

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/compound
_state_validator.h

```
graph BT; A["tesseract_motion_planners/ompl/src/compound_state_validator.cpp"] --> C["tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/compound_state_validator.h"]; B["tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp"] --> C;
```

This diagram illustrates the relationship between two source files and a common header file. At the top, a grey-shaded box contains the header file path: `tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/compound_state_validator.h`. Below this, two white boxes represent source files. The left box contains `tesseract_motion_planners/ompl/src/compound_state_validator.cpp`, and the right box contains `tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp`. Two blue arrows point from the bottom of each source file box to the bottom of the header file box, indicating that both source files include this header.

tesseract_motion_planners
/ompl/src/compound_state
_validator.cpp

tesseract_motion_planners
/ompl/src/profile/ompl
_default_plan_profile.cpp