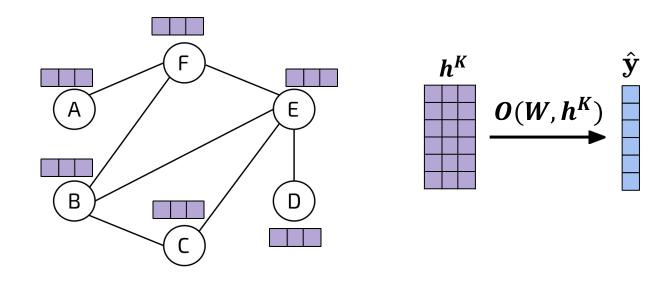
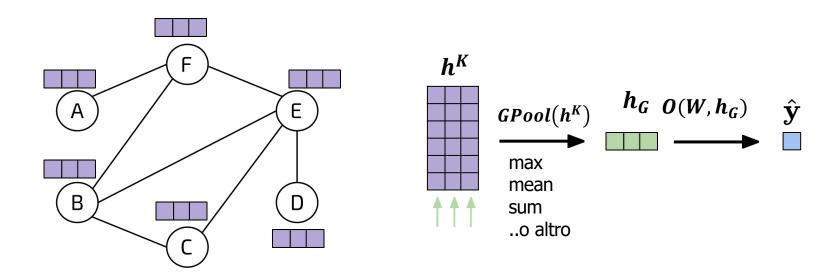
Graph Classification

Predizione dell'etichetta di un nodo



$$m{h^{k+1}} = m{GNN}ig(W^k, m{h^k}, m{A}ig) \, m{k} = m{0}, ..., m{K}$$
 $m{O}(W, m{h^K})$ — Funzione node readout

Classificazione grafi



$$h^{k+1} = GNN(W^k, h^k, A) \ k = 0, ..., K$$
 $h_G = GPool(h^K) \longrightarrow$ Funzione di pooling globale $O(W, h_G) \longrightarrow$ Funzione di graph readout

Graph Pooling?

- Processo di aggregazione delle informazioni a livello di nodi per ottenere una rappresentazione a livello di grafo
- Obiettivo: Ridurre la dimensionalità da node-level a graph-level
- **Necessità**: I grafi hanno dimensioni variabili, ma i classificatori richiedono input di dimensione fissa

$$h_G = GPool(\{h_v^K \mid v \in V\})$$

Vari tipi

Sum Pooling

$$h_G = \sum_{v \in V} h_v^K$$

Mean Pooling:

$$h_G = \frac{1}{|V|} \sum_{v \in V} h_v^K$$

Max Pooling

$$h_G = max_{v \in V} h_v^K$$

Attention Pooling

$$h_G = \sum_{v \in V} \alpha_v h_v^K$$

Come calcoliamo il mecccanismo di attenzione (semplificaizone)

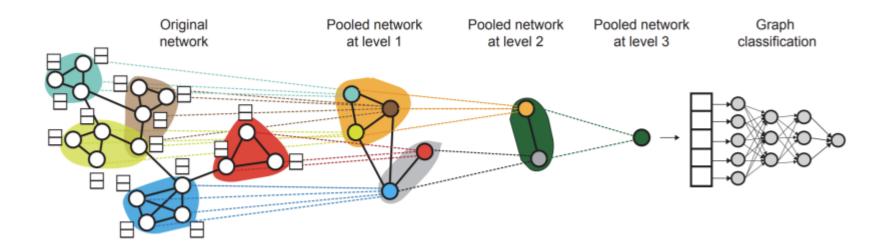
$$\boldsymbol{e}_{\boldsymbol{v}} = \boldsymbol{W} \times \boldsymbol{h}_{\boldsymbol{v}}^K + \boldsymbol{B}$$

$$\alpha_{\rm v} = \frac{\exp(\mathbf{e}_{\rm v})}{\sum exp(e_{\rm u})}$$

Varianti

- Self-attention
- Multi-head attention
- GAT
- Gerarchico

Pooling gerarchico



Approccio multi-livello: Riduce gradualmente la dimensione del grafo

Preserva struttura: Mantiene le connessioni importanti

Selezione intelligente: Sceglie i nodi più rilevanti

Coarsening: Processo iterativo di semplificazione

SAG Pooling

pool.SAGPooling

Bases: Module

The self-attention pooling operator from the "Self-Attention Graph Pooling" and "Understanding Attention and Generalization in Graph Neural Networks" papers.

If min_score \tilde{lpha} is None , computes:

$$egin{aligned} \mathbf{y} &= \operatorname{GNN}(\mathbf{X}, \mathbf{A}) \ \mathbf{i} &= \operatorname{top}_k(\mathbf{y}) \ \mathbf{X}' &= (\mathbf{X} \odot \operatorname{tanh}(\mathbf{y}))_{\mathbf{i}} \ \mathbf{A}' &= \mathbf{A_{i,i}} \end{aligned}$$

If min_score $\tilde{\alpha}$ is a value in [0, 1], computes:

$$egin{aligned} \mathbf{y} &= \operatorname{softmax}(\operatorname{GNN}(\mathbf{X}, \mathbf{A})) \ \mathbf{i} &= \mathbf{y}_i > \tilde{lpha} \ \mathbf{X}' &= (\mathbf{X} \odot \mathbf{y})_{\mathbf{i}} \ \mathbf{A}' &= \mathbf{A}_{\mathbf{i} \ \mathbf{i}}. \end{aligned}$$

Projections scores are learned based on a graph neural network layer.

PARAMETERS:

- in_channels (int) Size of each input sample.
- ratio (float or int) Graph pooling ratio, which is used to compute $k = \lceil \text{ratio} \cdot N \rceil$, or the value of k itself, depending on whether the type of ratio is float or int. This value is

TopK Pooling

pool.TopKPooling

Bases: Module

 top_k pooling operator from the "Graph U-Nets", "Towards Sparse Hierarchical Graph Classifiers" and "Understanding Attention and Generalization in Graph Neural Networks" papers.

If $\min_$ score \tilde{lpha} is None , computes:

$$egin{aligned} \mathbf{y} &= \sigma \left(rac{\mathbf{X}\mathbf{p}}{\|\mathbf{p}\|}
ight) \ \mathbf{i} &= ext{top}_k(\mathbf{y}) \ \mathbf{X}' &= (\mathbf{X} \odot ext{tanh}(\mathbf{y}))_{\mathbf{i}} \ \mathbf{A}' &= \mathbf{A}_{\mathbf{i},\mathbf{i}} \end{aligned}$$

If min_score $\tilde{\alpha}$ is a value in [0, 1], computes:

$$egin{aligned} \mathbf{y} &= \operatorname{softmax}(\mathbf{X}\mathbf{p}) \ \mathbf{i} &= \mathbf{y}_i > ilde{lpha} \ \mathbf{X}' &= (\mathbf{X} \odot \mathbf{y})_{\mathbf{i}} \ \mathbf{A}' &= \mathbf{A}_{\mathbf{i},\mathbf{i}}, \end{aligned}$$

where nodes are dropped based on a learnable projection score \mathbf{p} .

PARAMETERS:

- in_channels (int) Size of each input sample.
- ratio (float or int) The graph pooling ratio, which is used to compute $k = \lceil \text{ratio} \cdot N \rceil$, or the value of k itself, depending on whether the type of ratio is float or int. This value is ignored if min score is not None. (default: 0.5)