

tesseract\_motion\_planners  
/ompl/include/tesseract  
\_motion\_planners/ompl/serialize.h

```
graph BT; A["tesseract_motion_planners  
/ompl/src/serialize.cpp"] --> C["tesseract_motion_planners  
/ompl/include/tesseract  
_motion_planners/ompl/serialize.h"]; B["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C;
```

The diagram illustrates the relationship between three source files. At the top is a header file, 'tesseract\_motion\_planners/ompl/include/tesseract\_motion\_planners/ompl/serialize.h', which is shaded gray. Below it are two source files: 'tesseract\_motion\_planners/ompl/src/serialize.cpp' on the left and 'tesseract\_motion\_planners/test/serialize\_test.cpp' on the right. Both source files have blue arrows pointing upwards to the header file, indicating that they include it.

tesseract\_motion\_planners  
/ompl/src/serialize.cpp

tesseract\_motion\_planners  
/test/serialize\_test.cpp