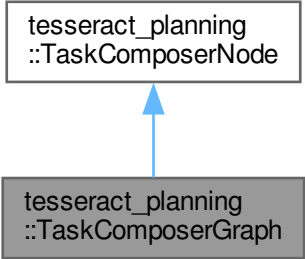


tesseract_planning
::TaskComposerNode



```
graph BT; A[tesseract_planning::TaskComposerGraph] --> B[tesseract_planning::TaskComposerNode]
```

The diagram consists of two rectangular boxes. The top box is white with a black border and contains the text 'tesseract_planning' followed by '::TaskComposerNode' on two lines. The bottom box is gray with a black border and contains the text 'tesseract_planning' followed by '::TaskComposerGraph' on two lines. A blue arrow points vertically from the top of the gray box to the bottom of the white box, indicating an inheritance or relationship.

tesseract_planning
::TaskComposerGraph