

tesseract\_motion\_planners  
/trajopt/include/tesseract  
\_motion\_planners/trajopt/deserialize.h

```
graph BT; A["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C["tesseract_motion_planners  
/trajopt/include/tesseract  
_motion_planners/trajopt/deserialize.h"]; B["tesseract_motion_planners  
/trajopt/src/deserialize.cpp"] --> C;
```

The diagram illustrates a dependency structure where two source files include a common header file. The header file is located at `tesseract_motion_planners/trajopt/include/tesseract_motion_planners/trajopt/deserialize.h`. The first source file, `tesseract_motion_planners/test/serialize_test.cpp`, is on the left, and the second source file, `tesseract_motion_planners/trajopt/src/deserialize.cpp`, is on the right. Both source files have blue arrows pointing to the header file, indicating that they both include it.

tesseract\_motion\_planners  
/test/serialize\_test.cpp

tesseract\_motion\_planners  
/trajopt/src/deserialize.cpp