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In[1]:= ClearAll["Global`*"]
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$$\eta = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix};$$

$$pVec = \begin{pmatrix} p \\ 0 \\ 0 \\ p \end{pmatrix}; \quad pPrimVec = \begin{pmatrix} p \\ 0 \\ 0 \\ -p \end{pmatrix};$$

$$kPrimVec = \begin{pmatrix} p \\ 0 \\ -\text{Sin}[\theta] p \\ -\text{Cos}[\theta] p \end{pmatrix}; \quad kVec = \begin{pmatrix} p \\ 0 \\ \text{Sin}[\theta] p \\ \text{Cos}[\theta] p \end{pmatrix};$$

$$u = ((pVec - kPrimVec)^T \cdot \eta \cdot (pVec - kPrimVec))[[1, 1]] // \text{FullSimplify};$$

```
Print["u = ", u]
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$$s = ((pVec + pPrimVec)^T \cdot \eta \cdot (pVec + pPrimVec))[[1, 1]] // \text{FullSimplify};$$

```
Print["s = ", s]
```

$$t = ((pVec - kVec)^T \cdot \eta \cdot (pVec - kVec))[[1, 1]] // \text{FullSimplify};$$

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Print["t = ", t]
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$$u = -2 p^2 (1 + \text{Cos}[\theta])$$

$$s = 4 p^2$$

$$t = 2 p^2 (-1 + \text{Cos}[\theta])$$

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In[11]:= differentialCrossSection = 
$$\frac{\pi \alpha^2}{s} \left( u^2 \left( \frac{1}{s} + \frac{1}{t} \right)^2 + \left( \frac{t}{s} \right)^2 + \left( \frac{s}{t} \right)^2 \right) // \text{FullSimplify};$$

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Print[" $\frac{d\sigma}{d(\cos \theta)}$ =", differentialCrossSection]
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$$\frac{d\sigma}{d(\cos \theta)} = \frac{\pi \alpha^2 (7 + \text{Cos}[2 \theta])^2}{32 p^2 (-1 + \text{Cos}[\theta])^2}$$