

HW#5 Problems

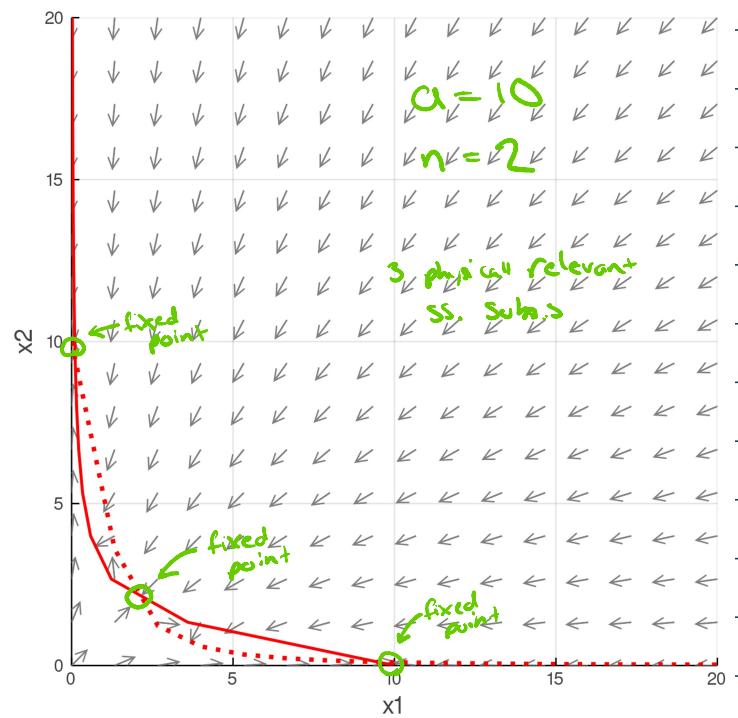
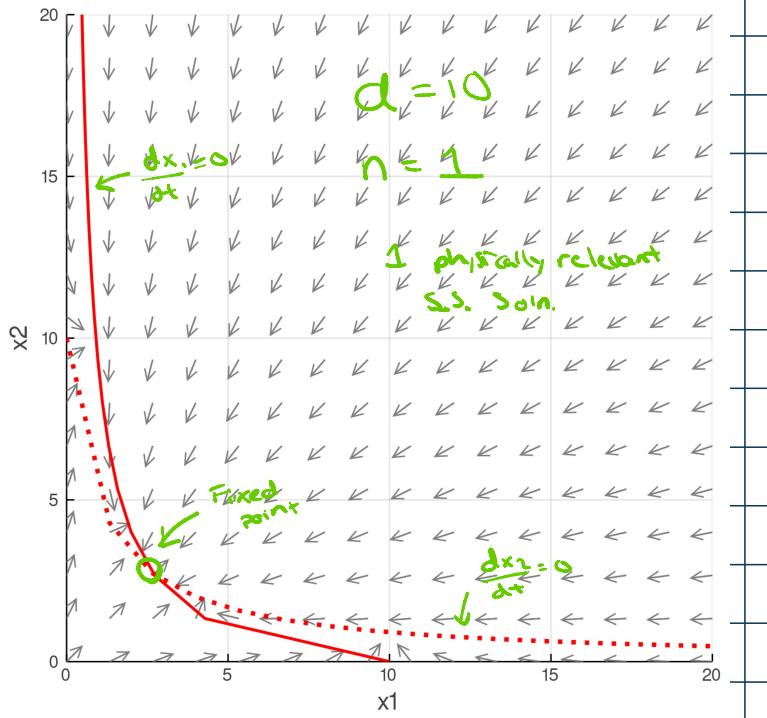
Wednesday, May 6, 2020 8:11 PM

$$\frac{du}{dt} = \frac{a}{1+u^n} - u = f(u, v) \quad (1)$$

$$\frac{dv}{dt} = \frac{a}{1+u^n} - v = g(u, v) \quad (2)$$

- a) i) u, v
 ii) a
 iii) n
 iv) -1

b) As the degree of cooperativity increased the S.S. soln. became unstable



c) See Problem 3 part b)

