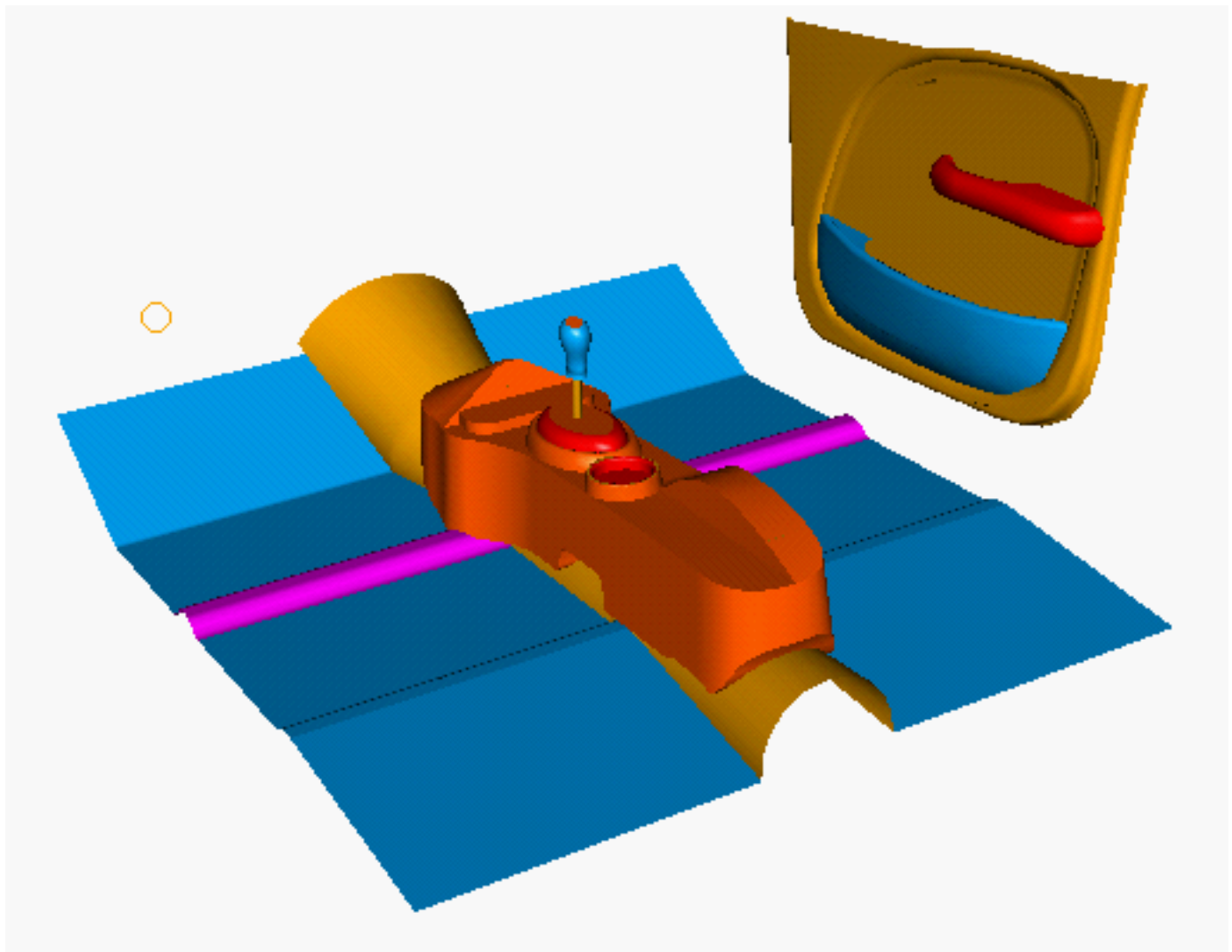


# Seat Track Assembly Vignette



March 9, 1998

## Demonstration Particulars

### Installation

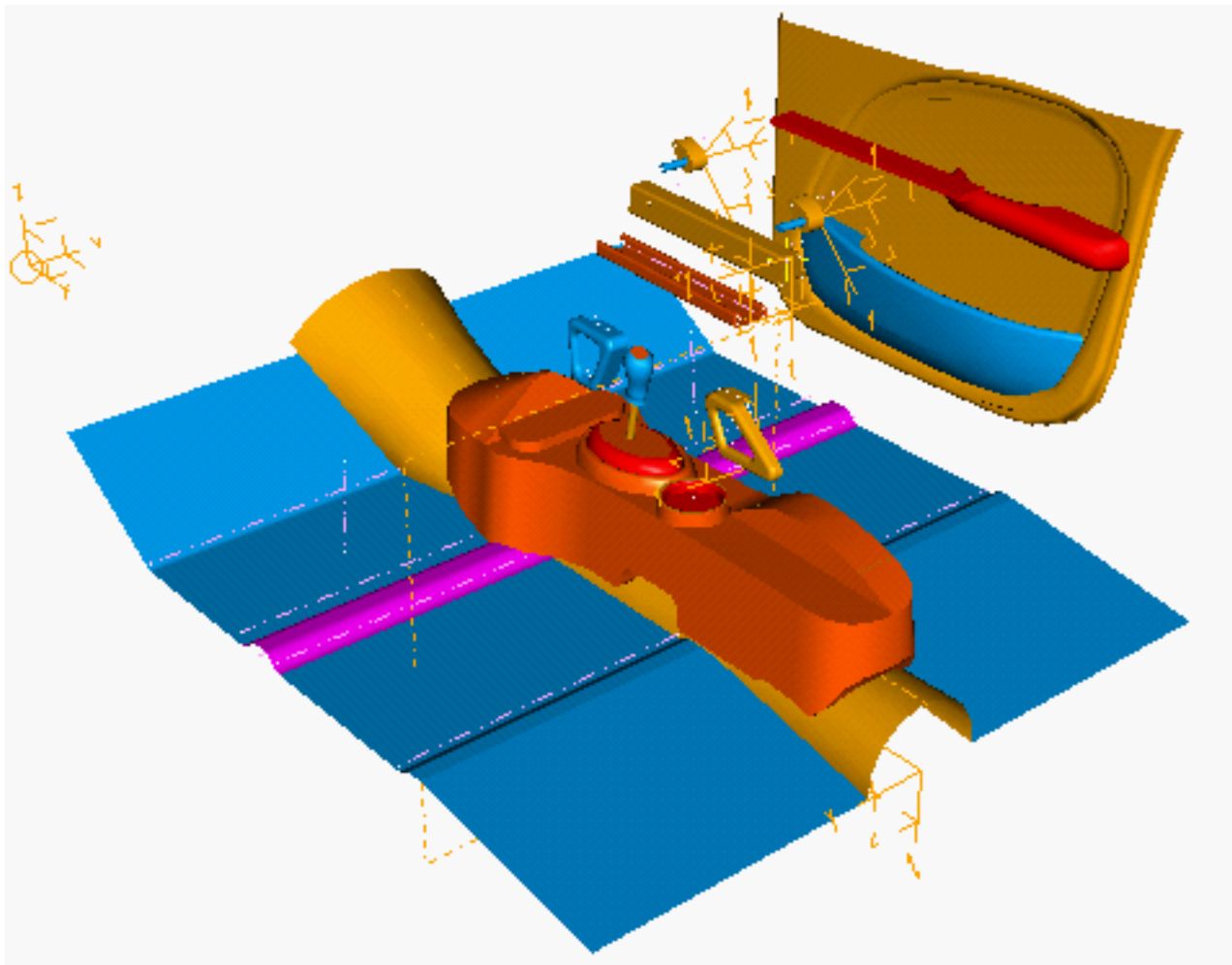
- Copy or unload the demo files to a local directory
- cd to the directory containing the demo files
- Start I-DEAS
  - Project = **Any**
  - Model File = **Auto**
  - Application = **Design**
  - Task = **Master Assembly**
- Import auto.arc archive file
- Run startup.prg

### Files:

Archive file	<b>auto.arc</b>
SGI Showcase documentation	<b>auto.sc</b>
Adobe Acrobat File	<b>auto.pdf</b>

