

Problem 1

$$(1) \frac{d[R^*]}{dt} = k_{on}[R][L] - k_{off}[R^*] \quad (2) \frac{d[X^*]}{dt} = -d[X^*] = v_1[x] - \frac{v_1[x]}{k_1 + [x]} - \frac{v_2[x^*]}{k_2 + [x^*]}$$

$$(3) \frac{d[Y^*]}{dt} = -\frac{d[Y]}{dt} = \frac{v_3[Y]}{k_3 + [Y]} - \frac{v_4[Y^*]}{k_4 + [Y^*]} \quad v_1 = \gamma_1[R^*]$$

$$(4) R_t = [R] + [R^*] \quad (5) X_t = [X] + [X^*] \quad (6) Y_t = [Y] + [Y^*]$$

a) SS solution  $y^*$   $\frac{dy}{dt} \Rightarrow 0$

$$0 = k_{on}[R][L] - k_{off}[R^*] \quad \frac{k_{on}[L][R]}{k_{off}} = [R^*] \quad \frac{1}{k_0}(R_t - [R^*]) = [x^*]$$

$$\therefore R_t \Rightarrow \frac{1}{k_0}(1 - Q_b) = Q_b$$

$$0 = \frac{v_1[x]}{k_1 + [x]} - \frac{v_2[x^*]}{k_2 + [x^*]} \quad \frac{v_1[x]}{k_1 + [x]} = \frac{v_2[x^*]}{k_2 + [x^*]} \quad v_2[x^*](k_1 + [x]) = v_1[x](k_2 + [x^*])$$

$$\frac{v_1}{v_2} = \frac{[x^*](k_1 + [x])}{[x](k_2 + [x^*])} = \frac{\gamma_1[R^*]}{v_2} = \frac{\gamma_1 Q_b(R_t)}{v_2}$$

$$\frac{[x^*](k_1 + x_t - [x^*])}{(x_t - [x^*])(k_2 + [x^*])} = \frac{x^*(k_1 + 1 - x^*)}{(1 - x^*)(k_2 + x^*)}$$

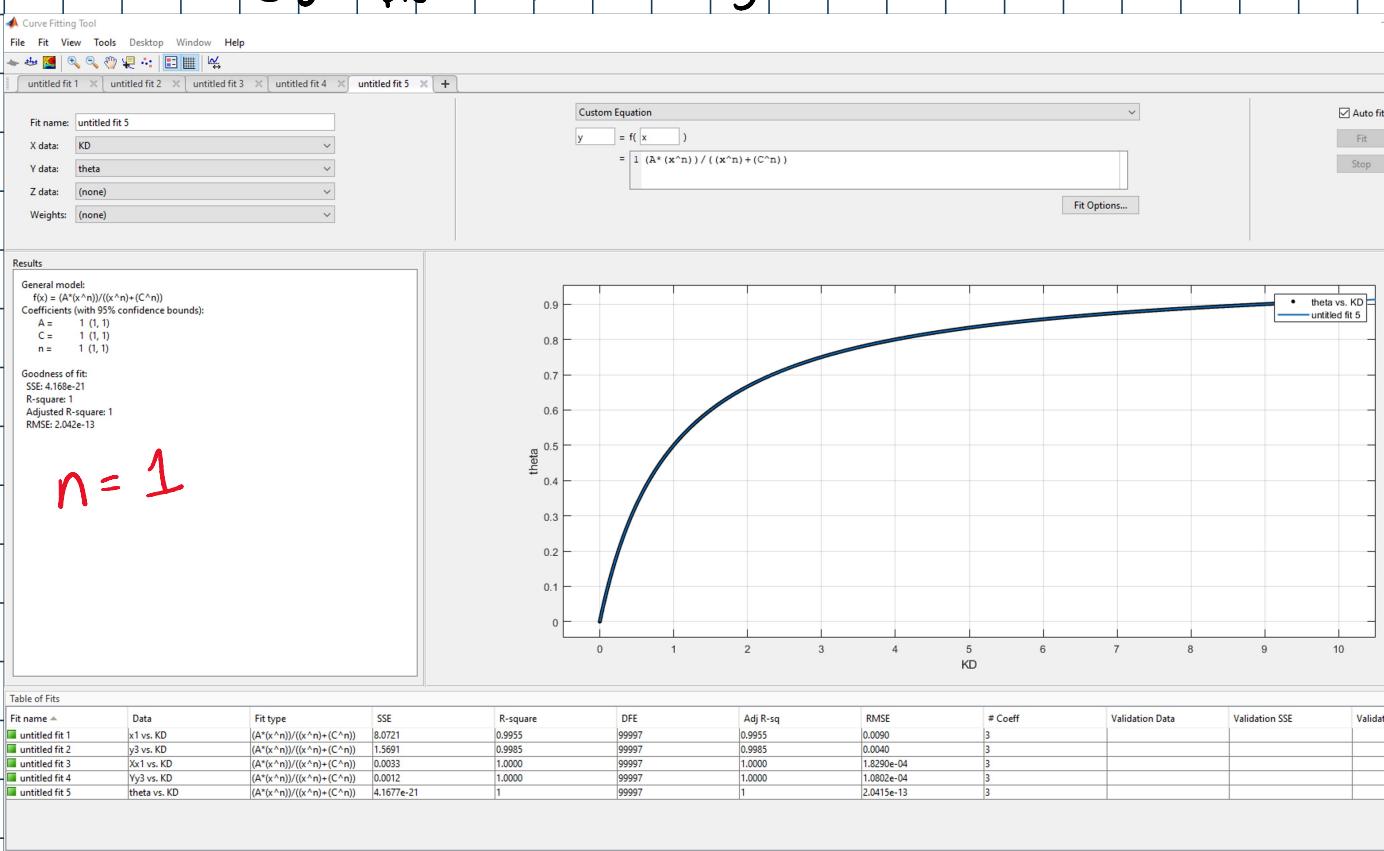
$$\text{Eqn 3 is of same form} \Rightarrow \frac{v_3}{v_4} = \frac{y^*(k_3 + 1 - y^*)}{(1 - y^*)(k_4 + y^*)} = \frac{\gamma_3(x^*)}{v_4} = \frac{\gamma_3 x^*}{v_4} x_t$$

