Linear Algebra for Machine Learning and Data

Week 18 System of Linear Equations

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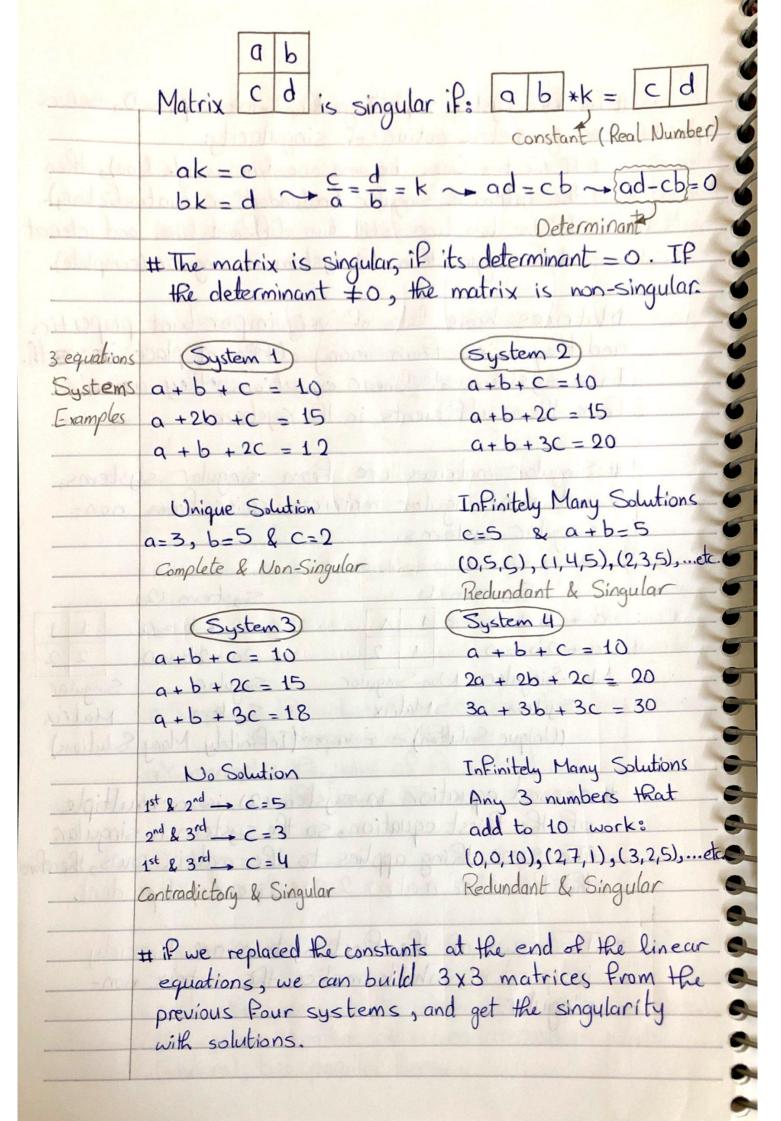
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|-----|------------------------------|--|------------------------------|
| | of equations. contradictions | sentences behaves a Lo IP a system has redund or both, the system is | lancies, called Singular, |
| | otherwise, the | system is complete and | Non-Singular |
| | System 18 | | 461 200 |
| | | apple and 1 banana for \$10 apple and 2 bananas for \$1 | |
| | System 28 | | |
| | | apple and 1 banana for \$ | 610. Day 1 |
| | * You bought 2 | apples and 2 bananas for & | 520. Day 2 |
| | System 3 8 | | |
| ù l | | apple and 1 banana for \$ | |
| | * You bought 2 | apples and 2 bananas for a | \$24. Day 2 |
| | System 1 | System 2 | System 3 |
| | a + b = 10 | | a+b=10 |
| | a + 2b = 12 | 2a + 2b = 20 | 2a + 2b = 24 |
| | Unique Solution | Infinite Solutions | No Solution |
| | a = 8 | a=8 7 6 | 859F4 |
| | b = 2 | b=2'3'4" | na Jo |
| | Complete | Redundant | Contradictory |
| - | Non-Singular | Singular | Singular |
| | | | |

