freespace_manager_example.cpp
tesseract_process_managers /examples/memory_usage_example.cpp
tesseract_examples /src/pick_and_place_example.cpp
tesseract_examples /src/puzzle_piece_example.cpp
tesseract_command_language /test/type_erasure_benchmark.cpp
tesseract_motion_planners /core/src/core/utils.cpp
tesseract_command_language /test/utils_test.cpp
tesseract_motion_planners /simple/src/simple_motion_planner.cpp
tesseract_motion_planners /descartes/include/tesseract_motion_planners/descartes/impl/descartes_motion_planner.hpp
tesseract_examples /src/scene_graph_example.cpp
tesseract_motion_planners /ompl/src/ompl_motion_planner.cpp
tesseract_process_managers /examples/raster_dt_example/program.h
tesseract_motion_planners /trajopt/src/trajopt_motion_planner.cpp
tesseract_motion_planners /core/include/tesseract_motion_planners/core/utils.h
tesseract_motion_planners /trajopt_ifopt/src/trajopt_ifopt_motion_planner.cpp
tesseract_command_language /test/serialize_test.cpp
tesseract_examples /src/basic_cartesian_example.cpp
tesseract_examples /src/car_seat_example.cpp
tesseract_examples /src/freespace_hybrid_example.cpp
tesseract_examples /src/freespace_ompl_example.cpp
tesseract_examples /src/glass_upright_example.cpp
tesseract_examples /src/puzzle_piece_auxiliary_axis_example.cpp
tesseract_motion_planners /trajopt/src/profile/trajopt_default_composite_profile.cpp
tesseract_motion_planners /test/trajopt_planner_tests.cpp
tesseract_motion_planners /test/utils_test.cpp