The steady state is stable (only considering physically relevant concentration ranges i.e. $[] \geq 0$)

$$d) S.S. f(u_s, v_s) = g(u_s, v_s) \quad a=10, n=1$$

$$\frac{10}{1+u_s^2} - u_s = 0 \quad u_s = \frac{10}{1+u_s^2}$$

$$\frac{10}{1+v_s^2} - v_s = 0 \Rightarrow \frac{10}{1+\frac{10}{1+u_s^2}} = v_s \quad 10 = v_s + \frac{10u_s}{1+u_s^2}$$

$$10 - u_s = \frac{10v_s}{1+u_s} \quad (1+u_s)(10-u_s) = 10v_s \quad 10 - u_s + 9u_s - u_s^2 = 10v_s$$

$$u_s^2 + v_s - 10 = 0 \Rightarrow v_s = \{-3.7, 2.7\} \quad v_s \Rightarrow 2.7 \text{ only physically relevant root}$$

$$u_s = \frac{10}{1+2.7} = 2.7$$

$$U = u - u_s \quad V = v - v_s$$

$$\frac{dU}{dt} = f(u_s, v_s) + \left. \frac{\partial f}{\partial u} \right|_{u_s, v_s} U + \left. \frac{\partial f}{\partial v} \right|_{u_s, v_s} V = -1(U) - \frac{10}{(1+u_s)^2} V = -U - \frac{10V}{(1+u_s)^2} = -U - \frac{10V}{(1+2.7)^2}$$

$$\frac{dV}{dt} = g(u_s, v_s) + \left. \frac{\partial g}{\partial u} \right|_{u_s, v_s} U + \left. \frac{\partial g}{\partial v} \right|_{u_s, v_s} V = \frac{-10U}{(1+u_s)^2} - V = \frac{-10U}{(1+2.7)^2} - V$$

$$\Rightarrow \frac{dV}{dt} = \frac{-10}{13.69} V - U \quad \frac{dV}{dt} = \frac{-10}{13.69} U - V$$

$$\dot{\bar{x}} = J \bar{x} \quad \text{where} \quad \bar{x} = \begin{pmatrix} U \\ V \end{pmatrix}, J = \begin{pmatrix} f_u & f_v \\ g_u & g_v \end{pmatrix} = \begin{pmatrix} -1 & \frac{-10}{(1+u_s)^2} \\ \frac{-10}{(1+u_s)^2} & -1 \end{pmatrix}$$

Stability criterion is that real part of eigenvalue (λ_1) is < 0

Degree of cooperativity has a large effect on stability while the rate of synthesis does not. As degree of cooperativity increases the real part of λ_1 becomes increasingly positive.

e) SS. soln $a=10, n=2 \xrightarrow{\text{wofram}} \{(0.10, 0.69), (2, 2), (0.69, 0.10)\}$

Assuming $(2, 2)$ is central SS with

For $n=1$: $J = \begin{pmatrix} -1 & -10/(1+2)^2 \\ -10/(1+2)^2 & -1 \end{pmatrix} \quad \lambda_1 = \frac{-2.569}{1.364} \quad \lambda_2 = \frac{-3.69}{1.364}$

$$\lambda_1 = -1.73 \quad \lambda_2 = -0.27 \quad \text{stable as } < 0$$

For $n=2$: $J = \begin{pmatrix} -1 & -2 \cdot 10 \cdot 2 \\ \frac{2 \cdot 10 \cdot 2}{(1+2^2)^2} & -1 \end{pmatrix} \quad \lambda_1 = -2.6 \quad \lambda_2 = 0.6$

One eigenvalue greater than zero so unstable

f) Part 1

$$\frac{dR_i^*}{dt} = k_f L R_i - k_r R_i^* \quad (1)$$

$$\frac{dN_j^*}{dt} = k_f^{ND} N_j D_j - k_r^{ND} N_j^* \quad (2)$$

$$\frac{dD_i}{dt} = k_f R_i^* - \gamma_D D_i \quad (3)$$

$$\frac{dR_i}{dt} = \frac{\beta^n}{K^n + N_i^n} - \gamma_R R_i \quad (4) \rightarrow \frac{dR_i}{dt} = \frac{\beta^n}{K^n + N_i^n} - \gamma_R R_i$$

