

tesseract\_planning  
::TaskInfo



```
classDiagram
    class tesseract_planning_FixStateCollisionTaskInfo["tesseract_planning::FixStateCollisionTaskInfo"]
    class tesseract_planning_TaskInfo["tesseract_planning::TaskInfo"]
    tesseract_planning_FixStateCollisionTaskInfo --|> tesseract_planning_TaskInfo
```

The diagram illustrates a class hierarchy. At the bottom is a gray-shaded box representing the base class, `tesseract_planning::FixStateCollisionTaskInfo`. A blue arrow points upwards from this box to a white box above it, representing the derived class, `tesseract_planning::TaskInfo`. Both boxes have a black border and contain their respective class names in two lines.

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