

BAD HONNEF LECTURE 1

'QUANTUM ALGORITHMIC TECHNIQUES'

PROBLEM: "imaginary time evolution"

First: real time evolution

~ Schrödinger's equation

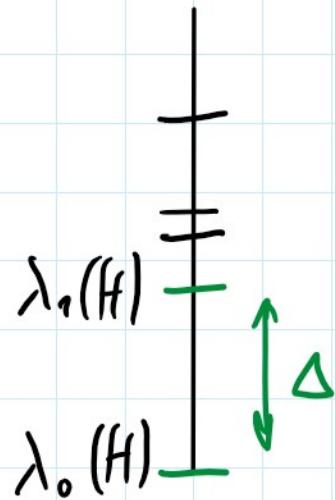
$$\partial_t |\psi_t\rangle = -iH |\psi_t\rangle, t \in \mathbb{R}$$

$$|\psi_0\rangle \rightarrow |\psi_t\rangle = e^{-iHt} |\psi_0\rangle$$

~ quantum dynamics

However, often interested in

GROUND STATES



? prepare ground state of Hamiltonian $H \geq 0$



|| imaginary time evolution

$$t \rightarrow -it$$

$$e^{-iHt} \rightsquigarrow e^{-tH} = \sum e^{-t\lambda_j(H)} |v_j\rangle \langle v_j|$$

$\sim 1 \ll 1$ for $t \gg 1$

$$\approx |v_0 \times v_0| \text{ for } t \gg \frac{1}{\Delta}.$$

So, given $|y_0\rangle$ with $\langle y_0 | v_0 \rangle \neq 0$,

$$e^{-tH} |y_0\rangle \rightarrow |v_0 \times v_0 | y_0 \rangle \sim |v_0\rangle.$$

? How to implement e^{-tH} ?



real time evolution

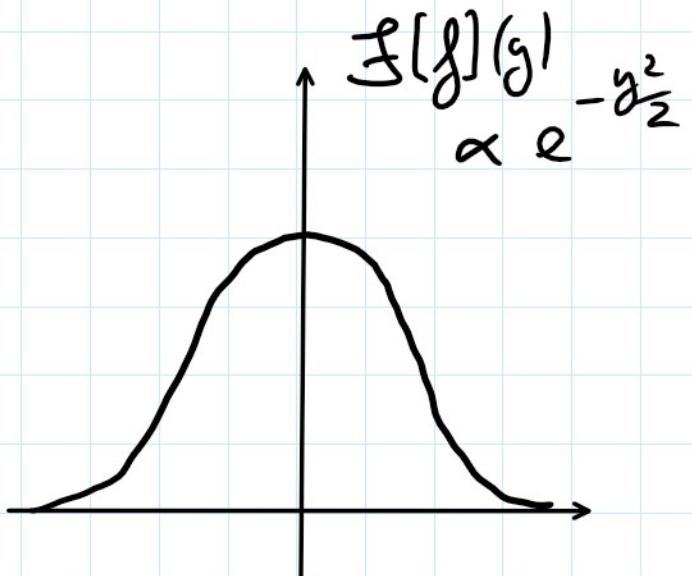
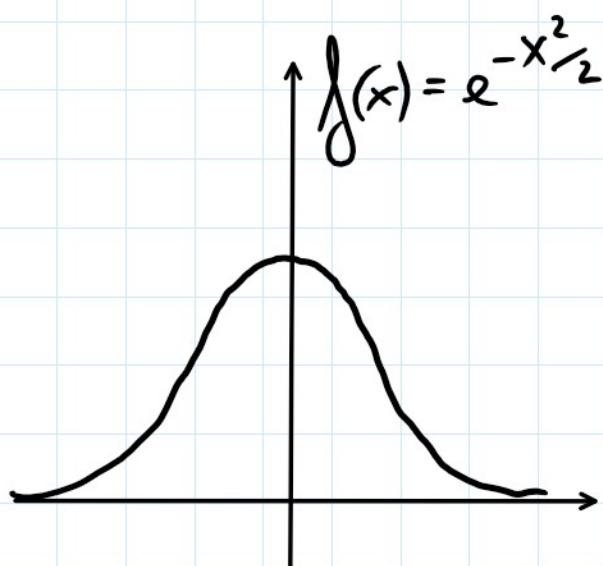
+

