



---

# LINMA2471 Optimization models and methods II

---

SIMON DESMIDT

Academic year 2024-2025 - Q1



UCLouvain

# Table des matières

<b>1</b>	<b>Gradient Method</b>	<b>2</b>
1.1	Definitions . . . . .	2
1.2	Complexity . . . . .	3
1.3	GM with Armijo Line Search . . . . .	3
1.4	Problems with convex constraints . . . . .	4

# Gradient Method

An optimization problem is defined as

$$\min_{x \in \mathbb{R}^n} f(x) \quad (1.1)$$

where  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is a continuously differentiable function.

## 1.1 Definitions

— A function  $F : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is L-Lipschitz continuous when

$$\|F(y) - F(x)\| \leq L\|y - x\| \quad \forall x, y \in \mathbb{R}^n$$

where we use the euclidian norm.

— If  $\nabla f$  is L-Lipschitz then, given  $x \in \mathbb{R}^n$ ,

$$f(y) \leq f(x) + \langle \nabla f(x), y - x \rangle + \frac{L}{2}\|y - x\|^2 = m_x(y) \quad \forall y \in \mathbb{R}^n$$

and  $f$  is said to be a L-smooth function.

— We say that a differentiable function  $\Psi : \mathbb{R}^n \rightarrow \mathbb{R}$  is L-smooth for some  $L \geq 0$  when, given  $x \in \mathbb{R}^n$ ,

$$\Psi(y) \leq \Psi(x) + \langle \nabla \Psi(x), y - x \rangle + \frac{L}{2}\|y - x\|^2 \quad \forall y \in \mathbb{R}^n$$

— A convex function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is convex when, given  $x, y \in \mathbb{R}^n$  and  $\lambda \in [0, 1]$ , we have

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y)$$

— Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  be convex. If  $f$  is differentiable, then

$$f(y) \geq f(x) + \nabla f(x)^T(y - x) \quad \forall x, y \in \mathbb{R}^n$$

— A differentiable function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is  $\mu$ -strongly convex ( $\mu > 0$ ) if, given  $x \in \mathbb{R}^n$ ,

$$f(y) \geq f(x) + \nabla f(x)^T(y - x) + \frac{\mu}{2}\|y - x\|^2 \quad \forall y \in \mathbb{R}^n$$

— PL inequality for a  $\mu$ -strongly convex function<sup>1</sup> :

$$f(x) - f(x^*) \leq \frac{1}{2\mu}\|\nabla f(x)\|^2 \quad \forall x \in \mathbb{R}^n$$

---

1.  $x^*$  is the minimizer of  $f$

## 1.2 Complexity

The demonstration of the final results here obtained is in the notes, but not explained here.

### 1.2.1 Hypotheses

- $f$  is convex and differentiable;
- $\nabla f$  is  $L$ -Lipschitz;
- we start from a  $x_0 \in \mathbb{R}^n$  that is not a minimizer of  $f$ ;

### 1.2.2 Results

We use the sequence  $\{x_k\}_{k \geq 0}$ , given a  $x_0 \in \mathbb{R}^n$ , such that

$$x_{k+1} = x_k - \frac{1}{L} \nabla f(x_k)$$

Problem class	Goal	Complexity bound
Non-convex $f$	$\ \nabla f(x_k)\  \leq \varepsilon$	$\mathcal{O}(\varepsilon^{-2})$
Convex $f$	$f(x_k) - f(x^*) \leq \varepsilon$	$\mathcal{O}(\varepsilon^{-1})$
$\mu$ -strongly-convex $f$	$f(x_k) - f(x^*) \leq \varepsilon$	$\mathcal{O}(\log(\varepsilon^{-1}))$

## 1.3 GM with Armijo Line Search

The Armijo Line Search consists of changing the constant in the GM in order to be more efficient and be able to make bigger steps in some directions where it is possible.

$$x_{k+1} = x_k - \alpha \nabla f(x_k) \quad \alpha > 0 \quad (1.2)$$

---

### Algorithm 1 Gradient Method with Armijo Line Search

---

- 1: **Step 0** : Given  $x_0 \in \mathbb{R}^n$  and  $\alpha_0 > 0$ , set  $k := 0$ .
- 2: **Step 1** : Set  $\ell := 0$ .
- 3: **Step 1.1** : Compute  $x_k^+ = x_k - (0.5)^\ell \alpha_k \nabla f(x_k)$ .
- 4: **Step 1.2 (Armijo Line Search)** : If

$$f(x_k) - f(x_k^+) \geq \frac{(0.5)^\ell \alpha_k}{2} \|\nabla f(x_k)\|^2 \quad (1)$$

set  $\ell_k := \ell$  and go to Step 2. Otherwise, set  $\ell := \ell + 1$  and go back to Step 1.1.

- 5: **Step 3** : Define  $x_{k+1} = x_k^+$ ,  $\alpha_{k+1} = (0.5)^{\ell_k - 1} \alpha_k$ , set  $k := k + 1$  and go back to Step 1.
-

## 1.4 Problems with convex constraints

Consider the problem

$$\min_{x \in \mathbb{R}^n} f(x) \text{ such that } x \in \Omega \quad (1.3)$$

where  $f$  is  $L$ -smooth, and  $\Omega \subseteq \mathbb{R}^n$  is nonempty, closed and convex. Given an approximation  $x_k \in \Omega$  for a solution of 1.3, a possible generalization of the Gradient Method is to define

$$x_{k+1} = P_\Omega \left( x_k - \frac{1}{L} \nabla f(x_k) \right) \quad (1.4)$$

where  $P_\Omega$  is the projection of  $z$  onto  $\Omega$ , and we call this method the Projected Gradient Method.

If  $\Omega = [a, b]^n$ , then the projection of an element  $z$  onto  $\Omega$  is such that its element  $i$  is given by :

$$[P_\Omega(z)]_i = \begin{cases} z_i & \text{if } a \leq z_i \leq b \\ a & \text{if } z_i < a \\ b & \text{if } z_i > b \end{cases} \quad \forall i = 1, \dots, n \quad (1.5)$$