## Demonstration Summary

- 1) Upper (UT) and Lower track(LT)
  - Coincident* - XY plane (UT)and XY plane (LT)
  - Linear dimension* - ZY/ZY ( value=5)
  - Linear dimension* - XZ/XZ ( value = 50)
- 2) Rear Riser/ Lower Track
  - Coincident* - Top surface of riser/bottom surface of lower track
  - Coincident* - riser hole CL/ track hole CL
- 3) Front Riser/ Lower Track
  - same as above for the other riser
- 4) Cams to Upper Track
  - Coincident* - CL to CL coincident
  - coplanar* - shaft face to side plane of UT
  - Angular dim* - cams to track surfaces
- 5) Seat pan to cams
  - Coincident* - Pan back XZ to YZ lower track
  - Tangent* - Seat pan bottom surface to cam
  - Colanar* - Side of pan to side of cam
- 6) Assembly equations
- 7) Hardware animation
- 8) Relation Browser
- 9) Seat track to Floor
  - Lock Floor*
  - Coincident* - rear riser to floor
  - Coincident* - hole CL to ref point
- 10) VGX drag of lower track



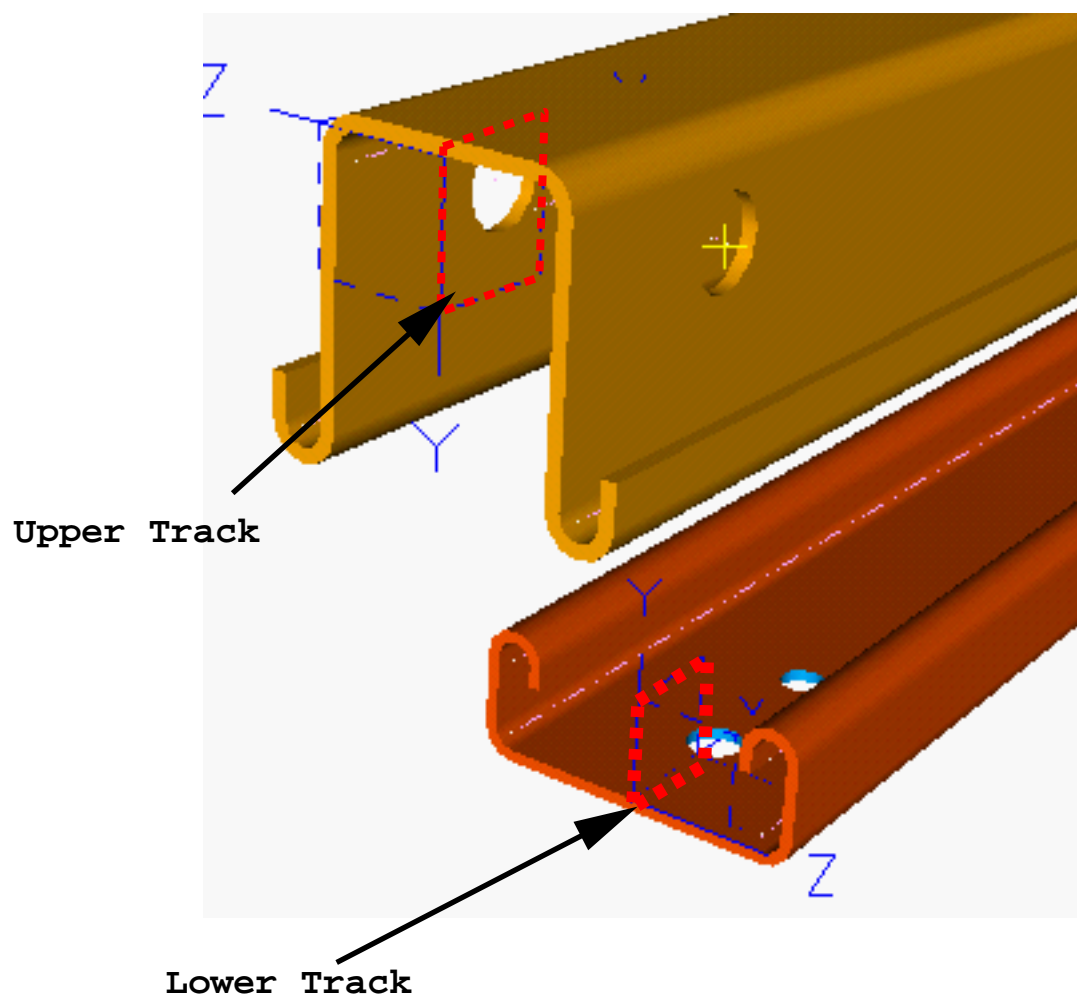
**Master Assembly**

**Heirarchy**

Suppress the env subassembly  
Suppress Seat Pan

**Deselect**

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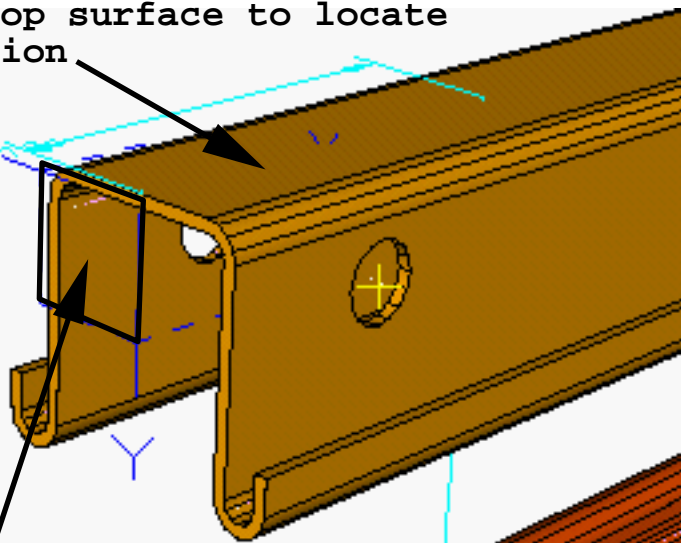
## Constrain and Dimension

### Coincident

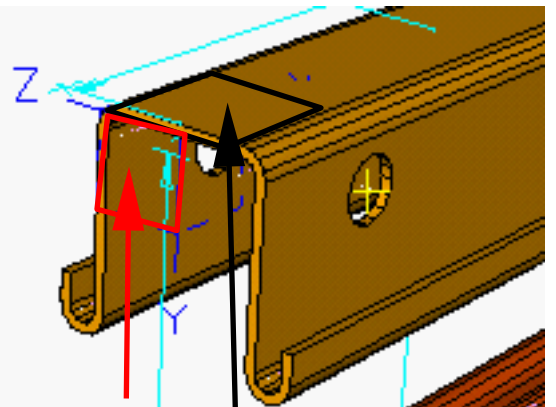
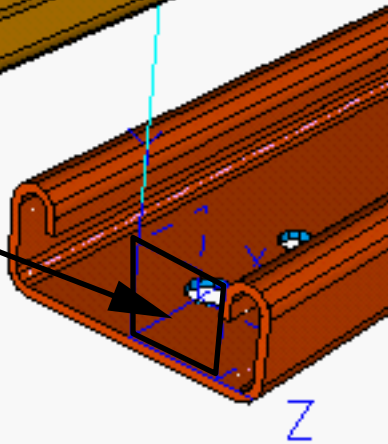
Select the XY plane from the coordinate system on the Upper Track, select the XY plane from the Lower Track