"Linear combination of unitaries"

↳ uses elementary Fourier analysis

* uses elementary unitary arrays

(or "Bose-Hubbard transform"):



$$\text{i.e., } e^{-\frac{x^2}{2}} = \frac{1}{\sqrt{2\pi}} \int dy e^{-\frac{y^2}{2}} e^{-ixy}$$

$$x = \sqrt{2E} H$$

$$e^{-tH^2} = \frac{1}{\sqrt{2\pi}} \int dy e^{-\frac{y^2}{2}} e^{-iy\sqrt{2E}H}$$

↓

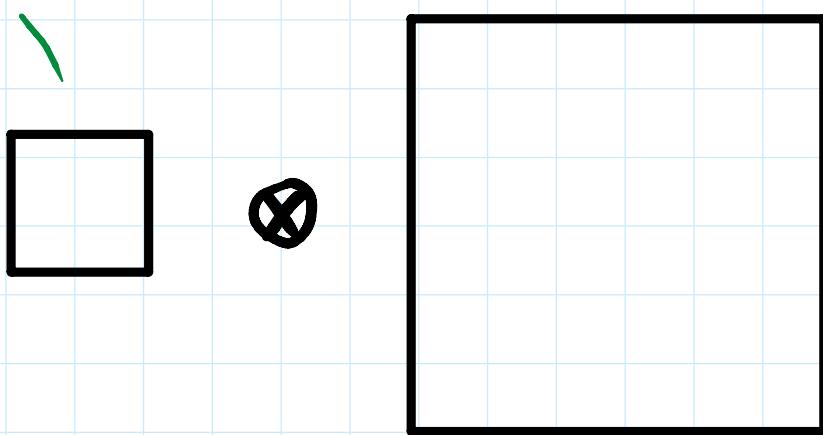
(imaginary, nonunitary) (real, unitary)

linear combination

* LINEAR COMBINATION OF UNITARIES:

auxiliary system

primary System



state $|N\rangle \otimes |y\rangle$

||

$$\frac{1}{(2\pi)^{\frac{1}{4}}} \int dy e^{-\frac{y^2}{4}} |y\rangle = \text{"Gaussian state"}$$

Hamiltonian $H' = \hat{y} \otimes H$

$$\int dy y |y\rangle \langle y| = \text{"position operator"}$$

$\int dy |y\rangle \langle yx| = \text{"position operator"}$

s.t. $e^{-itH'} (|y\rangle \otimes |\psi\rangle)$

$$= |y\rangle \otimes (e^{-it_y H} |\psi\rangle)$$

$\hookrightarrow H' = \text{"controlled"} - H$

LEMMA:

$$(|N\rangle\langle N| \otimes \mathbb{1}) e^{-i\sqrt{2\epsilon} H'} (|N\rangle \otimes |\psi\rangle)$$

$$\quad\quad\quad \swarrow = |N\rangle \otimes (e^{-\epsilon H^2} |\psi\rangle).$$

postselection after measurement $\{|N\rangle, |N^\perp\rangle, \dots\}$,
success probability $\|e^{-\epsilon H^2} |\psi\rangle\|_2^2$

Proof:

$$\left(\frac{1}{(2\pi)^{\frac{1}{4}}} \int dy e^{-\frac{y^2}{2}} |\psi_0\rangle |y\rangle \right)$$

$$(|N\rangle\langle N| \otimes \mathbb{1}) e^{-i\sqrt{2f} H'} (|N\rangle\langle \psi\rangle)$$

$$= (|N\rangle\langle N| \otimes \mathbb{1}) \frac{1}{(2\pi)^{\frac{1}{4}}} \int dy e^{-\frac{y^2}{2}} e^{-iy\sqrt{2f} H} |y\rangle |\psi\rangle$$

$$= |N\rangle \otimes \left(\frac{1}{\sqrt{2\pi}} \int dy e^{-\frac{y^2}{2}} e^{-iy\sqrt{2f} H} |\psi_0\rangle \right)$$

$$e^{-tH^2} |\psi_0\rangle$$

□

More general (and discrete):

$$\text{if } \begin{cases} cU = \sum_t |t\rangle X_t |t\rangle \otimes U^t \\ |\chi\rangle = \sum_t \sqrt{f(t)} |t\rangle \end{cases}$$

$$|\psi\rangle = \sum_{\epsilon} \sqrt{f(\epsilon)} |e\rangle$$

then

$$(f(X)f^{\dagger} \otimes \mathbb{1}) \langle U | \psi \rangle |U\rangle$$

$$= |\psi\rangle \left(\sum f(\epsilon) U^{\epsilon} |U\rangle \right).$$

$$= LC U.$$



(2ND) PROBLEM:

