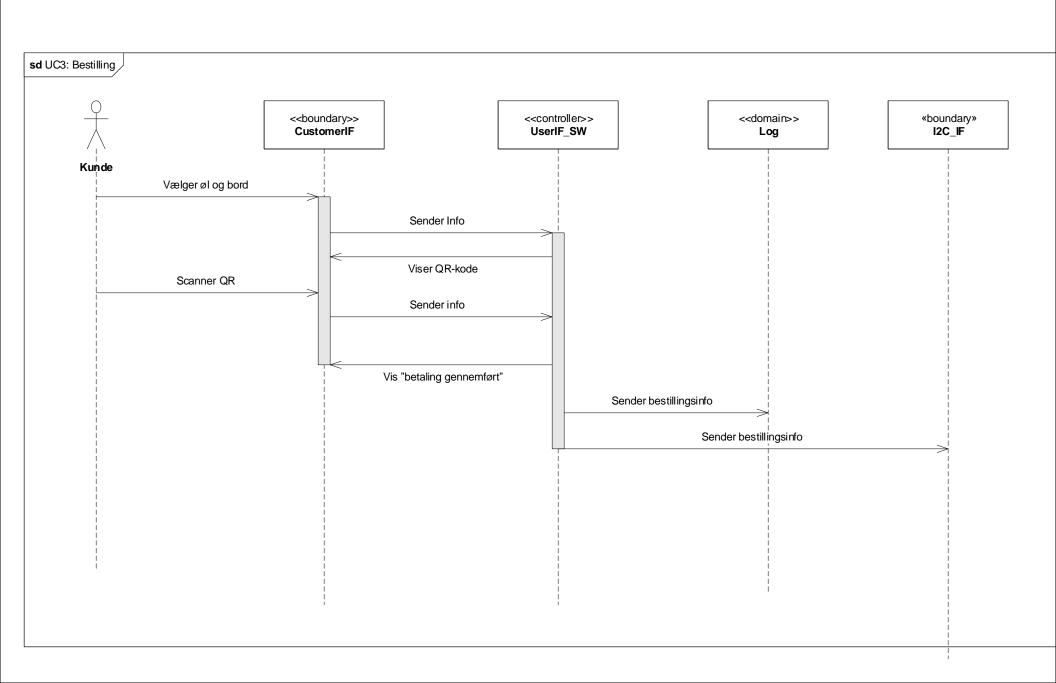
Class UC3: Bestilling

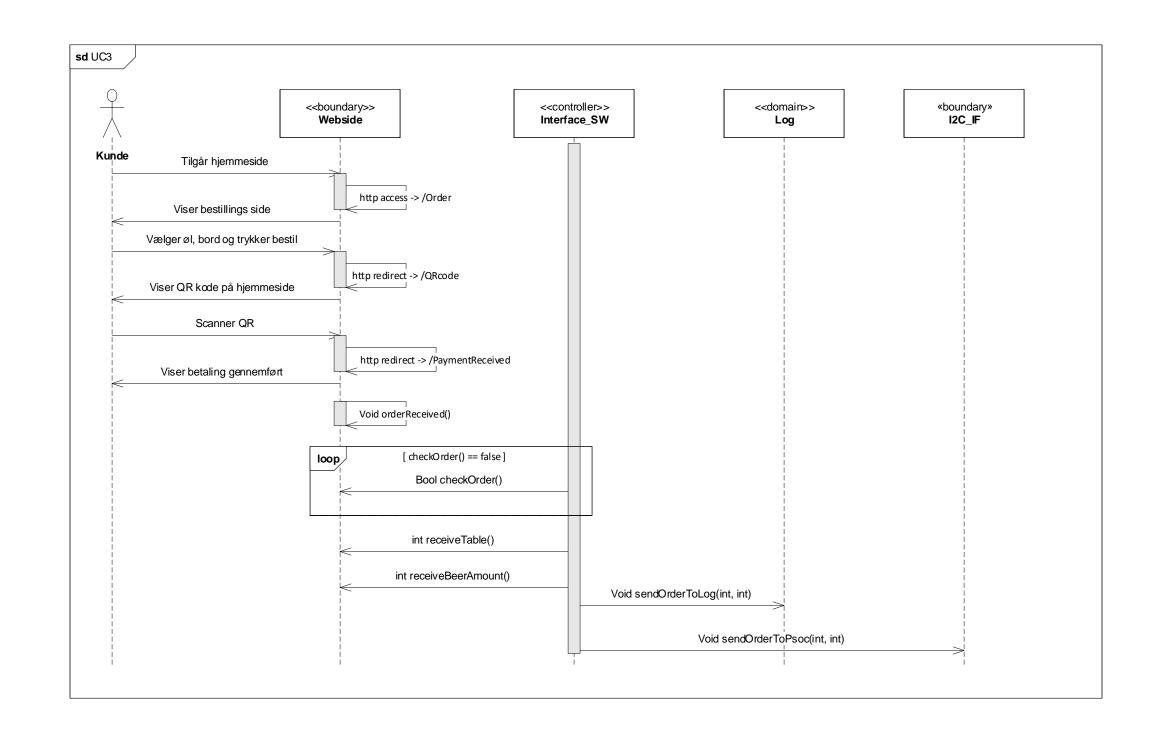
"boundary"
Webside

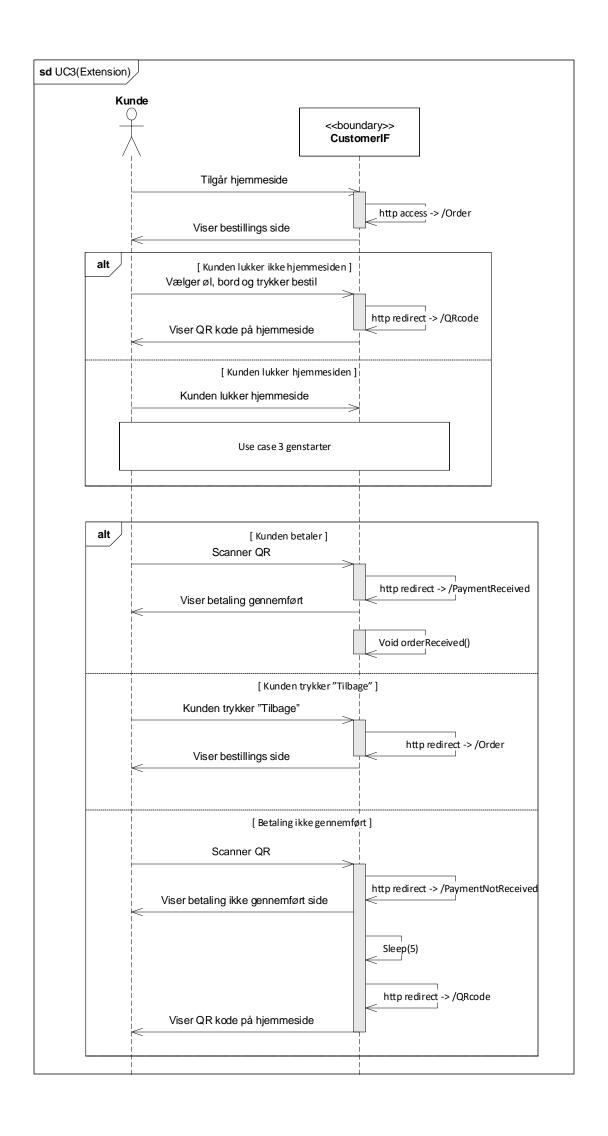
"Controller"
Interface\_SW

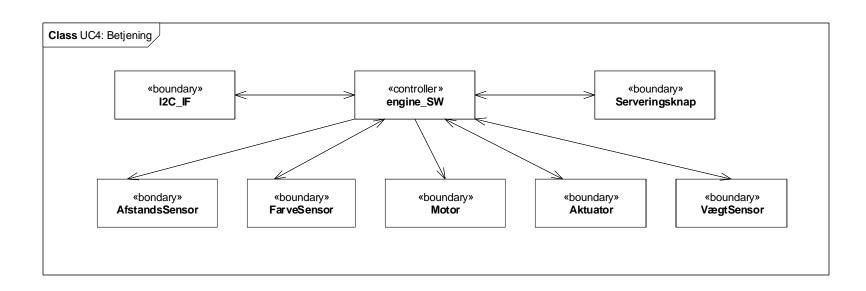
