```
tesseract_planning          tesseract_planning          tesseract_planning
::TaskComposerNode    ◄──── ::TaskComposerGraph   ◄──── ::MotionPipelineTask
                                                         < MotionPlannerTaskType,
                                                          ContactCheckTaskType,
                                                          TimeParameterizationTaskType >
```

tesseract_planning
::DescartesMotionPipelineTask
< DescartesMotionPlannerTask,
 DiscreteContactCheckTask, Iterative
 SplineParameterizationTask >

tesseract_planning
::OMPLMotionPipelineTask
< OMPLMotionPlannerTask,
 DiscreteContactCheckTask,
 IterativeSplineParameterizationTask >

tesseract_planning
::TrajOptIfoptMotionPipeline
Task< TrajOptIfoptMotionPlannerTask,
 DiscreteContactCheckTask, IterativeSpline
 ParameterizationTask >

tesseract_planning
::TrajOptMotionPipelineTask
< TrajOptMotionPlannerTask,
 DiscreteContactCheckTask,
 IterativeSplineParameterizationTask >