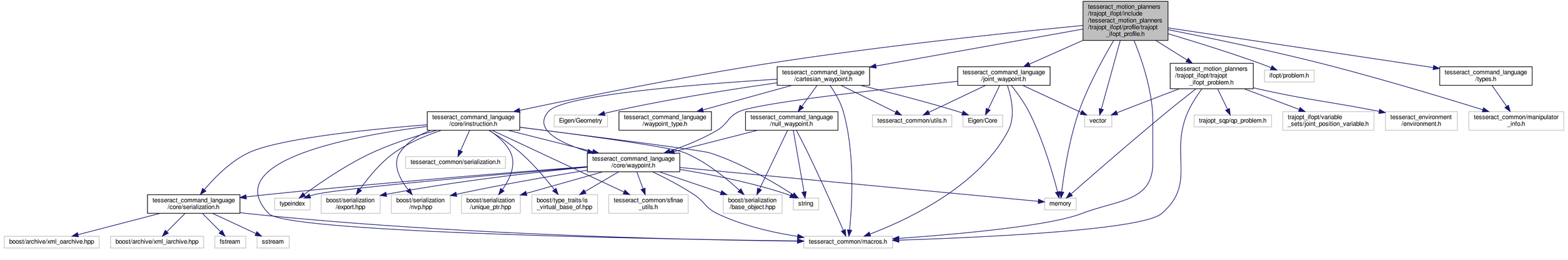
tesseract_motion_planners/trajopt_ifopt/include/tesseract_motion_planners/trajopt_ifopt/profile/trajopt_ifopt_profile.h
tesseract_command_language/cartesian_waypoint.h
tesseract_command_language/joint_waypoint.h
tesseract_motion_planners/trajopt_ifopt/trajopt_ifopt_problem.h
ifopt/problem.h
tesseract_command_language/types.h
tesseract_command_language/core/instruction.h
Eigen/Geometry
tesseract_command_language/waypoint_type.h
tesseract_command_language/null_waypoint.h
tesseract_common/utils.h
Eigen/Core
vector
trajopt_sqp/qp_problem.h
trajopt_ifopt/variable_sets/joint_position_variable.h
tesseract_environment/environment.h
tesseract_common/manipulator_info.h
tesseract_common/serialization.h
tesseract_command_language/core/waypoint.h
tesseract_command_language/core/serialization.h
typeindex
boost/serialization/export.hpp
boost/serialization/nvp.hpp
boost/serialization/unique_ptr.hpp
boost/type_traits/is_virtual_base_of.hpp
tesseract_common/sfinae_utils.h
boost/serialization/base_object.hpp
string
memory
boost/archive/xml_oarchive.hpp
boost/archive/xml_iarchive.hpp
fstream
sstream
tesseract_common/macros.h