

2020-09-28

PRML Ch. 7

- sparse Kernel methods
- maximum margin classifier
- support vector machines
 - linearly separable data
 - overlapping data

Maximum margin classifier

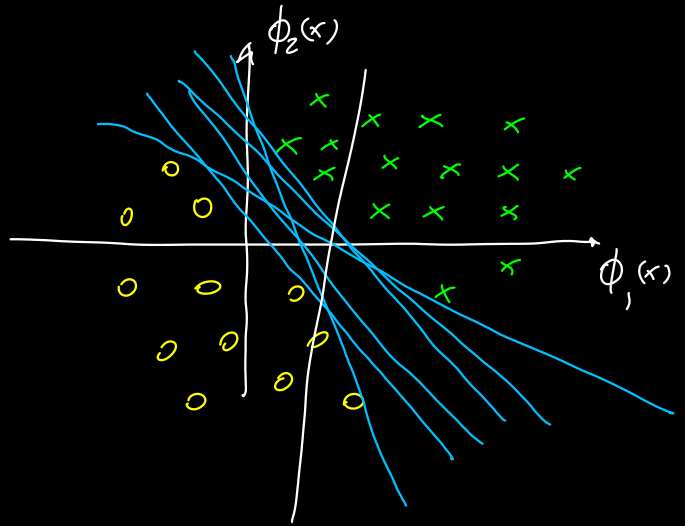
two-class problem

$$y(x) = w^T \phi(x) + b$$

training data

$$\{x_1, \dots, x_N; x_n \in \mathbb{R}^D\}$$

$$\{t_1, \dots, t_N; t_n \in \{-1, +1\}\}$$

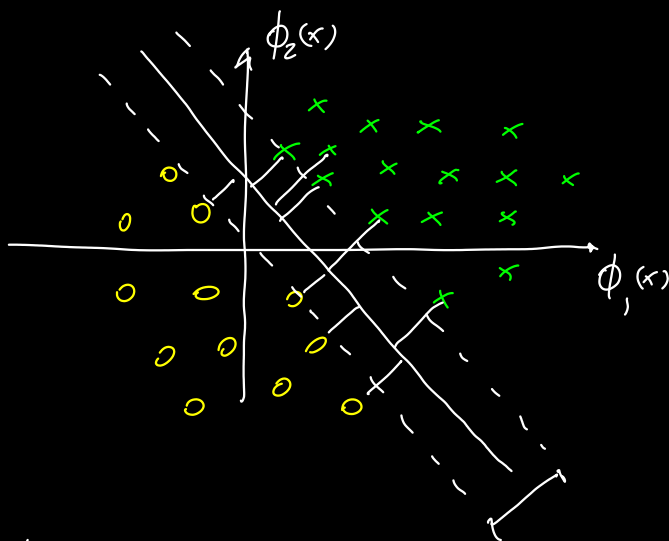


$$\left. \begin{array}{l} \exists w, b \text{ s.t. } y(x_n) > 0 \Leftrightarrow t_n = +1 \\ y(x_n) < 0 \Leftrightarrow t_n = -1 \end{array} \right\} \Rightarrow y(x_n) \cdot t_n > 0 \quad \forall n$$

Goal: minimize generalization error

We only have the training data (do not know the underlying distribution)

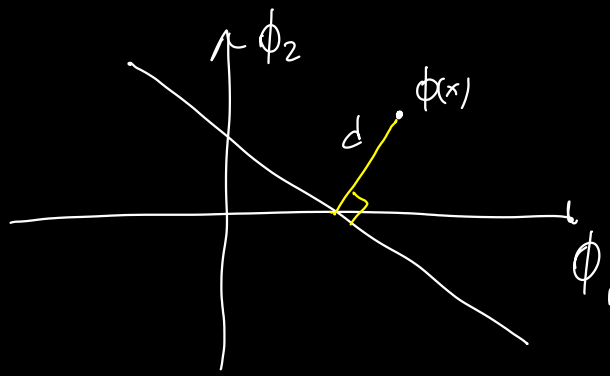
Heuristic solution: maximize margin



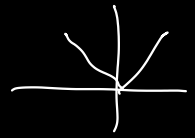
w, b

Recall:

