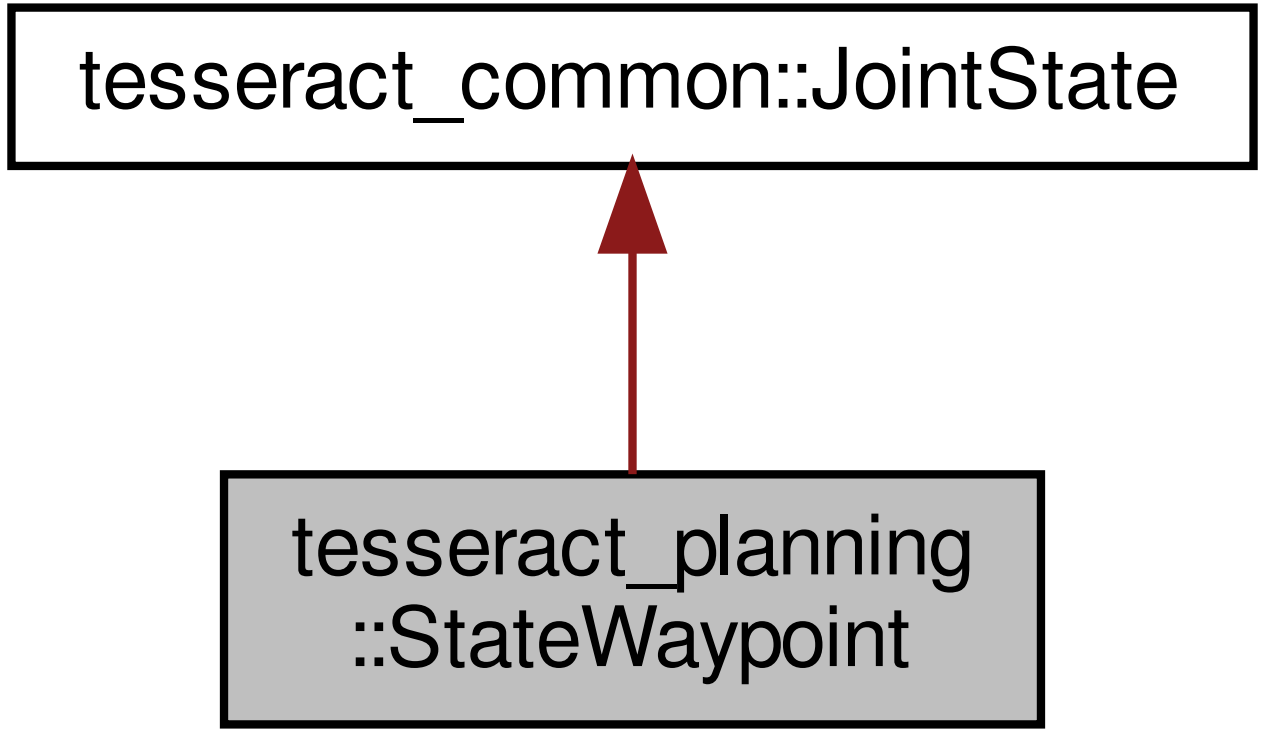
tesseract_common::JointState
tesseract_planning
::StateWaypoint