# Algebraic Structures and Polynomials

CS70 Summer 2016 - Lecture 7C

David Dinh 03 August 2016

UC Berkeley

## **Today**

Review: Chinese Remainder Theorem and Blum Coin Flipping

Algebraic Structures: Groups, Rings, and Fields

Galois Fields

Polynomials

Applications: Secret Sharing and Erasure Codes

#### Motivation

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Define *algebraic structures* through axioms that define how they behave.

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Notice that there no commutativity requirement. "·" may be non-commutative! If it is commutative, we refer to the group as *abelian*. Formally, Abelian groups must satisfy requires another axiom:

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Also, note that + doesn't necessarily have to represent addition in the normal sense. Elements of G may not even be numbers!

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Examples: With addition and multiplication defined in the usual sense  $\mathbb{R}$ ,  $\mathbb{Q}$ , and  $\mathbb{C}$  are fields.  $\mathbb{Z}$  is a commutative ring but not a field.

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**Definition:** For prime p, the field  $(\mathbb{Z}_p, +, \cdot)$ , with + and  $\cdot$  defined as modular arithmetic  $\pmod{p}$ , is known as the prime field of order p, denoted GF(p).

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A polynomial is said to contain a point (x,y) if p(x) = y.

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$$\begin{array}{rcl}
\widetilde{V_1} &=& a_0 + a_1 \widetilde{x_1} + a_2 \widetilde{x_1} + \dots + a_d \widetilde{x_d} \\
&\vdots \\
\widetilde{V_{d+1}} &=& a_0 + a_1 x_{d+1} + a_2 x_{d+1}^2 + \dots + a_d x_{d+1}^d
\end{array}$$

Or in matrix form:

$$\begin{bmatrix} 1 & x_1 & x_1^2 & \dots & x_1^d \\ 1 & x_2 & x_2^2 & \dots & x_2^d \\ 1 & x_3 & x_3^2 & \dots & x_3^d \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{d+1} & x_{d+1}^2 & \dots & x_{d+1}^d \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_d \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_{d+1} \end{bmatrix}$$

(This matrix is called the Vandermonde matrix.)

How do we know the system of equations on the previous slide has a solution? Unfortunately, we don't. (If you know linear algebra you can prove directly through determinants or through linear independence that the Vandermonde matrix is nonsingular, but that's beyond the scope of this course.)

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$$y_1 = \frac{(n-n_2)(n-n_3)...(n-n_{d+1})^2}{(n_1-n_2)(n_1-n_3)...(n_1-n_{d+1})}$$

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$$\Delta_1(x) := y_1 \frac{(x - x_2)(x - x_3) \dots (x - x_{d+1})}{(x_1 - x_2)(x_1 - x_3) \dots (x_1 - x_{d+1})}$$

Value at  $x_1$ ?

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Value at  $x_1$ ?  $y_1$ . Value at  $x_2, ..., x_{d+1}$ ? 0. General idea behind interpolation: make these polynomials for all i and add them together.

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Now we have a polynomial passing through a collection of d+1 points. Is it the *only* polynomial passing through these points? Or: we know the system given by the Vandermonde matrix has a solution. Is it a unique solution or is the system underdetermined?

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**Theorem 1:** A nonzero polynomial of degree *d* has at most *d* roots.

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We already know there is such a polynomial (we constructed one). Remains to show uniqueness.

#### Proof of Theorem 2

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Given a degree-d polynomial f(x) and a polynomial g(x) of degree at most d, we can use long division to write f(x) = g(x)q(x) + r(x) for some polynomials q(x), r(x) such that the degree of r(x) is strictly smaller than the degree of f(x). Method: same as elementary-school long division for numbers!

Example: divide  $x^3 - 2x^2 - 4$  by x - 3.

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So 
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#### Up next...

Counting polynomials.

Applications: Shamir's secret sharing and error-correcting codes.

Polynomial identity testing and the Schwartz-Zippel lemma