Using low-rank tensor formats to enable computations of cancer progression models in large state spaces

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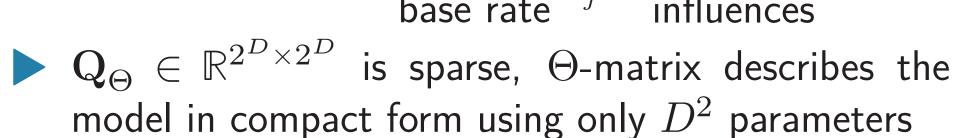
Summary

- Comprehensive cancer progression models should include a high number D of genomic events
- Mutual Hazard Networks model the progression process using only \mathbb{D}^2 parameters [1]
 - Computational complexity of a straight-forward implementation still scales exponential in D
 - \triangleright Calculations using $\gtrsim 25$ events are computationally infeasible [2]
- Tensor Trains allow for cost-efficient storage and calculations for high-dimensional tensors
 - This method reduces the computational complexity from exponential to polynomial in D

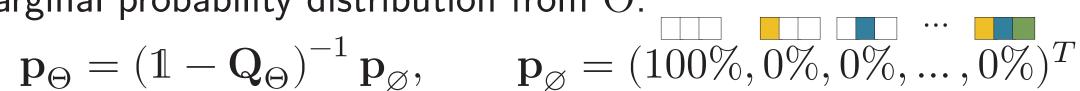
Mutual Hazard Network (MHN) model

- MHN models tumor progression as a continuous-time Markov chain on the 2^{D} -dimensional state space of possibly active events [1]
- Events can only occur one at a time
- Transition rates are given by

$$\mathbf{Q}_{\mathbf{x} o \mathbf{x}_{+i}} = \underbrace{\Theta_{ii}}_{ ext{base rate}} \prod_{\mathbf{x}_{j}=1}^{} \underbrace{\Theta_{ij}}_{ ext{influences}}$$







 \triangleright Optimal Θ matrices are found by optimizing the time marginalized Kullback-Leibler divergence from the given data distribution $\mathbf{p}_{\mathcal{D}}$:

$$S_{\mathrm{KL}}(\mathbf{p}_{\Theta}) = \sum_{\mathbf{x}} (\mathbf{p}_{\mathcal{D}})_{\mathbf{x}} \log ((\mathbf{p}_{\Theta})_{\mathbf{x}})$$

Gradients can be calculated analytically:

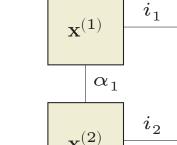
$$\frac{\partial S_{\mathrm{KL}}}{\partial \Theta_{ij}} = \underbrace{\frac{\partial S_{\mathrm{KL}}}{\partial \left(\mathbf{p}_{\Theta}\right)_{\mathbf{x}}} \left(\mathbb{1} - \mathbf{Q}_{\Theta}\right)_{\mathbf{xy}}^{-1}}_{\mathbf{q}_{\mathbf{y}}} \left(\frac{\partial \mathbf{Q}_{\Theta}}{\partial \Theta_{ij}}\right)_{\mathbf{yz}} \left(\mathbf{p}_{\Theta}\right)_{\mathbf{z}}$$

Score and gradient calculation time is dominated by solution time of two linear equations:

$$(\mathbb{1} - \mathbf{Q}_{\Theta}) \, \mathbf{p}_{\Theta} = \mathbf{p}_{\varnothing} \qquad (\mathbb{1} - \mathbf{Q}_{\Theta})^T \, \mathbf{q} = \frac{\partial S_{\mathrm{KL}}}{\partial \mathbf{p}_{\Theta}}$$