Pick top surface to locate dimension

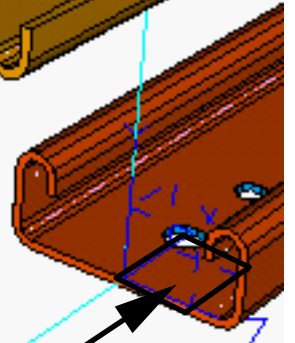
Z



Select both XY Planes



Pick plane to locate dimension



Select XZ planes

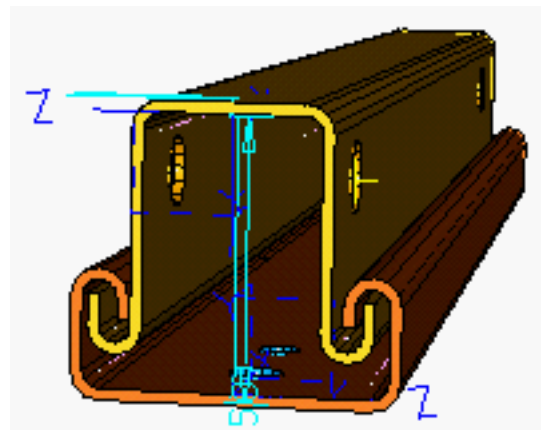
## Dimension

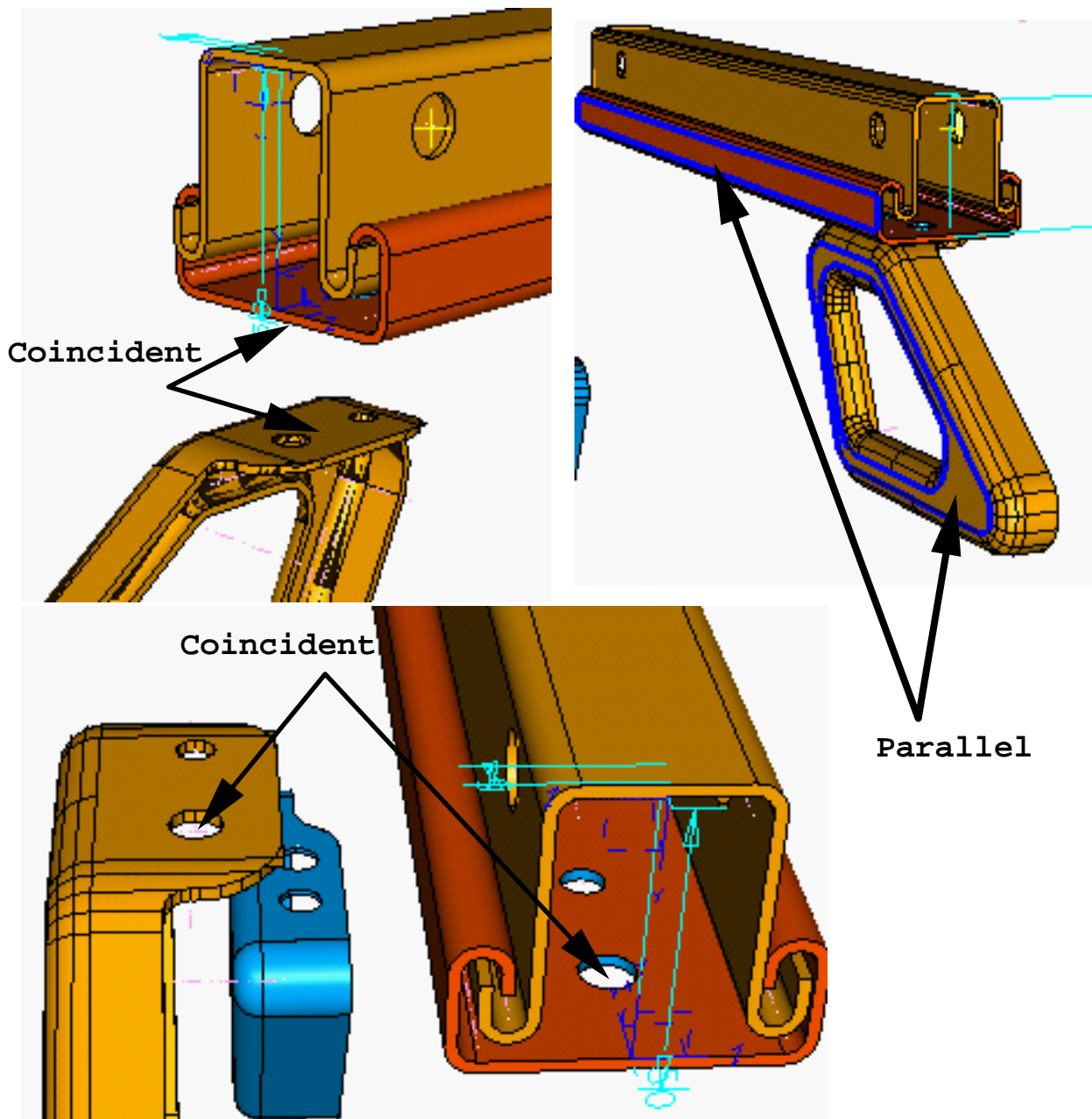
Dimension between ZY coordinate systems on both parts, select top surface shown to locate dimension.

Dimension between both XZ coordinate system planes, select the ZY coordinate system plane to locate the dimension

## Modify

Change ZY dimension to d=5  
Change XZ dimension to d=50





coo - global symbol to turn off coord systems

### Constrain and Dimension

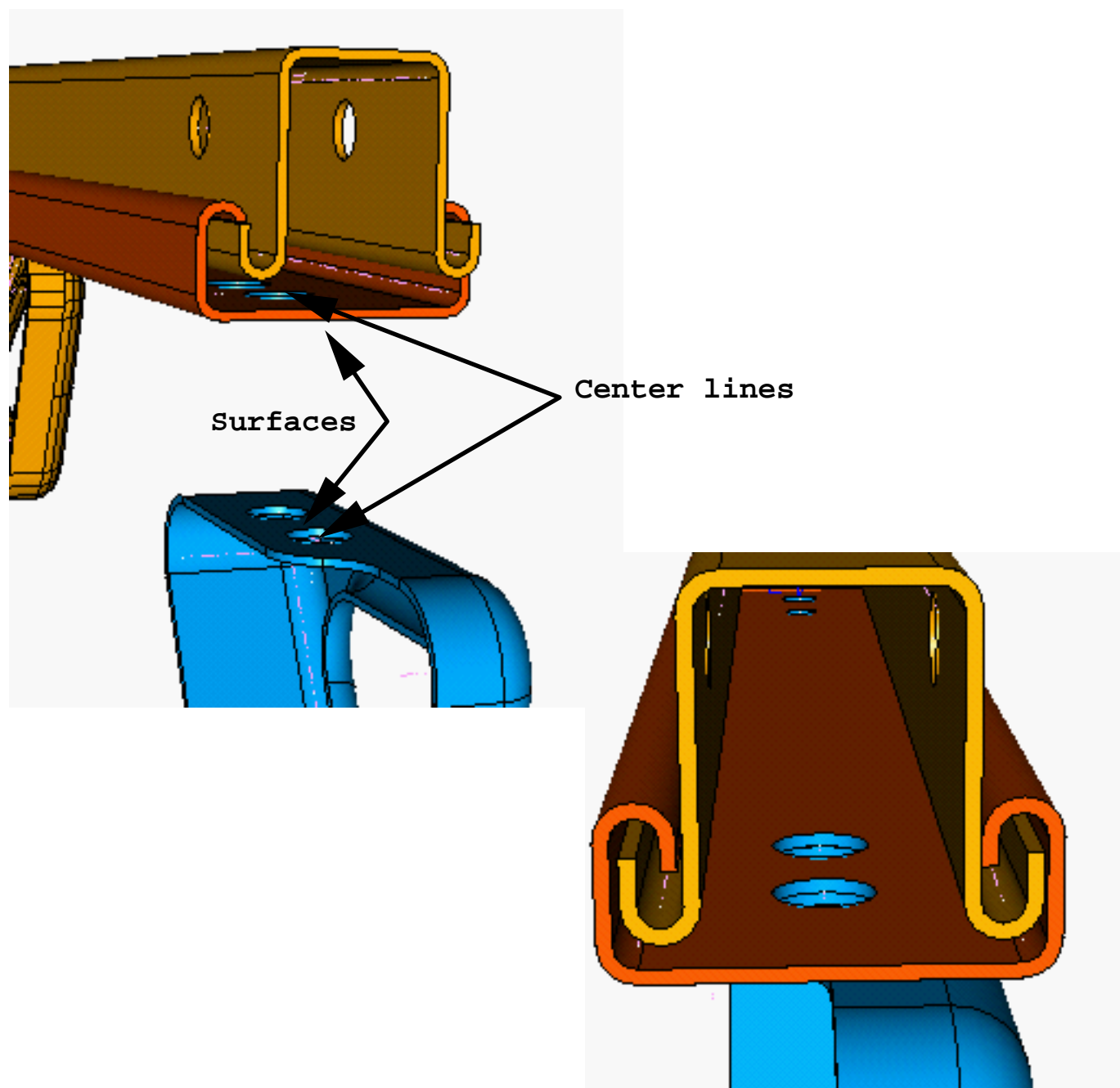
#### Coincident

Select top surface from riser (f48) and  
bottom surface from the lower track (F26)

