

tesseract\_planning  
::MotionPlanner



```
classDiagram
    class tesseract_planning_MotionPlanner["tesseract_planning::MotionPlanner"]
    class tesseract_planning_TrajOptMotionPlanner["tesseract_planning::TrajOptMotionPlanner"]
    tesseract_planning_TrajOptMotionPlanner --|> tesseract_planning_MotionPlanner
```

The diagram consists of two rectangular boxes. The top box is white with a black border and contains the text 'tesseract\_planning' followed by '::MotionPlanner' on the next line. The bottom box is gray with a black border and contains the text 'tesseract\_planning' followed by '::TrajOptMotionPlanner' on the next line. A blue arrow points vertically from the top edge of the bottom box to the bottom edge of the top box, indicating an inheritance relationship.

tesseract\_planning  
::TrajOptMotionPlanner