Tensor Train (TT) representation

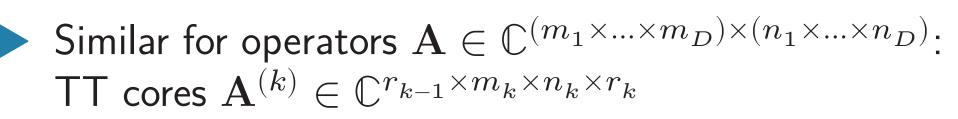
D-dimensional tensors $\mathbf{x} \in \mathbb{C}^{n_1 \times ... \times n_D}$ can be written as a product of D Tensor Train cores $\mathbf{x}^{(k)} \in \mathbb{C}^{r_{k-1} \times n_k \times r_k}$:

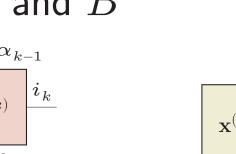


 $\Theta_{22}\Theta_{23}$

$$\mathbf{x}(i_1,\ldots,i_D) = \mathbf{x}^{(1)} \circ \ldots \circ \mathbf{x}^{(D)}$$

 $A \circ B$ denotes contraction of the last and first indices of A and B





Storage cost goes from exponential to linear in D, but additional dependency on TT ranks is introduced

Many arithmetic operations are performable directly in the TT format, reducing the computational complexity [3]:

Superposition $\lambda \mathbf{a} + \nu \mathbf{b}$: $\mathcal{O}\left(Dn(r_{\mathbf{a}} + r_{\mathbf{b}})^2\right)$

 $n := \max(n_k)$ Inner product $\langle \mathbf{a}, \mathbf{b} \rangle$: $\mathcal{O}\left(Dnr_{\mathbf{a}}r_{\mathbf{b}}(r_{\mathbf{a}} + r_{\mathbf{b}})\right)$ analogously for $m, r_{\mathbf{X}}$

Operator-by-Tensor product \mathbf{Ab} : $\mathcal{O}\left(Dmn(r_{\mathbf{A}}r_{\mathbf{b}})^2\right)$

Linear equations $\mathbf{A}\mathbf{x}=\mathbf{b}$ can also be solved efficiently directly in the format

References

- [1] R. Schill, S. Solbrig, T. Wettig, and R. Spang, Modelling cancer progression using mutual hazard networks, Bioinformatics 36 (January, 2020) 241.
- [2] P. Georg, L. Grasedyck, M. Klever, R. Schill, R. Spang, and T. Wettig, Low-rank tensor methods for markov chains with applications to tumor progression models, Journal of Mathematical Biology 86 (December, 2022).
- [3] P. Georg, Tensor train decomposition for solving high-dimensional mutual hazard networks, PhD thesis, Universität Regensburg, October, 2022.

