

**TTT4120 Digital Signal Processing  
Fall 2021****Lecture: Correlation and Energy Spectral Density**

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**Lecture in course book\***

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- Proakis, Manolakis Digital Signal Processing, 4<sup>th</sup> Ed.
  - 2.6.1 Crosscorrelation and autocorrelation sequences
  - 2.6.2 Properties of crosscorrelation and autocorrelation...
  - 2.6.4 Input-output correlation sequences
  - 4.2.5 Energy density spectrum of aperiodic signals
  - 5.3.1 Input-output correlation functions and spectra

\*Level of detail is defined by lectures and problem sets

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## Contents and learning outcomes

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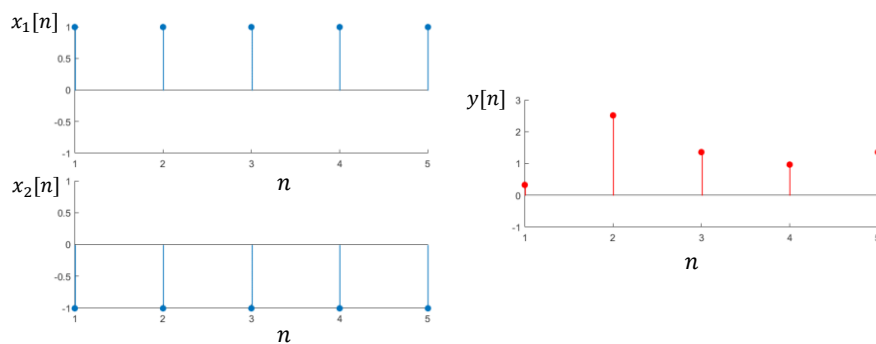
- Cross- and autocorrelation sequences
- Properties of cross- and autocorrelation sequences
- Linear time-invariant systems
- Energy spectral density

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## Introduction

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- Which of the sequences  $x_1[n]$  and  $x_2[n]$  resembles  $y[n]$ ?
- How to measure similarity between signal sequences

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## Introduction...

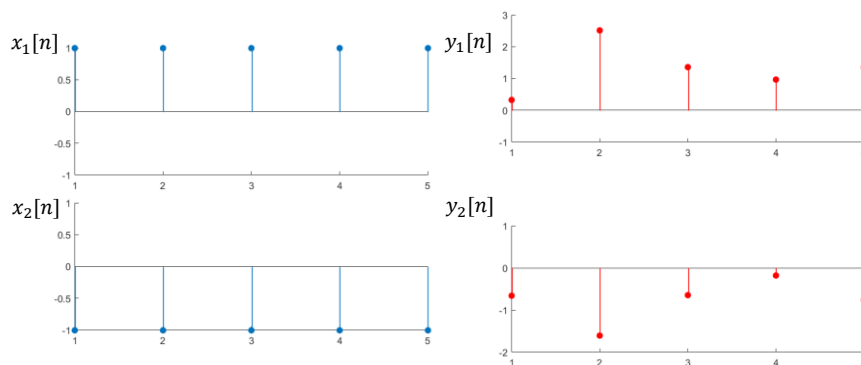
- Signals transmitted over some medium, e.g., wireless channels, experience delays, echoes, and noise
  - Difficult to recognize/or detect the signals at the receiving end
- Suppose that  $x_1[n]$  or  $x_2[n]$  is transmitted and  $y[n]$  is received
  - If  $y[n]$  is more similar to  $x_1[n]$  than to  $x_2[n]$ , we decide that  $x_1[n]$  was transmitted
  - If  $y[n]$  is more similar to  $x_2[n]$  than to  $x_1[n]$ , we decide that  $x_2[n]$  was transmitted
- Correlation is a measure of similarity

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## Introduction...

- Digital communication example:  $y_i[n] = x_i[n] + w[n]$



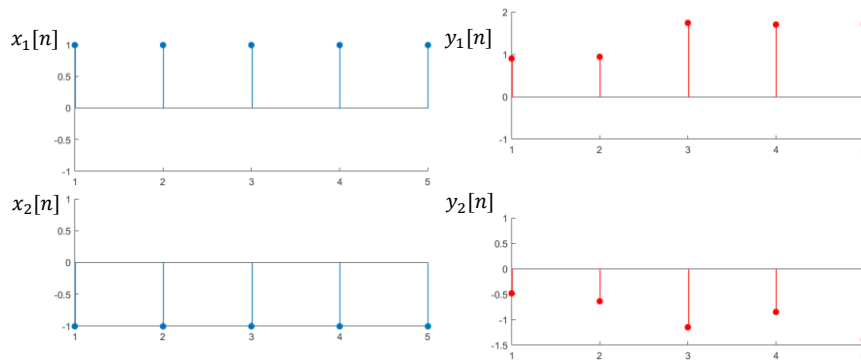
- Noise can make received signal fluctuate significantly

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## Introduction...

