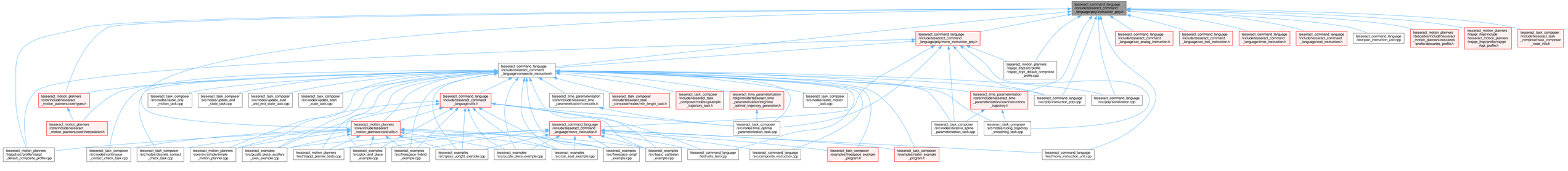
tesseract_command_language /include/tesseract_command _language/poly/instruction_poly.h
tesseract_command_language /include/tesseract_command _language/poly/move_instruction_poly.h
tesseract_command_language /include/tesseract_command _language/composite_instruction.h
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tesseract_command_language /include/tesseract_command _language/timer_instruction.h
tesseract_command_language /include/tesseract_command _language/wait_instruction.h
tesseract_command_language /test/plan_instruction_unit.cpp
tesseract_motion_planners /descartes/include/tesseract _motion_planners/descartes _profile/descartes_profile.h
tesseract_motion_planners /trajopt_ifopt/include /tesseract_motion_planners /trajopt_ifopt/profile/trajopt _ifopt_profile.h
tesseract_task_composer /include/tesseract_task _composer/task_composer _node_info.h
tesseract_motion_planners /trajopt_ifopt/src/profile /trajopt_ifopt_default_composite _profile.cpp
tesseract_motion_planners /core/include/tesseract _motion_planners/core/types.h
tesseract_motion_planners /core/include/tesseract _motion_planners/core/interpolation.h
tesseract_task_composer /src/nodes/raster_only _motion_task.cpp
tesseract_task_composer /src/nodes/update_end _state_task.cpp
tesseract_task_composer /src/nodes/update_start _and_end_state_task.cpp
tesseract_task_composer /src/nodes/update_start _state_task.cpp
tesseract_motion_planners /core/include/tesseract _motion_planners/core/utils.h
tesseract_time_parameterization /core/include/tesseract_time _parameterization/core/utils.h
tesseract_task_composer /include/tesseract_task _composer/nodes/min_length_task.h
tesseract_task_composer /include/tesseract_task _composer/nodes/upsample _trajectory_task.h
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tesseract_task_composer /src/nodes/raster_motion _task.cpp
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tesseract_command_language /src/poly/instruction_poly.cpp
tesseract_command_language /src/poly/serialization.cpp
tesseract_task_composer /src/nodes/time_optimal _parameterization_task.cpp
tesseract_task_composer /src/nodes/iterative_spline _parameterization_task.cpp
tesseract_task_composer /src/nodes/ruckig_trajectory _smoothing_task.cpp
tesseract_motion_planners /trajopt/src/profile/trajopt _default_composite_profile.cpp
tesseract_task_composer /src/nodes/continuous _contact_check_task.cpp
tesseract_task_composer /src/nodes/discrete_contact _check_task.cpp
tesseract_motion_planners /core/src/simple/simple _motion_planner.cpp
tesseract_examples /src/puzzle_piece_auxiliary _pass_example.cpp
tesseract_motion_planners /test/trajopt_planner_tests.cpp
tesseract_examples /src/pick_and_place _example.cpp
tesseract_examples /src/freespace_hybrid _example.cpp
tesseract_examples /src/glass_upright_example.cpp
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tesseract_command_language /src/composite_instruction.cpp
tesseract_task_composer /examples/freespace_example _program.h
tesseract_task_composer /examples/raster_example _program.h
tesseract_command_language /test/move_instruction_unit.cpp