Select Centerline of both holes shown  
MB3 filter centerlines if necessary

#### Parallel

Select the 2 surfaces shown

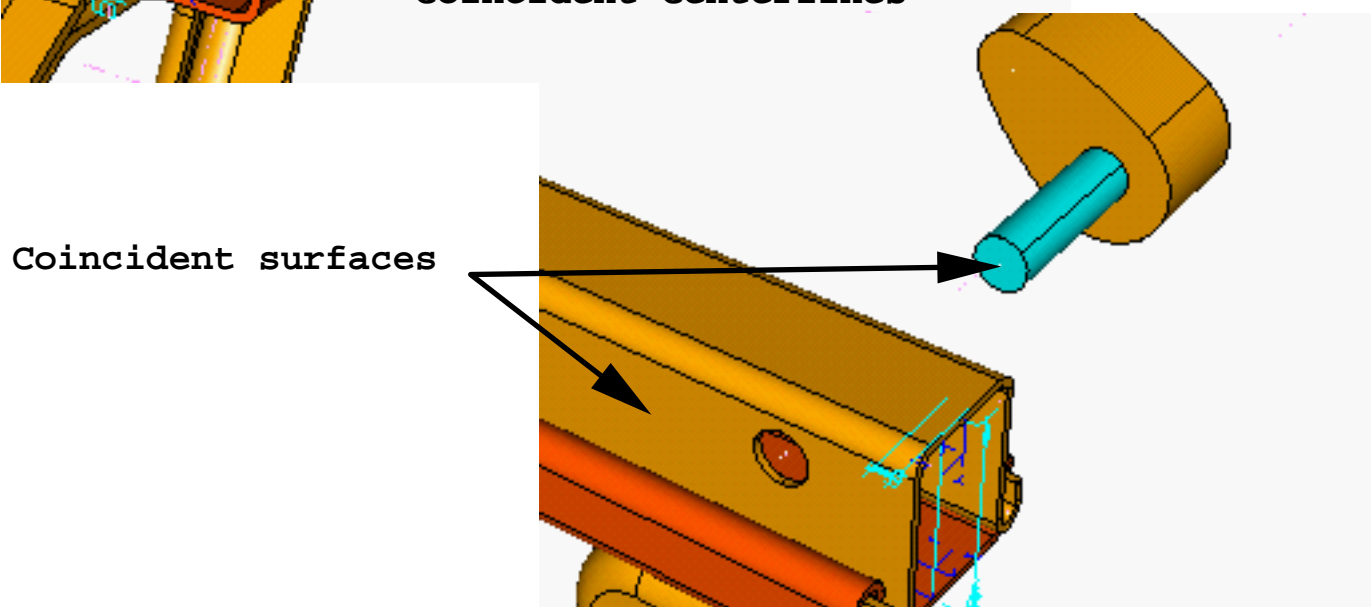
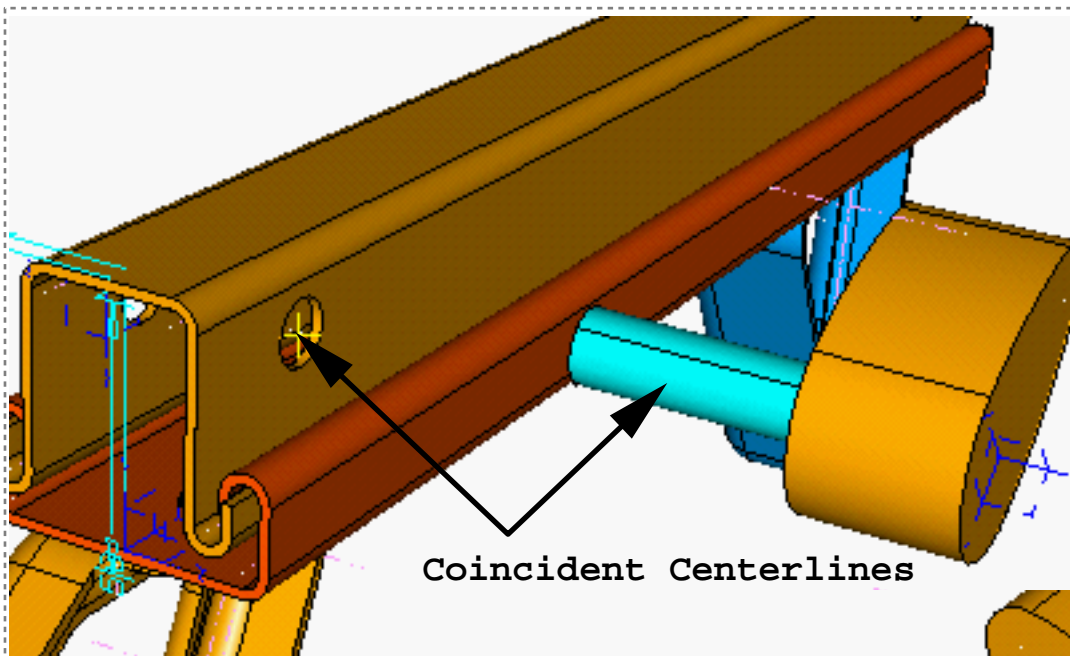


### Constrain and Dimension

Select the top surface of the front riser (F55) and the lower surface from the lower track (F26)

