Lemma: Additive Models and Additive Penalties

Consider the problem

$$\frac{1}{2} \|y - \sum_{j=1}^{J} g_j\|_T^2 + \sum_{j=1}^{J} \lambda_j P_j(g_j) + \frac{w}{2} \|g_j\|_D^2$$

We suppose the penalty functions P_j are convex and twice-differentiable. (We do not need the semi-norm assumption.)

Suppose that $\sup_{g \in \mathcal{G}} ||g||_D \leq G$.

For all d > 0, any $\lambda^{(1)}, \lambda^{(2)}$ that satisfy

$$\|\lambda^{(1)} - \lambda^{(2)}\| \le \frac{dw}{2J} \left(\frac{n}{n_T} n^{\tau_{min}} \left(2G + \|\epsilon\|_T\right) + wG + G\right)^{-1} n^{-\tau_{\min}}$$

we have

$$\|\hat{g}_i(\cdot|\lambda^{(1)}) - \hat{g}_i(\cdot|\lambda^{(2)})\|_D \le d/J$$

Hence

$$\| \sum_{j=1}^{J} \hat{g}_{j}(\cdot | \lambda^{(1)}) - \hat{g}_{j}(\cdot | \lambda^{(2)}) \|_{D} \le d$$

Proof

Let $h_j = \hat{g}_j(\cdot|\lambda^{(1)}) - \hat{g}_j(\cdot|\lambda^{(2)})$. Suppose for contradiction that for \tilde{k} , we have $||h_{\tilde{k}}||_D > d/J$.

$$Z = \{j : ||h_j|| > 0\}$$

Consider the optimization problem

$$\{\hat{m}_j(\lambda)\}_{j \in Z} = \arg\min_{m} \frac{1}{2} \|y - \sum_{j=1}^{J} (g_j + m_j h_j)\|_T^2 + \sum_{j=1}^{J} \lambda_j P_j (g_j + m_j h_j) + \frac{w}{2} \|g_j + m_j h_j\|_D^2$$

Note that if $||h_i|| = 0$, then we just set $m_i = 0$ as a constant.

Now by the KKT conditions, for all $\ell \in \mathbb{Z}$, we have

$$\langle y - \sum_{j=1}^{J} (g_j + m_j h_j), h_\ell \rangle_T + \lambda_\ell \frac{\partial}{\partial m_\ell} P_\ell (g_\ell + m_\ell h_\ell) + \lambda_\ell w \langle h_\ell, g_\ell + m_\ell h_\ell \rangle_D = 0$$

It's implicit derivative with respect to λ_k is

$$\langle \sum_{j=1}^{J} \frac{\partial \hat{m}_{j}(\lambda)}{\partial \lambda_{k}} h_{j}, h_{\ell} \rangle_{T} + \lambda_{\ell} \frac{\partial^{2}}{\partial m_{\ell}^{2}} P_{\ell}(g_{\ell} + m_{\ell}h_{\ell}) \frac{\partial \hat{m}_{\ell}(\lambda)}{\partial \lambda_{k}} + \lambda_{\ell} w \|h_{\ell}\|_{D}^{2} \frac{\partial \hat{m}_{\ell}(\lambda)}{\partial \lambda_{k}}$$

$$+1 \left[\ell = k\right] \left(\frac{\partial}{\partial m_{\ell}} P_{\ell}(g_{\ell} + m_{\ell}h_{\ell}) + w \langle h_{\ell}, g_{\ell} + m_{\ell}h_{\ell} \rangle_{D}\right) = 0$$

Define the following matrices

$$S: S_{ij} = \langle h_j, h_\ell \rangle_T$$

$$D_1 = diag \left(\lambda_\ell \frac{\partial^2}{\partial m_\ell^2} P_\ell (g_\ell + m_\ell h_\ell) \right)$$

$$D_2 = diag\left(\lambda_{\ell} w \|h_{\ell}\|_D^2\right)$$

$$D_{3} = diag \left(\frac{\partial}{\partial m_{\ell}} P_{\ell}(g_{\ell} + m_{\ell}h_{\ell}) + w \langle h_{\ell}, g_{\ell} + m_{\ell}h_{\ell} \rangle_{D} \right)$$
$$M = \left(\begin{array}{cc} \frac{\partial \hat{m}_{1}(\lambda)}{\partial \lambda} & \frac{\partial \hat{m}_{2}(\lambda)}{\partial \lambda} & \dots & \frac{\partial \hat{m}_{J}(\lambda)}{\partial \lambda} \end{array} \right)$$

