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In[1]:= ClearAll["Global`*"]
$Assumptions = (M ∈ Reals && M > 0 && (*mass *)
                e ∈ Reals && (*energy*)
                x ∈ Reals && y ∈ Reals && z ∈ Reals &&
                px ∈ Reals && py ∈ Reals && pz ∈ Reals);

(*Calculate {L,H}*)
rvec = {x, y, z};
pvec = {px, py, pz};
Lvec = Cross[rvec, pvec];
V[vec_] := - $\frac{k}{\text{Norm}[vec]}$ ;
H =  $\frac{\text{Dot}[pvec, pvec]}{2 M}$  + V[rvec];
PoissonBracket[A_, B_] := D[A, x] D[B, px] - D[B, x] D[A, px] +
                        D[A, y] D[B, py] - D[B, y] D[A, py] +
                        D[A, z] D[B, pz] - D[B, z] D[A, pz];

In[9]:= Print["{L,H} = ", FullSimplify[PoissonBracket[Lvec, H]]]

{L,H} = {0, 0, 0}

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In[10]:= (*Check {L_i,L_m }*)
 $\epsilon$  = LeviCivitaTensor[3];
 $\delta$ [i_, j_] := KroneckerDelta[i, j];
poissonBracketLiLm = IdentityMatrix[3]; (*Initiate*)
poissonBracketLiLm2 = IdentityMatrix[3]; (*Initiate*)

For[i=1, i≤3, i++,
  For[m =1, m ≤3, m ++,
    poissonBracketLiLm [[i, m ]] = PoissonBracket[Lvec[[i]], Lvec[[m ]]];
    poissonBracketLiLm2 [[i, m ]] = Sum [ $\epsilon$ [[q, i, m ]] Lvec[[q]], {q, 1, 3}];
    (*su(2) structure constants*)
  ]
]

Print["{L_i,L_m } = ", MatrixForm [poissonBracketLiLm]]
Print[" $\epsilon_{qim}$  L_q = ", MatrixForm [poissonBracketLiLm2]]

{L_i,L_m } =  $\begin{pmatrix} 0 & pyx-pxy & pzx-pxz \\ -pyx+pxy & 0 & pzy-pyz \\ -pzx+pxz & -pzy+pyz & 0 \end{pmatrix}$ 

 $\epsilon_{qim}$  L_q =  $\begin{pmatrix} 0 & pyx-pxy & pzx-pxz \\ -pyx+pxy & 0 & pzy-pyz \\ -pzx+pxz & -pzy+pyz & 0 \end{pmatrix}$ 

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In[17]:= (*Check {B_i,B_m}*)
Avec = Cross[pvec, Lvec] - kMrvec/Norm[rvec];
Bvec = Avec/Sqrt[2MAbs[e]];
Print["{A,H} = ", FullSimplify[PoissonBraket[Avec, H]]]

{A,H} = {0, 0, 0}

In[20]:= poissonBraketBiBm = IdentityMatrix[3]; (*Initiate*)
poissonBraketBiBm2 = IdentityMatrix[3]; (*Initiate*)

For[i=1, i≤3, i++,
  For[m=1, m≤3, m++,
    poissonBraketBiBm[[i, m]] = PoissonBraket[Bvec[[i]], Bvec[[m]]];
    poissonBraketBiBm2[[i, m]] = Sum[ε[[q, i, m]] Lvec[[q]], {q, 1, 3}] Sign[e];
  ]
]

Print["{B_i,B_m} = ", MatrixForm[FullSimplify[poissonBraketBiBm  $\frac{e}{H}$ ]]]

(*multiply by 1= $\frac{e}{H}$  to help FullSimplify*)
Print["ε_qim L_q Sgn[e] = ", MatrixForm[FullSimplify[poissonBraketBiBm2]]]

{B_i,B_m} = 
$$\begin{pmatrix} 0 & (-p_y x + p_x y) \text{Sign}[e] & (-p_z x + p_x z) \text{Sign}[e] \\ (p_y x - p_x y) \text{Sign}[e] & 0 & (-p_z y + p_y z) \text{Sign}[e] \\ (p_z x - p_x z) \text{Sign}[e] & (p_z y - p_y z) \text{Sign}[e] & 0 \end{pmatrix}$$


ε_qim L_q Sgn[e] = 
$$\begin{pmatrix} 0 & (p_y x - p_x y) \text{Sign}[e] & (p_z x - p_x z) \text{Sign}[e] \\ (-p_y x + p_x y) \text{Sign}[e] & 0 & (p_z y - p_y z) \text{Sign}[e] \\ (-p_z x + p_x z) \text{Sign}[e] & (-p_z y + p_y z) \text{Sign}[e] & 0 \end{pmatrix}$$


In[25]:= (*Check {B_i,L_m}*)
poissonBraketBiLm = IdentityMatrix[3]; (*Initiate*)
poissonBraketBiLm2 = IdentityMatrix[3]; (*Initiate*)

For[i=1, i≤3, i++,
  For[m=1, m≤3, m++,
    poissonBraketBiLm[[i, m]] = PoissonBraket[Bvec[[i]], Lvec[[m]]];
    poissonBraketBiLm2[[i, m]] = Sum[ε[[q, i, m]] Bvec[[q]], {q, 1, 3}];
  ]
]

Print["{B_i,L_m} = ", MatrixForm[FullSimplify[poissonBraketBiLm]]]
Print["ε_qim B_q = ", MatrixForm[FullSimplify[poissonBraketBiLm2]]]

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$$\begin{aligned}
\{B_{i,L_m}\} &= \begin{pmatrix} 0 & \frac{-pxpzx - py pzy + px^2 z + py^2 z - \frac{kMz}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{\frac{eM}{\text{Sign}[e]}}} & \frac{pxpyx - px^2 y - pz^2 y + py pzy + \frac{kMy}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{\frac{eM}{\text{Sign}[e]}}} \\ \frac{pxpzx + py pzy - px^2 z - py^2 z + \frac{kMz}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{\frac{eM}{\text{Sign}[e]}}} & 0 & \frac{py^2 x + pz^2 x - pxpyy - px pzy - \frac{kMx}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{\frac{eM}{\text{Sign}[e]}}} \\ \frac{-pxpyx + px^2 y + pz^2 y - py pzy - \frac{kMy}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{\frac{eM}{\text{Sign}[e]}}} & \frac{-py^2 x - pz^2 x + pxpyy + px pzy + \frac{kMx}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{\frac{eM}{\text{Sign}[e]}}} & 0 \end{pmatrix} \\
\epsilon_{qim} B_q &= \begin{pmatrix} 0 & \frac{-pxpzx - py pzy + px^2 z + py^2 z - \frac{kMz}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{M} \sqrt{\text{Abs}[e]}} & \frac{pxpyx - px^2 y - pz^2 y + py pzy + \frac{kMy}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{M} \sqrt{\text{Abs}[e]}} \\ \frac{pxpzx + py pzy - px^2 z - py^2 z + \frac{kMz}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{M} \sqrt{\text{Abs}[e]}} & 0 & \frac{py^2 x + pz^2 x - pxpyy - px pzy - \frac{kMx}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{M} \sqrt{\text{Abs}[e]}} \\ \frac{-pxpyx + px^2 y + pz^2 y - py pzy - \frac{kMy}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{M} \sqrt{\text{Abs}[e]}} & \frac{-py^2 x - pz^2 x + pxpyy + px pzy + \frac{kMx}{\sqrt{x^2 + y^2 + z^2}}}{\sqrt{2} \sqrt{M} \sqrt{\text{Abs}[e]}} & 0 \end{pmatrix}
\end{aligned}$$