Select the hole center lines



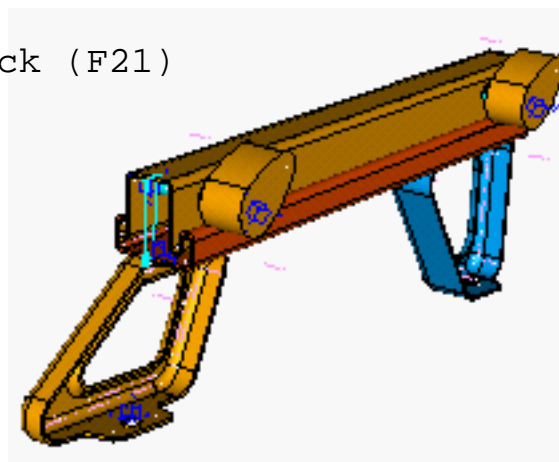


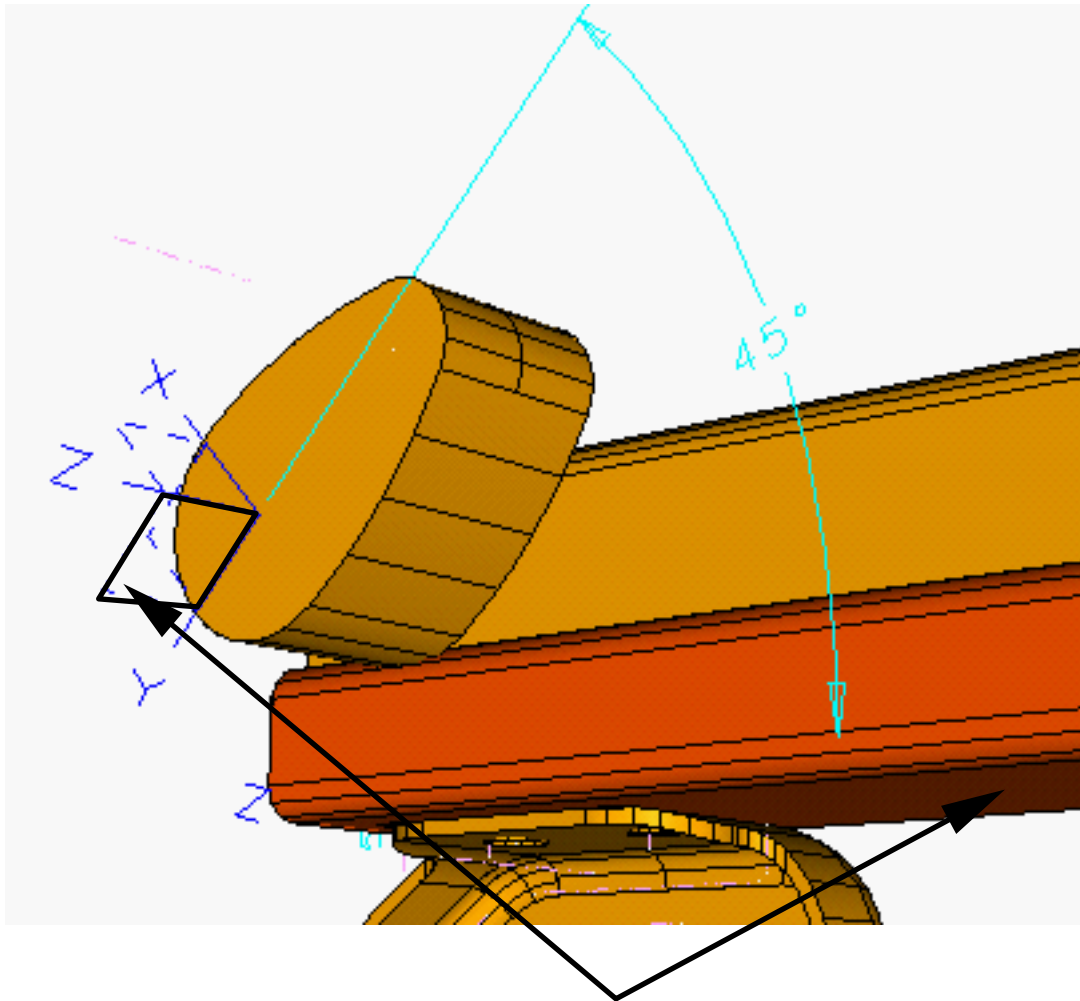
### Coincident

MB3, filter centerlines, pick only

Select surfaces from the Cam (F5)  
and the side face of the upper track (F21)

Repeat for the other cam



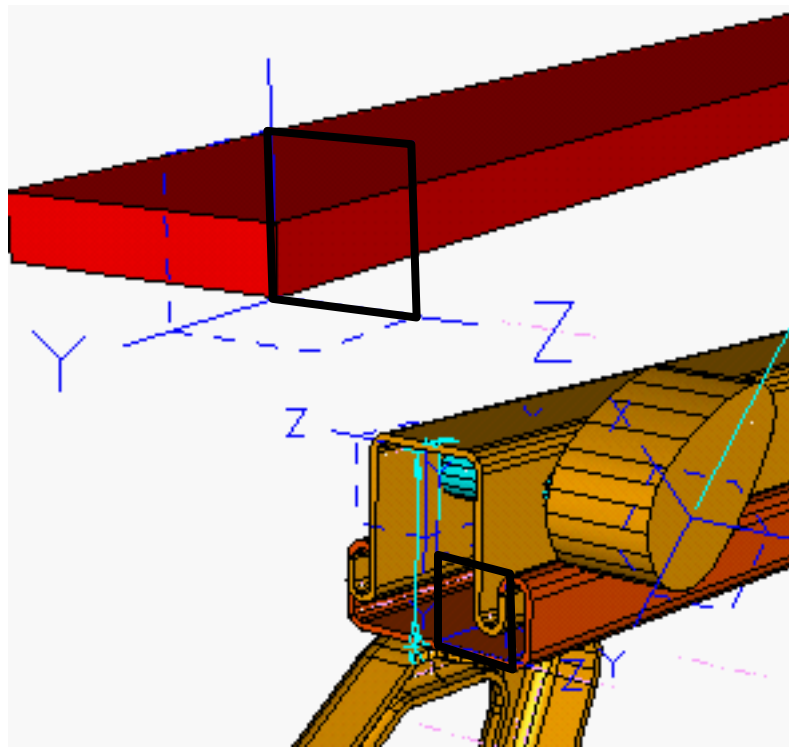


Dimension

### Dimension

Select the YZ Coordinate system plane  
Select the lower face (F26) from the lower track

Repeat for other Cam



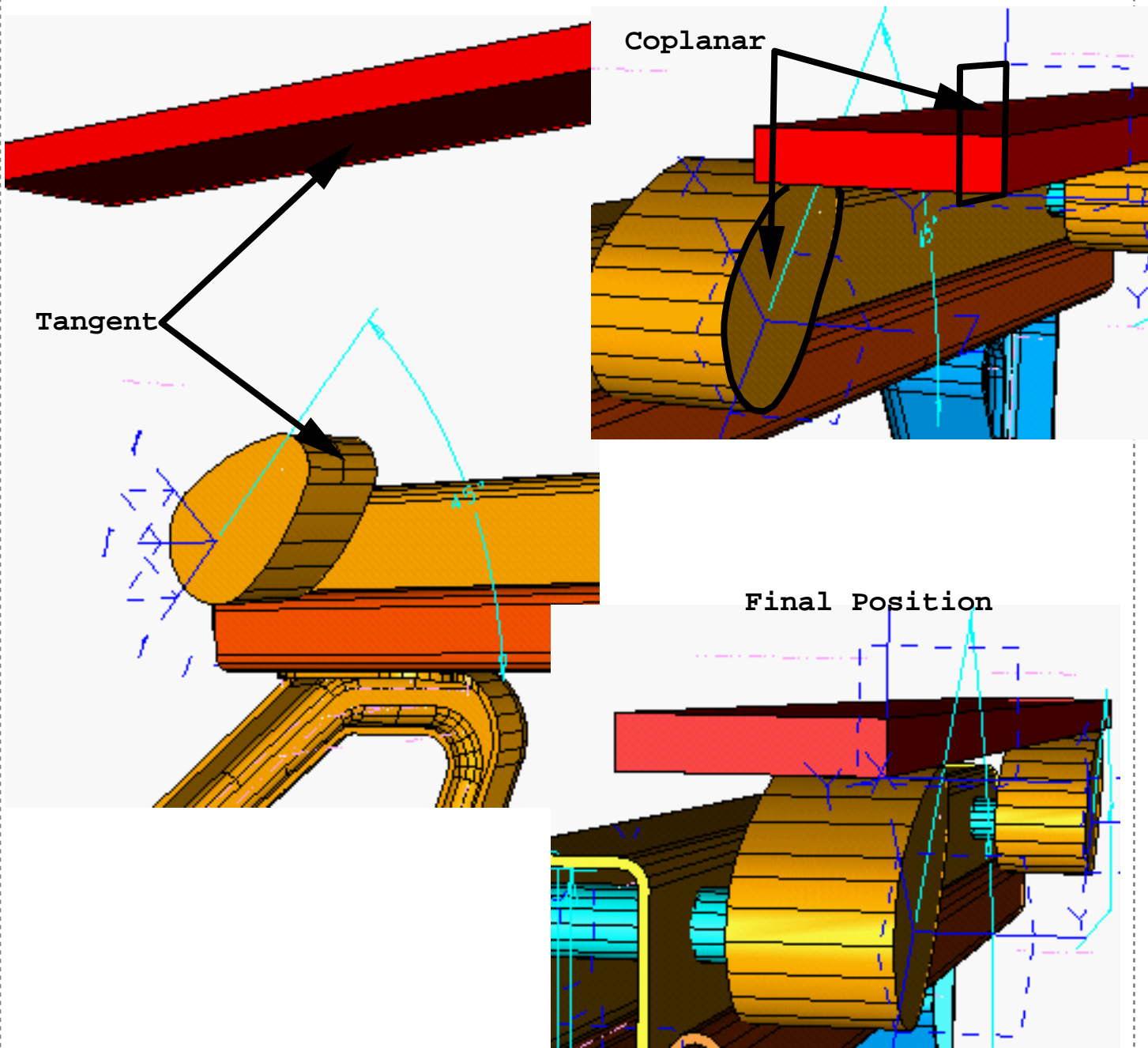
**Unsuppress Seat Pan instance**

**Constrain and Dimension**

**Coincident and Colinear**

Select the XZ coordinate system plane from the seat pan and the YZ coord. sys. plane from the lower track.

