

TET4100 Kretsanalyse – Løsning

Institutt: Elkraftteknikk

Dato: 2012.08.15

Øving 4

14) Effekt 4.A

14.1) $\phi_v - \phi_i = \phi > 0 \rightarrow \text{Induktiv}$

14.2) $pf = \cos(\phi)$

14.3) Spenningsviser: $\hat{V}_k = \hat{V}_k \angle \phi_v$

Strømviser: $\hat{I}_k = \hat{I}_k \angle \phi_i$

Kompleks effekt: $S_k = \frac{\hat{V}_k \cdot \hat{I}_k^*}{2}$

Tilsynelatende effekt: $|S_k| = \frac{\hat{V}_k \cdot \hat{I}_k}{2}$

Aktiv effekt: $P_k = \Re(S_k)$ or $P_k = |S_k| \cdot \cos(\phi)$ forbrukt

Reaktiv effekt: $Q_k = \Im(S_k)$ or $Q_k = |S_k| \cdot \sin(\phi)$ forbrukt

14.4) kompleks effekt: $S'_k = P'_k + jQ'_k$

Tilsynelatende effekt: $|S'_k|$

14.5) $\hat{I}'_k = \frac{2|S'_k|}{\hat{V}_k}$ $\phi'_i = \phi_v - \tan^{-1} \frac{Q'_k}{P'_k}$

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15) Effekt 4.B

$$15.1) \quad Z_T = R_T + j\omega_f L_T$$

$$Z_L = R_L + j\omega_f L_L$$

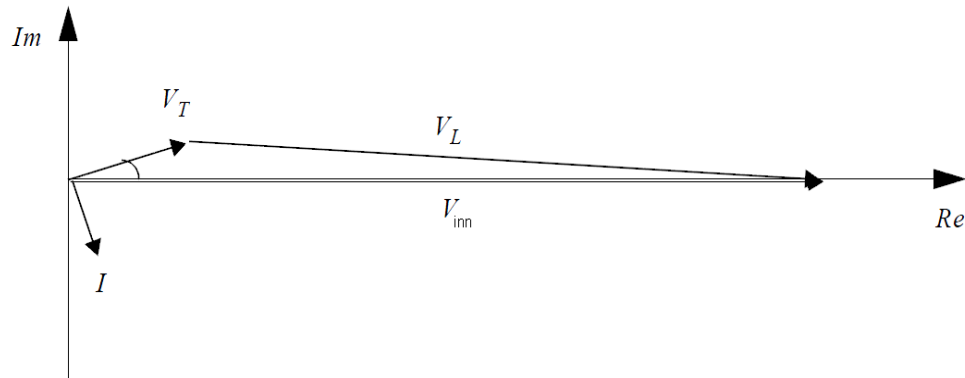
$$Z = Z_T + Z_L$$

$$I = \frac{V_{inn}}{Z} = \frac{V_{inn}}{|Z|} \angle \phi_v - \phi_Z = I \angle \phi_i$$

$$i(t) = I \cdot \sqrt{2} \cdot \cos(\omega t + \phi_i)$$

$$15.2) \quad V_T = I \cdot Z_T = I \cdot |Z_T| \angle \phi_i + \phi_{Z_T}$$

$$V_L = I \cdot Z_L = I \cdot |Z_L| \angle \phi_i + \phi_{Z_L}$$



$$15.3) \quad \phi_L = \phi_{v,L} - \phi_i$$

$$|S_L| = V_L \cdot I$$

$$P_L = |S_L| \cdot \cos(\phi_L)$$

$$Q_L = |S_L| \cdot \sin(\phi_L)$$

$$15.4) \quad \phi = \phi_v - \phi_i$$

$$pf = \cos(\phi)$$

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16) Effekt 4.C

$$16.1) \quad |S| = \sqrt{P^2 + Q^2}$$

$$\cos(\phi) = \frac{P}{|S|}$$

$$\phi = \cos^{-1}\left(\frac{P}{|S|}\right)$$

$$\phi = \phi_v - \phi_i$$

$$\phi_v = \phi + \phi_i$$

$$|S| = I_{eff} \cdot V_{g,eff}$$

$$V_{g,eff} = \frac{|S|}{I_{eff}}$$

$$V_g = V_{g,eff} \angle \phi_v$$

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17) Effekt 4.D

$$17.1) \quad X_{L_1} = \omega_f L_1 \quad X_{C_1} = -\frac{1}{\omega_f C_1} \quad X_{L_2} = \omega_f L_2 \quad X_{C_2} = -\frac{1}{\omega_f C_2}$$

$$Z_{par} = (R_1 + j X_{C_1}) || (R_2 + j (X_{L_2} + X_{C_2}))$$

$$R_a = R_1 \quad X_a = X_{C_1} \quad R_b = R_2 \quad X_b = X_{L_2} + X_{C_2}$$

$$R_{par} = \frac{R_a^2 R_b + R_a R_b^2 + R_a X_b^2 + X_a^2 R_b}{(R_a + R_b)^2 + (X_a + X_b)^2}$$

$$X_{par} = \frac{R_a^2 X_b + X_a R_b^2 + X_a X_b^2 + X_a^2 X_b}{(R_a + R_b)^2 + (X_a + X_b)^2}$$

