

tesseract\_planning  
::TaskComposerNode



```
graph BT; A[tesseract_planning::TaskComposerGraph] --> B[tesseract_planning::TaskComposerNode];
```

The diagram illustrates an inheritance relationship between two classes in the `tesseract_planning` namespace. A light gray box at the top represents the base class `TaskComposerNode`, and a darker gray box at the bottom represents the derived class `TaskComposerGraph`. A blue arrow points from the derived class box up to the base class box, indicating that `TaskComposerGraph` inherits from `TaskComposerNode`.

tesseract\_planning  
::TaskComposerGraph