

tesseract\_planning  
::MotionPlanner



```
graph BT; A[tesseract_planning::SimpleMotionPlanner] --> B[tesseract_planning::MotionPlanner];
```

The diagram illustrates an inheritance relationship between two classes in the `tesseract_planning` namespace. At the bottom is a gray box representing the base class, `tesseract_planning::SimpleMotionPlanner`. A blue arrow points upwards from this box to a white box at the top, which represents the derived class, `tesseract_planning::MotionPlanner`. This indicates that `SimpleMotionPlanner` inherits from or implements the interface of `MotionPlanner`.

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