$$Z_{par} = R_{par} + j X_{par}$$

$$Z = R_{par} + j (X_{par} + X_{L_1})$$

$$R = R_{par} \quad X = X_{par} + X_{L_1}$$

$$Z = R + j X$$

$$Z = \sqrt{R^2 + X^2} \angle \text{atan}\left(\frac{X}{R}\right) = |Z| \angle \phi_Z$$

$$17.2) \quad \mathbf{V}_s = \frac{\hat{V}_s \angle 0}{\sqrt{2}}$$

$$\mathbf{I} = \frac{\mathbf{V}_s}{\mathbf{Z}} = \frac{V_s}{|Z|} \angle \phi_v - \phi_Z = I \angle \phi_i$$

$$\hat{I} = \sqrt{2} I$$

$$i(t) = \hat{I} \cos(\omega_f t + \phi_i)$$

$$17.3) \quad \phi = \phi_v - \phi_i$$

$$|S| = V_s \cdot I$$

$$P = |S| \cdot \cos(\phi)$$

$$Q = |S| \cdot \sin(\phi)$$

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18) Effekt 4.E

$$18.1) \quad V_g = \frac{\hat{V}_g}{\sqrt{2}}$$

$$X_L = \omega_f L \quad X_C = -\frac{1}{\omega_f C}$$

$$Z = R + j(X_L + X_C) = |Z| \angle \phi$$

$$I = \frac{V_g}{|Z|}$$

$$P_{Last} = I^2 \cdot R$$

$$Q_{Last} = I^2 \cdot X_C$$

$$|S_{Last}| = \sqrt{P_L^2 + Q_L^2}$$

$$18.2) \quad P_L = 0$$

$$Q_L = I^2 X_L$$

$$18.3) \quad I = \frac{V_g}{Z} = I \angle -\phi$$

$$S_g = -V_g I^* = V_g I \angle \pi + \phi$$

$$P_g = \Re(S_g)$$

$$Q_g = \Im(S_g)$$

$$18.4) \quad P_{Last} + P_L + P_g = 0$$

$$Q_{Last} + Q_L + Q_g = 0$$

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19) Effekt 4.F

$$19.1) \quad Z_{Li} = R_{Li} + j X_{Li}$$

$$Z_{La} = R_{La,1} + \left((R_{La,2} + j X_{La,1}) \parallel j X_{La,2} \right)$$

$$Z_{La} = R_{La,1} + \frac{R_{La,2} X_{La,2}^2}{R_{La,2}^2 + (X_{La,1} + X_{La,2})^2} + j \frac{R_{La,2}^2 X_{La,2} + X_{La,1} X_{La,2}^2 + X_{La,1}^2 X_{La,2}}{R_{La,2}^2 + (X_{La,1} + X_{La,2})^2}$$

$$R_{La} = R_{La,1} + \frac{R_{La,2} X_{La,2}^2}{R_{La,2}^2 + (X_{La,1} + X_{La,2})^2}$$

$$X_{La} = \frac{R_{La,2}^2 X_{La,2} + X_{La,1} X_{La,2}^2 + X_{La,1}^2 X_{La,2}}{R_{La,2}^2 + (X_{La,1} + X_{La,2})^2}$$

$$Z_{La} = R_{La} + j X_{La}$$

$$Z_{tot} = Z_{Li} + Z_{La} = R_{Li} + R_{La} + j (X_{Li} + X_{La})$$

$$I_1 = \frac{V_s}{Z_{tot}}$$

Spenningsdeler: $V_{La} = V_s \cdot \frac{Z_{La}}{Z_{tot}}$

$$19.2) \quad S_{La} = V_{La} \cdot I_1^*$$

$$P_{La} = \Re(S_{La})$$

$$Q_{La} = \Im(S_{La})$$

$$pf_{La} = \frac{P_{La}}{|S_{La}|}$$

$$19.3) \quad I_1 = |I_1|$$

$$P_{Li} = R_{Li} \cdot I_1^2$$

$$Q_{Li} = X_{Li} \cdot I_1^2$$

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$$19.4) \quad Z_{La, Komp} = Z_{La} \parallel Z_C = (R_{La} + j X_{La}) \parallel j X_C$$

$$Z_{La, Komp} = \frac{X_C^2 R_{La}}{R_{La}^2 + (X_{La} + X_C)^2} + j \frac{(R_{La}^2 X_C + X_{La}^2 X_C + X_C^2 X_{La})}{R_{La}^2 + (X_{La} + X_C)^2}$$

$$pf_{La, Komp} = 1 \rightarrow Z_{La, Komp} \text{ må være reell}$$

$$R_{La}^2 X_C + X_{La}^2 X_C + X_C^2 X_{La} = 0$$

$$X_C = -\frac{X_{La}^2 + R_{La}^2}{X_{La}} \quad (\text{Teoretisk også } X_C = 0)$$

$$C = -\frac{1}{\omega_f X_C}$$

$$19.5) \quad Z_{La, Komp} = \frac{X_C^2 R_{La}}{R_{La}^2 + (X_{La} + X_C)^2}$$

$$Z_{tot, Komp} = Z_{Li} + Z_{La, Komp}$$

$$I_{1, Komp} = \frac{V_s}{|Z_{tot, Komp}|}$$

$$P_{Li, Komp} = R_{Li} \cdot I_{1, Komp}^2$$

$$Q_{Li, Komp} = X_{Li} \cdot I_{1, Komp}^2$$