

tesseract_motion_planners
/trajopt/include/tesseract
_motion_planners/trajopt/serialize.h

```
graph BT; A["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C["tesseract_motion_planners  
/trajopt/include/tesseract  
_motion_planners/trajopt/serialize.h"]; B["tesseract_motion_planners  
/trajopt/src/serialize.cpp"] --> C;
```

The diagram illustrates the relationship between three files in the tesseract_motion_planners package. At the top is a header file, `serialize.h`, located in `/trajopt/include/tesseract_motion_planners/trajopt/`. Below it are two source files. The file on the left, `serialize_test.cpp` in the `/test/` directory, has a blue arrow pointing to the header file. The file on the right, `serialize.cpp` in the `/trajopt/src/` directory, also has a blue arrow pointing to the header file. The header file box is shaded gray, while the source file boxes are white.

tesseract_motion_planners
/test/serialize_test.cpp

tesseract_motion_planners
/trajopt/src/serialize.cpp