We want the soln to  $y^*$ , however due to the complexity of the eqns they will not be solved for explicitly. Eqn (2) can be written as a quadratic function of which the soln is of the form:  $-b \pm \sqrt{b^2 - 4ac}$ . and solved for  $x^*$ . This value is then input into Eqn (3) which is also a quadratic and can now be solved for  $y^*$ .  $Q_b$  from Eqn (1) has an  $[L]$  dependency so  $x^*$  is a function of  $[L]$  and  $y^*$  inherits this dependency.

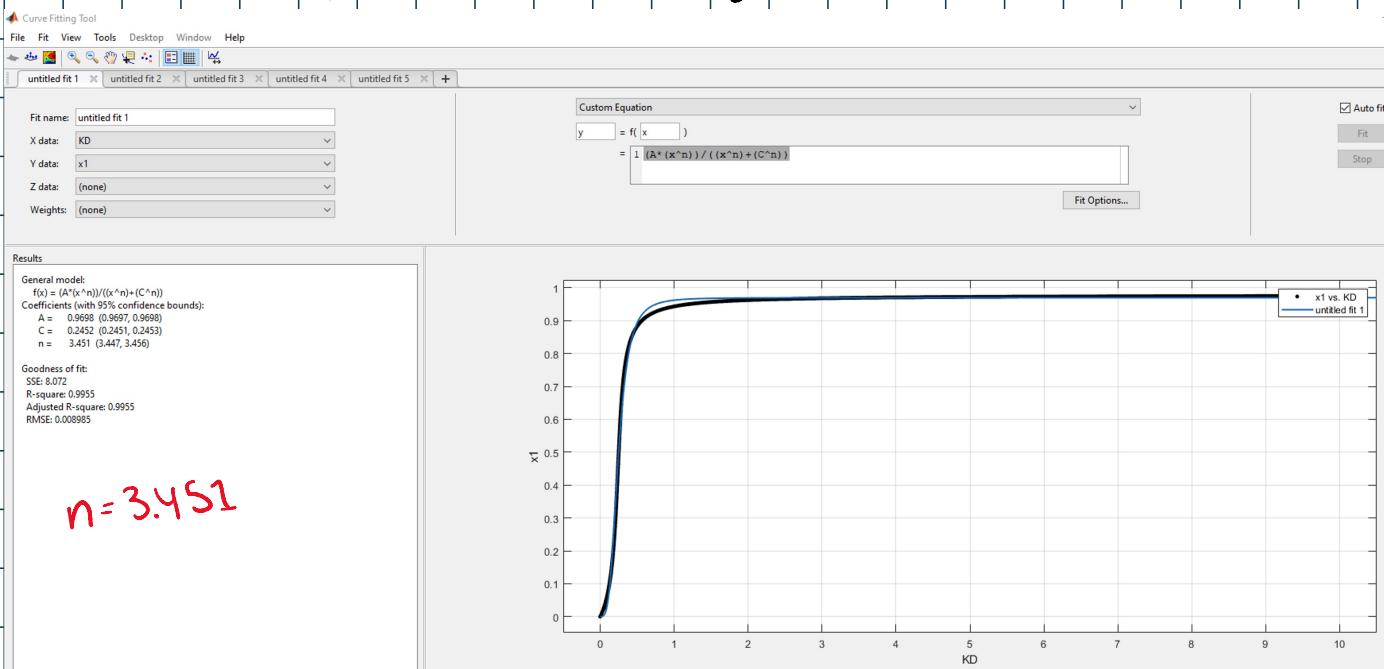
b) b c)

