

tesseract_planning
::TaskInfo



```
graph BT; A[tesseract_planning::CheckInputTaskInfo] --> B[tesseract_planning::TaskInfo];
```

The diagram illustrates an inheritance relationship between two classes in the tesseract_planning namespace. At the bottom is a gray-shaded box representing the base class, tesseract_planning::CheckInputTaskInfo. A blue arrow points vertically upwards from this box to a white box at the top, which represents the derived class, tesseract_planning::TaskInfo. Both boxes have a black border and contain their respective class names in two lines.

tesseract_planning
::CheckInputTaskInfo