

ompl::base::StateValidity  
Checker



```
graph BT; A[tesseract_planning::StateCollisionValidator] --> B[ompl::base::StateValidityChecker];
```

The diagram illustrates an inheritance relationship. A light gray box at the bottom contains the text 'tesseract\_planning::StateCollisionValidator'. A blue arrow points upwards from this box to a white box at the top, which contains the text 'ompl::base::StateValidityChecker'.

tesseract\_planning  
::StateCollisionValidator