A06 - Assignment 6

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Answers to the theory questions

1. Yes, we got a speedup, these are the measured times:

Host time: 2732.701 ms
Device calculation: 72.731 ms
Copy result: 14.103 ms
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Figure 1: Sequential code timing, cuda kernel and memory operations.

If we consider the single calculation of data as a time frame, the **speedup** we have achieved with the use of a **GPU** is:

Speed-up =
$$\frac{T_{\text{CPU}}}{T_{\text{GPU-calc}}} = \frac{2732.701ms}{72.731ms} \approx 37.573$$

If, on the other hand, we consider as **GPU time** both the calculation time and the time for **copying data into memory**, then we have that:

Speed-up =
$$\frac{T_{\text{CPU}}}{T_{\text{GPU-calc}} + T_{\text{GPU-mem}}} = \frac{2732.701ms}{72.731ms + 14.103ms} \approx 31.47$$

The significant speed-up achieved with CUDA parallelisation is due to the GPU's ability to execute a large number of operations in parallel, computationally intensive efficiency, CUDA kernel optimisation and efficient memory management. These factors combine to drastically reduce execution time compared to a sequential version running on a CPU.

- The GPU used to test the code is an Nvidia Tesla T4, as shown by the information obtained with the nvidia-smi command:
- 3. SIMD (Single Instruction Multiple Data) is a parallelism model in which a single instruction is executed simultaneously on multiple data. This model is commonly used in vector processing units and SIMD extensions of modern CPUs. SPMD (Single Program Multiple Data) is a parallelism model in which multiple processors execute the same program, but on different data. Each processor can execute different instructions depending on the data it is processing. CUDA uses the SPMD model: a CUDA kernel is a function that is executed in parallel

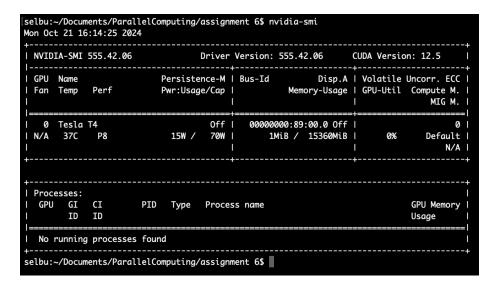


Figure 2: Output of the nvidia-smi command.

by many threads, each thread executing the same kernel, but on **different data**. The threads are organised in **blocks**, and the blocks are organised in a **grid**. Each thread has a unique identifier that can be used to access a different data element. Although all threads execute the same **kernel**, they may follow different execution paths depending on the data they process.