- if x is on decision boundary $\Rightarrow y(x) = 0$



$$d = \frac{|y(x)|}{\|w\|}$$



- we are only interested in no error $\Rightarrow t_n y(x_n) > 0$

$$d = \frac{t_n y(x_n)}{\|w\|} = \frac{t_n (w^T \phi(x_n) + b)}{\|w\|} \quad \forall n \in [1, N]$$

Optimization:

$$\arg \max_{w, b} \left\{ \frac{1}{\|w\|} \min_n [t_n (w^T \phi(x_n) + b)] \right\} \quad \begin{array}{l} \text{hard to} \\ \text{solve} \\ \text{directly} \end{array}$$

↑
independent of n

$$w, b \rightarrow K w, K b$$

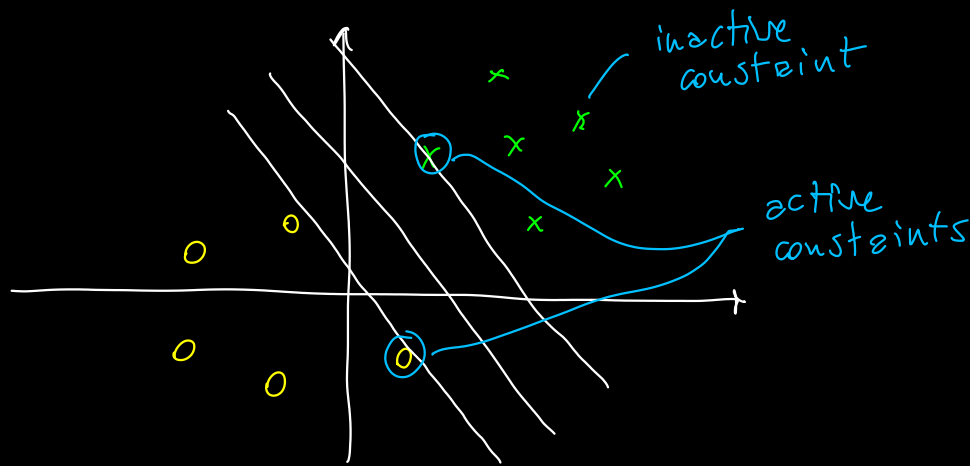
$$\frac{t_n (\cancel{K} w^T \phi(x) + \cancel{K} b)}{\cancel{\|K w\|}} = \frac{t_n (w^T \phi(x) + b)}{\|w\|}$$

Canonical representation of the decision hyperplane

$$t_n (w^T \phi(x_n) + b) = 1 \quad \text{for the point that is closest to the hyperplane}$$

Then

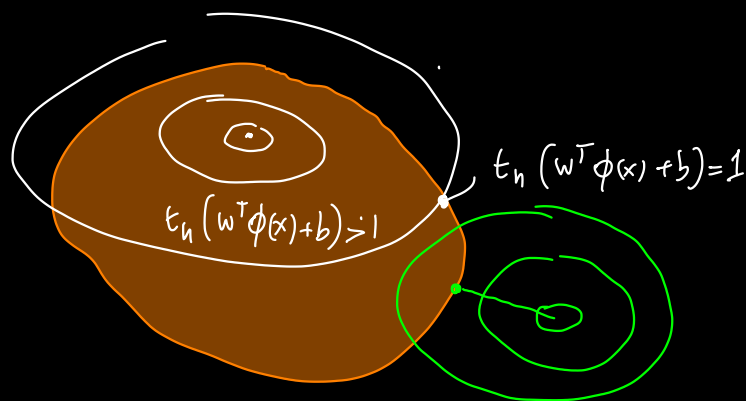
$$t_n (w^T \phi(x_n) + b) \geq 1 \quad \forall n \in [1, N]$$