| #Y-intercept: the value of the vertical axis at which #Y-intercept: the value of the vertical axis at which #Re line or the curve passes. (1) slope = -1 Y-intercept = 10 **He Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will averlape each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | | Linear Equation | Non-Linear Equation | | | | |
|--|--|---|--|--|--|--|--|
| 20 + 3b = 15 3.4a + 48.99 b - 2c = 122.5 3.4a + 48.99 b - 2c = 122.5 ab ² + b - 3 - log(c)=4 ^a # Linear equations can be represented as lines on the coordinate plane systems. 12 tb (2,12) to (0,10) of 2 linear equations (-8,10) a + b = 10 (1) - a + 2b = 12 (2) 4 4 4 Slope: is the value that describes the direction and the steepness of the line. #Y-intercept: the value of the vertical axis at which the line or the curve passes. (1) slope = -1 Y-intercept = 10 Y-intercept = 6 # Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will averlap each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | | a+b=10 | $a^2 + b^2 = 10$ | | | | |
| # Linear equations can be represented as lines on the coordinate plane systems. This is a system (-2,12) to (0,10) 8 (2,3) - a+b=10 (1) - a+2b=12 (2) 4 (8,2) - 3 - 6 (4 -2 -2 2 4 6 8 10 12 (10,0) 12-0) 4 Slope: is the value that describes the direction and the steepness of the line. #Y-intercept: the value of the vertical axis at which the line or the curve passes. (1) slope = -1 Y-intercept = 10 Y-intercept = 6 # Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will are hap each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | | | The second secon | | | | |
| # Linear equations can be represented as lines on ## Linear equations can be represented as lines on ## Coordinate plane systems. [2,12] to (0,10) 8 (0,6) - a + b = 10 (1) - a + 2b = 12 (2) ## Slope: is the value that describes the direction and ## Fintercept: the value of the line. ## V-intercept: the value of the vertical axis at which ## line or the curve passes. [1] slope = -1 Y-intercept = 10 ## Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will are the each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | St. Control of the Co | 3.4a + 48.99b - 2c = 122.5 | | | | | |
| # Linear equations can be represented as lines on #Re coordinate plane systems. 12 tb This is a system 12 tb (2,3) - a +b = 10 (1) - a +2b = 12 (2) - 8 6 4 -2 2 2 4 6 8 10 12 (12,2) 14 Slope: is the value that describes the direction and # steepness of the line. # Y-intercept: the value of the vertical axis at which # line or the curve passes. (1) slope = -1 Y-intercept = 10 # Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will are the each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | White and the control of the control | | ab2 + b - 3 - log(c)=4 | | | | |
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| the coordinate plane systems. This is a system of 2 linear equations (1-8,10) a +b = 10 u) -a+2b=12 (2) 4 Slope: is the value that describes the direction and the steepness of the line. #Y-intercept: the value of the vertical axis at which the line or the curve passes. (1) slope = -1 Y-intercept = 10 # Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will overlap each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | | # Linear equations can be rep | Linear equations can be represented as lines on | | | | |
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| # Slope: is the value that describes the direction and the steepness of the line. #Y-intercept: the value of the curve passes. (1) slope = -1 Y-intercept = 10 # Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will averlap each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | | (-2,12) | 6// | | | | |
| # Slope: is the value that describes the direction and the steepness of the line. #Y-intercept: the value of the vertical axis at which the line or the curve passes. (1) slope = -1 Y-intercept = 10 # Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will averlape each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | | This is a system 10 | | | | | |
| # Slope: is the value that describes the direction and the steepness of the line. #Y-intercept: the value of the vertical axis at which the line or the curve passes. (1) slope = -1 Y-intercept = 10 # Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will averlap each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | | | | | | | |
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| (1) slope = -1 Y-intercept = 10 W-intercept = 6 # Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will averlap each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | Carella | | | | | | |
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| Y-intercept = 10 Y-intercept = 6 # Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will overlap each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | 10 to 10 | 101 - 3 x DE | | | | | |
| # Because (1) & (2) has a unique solution, the intersect at one point. For system 2, the two lines will overlap each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | 110 - 25 | VI 1 C L C | | | | | |
| each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | | | | | | | |
| each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | | all souther stated | 11: 10 itset | | | | |
| each other, giving infinite intersection points (solutions). For system (3), there will be no intersection points | | # Because (1) & (2) has a uniq | me solution, the intersect | | | | |
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| for system (3), There will be no intersection points | | each other, giving infinite interse | ection points (solutions). | | | | |
| 1 1 1 20 1 1 20 000 | Canal Mante | for system (3), There will be no | intersection points | | | | |
| (solutions); two parallel lines. | | (solutions); two parallel wires. | Thingas energy | | | | |