Tensor Trains for MHN

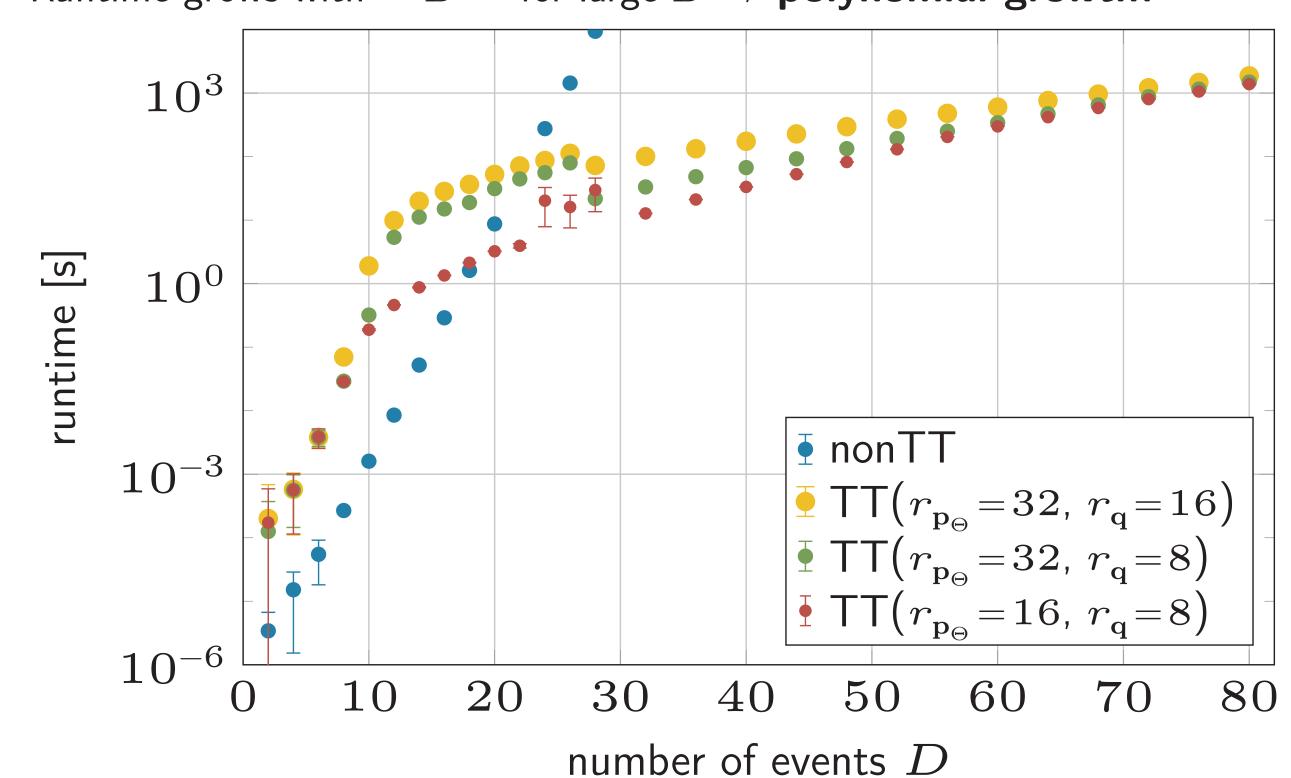
- lacksquare Events are binary $\rightarrow n_k = 2$ for all mode sizes
- $ightharpoonup \mathbf{Q}_{\Theta}$ can naturally be written as a Tensor Train [1]:

$$\mathbf{Q}_{\Theta} = \sum_{i=1}^{D} \left(\bigotimes_{j=1}^{i-1} \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & \Theta_{ij} \end{pmatrix}}_{\in \mathbb{R}^{1 \times 2 \times 2 \times 1}} \otimes \underbrace{\begin{pmatrix} -\Theta_{ii} & 0 \\ \Theta_{ii} & 0 \end{pmatrix}}_{\in \mathbb{R}^{1 \times 2 \times 2 \times 1}} \otimes \underbrace{\bigotimes_{j=i+1}^{D} \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & \Theta_{ij} \end{pmatrix}}_{\in \mathbb{R}^{1 \times 2 \times 2 \times 1}} \right)$$

- $ightharpoonup \mathbf{Q}_{\Theta}$ is a sum of D rank-1 Tensor Trains
- $\triangleright \mathbf{Q}_{\Theta}$ has TT-ranks D
- \mathbf{p}_{\varnothing} is a canonical unit Tensor Train, also has TT-rank 1
- ${f p}_{\Theta}$ and ${f q}$ can be calculated in the TT format (max. TT ranks $r_{{f p}_{\Theta}}$ and $r_{{f q}}$)
- lacksquare for gradients, each non-zero element in $\mathbf{p}_{\mathcal{D}}$ has to be treated individually
- \triangleright one linear equation has to be solved for each entry of $\mathbf{p}_{\mathcal{D}}$ (usually ~ 1000)
- this can trivially be parallelized