(You will have to omit certain columns/rows of the matrices if $m_j = 0$ is constant.) From the implicit differentiation equations, we have the following system of equations:

$$M = D_3 \left(S + D_1 + D_2 \right)^{-1}$$

We know that S is a PSD matrix (since it can be written as $S = HH^T$ where $H_j = h_j|_T$). Hence we can express $S = UD_4U^T$ (where U are orthonormal)

$$M = D_3 \left(U D_4 U^T + D_1 + D_2 \right)^{-1}$$

Let $D_{12} = D_1 + D_2$. By Woodbury's matrix identity,

$$M = D_3 \left(D_{12}^{-1} - D_{12}^{-1} U \left(\Sigma^{-1} + D_{12} \right)^{-1} U^T D_{12}^{-1} \right)$$

Now consider the \tilde{k} th column of M:

$$\nabla_{\lambda} \hat{m}_{\tilde{k}}(\lambda) = D_3 \left(D_{12}^{-1} - D_{12}^{-1} U \left(\Sigma^{-1} + D_{12} \right)^{-1} U^T D_{12}^{-1} \right) e_{\tilde{k}}$$

Note that the jth elements for $j \neq k$ must be zero since orthogonality is preserved by the orthonormal matrices U. Also note that $D_{12}^{-1}U\left(\Sigma^{-1}+D_{12}\right)^{-1}U^{T}D_{12}^{-1}$ is a positive definite matrix. Hence we have

$$\left|\frac{\partial}{\partial \lambda_{\tilde{k}}}\hat{m}_{\tilde{k}}(\lambda)\right| \leq \left|\frac{\partial}{\partial m_{\tilde{k}}}P_{\tilde{k}}(g_{\tilde{k}}+m_{\tilde{k}}h_{\tilde{k}})+w\langle h_{\tilde{k}},g_{\tilde{k}}+m_{\tilde{k}}h_{\tilde{k}}\rangle_{D}\right|\lambda_{\tilde{k}}^{-1}w^{-1}\|h_{\tilde{k}}\|_{D}^{-2}$$

Note that from the KKT conditions, we have that

$$\begin{split} \left| \frac{\partial}{\partial m_{\tilde{k}}} P_{\tilde{k}}(g_{\tilde{k}} + m_{\tilde{k}} h_{\tilde{k}}) \right| & \leq & \left| \frac{1}{\lambda_{\tilde{k}}} \langle y - \sum_{j=1}^{J} \left(g_{j} + m_{j} h_{j} \right), h_{\tilde{k}} \rangle_{T} + w \langle h_{\tilde{k}}, g_{\tilde{k}} + m_{\tilde{k}} h_{\tilde{k}} \rangle_{D} \right| \\ & \leq & n^{\tau_{min}} \| y - \sum_{j=1}^{J} \left(g_{j} + m_{j} h_{j} \right) \|_{T} \| h_{\tilde{k}} \|_{T} + w \| h_{\tilde{k}} \|_{D} \| g_{\tilde{k}} + m_{\tilde{k}} h_{\tilde{k}} \|_{D} \\ & \leq & \left(\frac{n}{n_{T}} n^{\tau_{min}} \left(2G + \| \epsilon \|_{T} \right) + wG \right) \| h_{\tilde{k}} \|_{D} \end{split}$$

Also

$$w\langle h_{\tilde{k}}, g_{\tilde{k}} + m_{\tilde{k}} h_{\tilde{k}} \rangle_D \le w \|h_{\tilde{k}}\|_D G$$

Hence

$$\left| \frac{\partial}{\partial \lambda_{\tilde{k}}} \hat{m}_{\tilde{k}}(\lambda) \right| \leq \left(\frac{n}{n_T} n^{\tau_{min}} \left(2G + \|\epsilon\|_T \right) + wG + G \right) n^{\tau_{\min}} w^{-1} \|h_{\tilde{k}}\|_D^{-1}$$

By the MVT, there is some $\alpha \in [0, 1]$ such that

$$\begin{aligned} \left| \hat{m}_{\tilde{k}}(\lambda^{(2)}) - \hat{m}_{\tilde{k}}(\lambda^{(1)}) \right| &= \left| \left\langle \lambda^{(2)} - \lambda^{(1)}, \frac{\partial}{\partial \lambda_{\tilde{k}}} \hat{m}_{\tilde{k}}(\lambda) \right\rangle_{\lambda = \alpha \lambda^{(1)} + (1 - \alpha) \lambda^{(2)}} \right| \\ &\leq \|\lambda^{(2)} - \lambda^{(1)}\| \left(\frac{n}{n_T} n^{\tau_{min}} \left(2G + \|\epsilon\|_T \right) + wG + G \right) n^{\tau_{\min}} \frac{J}{dw} \\ &= 1/2 \end{aligned}$$

But this is a contradiction since we know that $\hat{m}_{\tilde{k}}(\lambda^{(2)}) = 1$ and $\hat{m}_{\tilde{k}}(\lambda^{(1)}) = 0$.

Lemma: Additive Models and Additive Penalties, Nonsmooth

Same assumptions as above, but we allow the penalties to be nonsmooth.