$$\operatorname{argmax}_{w, b} \left\{ \frac{1}{\|w\|} \min_n \left[t_n (w^T \phi(x) + b) \right] \right\} =$$

$$= \operatorname{argmax}_{w, b} \left\{ \frac{1}{\|w\|} \right\} = \operatorname{argmin}_{w, b} \frac{1}{2} \|w\|^2$$

subject to the constraint $t_n (w^T \phi(x) + b) \geq 1 \quad \forall n \in [1, N]$



Appendix E

quadratic programming

Lagrange multipliers

$$a = (a_1, \dots, a_N)^T$$

$a_n \geq 0$ 1 for each data point

$$L(w, b, a) = \frac{1}{2} \|w\|^2 - \sum_{n=1}^N a_n \left\{ t_n (w^T \phi(x_n) + b) - 1 \right\}$$

\uparrow minimize \uparrow ≥ 0

$$\frac{\partial L}{\partial w} = 0 \quad w = \sum_{n=1}^N a_n t_n \phi(x_n) \quad \leftarrow$$

$$\frac{\partial L}{\partial b} = 0$$

$$0 = \sum_{n=1}^N a_n t_n$$

$$\tilde{L}(a) = \frac{1}{2} \left\| \sum_{n=1}^N a_n t_n \phi(x_n) \right\|^2 - \sum_{n=1}^N a_n \left\{ t_n \left(\sum_{m=1}^N a_m t_m \phi(x_m) \right) \phi(x_n) \right\}$$

$$- b \sum_{n=1}^N a_n t_n + \sum_{n=1}^N a_n =$$

$$= \frac{1}{2} \sum_{n=1}^N \sum_{m=1}^N a_n a_m t_n t_m \phi^T(x_n) \phi(x_m) - \sum_{n=1}^N \sum_{m=1}^N a_n a_m t_n t_m \phi^T(x_n) \phi(x_m)$$

$$\tilde{J}(a) + \sum_{n=1}^N a_n = -\frac{1}{2} \sum_{n=1}^N \sum_{m=1}^N a_n a_m t_n t_m \underbrace{\phi^T(x_n) \phi(x_m)}_{K(x_n, x_m)} + \sum_{n=1}^N a_n$$

dual representation for the optimality criterion

$$a_n \geq 0$$

$$\sum_{n=1}^N a_n t_n = 0$$

$$n \in [1, N]$$

Quadratic problem in M variables $\Rightarrow \underline{O(M^3)}$

$$L(\underbrace{w, b, a}_M)$$

$$\tilde{L}(a) \quad N \text{ variables} \Rightarrow O(N^3)$$

$$y(x) = w^T \phi(x) + b = \sum_{n=1}^N a_n t_n \underbrace{\phi^T(x_n) \phi(x)}_{K(x, x_n)} + b$$