Ob plot vs.  $\nu_{\text{ad}}$  + fitting

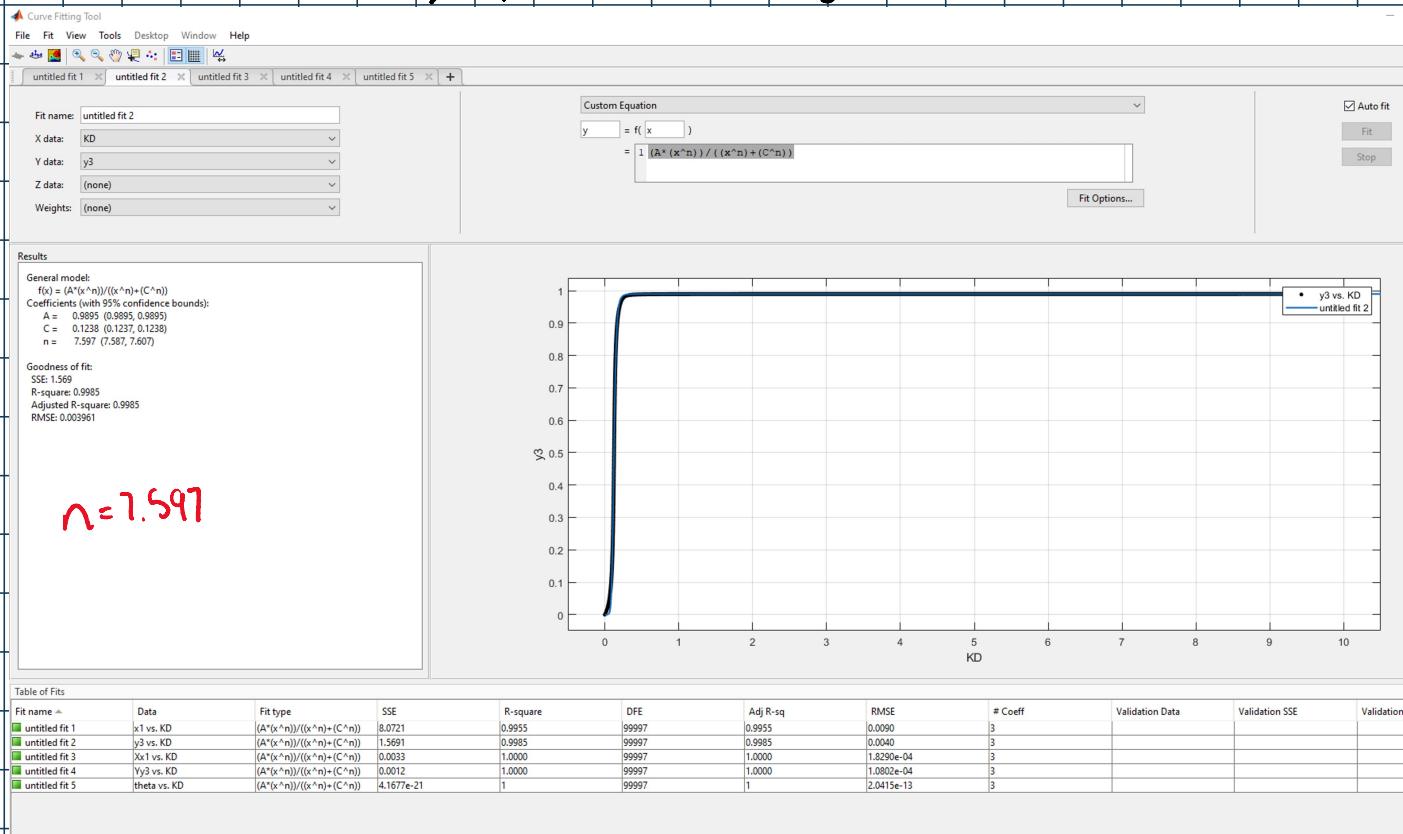
$$\kappa = 0.1 \Rightarrow \nu = 10$$