Suppose for almost every λ , the differentiable space $\Omega^{L_T(\cdot,\lambda)}(\hat{q}(\cdot|\lambda))$ is a local optimality space.

Suppose for almost every λ , the penalty function is twice differentiable in the differentiable space.

The conclusions are the same as before.

For all d > 0, any $\lambda^{(1)}, \lambda^{(2)}$ that satisfy

$$\|\lambda^{(1)} - \lambda^{(2)}\| \le \frac{dw}{2J} \left(\frac{n}{n_T} n^{\tau_{min}} \left(2G + \|\epsilon\|_T\right) + wG + G\right)^{-1} n^{-\tau_{\min}}$$

we have

$$\|\hat{g}_j(\cdot|\lambda^{(1)}) - \hat{g}_j(\cdot|\lambda^{(2)})\|_D \le d/J$$

Hence

$$\|\sum_{j=1}^{J} \hat{g}_{j}(\cdot|\lambda^{(1)}) - \hat{g}_{j}(\cdot|\lambda^{(2)})\|_{D} \le d$$

Proof

Let $\lambda^{(1)}, \lambda^{(2)}$ be the penalty parameters satisfying the distance constraint above. Let C be the constant defined in the assumption

$$\|\lambda^{(1)} - \lambda^{(2)}\| \le dC$$

Under the assumptions about the differentiable space and the local optimality space, we know that for almost every pair $\lambda^{(1)}, \lambda^{(2)}$, there is a line

$$\mathcal{L} = \left\{ \alpha \lambda^{(1)} + (1 - \alpha) \lambda^{(2)} : \alpha \in [0, 1] \right\}$$

- containing a finite set of points $\{\ell_i\}_{i=0}^{N+1} \subset \mathcal{L}$ where $\ell_0 = \lambda^{(1)}$ and $\ell_{N+1} = \lambda^{(2)}$ such that: 1. The differentiable spaces $\Omega^{L_T(\cdot,\ell_i)}(\hat{g}(\cdot|\ell_i))$ satisfy the condition that the differentiable space is a local optimality differentiable space conditions and
 - 2. The union of the differentiable spaces contains the entire line \mathcal{L} :

$$\mathcal{L} \subset \cup_{i=0}^{N+1} \Omega^{L_T(\cdot,\ell_i)}(\hat{g}(\cdot|\ell_i))$$

Now we partition \mathcal{L} according to the differentiable spaces. We will partition with the centers of each differentiable space and points in the intersection of all the differentiable spaces. Let $\{\ell_{(i)}\}_{i=0}^N \subset \mathcal{L}$ be the points such that $\ell_{(i)}$ is in the differentiable space $\Omega^{L_T(\cdot,\ell_i)}(\hat{g}(\cdot|\ell_i))$ and $\Omega^{L_T(\cdot,\ell_{i+1})}(\hat{g}(\cdot|\ell_{i+1}))$. That is, we choose

$$\ell_{(i)} \in \Omega^{L_T(\cdot,\ell_i)}(\hat{g}(\cdot|\ell_i)) \cap \Omega^{L_T(\cdot,\ell_{i+1})}(\hat{g}(\cdot|\ell_{i+1}))$$

Hence the following points form a partition of \mathcal{L}

$$\left(\ell_{0},\ell_{(0)}\right),\left(\ell_{(0)},\ell_{1}\right),...,\left(\ell_{N},\ell_{(N)}\right),\left(\ell_{(N)},\ell_{N+1}\right)$$

Note that

$$\|\ell_i - \ell_{(i)}\| \le \frac{\|\ell_i - \ell_{(i)}\|}{\|\lambda^{(1)} - \lambda^{(2)}\|} dC$$

Applying the smooth lemma to the pairs of points above, we have that

$$||g(\cdot|\ell_i) - g(\cdot|\ell_{(i)})||_D \le \frac{||\ell_i - \ell_{(i)}||}{||\lambda^{(1)} - \lambda^{(2)}||}d$$

Similarly,

$$||g(\cdot|\ell_{i+1}) - g(\cdot|\ell_{(i)})||_D \le \frac{||\ell_{i+1} - \ell_{(i)}||}{||\lambda^{(1)} - \lambda^{(2)}||}d$$

Hence

$$||g(\cdot|\lambda^{(1)}) - g(\cdot|\lambda^{(2)})||_{D} \leq \sum_{i=0}^{N} ||g(\cdot|\ell_{i}) - g(\cdot|\ell_{(i)})||_{D} + ||g(\cdot|\ell_{i+1}) - g(\cdot|\ell_{i()})||_{D}$$

$$\leq d \left(\sum_{i=0}^{N} \frac{||\ell_{i+1} - \ell_{(i)}||}{||\lambda^{(1)} - \lambda^{(2)}||} + \frac{||\ell_{i} - \ell_{(i)}||}{||\lambda^{(1)} - \lambda^{(2)}||} \right)$$

$$= d$$