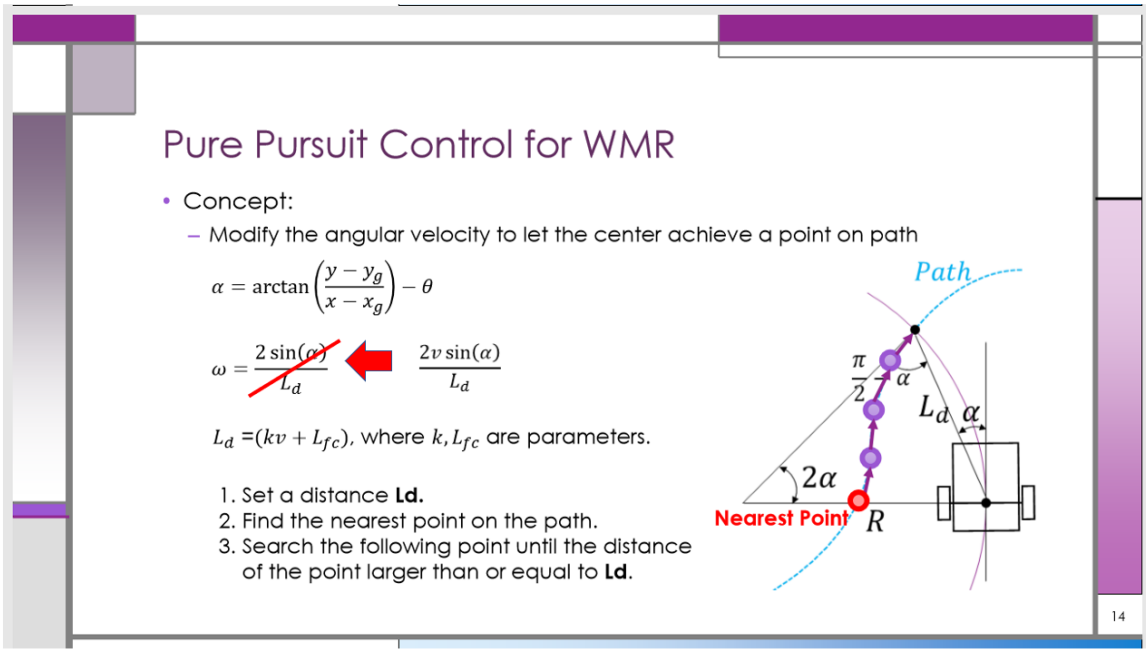
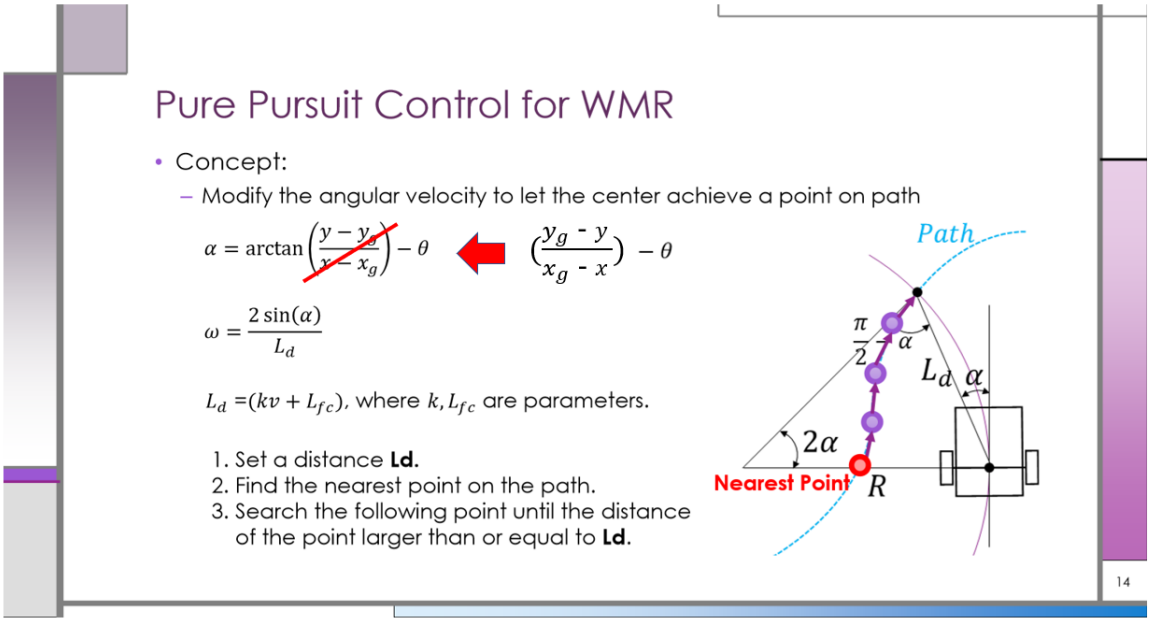
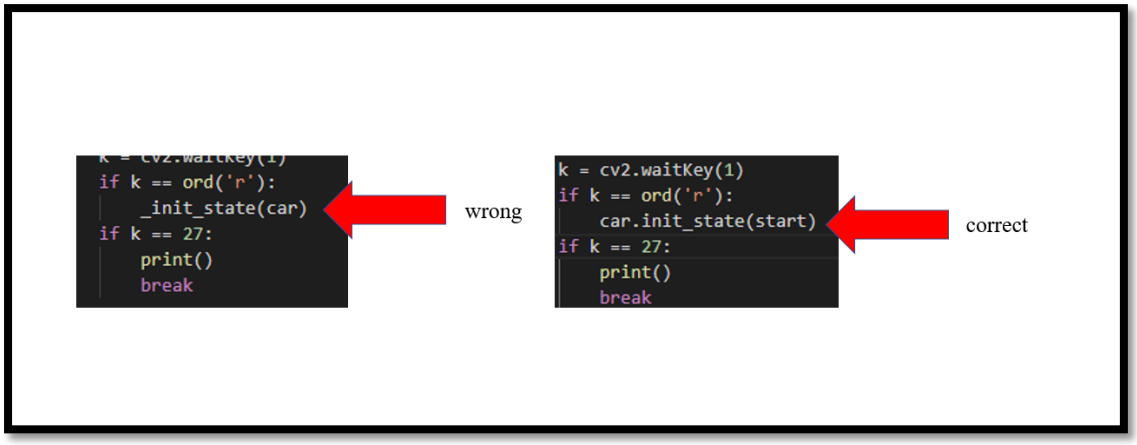
1. Page 14:



