

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/state
_collision_validator.h

```
graph BT; A["tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp"] --> C["tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/state_collision_validator.h"]; B["tesseract_motion_planners/ompl/src/state_collision_validator.cpp"] --> C;
```

This diagram illustrates the relationship between three source files in the tesseract_motion_planners/ompl directory. At the top, a grey box represents the header file `_collision_validator.h`. Below it, two white boxes represent source files: `_default_plan_profile.cpp` on the left and `_validator.cpp` on the right. Blue arrows point from each source file to the header file, indicating that both source files include this header.

tesseract_motion_planners
/ompl/src/profile/ompl
_default_plan_profile.cpp

tesseract_motion_planners
/ompl/src/state_collision
_validator.cpp