"domain"
Log

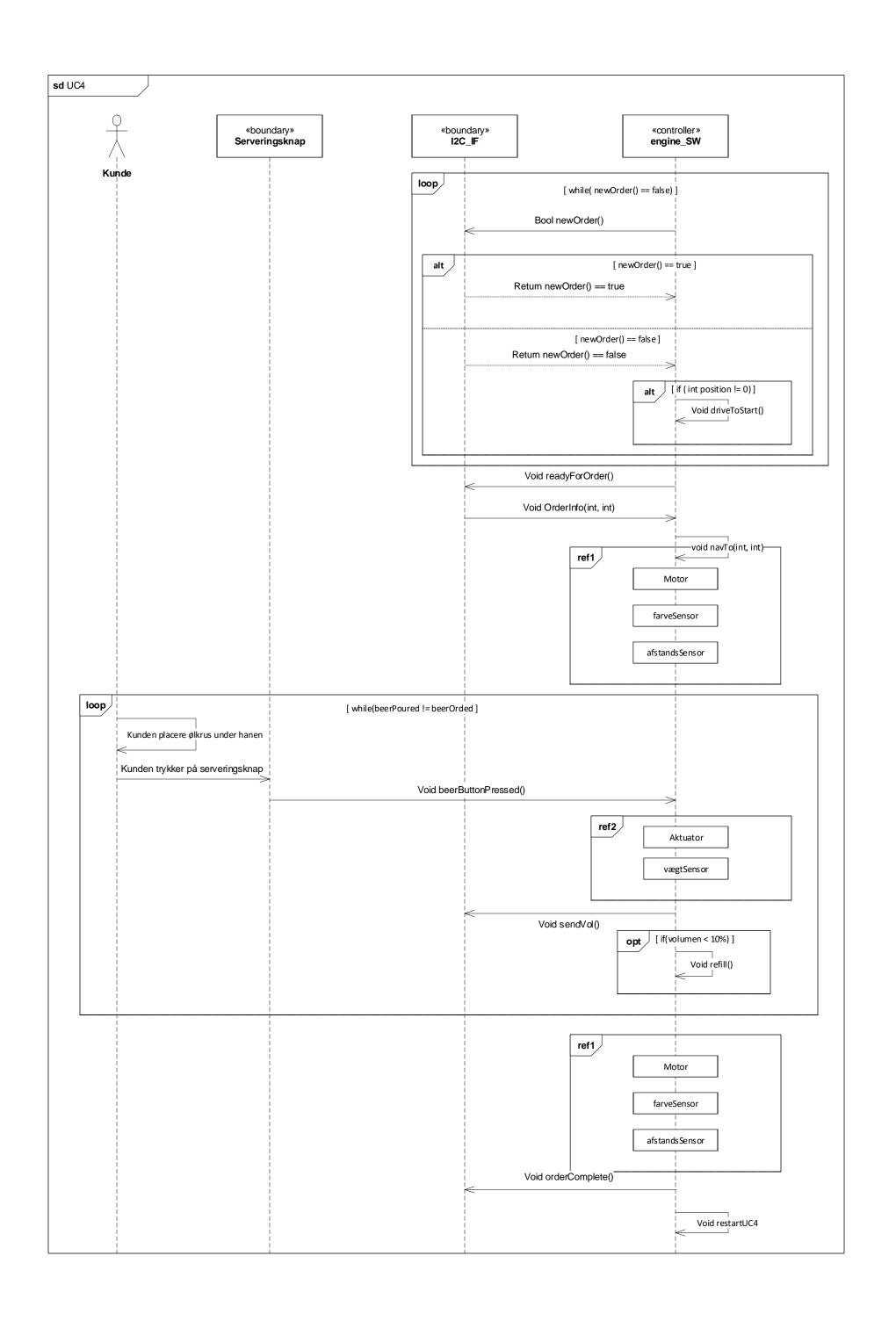
"boundary"
I2C\_IF











sd ref1	«bondary» <b>AfstandsSensor</b>		«boundary» Far veSensor		«bound <b>Mo</b> to	lary» or	«controller» engine_SW	
					initMotor()			
	loop	Navigeret til ønsket position						
					initColo	 or()		
			!		getCol	or()		
			init	tDistance()				
		-		tDistance()				
			j 90	etDistance()				
					opt	Hvis afstand til nærmeste	objekt er < 50 cm	
						-		
						motorStop()		
			į				i	