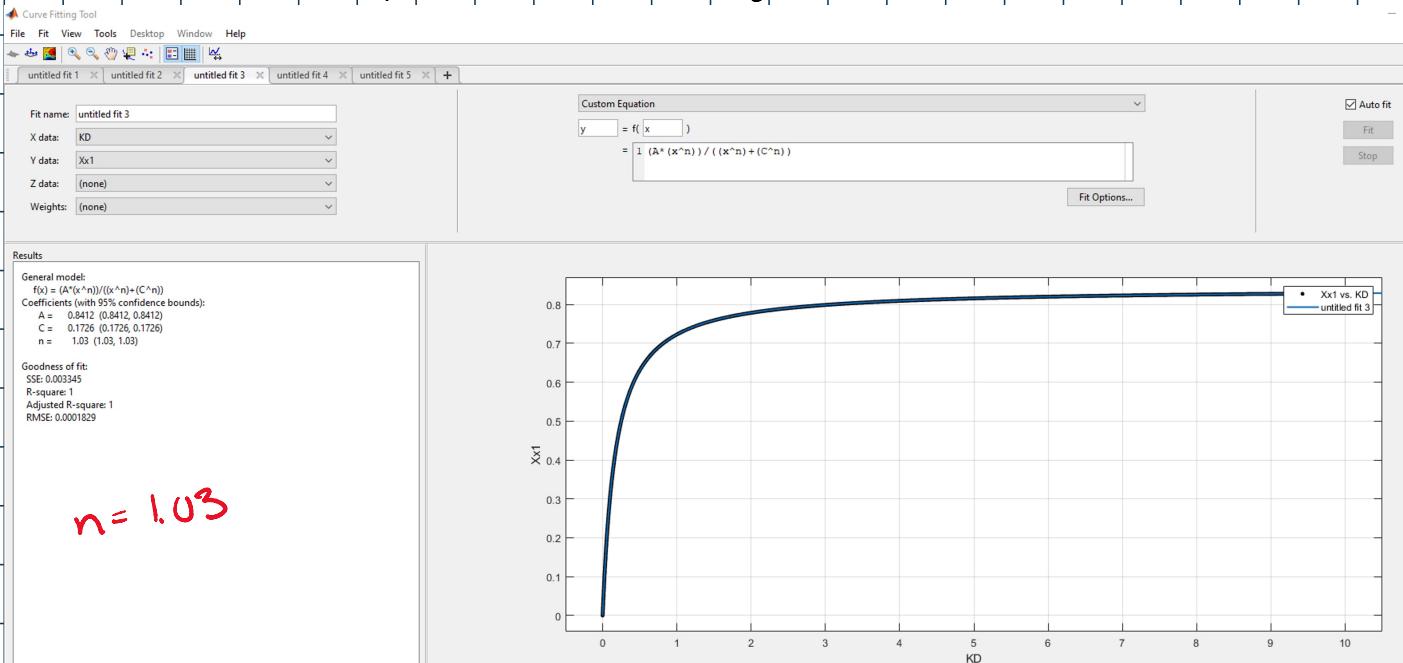
$x^*$  plot vs.  $\nu_{\text{ad}}$  + fitting  $\kappa = 0.1$



