

tesseract\_task\_composer  
/include/tesseract\_task  
\_composer/nodes/fix\_state  
\_bounds\_task.h

```
graph BT; A["tesseract_task_composer/src/nodes/fix_state_bounds_task.cpp"] --> C["tesseract_task_composer/include/tesseract_task_composer/nodes/fix_state_bounds_task.h"]; B["tesseract_task_composer/test/fix_state_bounds_task_unit.cpp"] --> C;
```

The diagram illustrates the relationship between three files in the tesseract\_task\_composer project. At the top is a header file, tesseract\_task\_composer/include/tesseract\_task\_composer/nodes/fix\_state\_bounds\_task.h, which is shaded gray. Below it are two source files: tesseract\_task\_composer/src/nodes/fix\_state\_bounds\_task.cpp on the left and tesseract\_task\_composer/test/fix\_state\_bounds\_task\_unit.cpp on the right. Both source files have blue arrows pointing up to the header file, indicating that they include it.

tesseract\_task\_composer  
/src/nodes/fix\_state\_bounds  
\_task.cpp

tesseract\_task\_composer  
/test/fix\_state\_bounds  
\_task\_unit.cpp