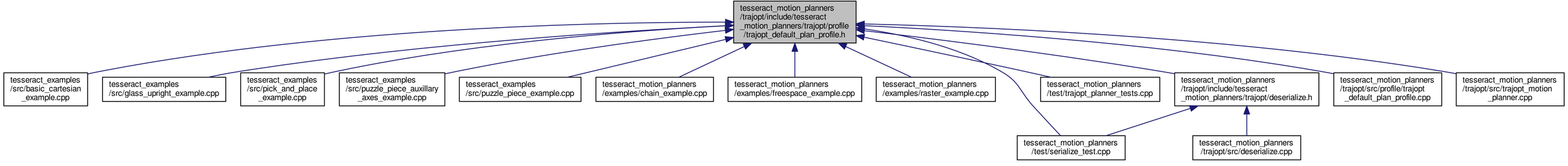
tesseract_motion_planners
/trajopt/include/tesseract
_motion_planners/trajopt/profile
/trajopt_default_plan_profile.h
tesseract_examples
/src/basic_cartesian
_example.cpp
tesseract_examples
/src/glass_upright_example.cpp
tesseract_examples
/src/pick_and_place
_example.cpp
tesseract_examples
/src/puzzle_piece_auxillary
_axes_example.cpp
tesseract_examples
/src/puzzle_piece_example.cpp
tesseract_motion_planners
/examples/chain_example.cpp
tesseract_motion_planners
/examples/freespace_example.cpp
tesseract_motion_planners
/examples/raster_example.cpp
tesseract_motion_planners
/test/trajopt_planner_tests.cpp
tesseract_motion_planners
/trajopt/include/tesseract
_motion_planners/trajopt/deserialize.h
tesseract_motion_planners
/trajopt/src/profile/trajopt
_default_plan_profile.cpp
tesseract_motion_planners
/trajopt/src/trajopt_motion
_planner.cpp
tesseract_motion_planners
/test/serialize_test.cpp
tesseract_motion_planners
/trajopt/src/deserialize.cpp