- Digital communication example:  $y_i[n] = x_i[n] + w[n]$



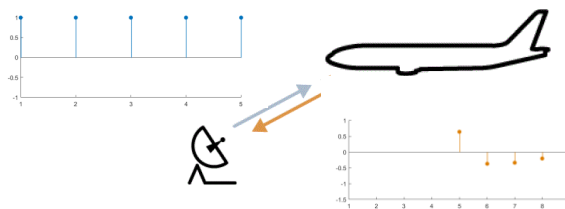
- Noise can make received signal fluctuate significantly

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## Introduction...

- Radar example:  $y[n] = \alpha x[n - D] + w[n]$ , find  $D$ ?



- Here we need a similarity measure that gives a maximum for  $D$ , considering all possible delays

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## Crosscorrelation and autocorrelation

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- **Crosscorrelation** of real-valued sequences  $x[n]$  and  $y[n]$

$$\begin{aligned} r_{xy}[l] &= \sum_{n=-\infty}^{\infty} x[n]y[n-l] \\ &= \sum_{n=-\infty}^{\infty} x[n+l]y[n], l = \pm 1, \pm 2, \dots \end{aligned}$$

- Measure of similarity between signals  $x[n]$  and  $y[n]$
- Reverse role  $r_{yx}[l] \neq r_{xy}[l]$

$$r_{yx}[l] = \sum_{n=-\infty}^{\infty} y[n]x[n-l] = r_{xy}[-l]$$

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## Crosscorrelation and autocorrelation...

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- Similarity to convolution of  $x[n]$  and  $y[n]$

$$\begin{aligned} x[l] * y[l] &= \sum_{k=-\infty}^{\infty} x[k]y[l-k] \\ r_{xy}[l] &= \sum_{k=-\infty}^{\infty} x[k]y[k-l] = x[l] * y[-l] \end{aligned}$$

- Relation can be exploited for efficient computation
- **Autocorrelation sequence** (self-similarity),  $y[n] = x[n]$

$$\begin{aligned} r_{xx}[l] &= \sum_{n=-\infty}^{\infty} x[n]x[n-l] \\ &= \sum_{n=-\infty}^{\infty} x[n+l]x[n] \end{aligned}$$

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## Crosscorrelation and autocorrelation...

- Finite causal sequences  $x[n] = y[n] = 0, n < 0, n \geq N$

$$x[n] = \{x[0], x[1], x[2], \dots, x[N-1]\}$$

$$y[n] = \{y[0], y[1], y[2], \dots, y[N-1]\}$$

$$r_{xy}[l] = \sum_{n=-\infty}^{\infty} x[n]y[n-l]$$

- Try a couple of values of  $l$  and search for pattern  $\Rightarrow$

$$r_{xy}[l] = \sum_{n=l}^{N-1} x[n]y[n-l], l \geq 0$$

$$r_{xy}[l] = \sum_{n=0}^{N-|l|-1} x[n]y[n-l], l < 0$$

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## Properties of autocorrelation

- Energy of sequences  $x[n]$

$$E_x = \sum_{n=-\infty}^{\infty} x^2[n] = r_x[0] \geq 0$$

- Autocorrelation is maximum at lag  $l=0$

$$|r_{xx}[l]| \leq r_{xx}[0] = E_x$$

- Autocorrelation is even  $\Rightarrow$  only compute values for  $l \geq 0$

$$r_{xy}[l] = r_{xy}[-l] \Rightarrow r_{xx}[l] = r_{xx}[-l]$$

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## Properties of autocorrelation...

- Normalized versions

$$\varrho_{xx}[l] = \frac{r_{xx}[l]}{r_{xx}[0]} \Rightarrow |\varrho_{xx}[l]| \leq 1$$

$$\varrho_{xy}[l] = \frac{r_{xy}[l]}{\sqrt{r_{xx}[0]r_{yy}[0]}} \Rightarrow |\varrho_{xy}[l]| \leq 1$$

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## Properties cross- and autocorrelation...