**Cont. Next Page**

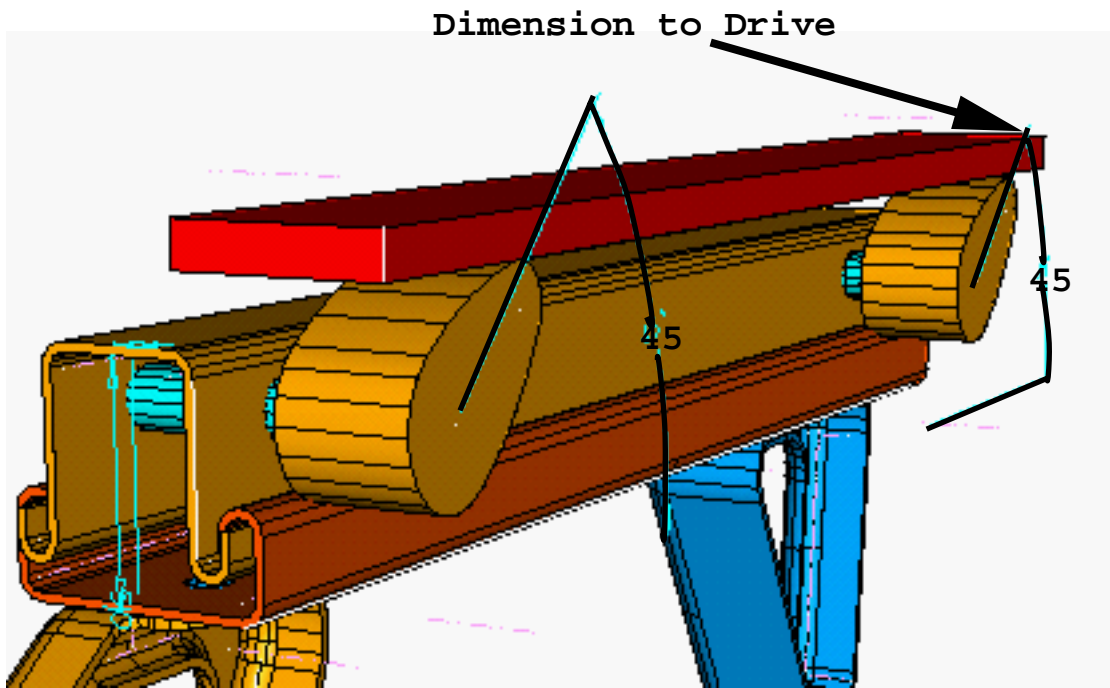


## Constrain and Dimension Tangent

Select the bottom face of the seat pan  
and the top face of the Cam shown

## Coincident and Colinear

Select the side face of the seat pan or  
the coordinate system XY plane,  
and the side face of the cam



### Assembly Equations

Create, navigate toward both of the angular dimensions and remember dimension labels, select rear dimension to drive, enter label of other dimension ( i.e. hi1\_d32)

Pull down to animate

H11\_D32 = 45 [->] >< 45 |Deg|

OK Apply Reset Cancel

30 80

Speed Frames 10 ☐ Bounce ☐ Inertia

☒ Sequence SEQU1 ? Start

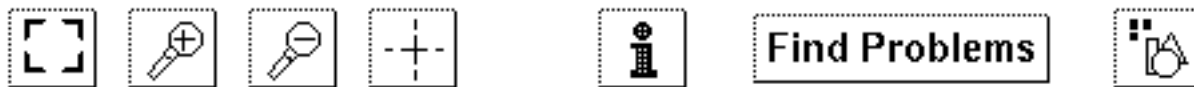
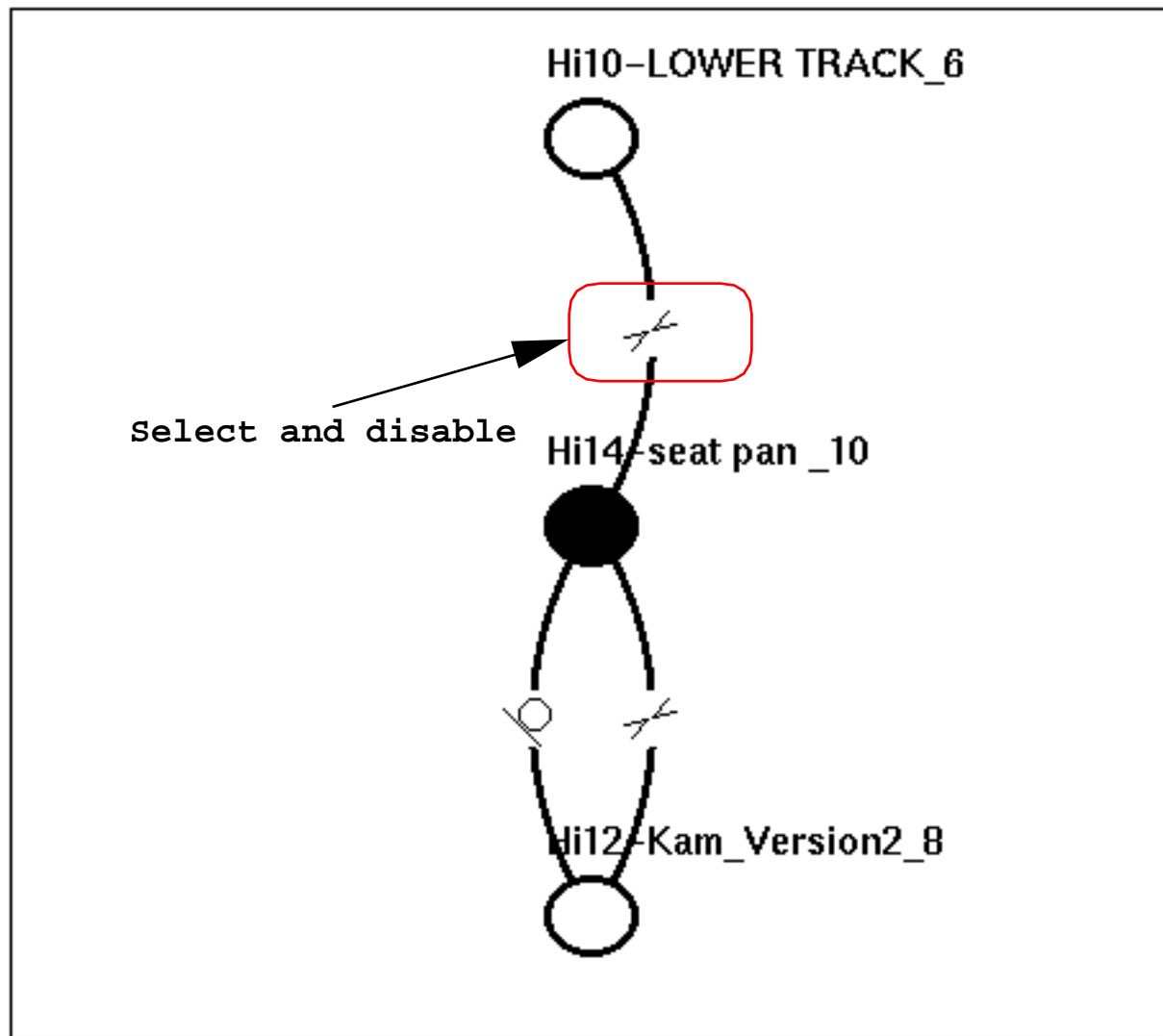
OK Cancel

## Modify

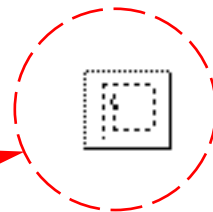
Select the driving angular dimension  
Pull down animate, set the values between 30 and 80, highlight sequence, drag the slider to the left and select start. This will write sequence data to be used next during hardware animation.

