

Note: Unsupervised Semantic Segmentation by Contrasting Object Mask Proposals

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June 5, 2022

1 Introduction

Previous works on unsupervised semantic segmentation mainly focus on building proxy works, thus only concentrate on limited domain of the image. This paper made a first attempt to build a pixel level prior, and then use a contrastive framework to learn embeddings.

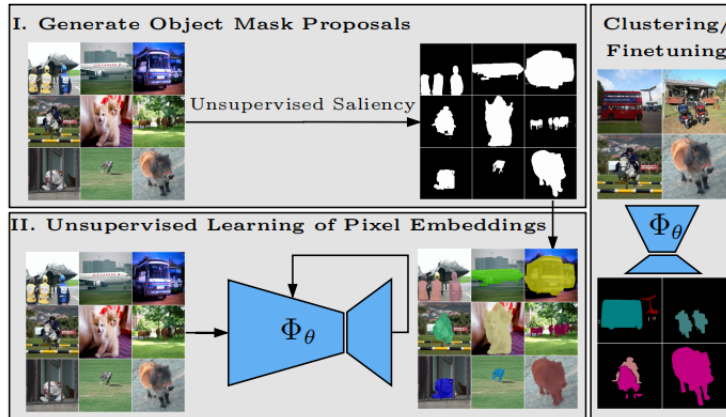


Figure 1. We learn pixel embeddings for semantic segmentation in an unsupervised way. First, we predict object mask proposals using unsupervised saliency. Second, we use the obtained masks as a prior in a self-supervised optimization objective. Finally, the pixel embeddings can be clustered or fine-tuned to a semantic segmentation of the image.

2 Method

The proposed method is based on divide-and-conquer strategy. It first look for images regions where pixels are likely to belong together. MaskContrast consists of 2 steps: first determine a prior by identifying objects in the images that can be grouped together, and then employ the obtained prior in a contrastive loss.

2.1 Mining Object Mask Proposals

The saliency estimation is use to generate the object mask proposals.

2.2 MaskContrast: Learning Pixel Embeddings by Contrasting Salient Objects

The goal is ti learn a pixel embedding function $\Phi_\theta : \mathcal{X} \rightarrow \mathcal{Z}$ parameterized by a neural network with weights θ , that maps each pixel i in an image to a point z_i on a D -dimensional normalized hyper-sphere.

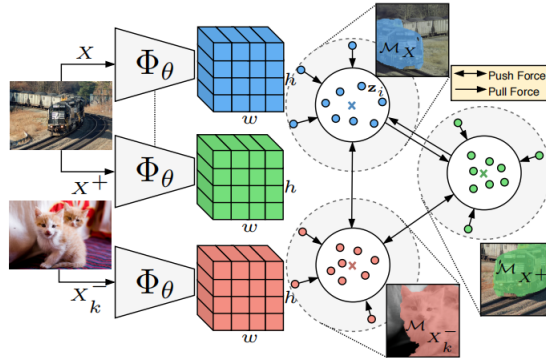


Figure 2. **MaskContrast** learns pixel embeddings for unsupervised semantic segmentation in the following way. We use a saliency estimator to generate positive pairs of object-centric crops (X, X^+) and negative pairs X_k^- . The model Φ_θ is trained to maximize the agreement between embeddings of pixels belonging to the objects in X, X^+ , while minimizing the agreement with pixels from objects in X_k^- .

Learning Image-Level Representations. Positive views contain the same object and they are generated by applying augmentations. Negative views never contain the same object.

Learning Pixel-Level Representations. The optimization is derived from a pull- and push-force.

$$\mathcal{L}_i = -\log \frac{\exp(\mathbf{z}_i \cdot \mathbf{z}_{\mathcal{M}_{x^+}}/\tau)}{\sum_{k=0}^K \exp(\mathbf{z}_i \cdot \mathbf{z}_{\mathcal{M}_{x_k^-}}/\tau)}.$$

where the mean pixel embedding $\mathbf{z}_{\mathcal{M}_n}$ of an object mask M_n be defined as:

$$\mathbf{z}_{\mathcal{M}_n} = \frac{1}{|\mathcal{M}_n|} \sum_{i \in \mathcal{M}_n} \mathbf{z}_i.$$

3 Summary

This work presented a general two-step framework based upon a mid-level visual prior for tackling unsupervised semantic segmentation. This work does not concentrate on low level information and get great performance.

References