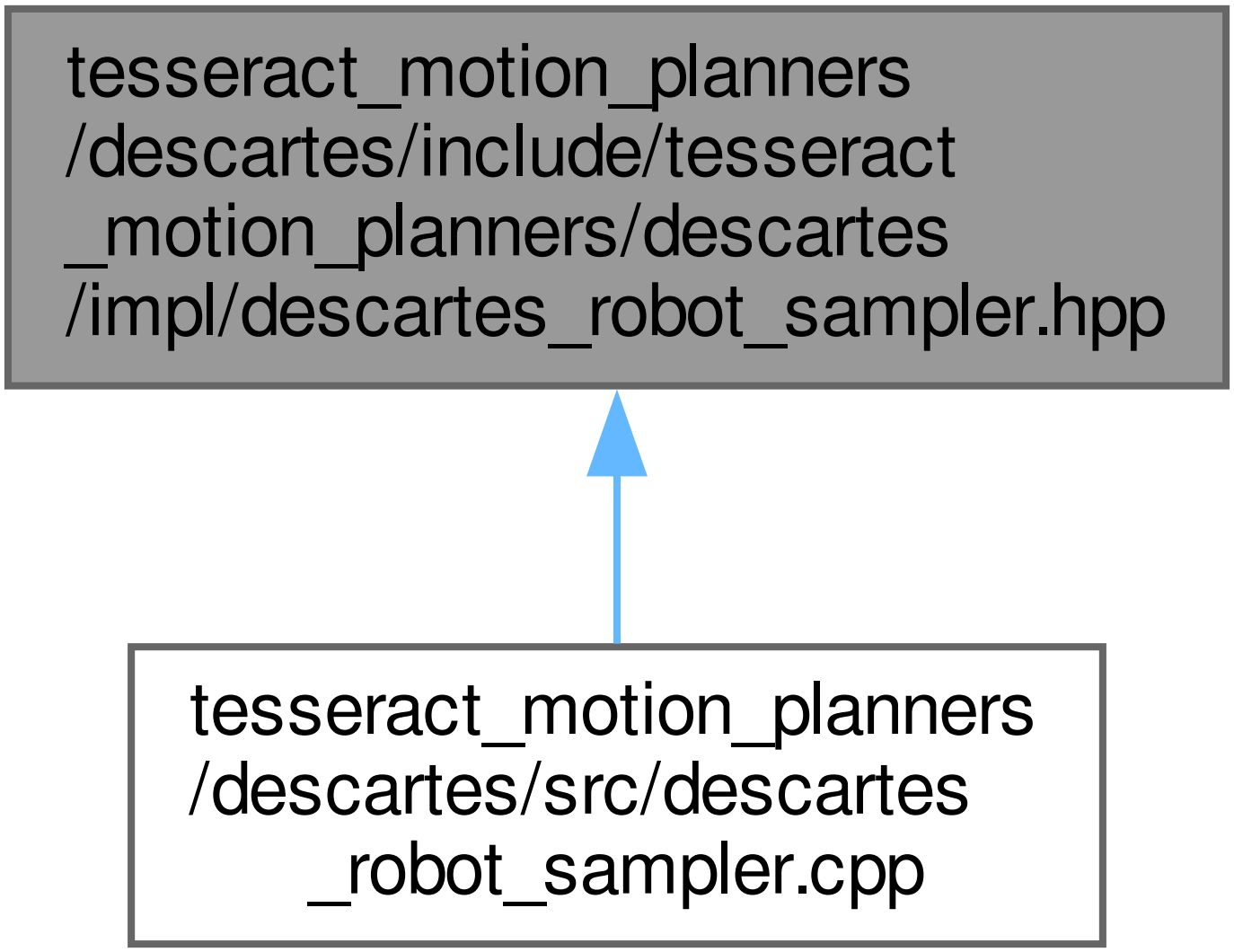
tesseract_motion_planners
/descartes/include/tesseract
_motion_planners/descartes
/impl/descartes_robot_sampler.hpp
tesseract_motion_planners
/descartes/src/descartes
_robot_sampler.cpp