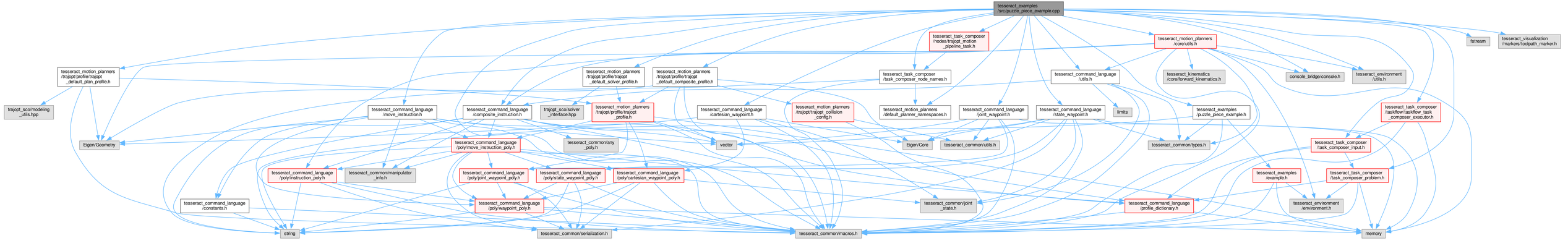
tesseract_examples/src/puzzle_piece_example.cpp
tesseract_task_composer/nodes/trajopt_motion_pipeline_task.h
tesseract_motion_planners/core/utils.h
fstream
tesseract_visualization/markers/toolpath_marker.h
tesseract_motion_planners/trajopt/profile/trajopt_default_plan_profile.h
tesseract_motion_planners/trajopt/profile/trajopt_default_solver_profile.h
tesseract_motion_planners/trajopt/profile/trajopt_default_composite_profile.h
tesseract_task_composer/task_composer_node_names.h
tesseract_command_language/utils.h
tesseract_kinematics/core/forward_kinematics.h
console_bridge/console.h
tesseract_environment/utils.h
trajopt_sco/modeling_utils.hpp
tesseract_command_language/move_instruction.h
tesseract_command_language/composite_instruction.h
trajopt_sco/solver_interface.hpp
tesseract_motion_planners/trajopt/profile/trajopt_profile.h
tesseract_command_language/cartesian_waypoint.h
tesseract_motion_planners/trajopt/trajopt_collision_config.h
tesseract_motion_planners/default_planner_namespaces.h
tesseract_command_language/joint_waypoint.h
tesseract_command_language/state_waypoint.h
limits
tesseract_examples/puzzle_piece_example.h
tesseract_task_composer/task/flow/task/flow_task_composer_executor.h
Eigen/Geometry
tesseract_command_language/poly/move_instruction_poly.h
tesseract_common/any_poly.h
vector
Eigen/Core
tesseract_common/utils.h
tesseract_common/types.h
tesseract_task_composer/task_composer_input.h
tesseract_command_language/poly/instruction_poly.h
tesseract_common/manipulator_info.h
tesseract_command_language/poly/joint_waypoint_poly.h
tesseract_command_language/poly/state_waypoint_poly.h
tesseract_command_language/poly/cartesian_waypoint_poly.h
tesseract_examples/example.h
tesseract_task_composer/task_composer_problem.h
tesseract_command_language/constants.h
tesseract_command_language/poly/waypoint_poly.h
tesseract_common/joint_state.h
tesseract_command_language/profile_dictionary.h
tesseract_environment/environment.h
string
tesseract_common/serialization.h
tesseract_common/macros.h
memory