Assume fast equilibrium

$$\frac{dR_2}{dt} = \frac{\beta^n}{K^n + N_2^n} - \gamma_R R_2$$

$$\Rightarrow 0 = k_f L R_1 - k_r R_1^* \rightarrow 0 = k_f L R_1 - k_r R_1^* \quad 0 = k_f L R_2 - k_r R_2^*$$

$$0 = k_f^{ND} N_1 D_1 - k_r^{ND} N_1^* \rightarrow 0 = k_f^{ND} N_1 D_1 - k_r^{ND} N_1^* \quad 0 = k_f^{ND} N_2 D_2 - k_r^{ND} N_2^*$$

$$0 = k_f R_1^* - \gamma_R D_1 \rightarrow 0 = k_f R_1^* - \gamma_R D_1 \quad 0 = k_f R_2^* - \gamma_R D_2$$

$$N_1^* = \frac{K_f^{ND}}{K_r^{ND}} N_1 D_2 = \left(\frac{K_f}{K_r} \right)^{ND} N_1 D_2 \quad N_2^* = \left(\frac{K_f}{K_r} \right)^{ND} N_2 D_1$$

$$D_1 = \frac{V_0 R_1^*}{\gamma_0} \quad D_2 = \frac{V_0 R_2^*}{\gamma_0}$$

$$R_1^* = \frac{V_f L R_1}{K_r} \quad R_2^* = K_f L R_2 \rightarrow D_1 = \frac{K_f V_f L R_1}{\gamma_0 K_r} \quad D_2 = \frac{K_f V_f L R_2}{\gamma_0 K_r}$$

$$\Rightarrow N_1^* = \left(\frac{K_f}{K_r} \right)^{ND} N_1 \frac{V_0 V_f L R_2}{\gamma_0 K_r} - \left(\frac{K_f}{K_r} \right)^{ND+1} \frac{N_1 V_0 L R_2}{\gamma_0}$$

$$N_2^* = \left(\frac{K_f}{K_r} \right)^{ND+1} \frac{N_2 V_0 L R_1}{\gamma_0}$$

$$\Rightarrow \frac{dR_1}{dt} = \frac{\beta^n}{K^n + \left(\frac{K_f}{K_r} \right)^{ND+1} \frac{N_1 V_0 L R_2}{\gamma_0}} - \gamma_R R_1$$

$$\frac{dR_2}{dt} = \frac{\beta^n}{K^n + \left(\frac{K_f}{K_r} \right)^{ND+1} \frac{N_2 V_0 L R_1}{\gamma_0}} - \gamma_R R_2$$

Part 2) Non-dimensionalize $u = R_1/K$, $v = R_2/K$, $\tau = \gamma_R t$

$$\rightarrow R_1 = uK \quad \frac{dR_1}{dt} = K \frac{du}{dt}$$

$$\rightarrow K \gamma_R \frac{du}{dt} = \frac{\beta^n}{K^n + \left(\frac{K_f}{K_r} \right)^{ND+1} \frac{N_1 V_0 L v K}{\gamma_0}} - \gamma_R u K$$

$$\rightarrow R_2 = vK \quad \frac{dR_2}{dt} = K \frac{dv}{dt}$$

$$\rightarrow t = \tau / \gamma_R \quad \frac{d}{dt} = \frac{d}{d\tau} / \gamma_R = \gamma_R \frac{d}{d\tau}$$

$$\Rightarrow \frac{dR_1}{dt} = K \gamma_R \frac{du}{d\tau}$$

$$\frac{dR_2}{dt} = K \gamma_R \frac{dv}{d\tau}$$

$$\Rightarrow \frac{du}{d\tau} = -u + \frac{\beta^n}{\gamma_R K^{n+1} + \gamma_R K^{n+1} \left(\frac{K_f}{K_r} \right)^{ND+1} \frac{N_1 V_0 L v}{\gamma_0}} = \frac{\beta^n}{\gamma_R K^{n+1} + \gamma_R K^{n+1} \left(\frac{K_f}{K_r} \right)^{ND+1} \frac{N_1 V_0 L}{\gamma_0} v^n} - u$$

$$= \frac{(\beta^n / \gamma_R K^{n+1})}{1 + \left(\frac{K_f}{K_r} \right)^{ND+1} \frac{N_1 V_0 L}{\gamma_0} v^n} - u \rightarrow$$

$$\frac{\alpha}{1 + \beta^n v^n} - u$$

$$\frac{dv}{d\tau} = \frac{\alpha}{1 + \beta^n u^n} - v$$

As $[L]$ increases the soln becomes more unstable. We can also drive the system towards instability by increasing n .