

tesseract_planning
::TrajectoryContainer



```
graph BT; A[tesseract_planning::TesseractCommonTrajectory] --> B[tesseract_planning::TrajectoryContainer];
```

The diagram illustrates an inheritance relationship between two classes in the tesseract_planning namespace. A light gray box at the bottom represents the base class, tesseract_planning::TesseractCommonTrajectory. A blue arrow points upwards from this box to a white box at the top, which represents the derived class, tesseract_planning::TrajectoryContainer. This indicates that TesseractCommonTrajectory inherits from TrajectoryContainer.

tesseract_planning
::TesseractCommonTrajectory