

# Exam project: Enumerate all neighborly 4-polytopes on 7 vertices

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## 1 Introduction

Our goal is to solve the following problem:

**Problem 1.** Enumerate all simplicial neighbourly 4-polytopes on 8 vertices up to combinatorial equivalence.

The idea of how we will solve this problem is the following. We start from all possible affine Gale diagrams of a 4-polytope on 8 vertices. These are point configurations of 8 points in the plane, each with an assigned positive or negative sign. We check which of these affine Gale diagrams correspond to neighbourly, simplicial polytopes, and consider only these configurations. Then, check whether they correspond to the same polytope (i.e. to a combinatorially equivalent polytope) and once we have all different Gale diagrams, retrieve the polytope they correspond to.

## 2 Results

There are 3 neighbourly simplicial 4-polytopes on 8 vertices up to combinatorial equivalent. These can be represented by (?)

### 3 Discussion

Since this is a studied problem (see [2]), we know that the 3 different simplicial neighbourly 4-polytopes on 8 vertices are  $C_4(8)$ ,  $N_8$  and  $N_8^*$ , where  $C_4(8)$  is the cyclic polytope on 8 vertices, and an explicit description of  $N_8$  and  $N_8^*$  can be found in page 125 of [1].

## 4 Methods

### 4.1 Program structure

### 4.2 Program details

The first thing the code does is find a finite number of points in the plane where our points of the different Gale diagrams will be. To do this, we use the fact that not the exact the location of the points is important, but the position of each point with respect to the lines defined by the other points. Therefore we can fix two of our points, 1 and 2, to be the lowermost, and choose the lines through these two points on which the other points will lie. To get more or less reasonable coordinates, we chose to fix the points  $(0,0)$  and  $(2,0)$ , and the lines through them and  $(1,i)$ , with  $i = 1, \dots, 6$ . Then, the points that we will consider to be on the Gale diagram are the intersections through the lines from 1 and from 2.

`enumerate_all_gale` uses backtracking to find all possible combinations of points on the grid of intersections previously defined. To do this, it takes into account that for a polytope to be simplicial, no three points can be aligned, so when it chooses a point to lie in a line through 1, it of course lies in a line through 2 and automatically bans any other point to go through the same line through 2. This procedure produces  $6! = 720$  configurations of points in the plane. In addition, it has to give a sign to each point. The first sign is prescribed (since configurations with all signs interchanged are equivalent, we can prescribe one sign). Furthermore, only configurations with 3 or 4 negative signs are considered, since other configurations will not result in a neighbourly polytope. This gives for each of the Gale diagrams found  $\binom{7}{5} + \binom{7}{4} = 91$  possible combinations of signs, so in total our program runs initially through  $720 \cdot 91 = 65520$  possible Gale diagrams.

Since the computation of checking if a Gale diagram is neighbourly is a bit expensive, we try to reduce the number of Gale diagrams by eliminating the ones that are not simplicial. `isSimplicial` checks that in every set of four points of the diagram, no three points are aligned.

`is_neighborly` loops through every pair of two points, and for each choice of pair, it removes the pair from the Gale diagram and then checks if the convex hulls of the negative and positive points intersect.

`makeVertexFacetStructure` gives the vertex-facet lattice obtained from the Gale di-

agram, by creating a vertex  $i$  for every point  $i$  ( $i=0, \dots, 7$ ) and making a vertex for every facet, so we have 28 vertices. The result is returned in an `igraph_t` object, from the `igraph` library<sup>1</sup>.

To check whether two Gale diagrams are isomorphic, we use the `in_igraph` built in `graph` isomorphism algorithm (uses BLISS).

`gale_to_polytope` takes an affine Gale diagram that we know corresponds to a simplicial and neighbourly polytope and returns projective coordinates for the vertices of the polytope. The procedure follows the reverse idea of how the vectors of the Gale transform are obtained. We initially have a matrix  $B$  with the Gale points in the plane, and a sign assigned to each of the points. We project from the origin in  $\mathbb{R}^3$  all positive points to the plane  $Z = 1$ , and all negative points to the plane  $Z = -1$ . Once we have this, we need the vector configuration to be balanced. Therefore we scale the vectors. We need coefficients  $\lambda_i$  that multiply each vector  $v_i$  and such that then all rows of the matrix  $B$  sum to zero. To do this we can fix 5 of the  $\lambda_i$  since any other set of three points will have full rank because we are taking Gale diagrams where no three points are aligned, and then we only need to solve a  $3 \times 3$  linear system of equations. After the rescaling of the vectors of the Gale transform, we can get the kernel of their matrix and the vector of all ones is in its affine span, so we either move it or add it to the last row (which we can do by Steinitz Exchange Lemma) and we get 8 points of  $\mathbb{R}^4$  in projective coordinates that are the vertices of a polytope to which the Gale diagram corresponds to.

`enumerate_all_polytope` (?)

## 5 Proof

## References

- [1] Branko Grünbaum, Convex polytopes. *Graduate Texts in Mathematics* vol 221, (2003).
- [2] B. Grünbaum, V.P. Sreedharan, An enumeration of simplicial 4-polytopes with 8 vertices. *Journal of Combinatorial Theory* 2, 437-465, (1967).

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<sup>1</sup><http://igraph.org/c/>