\$Assumptions = (L ∈ Reals && L > 0);

$$g = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}; (* ds^2 = -du^2 - dv^2 + dx^2 + dy^2 *)$$

$$u = \sqrt{L^2 + r[\bullet]^2} \cos\left[\frac{t[\bullet]}{L}\right];$$

$$v = \sqrt{L^2 + r[\bullet]^2} \operatorname{Sin}\left[\frac{t[\bullet]}{L}\right];$$

$$x = r[\bullet] \, \mathsf{Cos}[\phi[\bullet]];$$

$$y = r[\bullet] \, \mathsf{Sin}[\phi[\bullet]];$$

$$Print["ds^2 = ", FullSimplify[(\partial_{\bullet}u \ \partial_{\bullet}v \ \partial_{\bullet}x \ \partial_{\bullet}y).g.\begin{pmatrix} \partial_{\bullet}u \\ \partial_{\bullet}v \\ \partial_{\bullet}x \\ \partial_{\bullet}y \end{pmatrix}][[1, 1]]]$$

$$ds^{2} = \frac{L^{2} r'[\bullet]^{2}}{L^{2} + r[\bullet]^{2}} - \frac{\left(L^{2} + r[\bullet]^{2}\right) t'[\bullet]^{2}}{L^{2}} + r[\bullet]^{2} \phi'[\bullet]^{2}$$