

# Assignment 2

MT-1004: Linear Algebra

Due: October 18, 2025

## Instructions

- Submit your solutions electronically as a PDF file
- Show all your work and reasoning

**Problem 1** (Vector Space - Application in Computer Science). *In computer graphics and game development, colors are often represented as vectors. Consider the set  $V$  of all RGB color vectors of the form  $(r, g, b)$  where  $r, g, b \in \mathbb{R}$  represent red, green, and blue components respectively.*

*Define two operations on  $V$ :*

- **Color Blending (Addition):**  $(r_1, g_1, b_1) \oplus (r_2, g_2, b_2) = (r_1 + r_2, g_1 + g_2, b_1 + b_2)$
- **Color Scaling (Scalar Multiplication):**  $k \odot (r, g, b) = (kr, kg, kb)$  for  $k \in \mathbb{R}$

*However, in practical applications, we need to ensure colors don't exceed display capabilities. Consider the modified operations:*

- **Bounded Addition:**  $(r_1, g_1, b_1) \oplus (r_2, g_2, b_2) = (\min(r_1 + r_2, 1), \min(g_1 + g_2, 1), \min(b_1 + b_2, 1))$
- **Bounded Scaling:**  $k \odot (r, g, b) = (\min(kr, 1), \min(kg, 1), \min(kb, 1))$  for  $k \in \mathbb{R}$

- (a) *Show that  $V$  with the standard operations (first definition) forms a vector space. Identify the zero vector and additive inverses.*
- (b) *Determine whether  $V$  with the bounded operations (second definition) forms a vector space. If not, identify which vector space axioms fail and provide counterexamples.*

**Problem 2** (Subspace - Application in Data Science). *In machine learning, datasets are often represented as vectors in  $\mathbb{R}^n$ . Consider a dataset where each data point is a vector  $(x_1, x_2, x_3, x_4)$  representing four features of an object.*

*Let  $V = \mathbb{R}^4$  be the vector space of all possible data points. Consider the following subsets:*

(b)  $W_2 = \{(x_1, x_2, x_3, x_4) \in \mathbb{R}^4 \mid x_1 + x_2 + x_3 + x_4 = 1\}$

(c)  $W_3 = \{(x_1, x_2, x_3, x_4) \in \mathbb{R}^4 \mid x_1 = 2x_3 \text{ and } x_2 = x_4\}$

For each subset:

(i) Determine whether it is a subspace of  $\mathbb{R}^4$  using the Subspace Test.

(ii) If it is not a subspace, explain which condition fails and provide a specific counterexample.

**Problem 3.** In computer graphics, transformations are often represented using matrices. Consider a 2D graphics system where we want to represent all possible linear transformations that can be applied to points in the plane.

Let  $S = \{A_1, A_2, A_3, A_4\}$  be a set of  $2 \times 2$  matrices where:

$$A_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad A_2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \quad A_3 = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \quad A_4 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

1. Show that  $S$  spans the vector space  $M_{22}$  of all  $2 \times 2$  matrices.

2. A computer graphics programmer wants to create a new transformation matrix:

$$B = \begin{bmatrix} 3 & -2 \\ 5 & 4 \end{bmatrix}$$

Express  $B$  as a linear combination of the matrices in  $S$ .

**Problem 4.** In machine learning and data science, feature vectors often represent different attributes of data points. Consider a dataset where each data point is represented by a 3-dimensional feature vector.

Let  $V = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$  be a set of feature vectors where:

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 3 \\ 1 \\ 4 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 2 \\ -1 \\ 5 \end{bmatrix}, \quad \mathbf{v}_4 = \begin{bmatrix} 0 \\ 5 \\ 2 \end{bmatrix}$$

1. Determine whether the set  $V$  is linearly independent or linearly dependent. Show your work using the definition of linear independence.

2. If the set is linearly dependent, identify the dependency relationship and express one vector as a linear combination of the others.

3. In data preprocessing, we often encounter the problem of multicollinearity where features are highly correlated. Consider a modified set:

$$W = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} a \\ b \\ c \end{bmatrix} \right\}$$

Find the conditions on  $a, b, c$  such that  $W$  is linearly independent.

**Problem 5.** In computer graphics and data science, we often work with different coordinate systems to represent the same data. Consider a vector space  $V$  of 2D geometric transformations with basis:

$$B = \left\{ T_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, T_2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, T_3 = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, T_4 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

This is the standard basis for  $M_{22}$  representing basic transformation matrices.