2. Page 14:



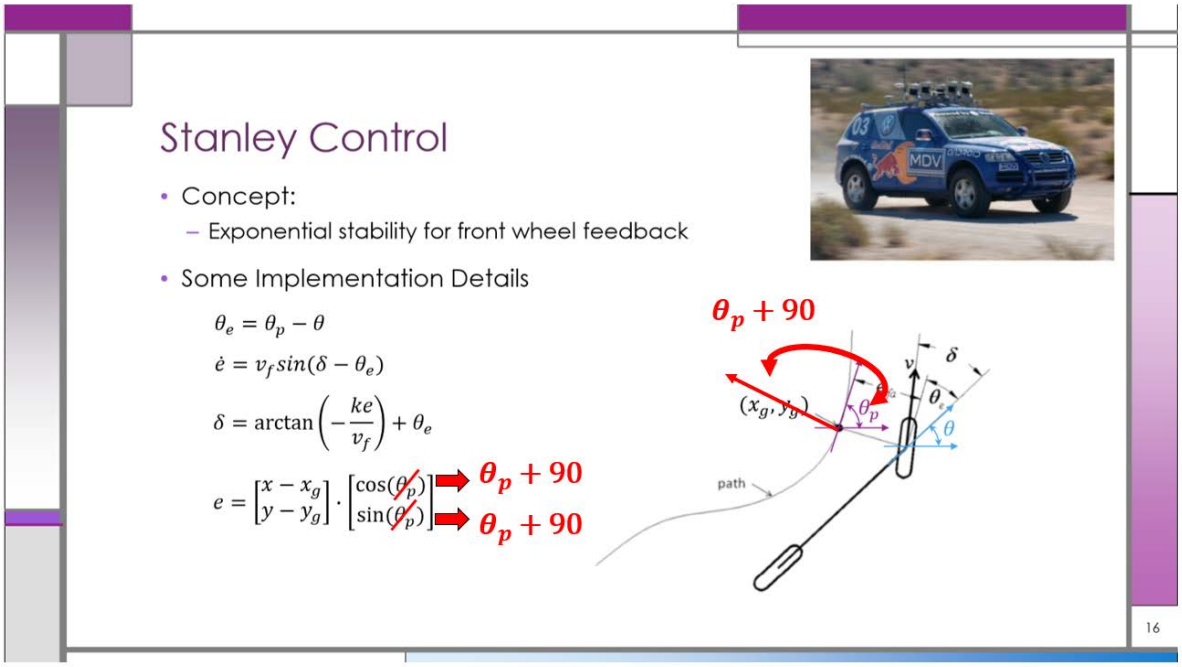
3. initial function in all of the code: initial function usage in some file is wrong



Start may like this: (x, y, yaw)

```
start = (50,300,0)
```

4. Page 16



5. Before use the **yaw**, you need to transform the yaw' s degree to radian
   After calculate the angle you need to transform back
   Something like this:

```
alpha = np.arctan2(target[1]-y, target[0]-x) - np.deg2rad(yaw)
next_w = np.rad2deg(2*v*np.sin(alpha) / Ld)
```