## Animate Hardware

Start animation



- ◆ Instance Specific
- ◆ Constraint Loops



Dismiss

## Browse relations

Select the Seat Pan

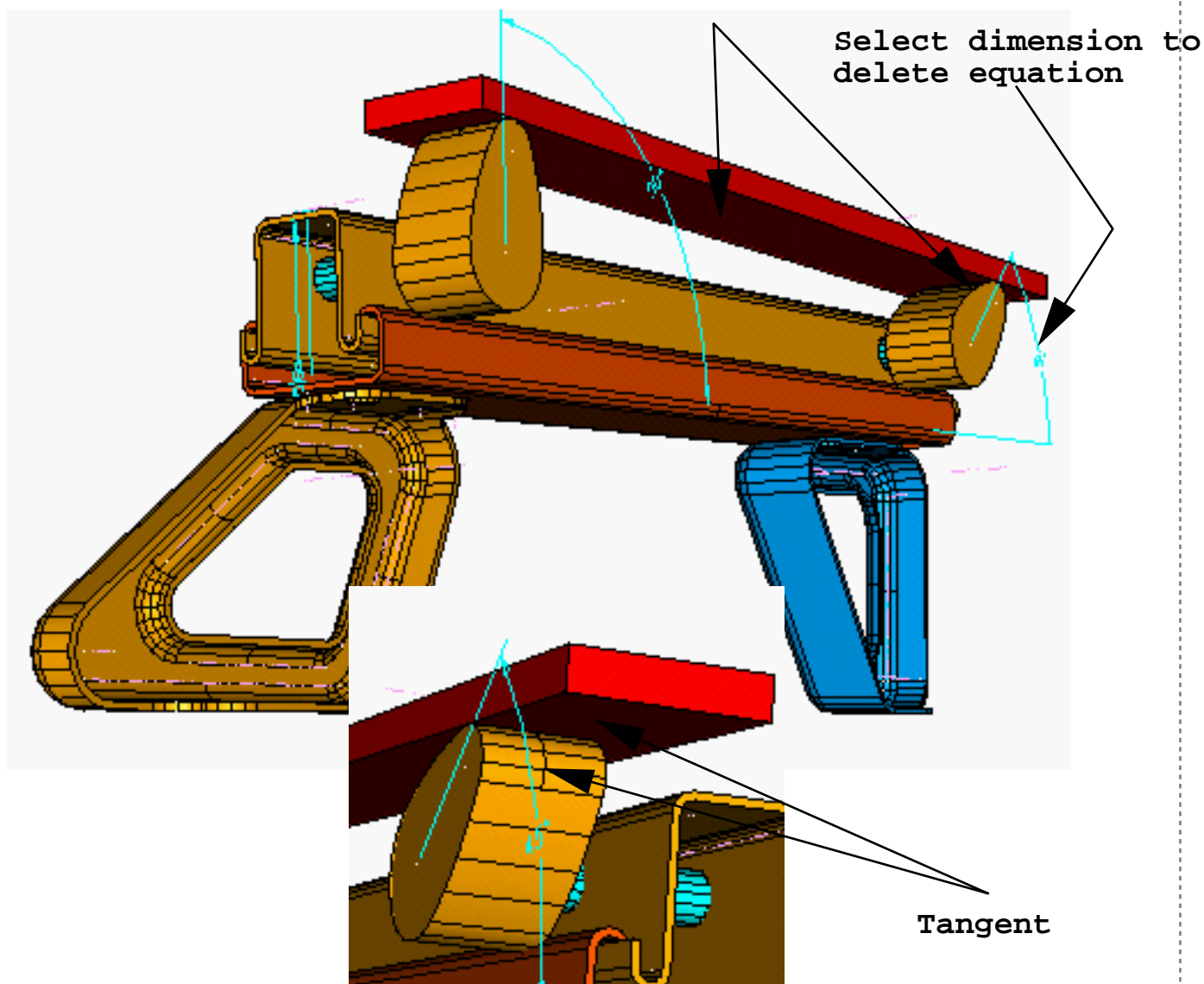
Pick the coincident relation off of the form, Dismiss

## Modify

Disable

Dismiss

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**Assembly Equations**

delete, pick the driven dimension, MB2

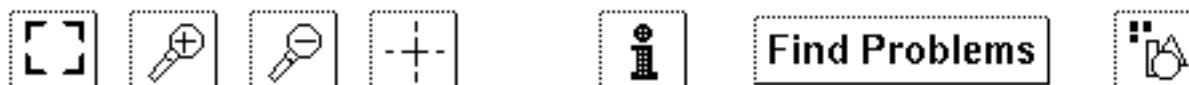
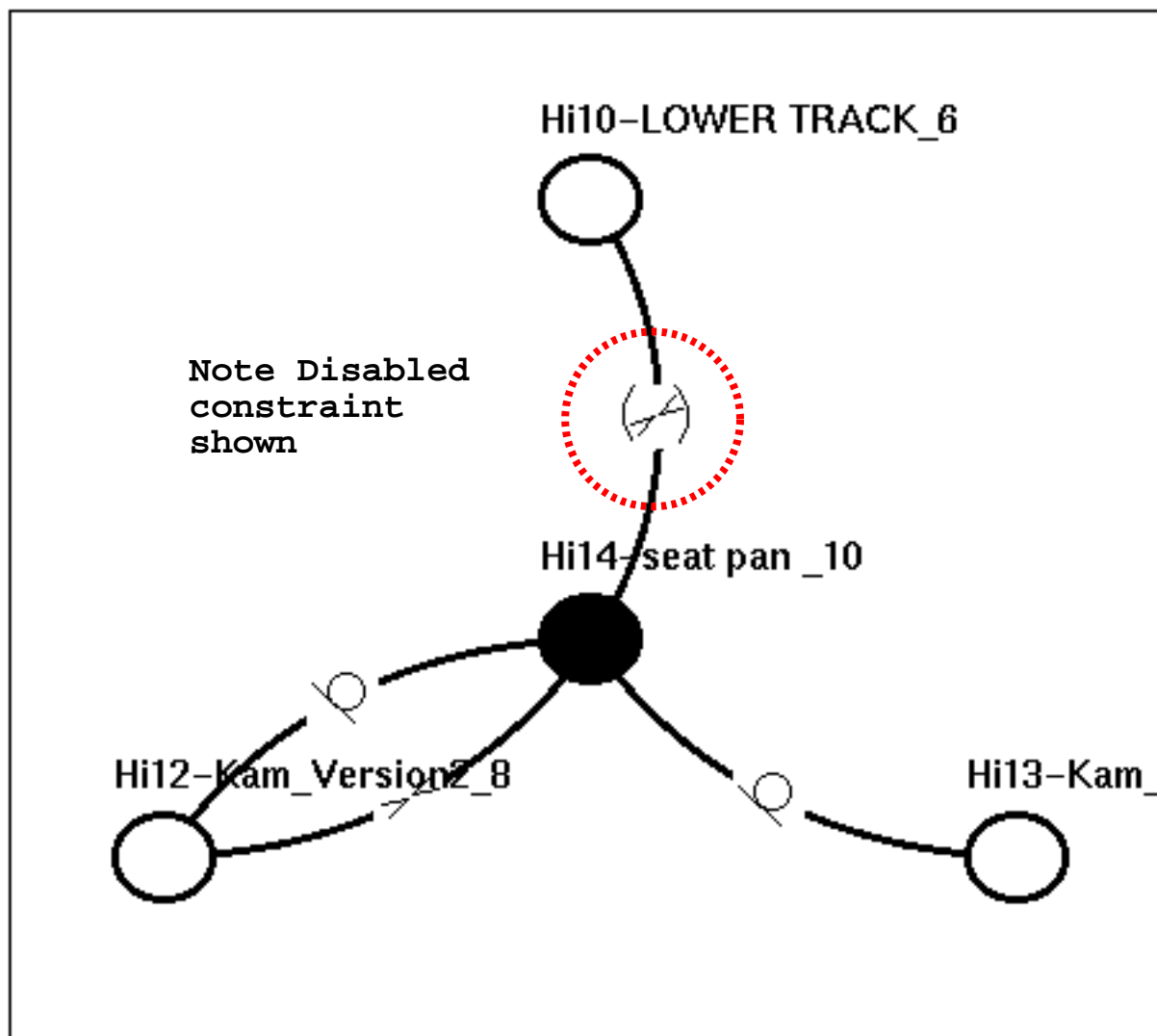
**Constrain and Dimension**

Tangent, select the bottom surface of the seat pan and the surface of the Cam shown.

**Modify**

Change both angular dimensions to different values. 45 and 90 degrees are shown.