- Example: Compute the autocorrelation of  $x[n] = \alpha^n u[n]$
- Solution:

$$\begin{aligned} r_{xx}[l] &= \sum_{n=-\infty}^{\infty} x[n+l]x[n] \\ &= \sum_{n=-\infty}^{\infty} \alpha^{n+l} u[n+l] \alpha^n u[n] \\ &= \alpha^l \sum_{n=0}^{\infty} \alpha^{2n} = \frac{\alpha^l}{1-\alpha^2}, l \geq 0 \end{aligned}$$

Since  $r_{xx}[-l] = r_{xx}[l]$ , we get the final expression

$$r_{xx}[l] = \frac{\alpha^{|l|}}{1-\alpha^2}, \forall l$$

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## Example 1

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- Let  $y[n] = Ax[n - D]$ . Show that  $D = \arg \max_l |r_{yx}[l]|$

- Solution:

$$\begin{aligned} r_{yx}[l] &= \sum_{n=-\infty}^{\infty} y[n]x[n - l] = \sum_{n=-\infty}^{\infty} y[n + l]x[n] \\ &= \sum_{n=-\infty}^{\infty} Ax[n + l - D]x[n] = Ar_{xx}[D - l] \end{aligned}$$

From properties of autocorrelation sequences, we know

$$|r_{xy}[l]| = |A||r_{xx}[D - l]| \leq |A||r_{xx}[0]|, \forall l$$

$$\therefore |r_{xy}[l]| \text{ reach its maximum for } l = D$$

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## Example 2

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- Let  $y[n] = x[n] + Rx[n - D]$ , i.e., received signal contains an echo. How to estimate  $R, D$  using the autocorrelation of  $y[n]$ ?

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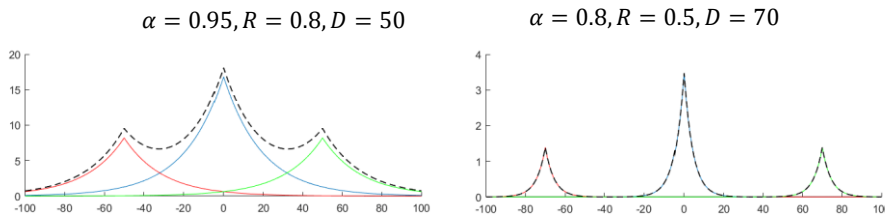
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### Example 3

- Let  $x[n] = \alpha^n u[n]$  and  $y[n] = x[n] + Rx[n - D]$

$$\Rightarrow r_{yy}[l] = (1 + R^2)r_{xx}[l] + Rr_{xx}[l + D] + Rr_{xx}[l - D]$$



- Shape of  $r_{yy}[l]$  depends on  $R, D$

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### Example 3...

- Details on how to obtain  $r_{yy}[l]$  and  $R$  in previous slide
- From Slide 14:  $r_{xx}[l] = \frac{\alpha^{|l|}}{1 - \alpha^2}$
- $$\begin{aligned}
 r_{yy}[l] &= \sum_{n=-\infty}^{\infty} y[n+l]y[n] \\
 &= \sum_{n=-\infty}^{\infty} (x[n+l] + Rx[n+l-D])(x[n] + Rx[n-D]) \\
 &= \sum_{n=-\infty}^{\infty} x[n+l]x[n] + R \sum_{n=-\infty}^{\infty} x[n+l-D]x[n] \\
 &\quad + R \sum_{n=-\infty}^{\infty} x[n+l]x[n-D] + R^2 \sum_{n=-\infty}^{\infty} x[n-D]x[n+l-D] \\
 &= r_{xx}[l] + Rr_{xx}[l-D] + Rr_{xx}[l+D] + R^2r_{xx}[l]
 \end{aligned}$$
- Look at the following values (corresponding to the peaks in figure)
 
$$r_{yy}[0] = (1 + R^2)r_{xx}[0] + Rr_{xx}[-D] + Rr_{xx}[D] \approx (1 + R^2)r_{xx}[0]$$

$$r_{yy}[D] = (1 + R^2)r_{xx}[D] + Rr_{xx}[0] + Rr_{xx}[2D] \approx Rr_{xx}[0]$$
- Given values  $r_{yy}[0]$  and  $r_{yy}[D]$ , we can solve for  $R$

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## Example 2...

