

tesseract\_planning  
::MotionPlanner



```
graph BT; A[tesseract_planning::SimpleMotionPlanner] --> B[tesseract_planning::MotionPlanner];
```

The diagram consists of two rectangular boxes. The top box is white with a thin black border and contains the text 'tesseract\_planning' followed by '::MotionPlanner' on the next line. The bottom box is gray with a thin black border and contains the text 'tesseract\_planning' followed by '::SimpleMotionPlanner' on the next line. A blue arrow points vertically from the top edge of the gray box to the bottom edge of the white box, indicating an inheritance or specialization relationship.

tesseract\_planning  
::SimpleMotionPlanner