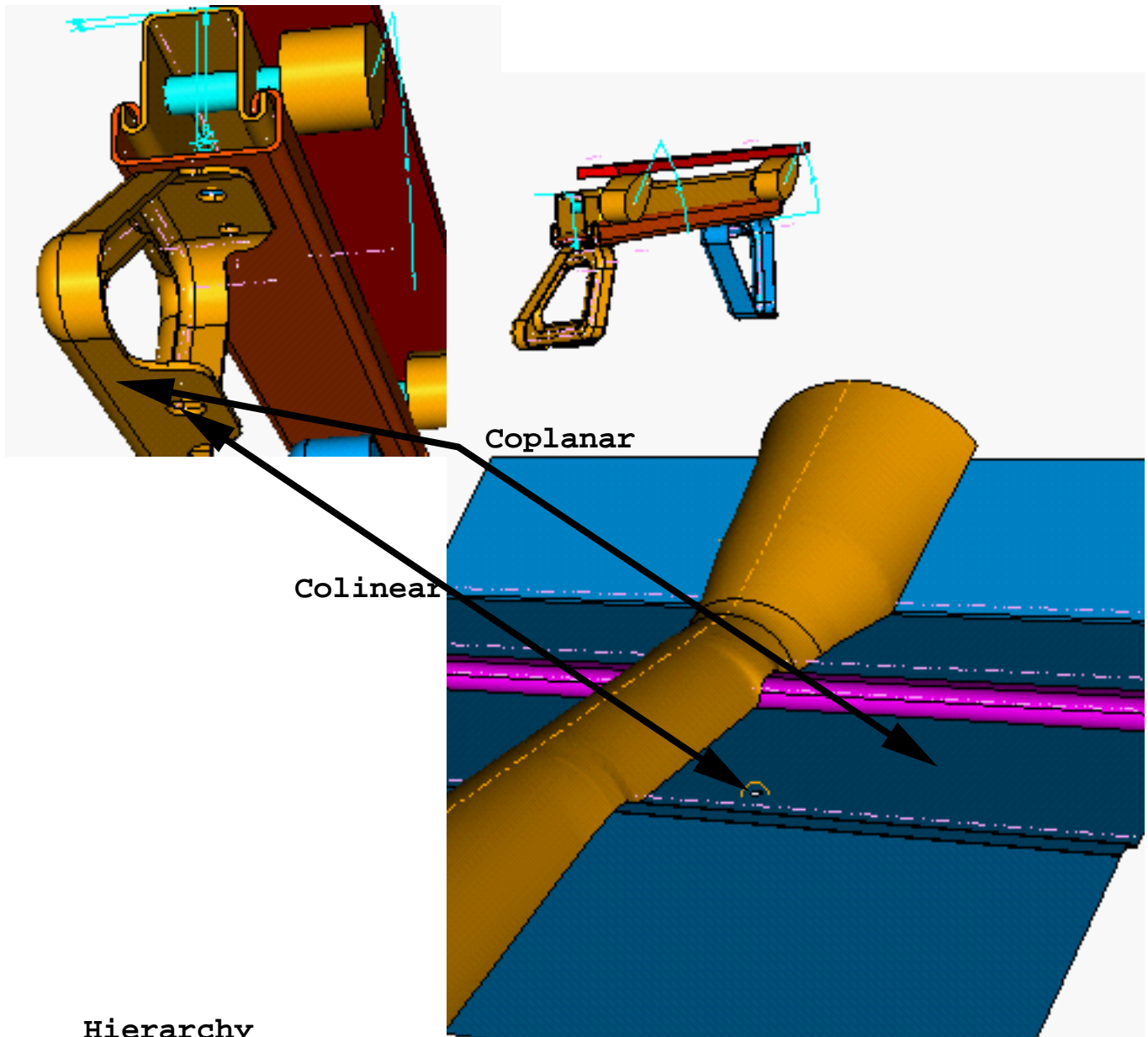
◆ Instance Specific  
 ◇ Constraint Loops



Dismiss

## Browse Relations

Select the seat pan and note the disabled seat pan constraint



## Hierarchy

Show "floor pan full" instance

## Deselect

## Constrain and Dimension

### Lock

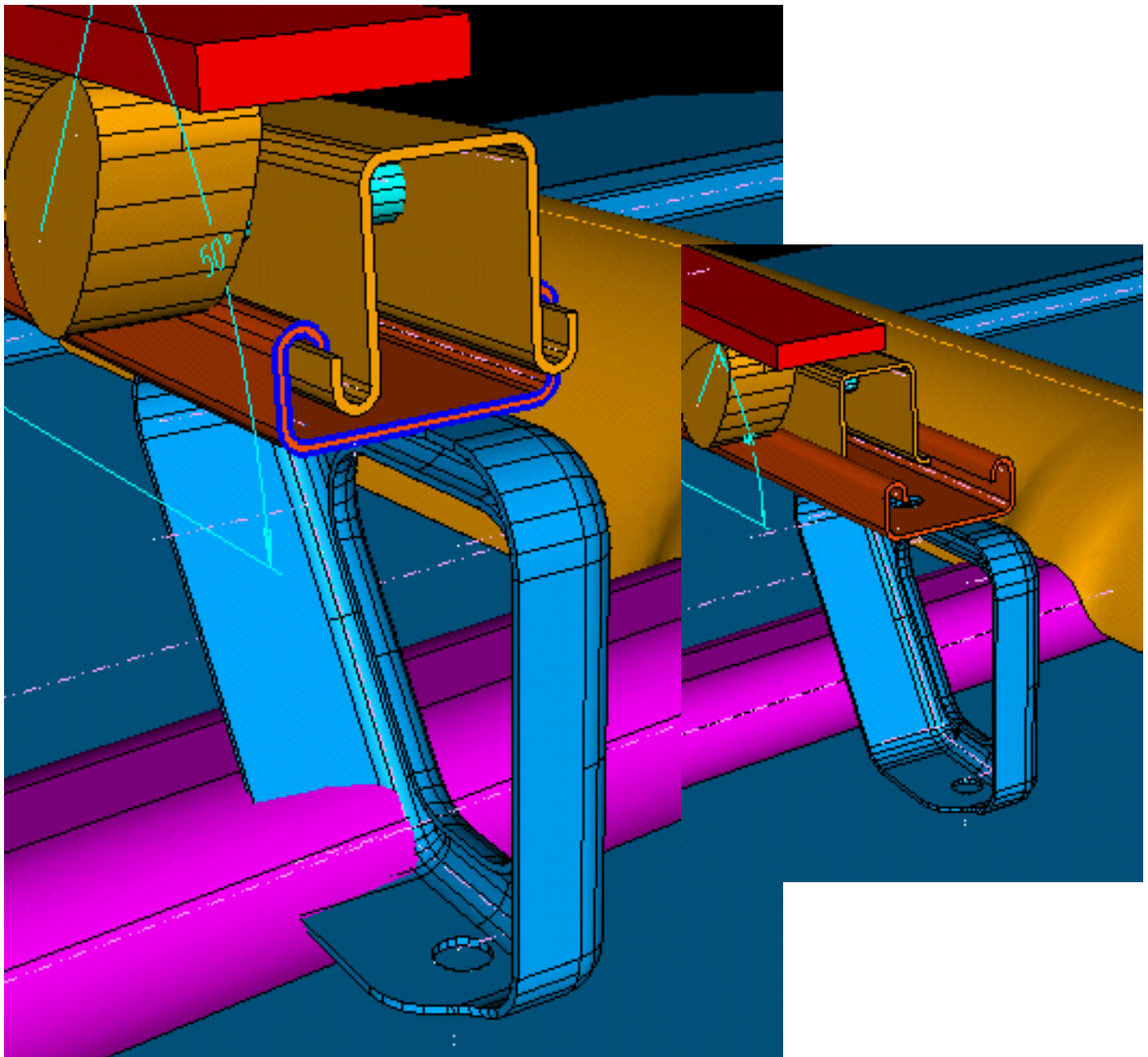
pick floor, MB3 hierarchy, select the env subassembly to lock relative to.

### Coincident and colinear

pick bottom surface of rear riser (f8) and floor (f146)

Pick centerline of riser hole and reference point on floor

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### Drag

Select the surface shown from the lower seat track, drag to alleviate interference.

### Update