

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/deserialize.h

```
graph BT; A["tesseract_motion_planners /ompl/src/deserialize.cpp"] --> C["tesseract_motion_planners /ompl/include/tesseract _motion_planners/ompl/deserialize.h"]; B["tesseract_motion_planners /test/serialize_test.cpp"] --> C;
```

The diagram illustrates a dependency structure. At the top is a grey box containing the path to a header file: `tesseract_motion_planners /ompl/include/tesseract _motion_planners/ompl/deserialize.h`. Below this box are two white boxes. The left box contains the path to a source file: `tesseract_motion_planners /ompl/src/deserialize.cpp`. The right box contains the path to another source file: `tesseract_motion_planners /test/serialize_test.cpp`. Two blue arrows point from the bottom of each white box to the bottom of the grey box, indicating that both source files depend on the header file.

tesseract_motion_planners
/ompl/src/deserialize.cpp

tesseract_motion_planners
/test/serialize_test.cpp