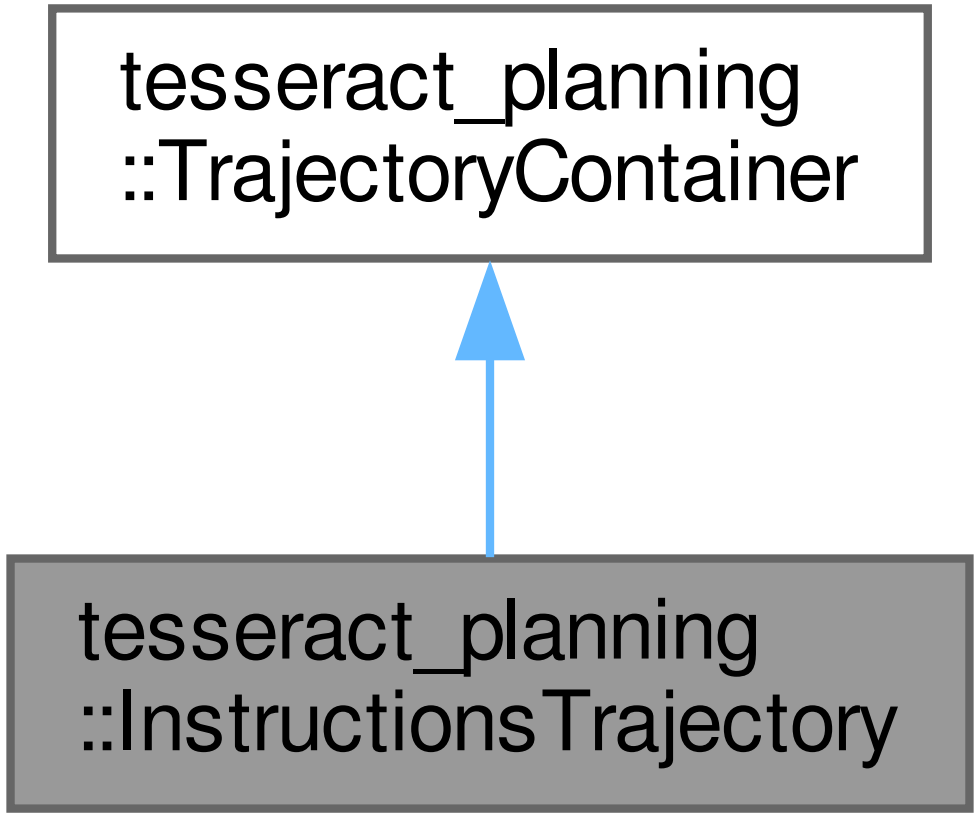
tesseract_planning
::TrajectoryContainer
tesseract_planning
::InstructionsTrajectory