### Matlab

```
l = (-100:100);
a=0.8; % decay rate
R = 0.5; % echo strength
D = 70; % delay of echo

rxx_l = a.^abs(l) / (1-a^2);
rxx_lpD = a.^abs(l+D) / (1-a^2);
rxx_lmD = a.^abs(l-D) / (1-a^2);
ryy = (1+R^2)*rxx_l+R*rxx_lpD+R*rxx_lmD;

figure
plot(l, (1+R^2)*rxx_l); hold on
plot(l, R*rxx_lpD, 'r');
plot(l, R*rxx_lmD, 'g');
plot(l, ryy, 'k--', 'LineWidth', 1)
```

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## Energy spectral density

- Quantity  $S_{xx}(\omega) \geq 0$  is the **energy density spectrum** of  $x[n]$

$$r_{xx}[l] = x[l] * x[-l] \xleftrightarrow{\mathcal{F}} S_{xx}(\omega) = X(\omega)X^*(\omega) = |X(\omega)|^2$$

- Energy of complex-valued sequence  $x[n]$

$$\begin{aligned} E_x &= r_{xx}[0] = \sum_{n=-\infty}^{\infty} |x[n]|^2 \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} S_{xx}(\omega) d\omega = \frac{1}{2\pi} \int_{-\pi}^{\pi} |X(\omega)|^2 d\omega \end{aligned}$$

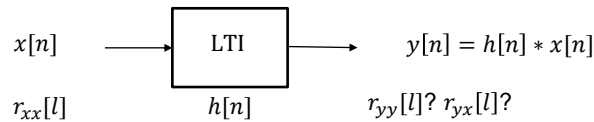
- Quantity  $S_{xy}(\omega)$  is the **cross-energy density spectrum**

$$r_{xy}[l] = x[l] * y[-l] \xleftrightarrow{\mathcal{F}} S_{xy}(\omega) = X(\omega)Y^*(\omega)$$

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## Input-output correlations



- Input-output correlations

$$r_{yx}[l] = h[l] * r_{xx}[l]$$

$$r_{yy}[l] = r_{hh}[l] * r_{xx}[l]$$

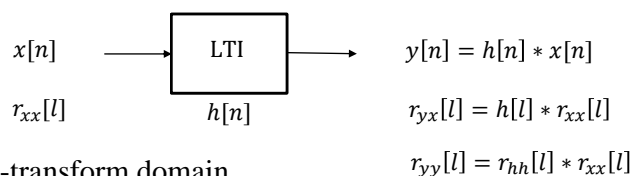
$$E_y = r_{yy}[0] = \sum_{k=-\infty}^{\infty} r_{hh}[k] r_{xx}[k]$$

- Crosscorrelation between  $x[n]$  and  $y[n]$  can be seen as the output signal of an LTI system when input signal is  $r_{xx}[n]$

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## Input-output correlations and energy spectrum



- In z-transform domain

$$h[l] * h[-l] \xleftrightarrow{Z} H(z)H(z^{-1})$$

$$r_{yx}[l] = h[l] * r_{xx}[l] \xleftrightarrow{Z} H(z)S_{xx}(z)$$

$$r_{yy}[l] = r_{hh}[l] * r_{xx}[l] \xleftrightarrow{Z} H(z)H(z^{-1})S_{xx}(z)$$

- Output- and cross-energy density spectra

$$S_{yy}(\omega) = |H(\omega)|^2 S_{xx}(\omega) = |H(\omega)|^2 |X(\omega)|^2$$

$$S_{yx}(\omega) = H(\omega) S_{xx}(\omega)$$

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## Input-output correlations and energy ...

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- We have the following relation Fourier transform pair

$$r_{yy}[l] = \frac{1}{2\pi} \int_{-\pi}^{\pi} S_{yy}(\omega) e^{j\omega l} d\omega$$

- Energy of output sequence (of an LTI system)

$$r_{yy}[0] = \frac{1}{2\pi} \int_{-\pi}^{\pi} S_{yy}(\omega) d\omega = \frac{1}{2\pi} \int_{-\pi}^{\pi} |H(\omega)|^2 S_{xx}(\omega) d\omega$$

- Determine impulse response by signal with flat spectrum

$$h[n] = \frac{1}{S_{xx}} r_{yx}[n]$$

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## Summary

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Today:

- Crosscorrelation and autocorrelation sequences
- Linear time invariant systems
- Energy spectrum

Next:

- Inverse z-transform

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## Example 2 (modified)

- Let  $y[n] = x[n] + Rx[n - D]$  be an audio signal corrupted by an echo. We would like to estimate  $R, D$  using the autocorrelation of  $y[n]$ , and design a filter to remove the echo.

$$\begin{array}{ccc}
 x[n] & \xrightarrow{\quad} & \boxed{h[n]} \xrightarrow{\quad} y[n] = -\sum_{k=1}^N a_k y[n - k] + \sum_{k=0}^M b_k x[n - k] \\
 X(z) & & Y(z) = H(z)X(z)
 \end{array}$$

Matlab files on BB:  
Correlation.m

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## Example 2 (modified)...

