

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/state
_collision_validator.h

```
graph BT; A["tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp"] --> C["tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/state_collision_validator.h"]; B["tesseract_motion_planners/ompl/src/state_collision_validator.cpp"] --> C;
```

A diagram illustrating the relationship between three files in the tesseract_motion_planners/ompl directory. At the top is a header file, tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/state_collision_validator.h, enclosed in a grey box. Below it are two source files, each in a white box with a black border. The file on the left is tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp, and the file on the right is tesseract_motion_planners/ompl/src/state_collision_validator.cpp. Blue arrows point from the bottom of each source file box up to the header file box, indicating that both source files include the header file.

tesseract_motion_planners
/ompl/src/profile/ompl
_default_plan_profile.cpp

tesseract_motion_planners
/ompl/src/state_collision
_validator.cpp