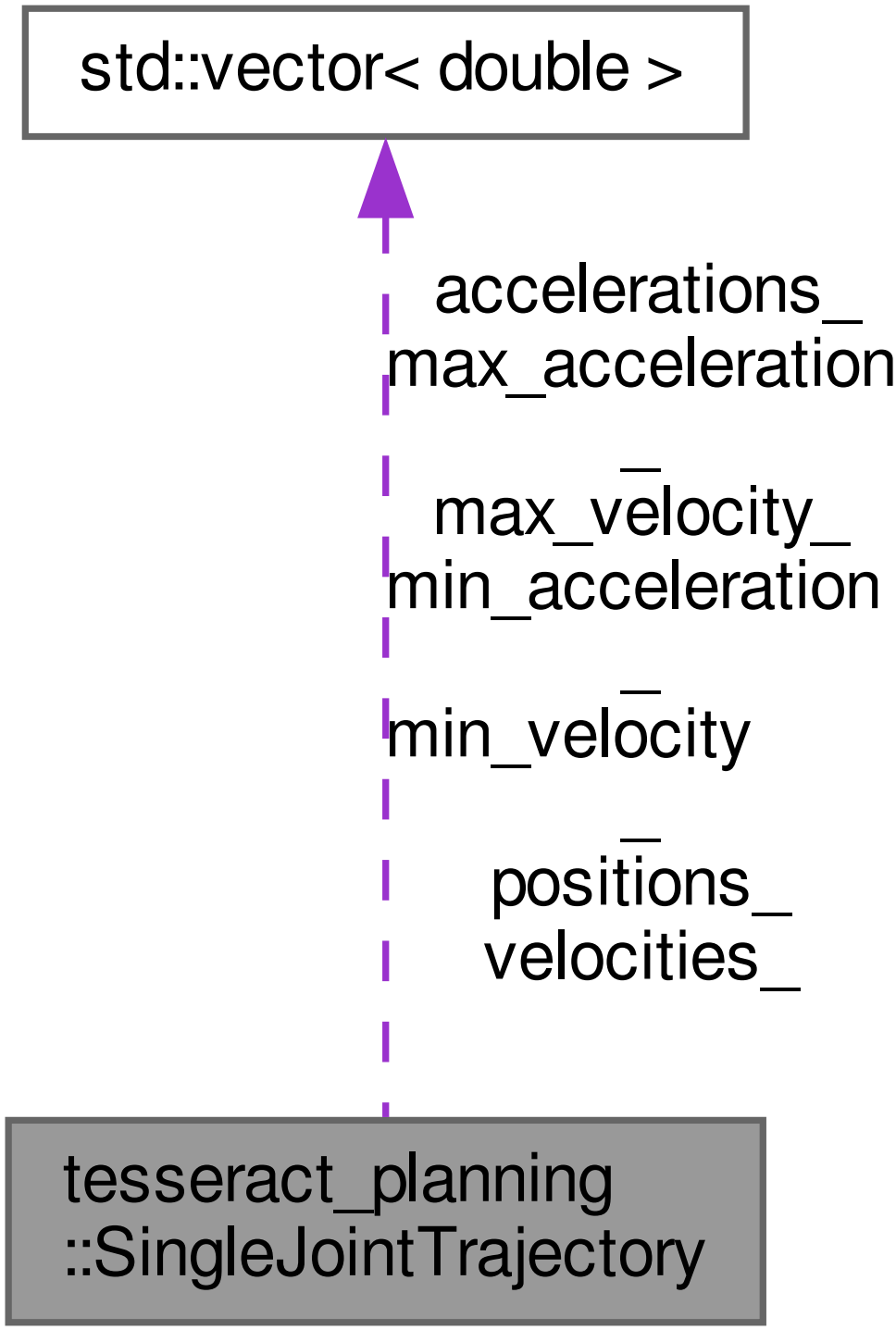
std::vector< double >
accelerations_
max_acceleration
_
max_velocity_
min_acceleration
_
min_velocity
_
positions_
velocities_
tesseract_planning
::SingleJointTrajectory