

tesseract_planning
::OMPLPlannerConfigurator



```
graph BT; A[tesseract_planning::RRTConfigurator] --> B[tesseract_planning::OMPLPlannerConfigurator];
```

The diagram illustrates an inheritance relationship between two C++ classes. A blue arrow points from the bottom box to the top box, indicating that the bottom class inherits from the top class.

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