Practice Problem #6

Newton's Laws of Motion

Question: An object of mass m is at rest in equilibrium at the origin. At t=0, a new force \vec{F} is applied that has components:

$$F_x(t) = k_1 + k_2 y$$
 $F_y(t) = k_3 t$

where k_1 , k_2 , and k_3 are constants.

Calculate the position $\vec{r}(t)$ and velocity $\vec{v}(t)$ vectors as functions of time.

Solution: Using the vector form of Newton's 2nd Law, we can obtain the expression for \vec{a} :

$$\vec{F} = m \vec{a}$$

$$\frac{\vec{F}}{m} = \vec{a}$$

$$\frac{(k_1+k_2y)\hat{\boldsymbol{i}}+(k_3t)\hat{\boldsymbol{j}}}{m}=\vec{a}$$

$$\left(\frac{k_1 + k_2 y}{m}\right)\hat{\boldsymbol{i}} + \left(\frac{k_3 t}{m}\right)\hat{\boldsymbol{j}} = \vec{a}$$

The idea is to integrate this expression with respect to time for $\vec{v}(t)$, and then once more for $\vec{r}(t)$. There is an issue, however, due to the \hat{i} -component of \vec{F} being expressed in terms of y. This means that we cannot integrate both components simultaneously.

What we can do is integrate the \hat{j} -component of the acceleration to obtain the expression for y. With that known, we can then plug that into the \hat{i} -component and integrate as intended.

Starting with the integration of the \hat{j} -component of \vec{a} :

$$v_y(t) = \int a_y(t) dt + v_{iy}$$

$$= \int \left(\frac{k_3 t}{m} \hat{\boldsymbol{j}}\right) dt + 0$$

$$= \frac{k_3}{m} \hat{\boldsymbol{j}} \int t dt$$

$$= \frac{k_3}{m} \hat{\boldsymbol{j}} \left[\frac{t^2}{2}\right]$$

$$= \frac{k_3 t^2}{2m} \hat{\boldsymbol{j}}$$

Integrating once more:

$$y(t) = \int v_y(t)dt + y_i$$

$$= \int \left(\frac{k_3 t^2}{2m}\hat{\boldsymbol{j}}\right)dt + 0$$

$$= \frac{k_3}{2m}\hat{\boldsymbol{j}}\int t^2 dt$$

$$= \frac{k_3}{2m}\hat{\boldsymbol{j}}\left[\frac{t^3}{3}\right]$$

$$= \frac{k_3 t^3}{6m}\hat{\boldsymbol{j}}$$

Plugging this value of y into the \hat{i} -component of \vec{a} :

$$a_x(t) = \left(\frac{k_1 + k_2\left(\frac{k_3t^3}{6m}\right)}{m}\right)\hat{\boldsymbol{i}}$$

$$= \left(\frac{k_1}{m} + \frac{k_2k_3t^3}{6m^2}\right)\hat{\boldsymbol{i}}$$

Integrating this component for the velocity:

$$v_x(t) = \int a_x(t) dt + v_{ix}$$

$$= \int \left[\left(\frac{k_1}{m} + \frac{k_2 k_3 t^3}{6m^2} \right) \hat{\boldsymbol{i}} \right] dt + 0$$

$$= \left[\frac{k_1 t}{m} + \frac{k_2 k_3 t^4}{24m^2} \right] \hat{\boldsymbol{i}}$$

Integrating once more:

$$x(t) = \int v_x(t) dt + x_i$$

$$= \int \left[\left(\frac{k_1 t}{m} + \frac{k_2 k_3 t^4}{24m^2} \right) \hat{i} \right] + 0$$

$$= \left[\frac{k_1 t^2}{2m} + \frac{k_2 k_3 t^5}{120m^2} \right] \hat{i}$$

Putting it all together for both vectors:

$$\vec{v}(t) = \boxed{ \left[rac{k_1 t}{m} + rac{k_2 k_3 t^4}{24m^2} \right] \hat{i} + rac{k_3 t^2}{2m} \hat{j} }$$

$$\vec{r(t)} = \left[\left[\frac{k_1 t^2}{2m} + \frac{k_2 k_3 t^5}{120m^2} \right] \hat{i} + \frac{k_3 t^3}{6m} \hat{j} \right]$$