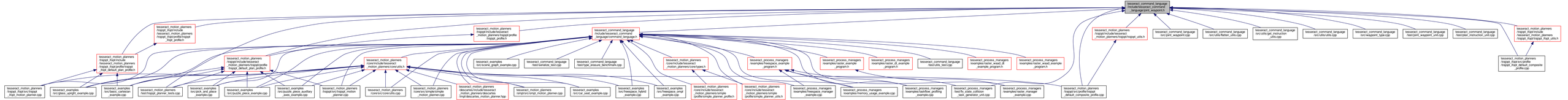
tesseract_command_language /include/tesseract_command_language/joint_waypoint.h
tesseract_motion_planners /trapopt_ifopt/include /tesseract_motion_planners /trapopt_ifopt/profile/trapopt_ifopt_profile.h
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tesseract_motion_planners /trapopt_ifopt/src/trapopt_ifopt_motion_planner.cpp
tesseract_examples /src/glass_upright_example.cpp
tesseract_examples /src/basic_cartesian_example.cpp
tesseract_motion_planners /test/trapopt_planner_tests.cpp
tesseract_examples /src/pick_and_place_example.cpp
tesseract_examples /src/puzzle_piece_example.cpp
tesseract_examples /src/puzzle_piece_auxiliary_axis_example.cpp
tesseract_motion_planners /trapopt/src/trapopt_motion_planner.cpp
tesseract_motion_planners /core/src/core/utils.cpp
tesseract_motion_planners /core/src/simple/simple_motion_planner.cpp
tesseract_motion_planners /descartes/include/tesseract_motion_planners/descartes /impl/descartes_motion_planner.hpp
tesseract_motion_planners /ompl/src/ompl_motion_planner.cpp
tesseract_examples /src/car_seat_example.cpp
tesseract_examples /src/freespace_hybrid_example.cpp
tesseract_examples /src/freespace_ompl_example.cpp
tesseract_motion_planners /core/include/tesseract_motion_planners/simple /profile/simple_planner_profile.h
tesseract_motion_planners /core/include/tesseract_motion_planners/simple /profile/simple_planner_utils.h
tesseract_process_managers /examples/freespace_manager_example.cpp
tesseract_process_managers /examples/memory_usage_example.cpp
tesseract_process_managers /examples/task/flow_profiling_example.cpp
tesseract_process_managers /test/fk_state_collision_task_generator_unit.cpp
tesseract_process_managers /examples/raster_manager_example.cpp
tesseract_motion_planners /trapopt/src/profile/trapopt_default_composite_profile.cpp
tesseract_examples /src/scene_graph_example.cpp
tesseract_command_language /test/serialize_test.cpp
tesseract_command_language /test/type_erasure_benchmark.cpp
tesseract_motion_planners /core/include/tesseract_motion_planners/core/types.h
tesseract_process_managers /examples/freespace_example_program.h
tesseract_process_managers /examples/raster_example_program.h
tesseract_process_managers /examples/raster_g_example_program.h
tesseract_process_managers /examples/raster_waad_dt_example_program.h
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tesseract_motion_planners /trapopt/include/tesseract_motion_planners/trapopt/trapopt_utils.h
tesseract_command_language /src/joint_waypoint.cpp
tesseract_command_language /src/utils/flatten_utils.cpp
tesseract_command_language /src/utils/get_instruction_utils.cpp
tesseract_command_language /src/utils/utils.cpp
tesseract_command_language /src/waypoint_type.cpp
tesseract_command_language /test/joint_waypoint_unit.cpp
tesseract_command_language /test/plan_instruction_unit.cpp