Now consider an alternative basis  $B'$  that represents shear transformations and scaling:

$$B' = \left\{ S_1 = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, S_2 = \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}, S_3 = \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}, S_4 = \begin{bmatrix} 0 & 0 \\ 1 & -1 \end{bmatrix} \right\}$$

A transformation matrix used in computer vision is given by:

$$A = \begin{bmatrix} 3 & 1 \\ 2 & 4 \end{bmatrix}$$

1. Find the coordinate vector  $[A]_B$  of matrix  $A$  relative to the standard basis  $B$ .
2. Find the transition matrix  $P_{B \rightarrow B'}$  from basis  $B$  to basis  $B'$ .
3. Using the transition matrix from part (1), find the coordinate vector  $[A]_{B'}$  of matrix  $A$  relative to basis  $B'$ .

**Problem 6.** In machine learning and data compression, understanding the dimension of vector spaces is crucial for feature selection and dimensionality reduction. Consider the following problems:

## Part a: Solution Spaces in Linear Systems

A machine learning model uses a linear system to extract features from image data. The system is represented by:

$$\begin{aligned} x_1 + 2x_2 - x_3 + 3x_4 - 2x_5 &= 0 \\ 2x_1 + 4x_2 - 2x_3 + 7x_4 - 3x_5 &= 0 \\ 3x_1 + 6x_2 - 3x_3 + 10x_4 - 5x_5 &= 0 \end{aligned}$$

1. Find a basis for the solution space of this homogeneous system.
2. Determine the dimension of the solution space.
3. If we add the constraint  $x_1 + x_2 + x_3 = 0$  to the system, how does this affect the dimension of the solution space? Find the new basis and dimension.

## Part b: Subspaces in Data Representation

In data science, we often work with structured data that forms subspaces of larger vector spaces.

1. Consider the set  $W$  of all  $3 \times 3$  symmetric matrices (matrices where  $A = A^T$ ). Prove that  $W$  is a subspace of  $M_{33}$  and find its dimension.
2. A data compression algorithm works with polynomials of degree at most 4 that satisfy  $p(1) = 0$  and  $p(-1) = 0$ . Show that these polynomials form a subspace of  $P_4$  and find its dimension. Provide an explicit basis for this subspace.

**Problem 7.** Consider the vector space  $\mathbb{R}^2$  with two bases:

$$B = \left\{ \mathbf{u}_1 = \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 4 \\ -1 \end{bmatrix} \right\} \quad \text{and} \quad B' = \left\{ \mathbf{u}'_1 = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \mathbf{u}'_2 = \begin{bmatrix} -1 \\ -1 \end{bmatrix} \right\}.$$

Let  $\mathbf{w} = \begin{bmatrix} 3 \\ -5 \end{bmatrix}$  and suppose its coordinate vector relative to basis  $B$  is  $[\mathbf{w}]_B = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$ .

1. Find the transition matrix  $P_{B \rightarrow B'}$  from basis  $B$  to basis  $B'$ .
2. Use the transition matrix  $P_{B \rightarrow B'}$  to find the coordinate vector  $[\mathbf{w}]_{B'}$ .

**Problem 8.** Let  $A$  be the matrix given by:

$$A = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 \\ 2 & -6 & 9 & -1 & 8 & 2 \\ 2 & -6 & 9 & -1 & 9 & 7 \\ -1 & 3 & -4 & 2 & -5 & -4 \end{bmatrix}$$

Its reduced row echelon form (RREF) is:

$$R = \begin{bmatrix} 1 & -3 & 0 & 0 & 3 & 0 \\ 0 & 0 & 1 & 0 & -2 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

1. Find a basis for the **row space** of  $A$ ,  $\text{row}(A)$ .
2. Find a basis for the **column space** of  $A$ ,  $\text{col}(A)$ . (Your basis must consist of column vectors from the original matrix  $A$ ).
3. Find a basis for the **null space** of  $A$ ,  $\text{null}(A)$ .
4. Is the vector  $\mathbf{b} = [1 \ -9 \ -5 \ 4]^T$  in the column space of  $A$ ? Justify your answer.

**Problem 9.** Let  $A$  be a  $5 \times 7$  matrix.

1. What is the largest possible value for the **rank** of  $A$ ? What is the smallest possible value for the **nullity** of  $A$ ? Explain your reasoning.
2. Suppose the linear system  $A\mathbf{x} = \mathbf{b}$  is consistent and  $\text{rank}(A) = 4$ .
  - (a) How many parameters (free variables) are in the general solution of  $A\mathbf{x} = \mathbf{b}$ ?
  - (b) Is the solution unique? Why or why not?
3. Now, suppose  $A$  is the coefficient matrix of a homogeneous system,  $A\mathbf{x} = \mathbf{0}$ , and its null space is 2-dimensional.
  - (a) What is the rank of  $A$ ?
  - (b) Do the **column vectors** of  $A$  span  $\mathbb{R}^5$ ? Justify your answer using the concept of rank.

### Grading Rubric:

- **Correctness (60%):** Accurate mathematical solutions
- **Reasoning (25%):** Clear explanation of steps and methods
- **Application (15%):** Meaningful interpretation in computer science context