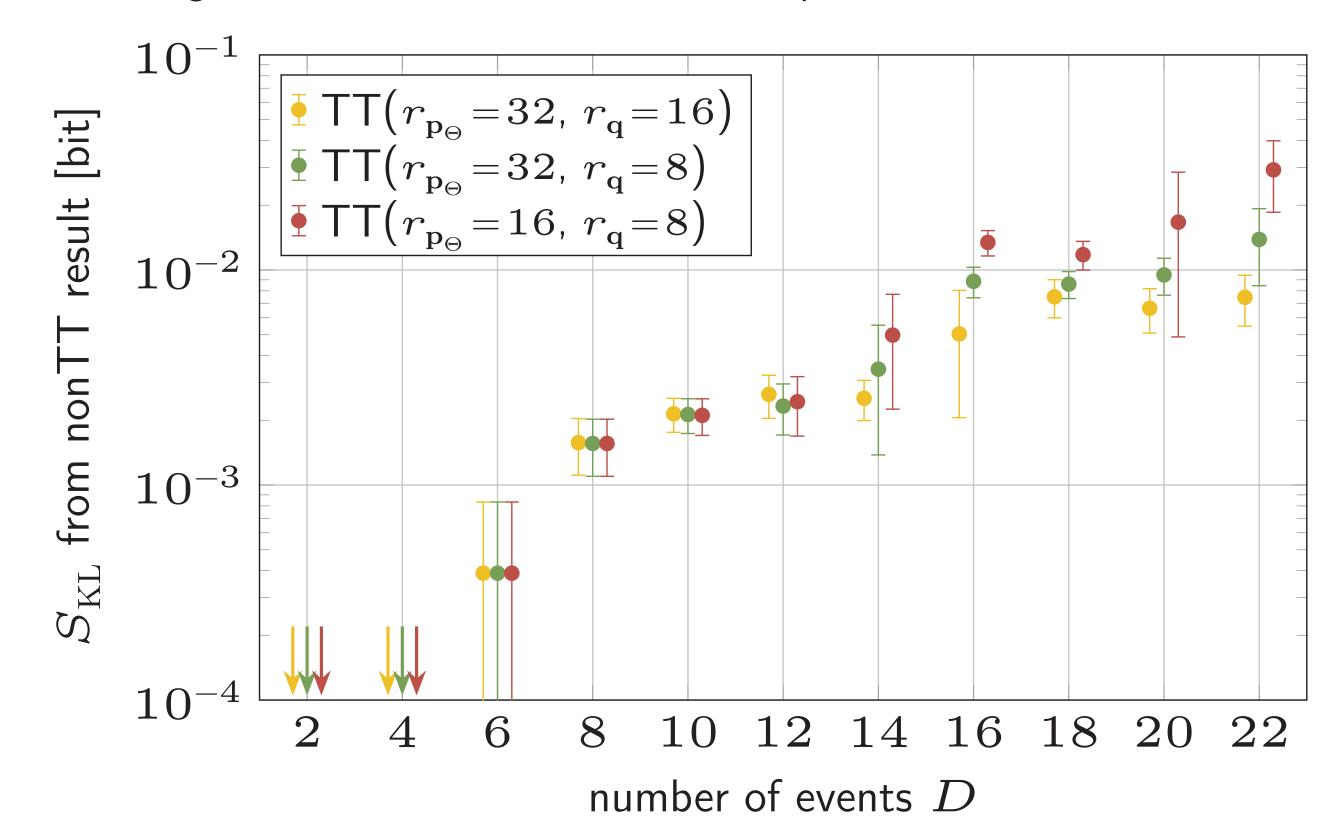
Results: Runtime improvement

- Runtime for one score and gradient calculation
- ${f p}_{\mathcal D}$ constructed from 1000 random samples, Θ at independence model
- Nuntime grows with $\sim D^{5.4}$ for large $D \Rightarrow$ polynomial growth!



Results: Accuracy of the TT solution

 \blacktriangleright KL-divergence from nonTT result after full optimization of Θ



Code availablility

- C++ library for TT-calculations pRC: gitlab.com/pjgeorg/pRC
- application-specific C++ library cMHN that utilizes pRC for MHN-calculations: soon to be open-source

Future improvements

- Reduce runtime by accellerating solution of linear equations in the TT format
- Include development of metastases into the model