

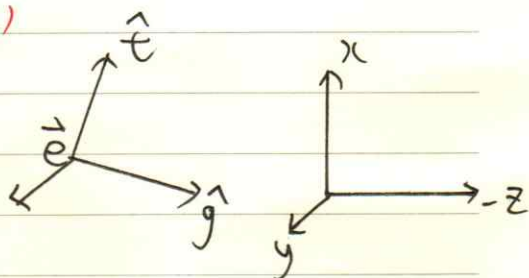
View / Camera Transformation 视图变换 / 相机变换

- 步骤
- ① 将相机位置 \vec{e} 移到 $(0, 0, 0)$
 - ② 将相机观察方向 \hat{g} 移到 $-z$ 轴方向
(gaze direction)
 - ③ 将相机的上方向 \hat{t} 移到 y 轴方向
(up direction)

如何表示:

$$M_{\text{view}} = R_{\text{view}} T_{\text{view}}$$

(视图矩阵) (再旋转) (先平移)



$$T_{\text{view}} = \begin{pmatrix} 1 & 0 & 0 & -x_e \\ 0 & 1 & 0 & -y_e \\ 0 & 0 & 1 & -z_e \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

R_{view} 不好写, 先写 R_{view}^{-1} , $(R_{\text{view}})^T$ 就是 R_{view} .
(正交矩阵)

$$R_{\text{view}}^{-1} = \begin{pmatrix} x_{\hat{g} \times \hat{t}} & x_t & x_{-g} & 0 \\ y_{\hat{g} \times \hat{t}} & y_t & y_{-g} & 0 \\ z_{\hat{g} \times \hat{t}} & z_t & z_{-g} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$R_{\text{view}} = \begin{pmatrix} x_{\hat{g} \times \hat{t}} & y_{\hat{g} \times \hat{t}} & z_{\hat{g} \times \hat{t}} & 0 \\ x_t & y_t & z_t & 0 \\ x_{-g} & y_{-g} & z_{-g} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$