HAMILTONIAN SIMULATION

! quantum computers expected to be

DIGITAL

(discrete time, space)

gates ↪ qubits

(time)

? integrate continuous Schrödinger equation ?

$$|\psi_0\rangle \rightarrow |\psi_f\rangle = e^{-iHt} |\psi_0\rangle$$



LCU?

$$e^{-iHt} = \sum_{k=0}^{+\infty} \frac{(-it)^k}{k!} H^k$$

↪ discrete,

$R=0$

$K:$

↳ discrete,

but nonunitary!

→ use "BLOCK ENCODING" of H ,
 $\|H\| < 1$

unitary

$$U = \begin{bmatrix} H & \cdot \\ \cdot & \cdot \end{bmatrix}$$

$$= |0\rangle\langle 0| \otimes H + \dots$$

$$\text{s.t. } (|0\rangle\langle 0| \otimes I) U |+\rangle|0\rangle$$

postselection,
success probability
 $\|H|+\rangle\|_2^2$

$$= |0\rangle (H|+\rangle)$$

$$\|H|\psi\rangle\|_2$$

→ implements H !
What about H^k ?

Let $\mathcal{U} = \begin{bmatrix} H & R \\ L & D \end{bmatrix}$,

assume \mathcal{U} is "reflection":

$$\mathcal{U}^2 = \mathbb{1} = \begin{bmatrix} H^2 + RL & HR + RD \\ LH + DL & LR + D^2 \end{bmatrix}$$

$= \mathbb{1}$ $= 0$
 $= 0$ $= \mathbb{1}$

Then

$$\mathcal{U} \begin{bmatrix} \mathbb{1} \\ -\mathbb{1} \end{bmatrix} \mathcal{U} = \begin{bmatrix} H & R \\ L & D \end{bmatrix} \begin{bmatrix} H & R \\ L & D \end{bmatrix}$$

$$U \begin{bmatrix} \cdot & \cdot \\ -1 & \end{bmatrix} U = \begin{bmatrix} \cdot & \cdot \\ C & D \end{bmatrix} \begin{bmatrix} -L & -D \end{bmatrix}$$

$$= \begin{bmatrix} H^2 - RL & HR - RD \\ LH - DL & LR - D^2 \end{bmatrix}$$

$$\begin{aligned} RL &= 1 - H^2 \\ &= \begin{bmatrix} 2H^2 - 1 & \cdot \\ \cdot & \cdot \end{bmatrix} \end{aligned}$$

$$\text{So } 1 = \begin{bmatrix} 1 & \cdot \\ \cdot & \cdot \end{bmatrix}, \quad U = \begin{bmatrix} H & \cdot \\ - & \cdot \end{bmatrix},$$

$$\begin{bmatrix} 1 & \\ -1 & \end{bmatrix} U \begin{bmatrix} 1 & \\ -1 & \end{bmatrix} U = \begin{bmatrix} 2H^2 - 1 & \cdot \\ - & \cdot \end{bmatrix}$$

CLAIM: (exercise?)

$$\left(\begin{bmatrix} 1 & \\ -1 & \end{bmatrix} U \right)^k = \begin{bmatrix} T_k(H) & \cdot \\ \downarrow & \cdot \end{bmatrix}$$

k -th Chebyshev poly
= basis for polynomials

Now, rewrite

$$\begin{bmatrix} e^{-i\theta H} & \cdot \\ \cdot & \ddots \\ \cdot & \cdot \end{bmatrix} = \begin{bmatrix} \sum \alpha_k T_k(H) & \cdot \\ \cdot & \ddots \\ \cdot & \cdot \end{bmatrix}$$

$$= \sum \alpha_k \left(\begin{bmatrix} 1 & \\ -1 & 1 \end{bmatrix} U \right)^k$$

$$= LCU.$$

? How to obtain block encoding

$$U = \begin{bmatrix} H & \cdot \\ \cdot & \cdot \end{bmatrix}$$

→ exercise.