

tesseract_planning
::MotionPlanner



```
graph BT; A["tesseract_planning::DescartesMotionPlanner < FloatType >"] --> B["tesseract_planning::MotionPlanner"]
```

The diagram illustrates an inheritance relationship between two C++ classes. At the bottom is a gray box representing the base class, and at the top is a white box representing the derived class. A blue arrow points from the base class box to the derived class box, indicating that the derived class inherits from the base class.

tesseract_planning
::DescartesMotionPlanner
< FloatType >