



Norwegian University of Science
and Technology
Department of Engineering
Cybernetics

TTK4195
Modeling and Control
of Robots
Spring 2015

Exercise set 1

Deliver on It's Learning by January 20th

The following problems are found in the book: "Robot Modeling and Control" (2006) by Spong et al.

Problem 1-2

1 Point

Problem 1-18

2 Points

Problem 2-13

1 Point

Problem 2-14

1 Point

Problem 2-15

1 Point

Problem 2-39

4 Points