

tesseract_motion_planners
/trajopt/include/tesseract
_motion_planners/trajopt/serialize.h

```
graph BT; A["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C["tesseract_motion_planners  
/trajopt/include/tesseract  
_motion_planners/trajopt/serialize.h"]; B["tesseract_motion_planners  
/trajopt/src/serialize.cpp"] --> C;
```

The diagram illustrates the relationship between two source files and a header file. At the top, a gray box contains the header file path: `tesseract_motion_planners/trajopt/include/tesseract_motion_planners/trajopt/serialize.h`. Below it, two white boxes represent source files. The left box contains `tesseract_motion_planners/test/serialize_test.cpp` and the right box contains `tesseract_motion_planners/trajopt/src/serialize.cpp`. Two blue arrows point from the bottom of each source file box to the bottom of the header file box, indicating that both source files include this header.

tesseract_motion_planners
/test/serialize_test.cpp

tesseract_motion_planners
/trajopt/src/serialize.cpp