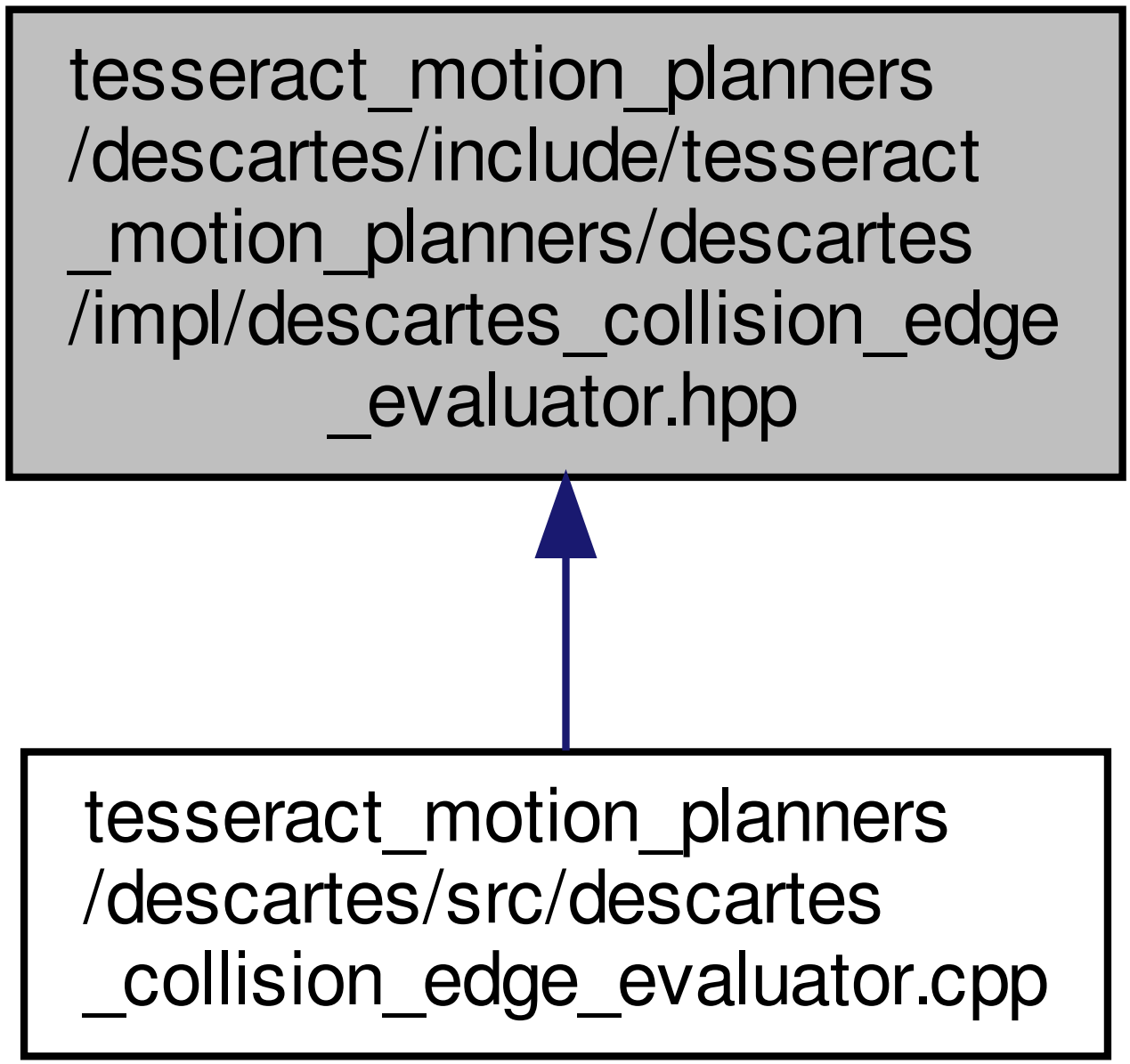
tesseract_motion_planners
/descartes/include/tesseract
_motion_planners/descartes
/impl/descartes_collision_edge
_evaluator.hpp
tesseract_motion_planners
/descartes/src/descartes
_collision_edge_evaluator.cpp