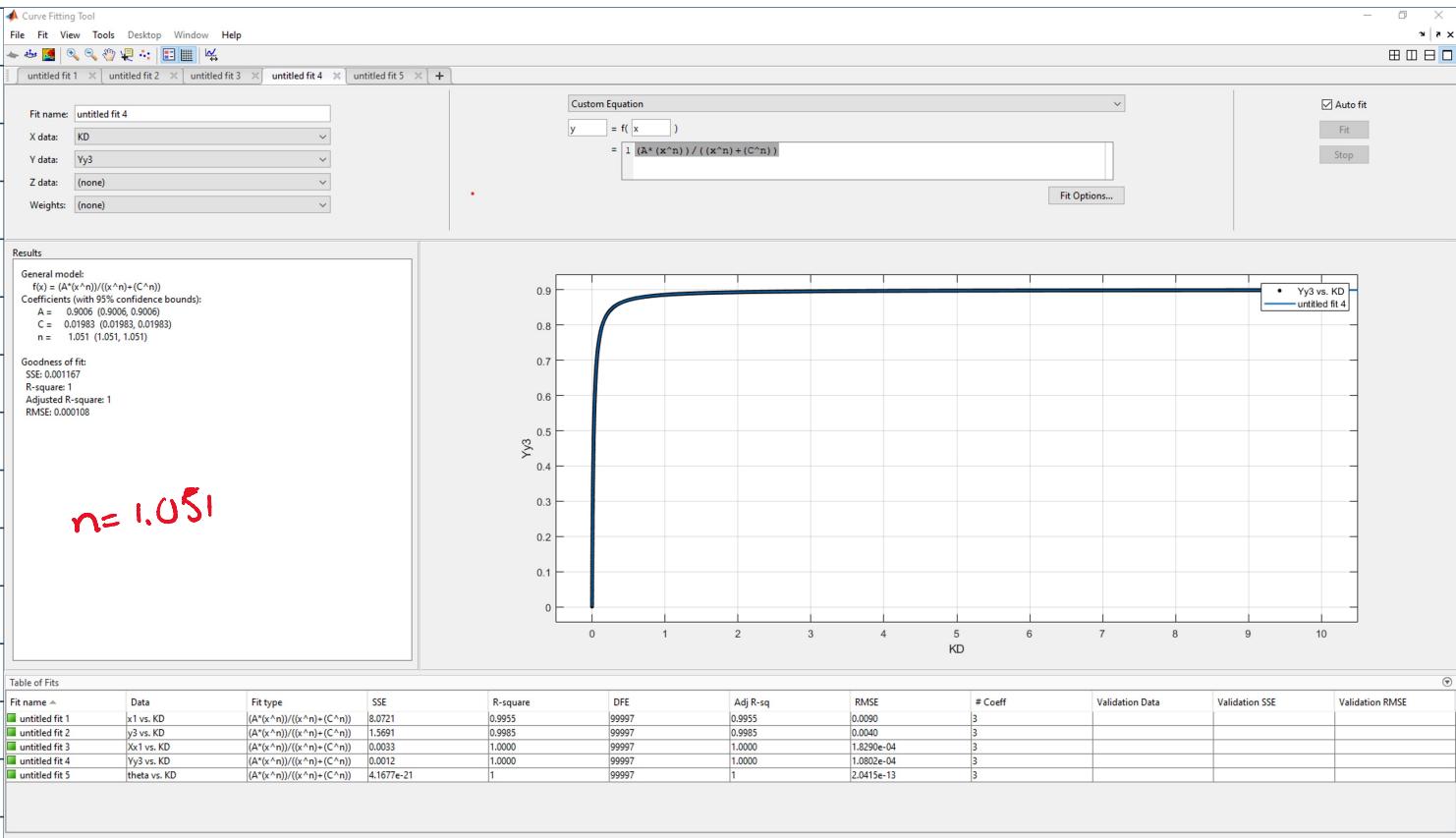
$y^*$  plot vs.  $1/KD$  + fitting  $K = 0.1$



$x^*$  vs.  $1/KD$  + fitting  $K = 10$



$y^*$  vs.  $1/KD$  + fitting  $K = 10$



d) Matlab Code Output

>> PS4\_Problem\_1\_percentchange

Output of MATLAB code for percent change. Uppercase represent values for K = 10 and lowercase K = 0.1

per\_theta =

43.4783

per\_x1 =

0

per\_y3 =

0

Per\_theta =

43.4783

Per\_x1 =

Formula Used:

$$\frac{\text{final} - \text{initial}}{\text{initial}} \times 100\% = \% \text{ change}$$

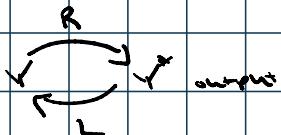
-77.1421

Per\_y3 =

-78.4281

>>

e) In a system



output or input amplification

is measured if

the system is a zero order ultrasensitive system (UCS) and the system operates at saturation. This allows tuning for ultra sensitive response to small input results in a large change in output