- Model the problem using an LTI system

$$\begin{array}{ccc}
 x[n] & \xrightarrow{\quad} & \boxed{h[n]} \xrightarrow{\quad} y[n] = x[n] + Rx[n - D] \\
 X(z) & & Y(z) = H(z)X(z) = (1 + Rz^{-D})X(z)
 \end{array}$$

- Estimate  $R$  and  $D$  using autocorrelation sequence  $r_{yy}[n]$
- Find the inverse system  $H_I(z)$  such that (see previous lecture)

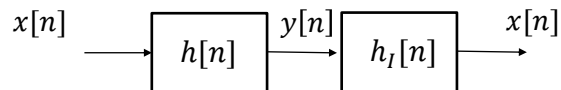
$$\begin{aligned}
 h[n] * h_I[n] &= \delta[n] \xleftrightarrow{Z} H(z)H_I(z) = 1 \\
 \Rightarrow H_I(z) &= \frac{1}{1 + Rz^{-D}}
 \end{aligned}$$

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## Example 2 (modified)...

- If  $R < 1$ ,  $H(z)$  is minimum phase and so is  $H_I(z)$
- We can find a causal and stable filter  $h_I[n]$



- We get  $D$  from inspecting the peaks of  $r_{yy}[l]$
- We obtain an estimate  $R$  from the relation

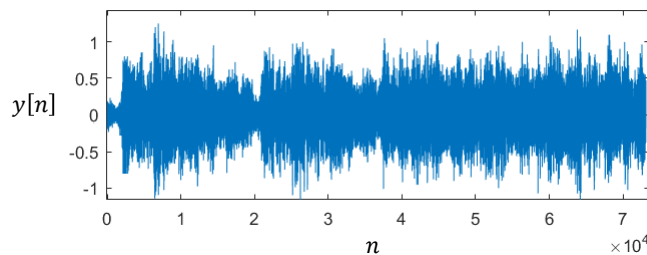
$$\frac{r_{yy}[0]}{r_{yy}[D]} = \frac{1+R^2}{R}$$

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## Example 2 (modified)...

- Plot of received signal  $y[n]$  ( $R = 0.98$ ,  $D = 4196$ ):

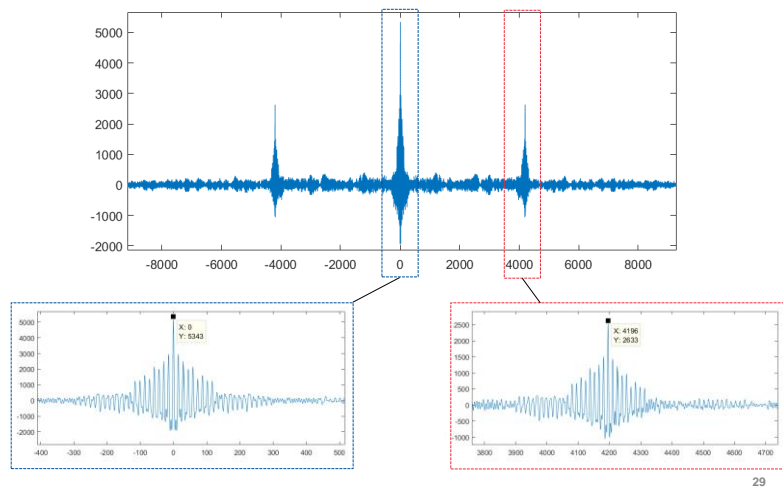


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## Example 2 (modified)...

- Autocorrelation of  $y[n]$ :



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## Example 2 (modified)...

- From figure we get:

$$D = 4196, \quad \frac{r_{yy}[0]}{r_{yy}[D]} = \frac{1+R^2}{R} = \frac{5343}{2633} \Rightarrow R = 0.8430$$

- Delay is correct but parameter estimate of  $R$  is not exact. Listen to the equalized signal and judge whether the echo is removed (or suppressed)

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