

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/state
_collision_validator.h

```
graph BT; A["tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp"] --> C["tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/state_collision_validator.h"]; B["tesseract_motion_planners/ompl/src/state_collision_validator.cpp"] --> C;
```

A diagram showing two source files at the bottom and a header file at the top. Two blue arrows point from the source files to the header file, indicating that they include it. The header file is in a grey box, while the source files are in white boxes with black borders.

tesseract_motion_planners
/ompl/src/profile/ompl
_default_plan_profile.cpp

tesseract_motion_planners
/ompl/src/state_collision
_validator.cpp