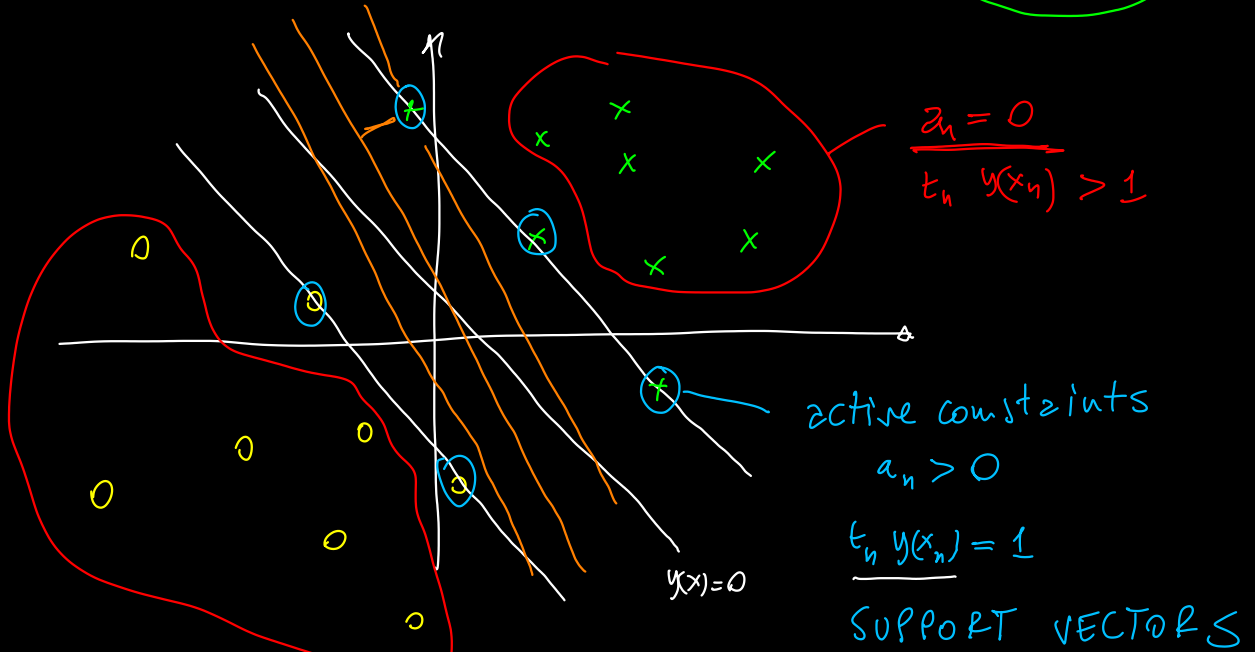
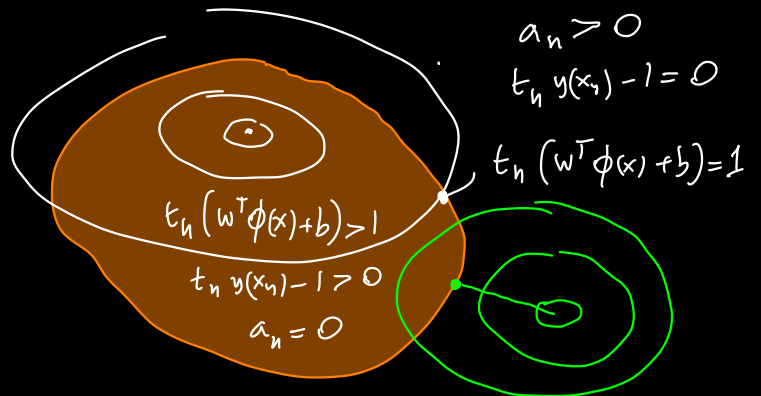
$$= \sum_{n \in N_S} a_n t_n K(x, x_n) + b$$

Karush-Kuhn-Tucker KKT conditions:

$$a_n \geq 0$$

$$t_n y(x_n) - 1 \geq 0$$

$$a_n \{ t_n y(x_n) - 1 \} = 0$$



if x_n is support vector

$$\Rightarrow 1 = t_n y(x_n) = t_n \left(\sum_{m \in S} a_m t_m K(x_n, x_m) + b \right)$$

+1, -1

$$t_n = t_n^2 \left(\begin{matrix} \vdots \\ 1 \end{matrix} \right)$$

$N_S b$

$$\sum_{n \in S} t_n = \sum_{n \in S} \sum_{m \in S} a_m t_m K(x_n, x_m) + \sum_{n \in S} b$$

$$w = \sum_{n \in S} a_n t_n \phi(x_n)$$

$$b = \frac{1}{N_S} \sum_{n \in S} \left[t_n - \sum_{m \in S} a_m t_m K(x_n, x_m) \right]$$

