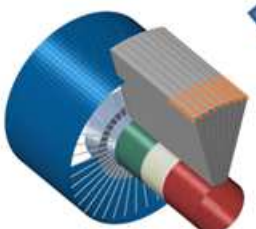

.inp

.mtx
.dat

$[K_{DZ}(\{x\})]$ $\{F_{DZ}(\{x\})\}$

MATLAB

$\oplus$

$[K(\{x\})]\{U(\{x\})\} = \{F(\{x\})\}$

$\{u_E\} = [P][\Pi_{cd}]\{u_d\} + \{u_0\}$

$\{\delta_{(s)}\} = [\gamma_{(s)}]\{u_E\}$

$\Delta TSFC\% = \sum_{s=1}^{ns} \lambda(s)R(s)$

$[\tilde{K}_{cc}]$ $\{\tilde{F}_c\}$ $[P]$
$\{u_0\}$
$[\Pi_{cd}]$