

$$\max_{\substack{\alpha_c, d_{r_j}, u_c^{(t)}, u_r^{(t)} \\ p \times 1 \quad p \times 1 \quad m \times p \quad m \times p}} \sum_{j=1}^p \alpha_{r_j} + \sum_{t=1}^T \sum_{j=1}^p \sum_{i=1}^m w_{ij} u_{rij}^{(t)}$$

Weights for control

Subject to

$$0 \leq \sum_{j=1}^p u_{rij}^{(t)} \leq (u_j^{\max} + u_j^{\min})/2, \quad \forall i=1, \dots, m, \quad \forall t=1, \dots, T$$

$$0 \leq u_{rij}^{(t)} \leq (u_j^{\max} + u_j^{\min})/2, \quad u_j^{\min} + u_{rij}^{(t)} \leq u_{cij}^{(t)} \leq u_j^{\max} - u_{rij}^{(t)}$$

$$-1 + d_{r_j} \leq \alpha_{c_j} \leq 1 - d_{r_j}, \quad \forall j=1, \dots, p$$

$$0 < \varepsilon \leq d_{r_j} \leq 1$$

// scaling is within constraint set

$$(c^{(0)} + G^{(0)} \alpha_c) + |G^{(0)}| \cdot d_r \leq X_{IS}^{\max} \leftarrow \text{initial set}$$

$$(c^{(0)} + G^{(0)} \alpha_c) - |G^{(0)}| \cdot d_r \geq X_{IS}^{\min}$$

// for  $t=1, \dots, T$

$$A^t (c^{(0)} + G^{(0)} \alpha_c) + \sum_{j=1}^p \sum_{s=1}^t A^{s-1} B u_{cj}^{(t-s+1)} +$$

$$+ \sum_{j=1}^p |A^t d_{r_j} g_j^{(0)} + \sum_{s=1}^t A^{s-1} B u_{rj}^{(t-s+1)}| \leq X_{CS}^{\max} \leftarrow \text{constraint set}$$

$$A^t (c^{(0)} + G^{(0)} \alpha_c) + \sum_{j=1}^p \sum_{s=1}^t A^{s-1} B u_{cj}^{(t-s+1)} - \sum_{j=1}^p |A^t d_{r_j} g_j^{(0)} + \sum_{s=1}^t A^{s-1} B u_{rj}^{(t-s+1)}| \geq X_{CS}^{\min}$$

There is only a single scaling at time  $t=0$ ,  
represented by 2 vectors:

$\mathcal{L}_c$  and  $\mathcal{L}_r$ , where  $p$  is the number  
( $p \times 1$ ) ( $p \times 1$ ) of generators

Reach set updating:

$$R^{(t)} = \left( A^{(t)} \left( C^{(0)} + G^{(0)} \cdot \mathcal{L}_c \right) + \sum_{j=1}^p \sum_{s=1}^{t-1} A \cdot B \cdot y_{c,j}^{(t-s+1)} \right)$$

$n \times n$     $n \times 1$     $n \times p$     $p \times 1$     $p$     $t$     $s-1$     $(t-s+1)$   
 $m \times 1$

Center      Sum over all generator input element centers

$$A^{(t)} \cdot \mathcal{L}_{r_1} \cdot g_1^{(0)} + \sum_{s=1}^t A^{s-1} \cdot B \cdot y_{r_1}^{(t-s+1)}, \dots,$$

$$A^{(t)} \cdot \mathcal{L}_{r_p} \cdot g_p^{(0)} + \sum_{s=1}^t A^{s-1} \cdot B \cdot y_{r_p}^{(t-s+1)}$$

$y_c^{(t)}$  and  $y_r^{(t)}$  are  $m \times p$ . As the scaling is done  
beforehand (at  $t=0$ ), we don't need to worry  
about nonlinearity.