for line systems, putting the Y-intercept = 0, serves Applies Por as geometric notion of singularity: system of 1. If the two lines become one line (single line), then 2 linear the system is singular (redundant or contradictory). = equations 2. If the two lines still two different lines and intersect at the origin, then the system is singular (complete). -Matrices have lots of very important properties and they arise from many different place in math. In a system of linear equations, they arise 0 2 from the coefficients in the system. 2 # Singular matrices are from singular systems, and non-singular matrices arise from non-singular systems. -System (1) System (2) a + b = 0 a + b = 0 1 -2a + 2b = 0Mostrices a+2b=0-Singular Singular System Matrix Non-Singular Non-Singular -System Matrix -(Infinitely Many Solutions) (Unique Solution) -# second equation in system (2) is a multiple of the first equation, so the system is singular. The same thing applies to the matrix rows, therefore the Rows of matrix 2 are linearly dependent. ----# The rows of the first system are linearly independent, which makes the matrix non-singular. ---



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|---|-----------------|---|--|---|--|--|--|
| 5 | | System 1 | 6 8 40 | 2 & System 3 | 5 4 11 | | |
| 5 | 2 4 2 | | System | 2 & System S | System 4 | | |
| 9 | 3×3 Matrices | 11117 | | 1 1 | $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix}$ | | |
| 5 | 1 (urrices | $\begin{bmatrix} 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$ | 9 1 7 | 1 2 1 3 | 2 2 2 | | |
| 9 | | | | | [5 5 5] | | |
| 3 | , | Carlota | . 0 | edundant | Redundant | | |
| 9 | 700 | Complete | | ingular | | | |
| 9 | | Non-Singular | | ingular | Singular | | |
| 9 | | matrix of | | 1 0: somet | olana — | | |
| 9 | | #1System one | in graph: ea | ch line represents | a plane. The | | |
| 9 | / | three planes | intersed at a | one point lung | ue solution) | | |
| 9 | | matrix of | 10) (6 | 10 -1 | internali | | |
| 3 | | #15ystems 28: | s in graph ai | re three planes | intersecting | | |
| 3 | 7 9 | al a line. | Solutions are | re three planes all the points o | in that line. | | |
| 3 | | 1 | Del and the second | 1 | The same of the sa | | |
| - | 4 91 | #Matrix of | system 4 in g | graph are three point on that p | identical planes. | | |
| 3 | 10 - W b | the solution | can be any | point on that p | olane. | | |
| 3 | 1.34 | | | | | | |
| 3 | 1,000 0 0 10 f | Linear Independence in 3x3 Matrices: | | | | | |
| 3 | Rows of | | | | | | |
| 3 | the Matrix are | Matrix is dependent, if: | | | | | |
| 3 | are | - One row's sum equal to a multiple of the two | | | | | |
| 3 | | other rows. (Matrix of systems 283) | | | | | |
| 3 | | one row is the multiple of the other (Matrix of system 4) | | | | | |
| - | | Otherwise, the matrix rows are independent (Matrix of system 1) | | | | | |
| - | | | | | | | |
| - | R, | 0 1 0 | [1 1 1] | [1 1 1] | 11 2 5 7 | | |
| - | R ₂ | 0 1 0 | $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 2 \\ 0 & 0 & -1 \end{bmatrix}$ | $\begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{bmatrix}$ | $\begin{bmatrix} 1 & 2 & 5 \\ 0 & 3 & -2 \\ 2 & 4 & 10 \end{bmatrix}$ | | |
| 3 | К3 | 3 2 3 | | | | | |
| - | | $3R_1 + 2K_2 = R_3$ | $R_1 - R_2 = R_3$ | No Relation | $2R_1 = R_3$ | | |
| - | | Descript | One dost | Todopoodest | Decodost | | |
| - | | Dependant | Dependent | Independent | Dependent | | |
| - | | 15:00 | 150000 | | 1 (2211 212) | | |
| 9 | | (Singular) Determinant=0 | (Singular) Determinant=0 | (Non-Singular) Determinant=6 | (Singular) Determinant=0 | | |

